



Modeling Cortical Dynamics in Visually-Evoked Responses Using the Human Neocortical Neurosolver (HNN)

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Introduction

- V1: first cortical stage of visual processing; key for transforming retinal input into perception.
- VEPs (C1: 50–90 ms; N1: 140–200 ms) reflect early and later visual responses, but their precise neural sources remain unclear.
- In previous work, HNN has been used to investigate ERPs in other sensory areas: A1 and S1 (Jones, 2007; Kohl, 2021).
- While V1 has unique network characteristics compared to other sensory cortices, it shares a common layered structure, pyramidal neurons that span across the layers, and layer specific thalamic and cortical input trajectories.
- **Here, we test whether HNN can reproduce a VEP.**

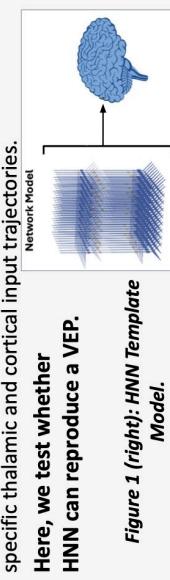


Figure 1 (right): HNN Template Model.

Results

A Sequence of Thalamocortical Drive can Generate VEP

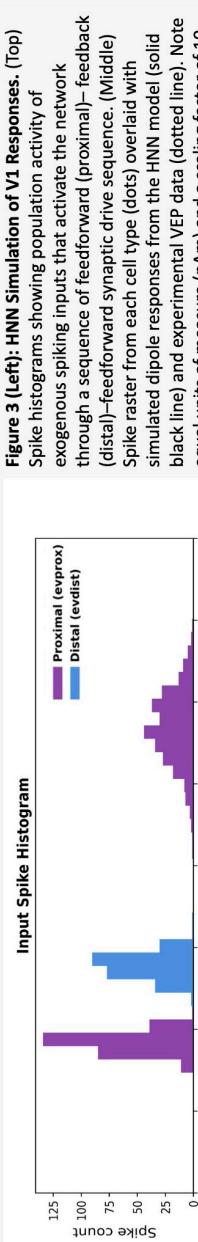


Figure 3 (Left): HNN Simulation of V1 Responses. (Top) Spike histograms showing population activity of exogenous spiking inputs that activate the network through a sequence of feedforward (proximal)—feedback (distal)—feedforward synaptic drive sequence. (Middle) Spike raster from each cell type (dots) overlaid with simulated dipole responses from the HNN model (solid black line) and experimental VEP data (dotted line). Note equal units of measure (nAm) and a scaling factor of 10. When comparing the two dipole waveforms, the root-mean-square error (RMSE) was 0.04, indicating a close match between the simulated and experimental signals. Figure 4 (Below): Layer-Specific Dipoles.

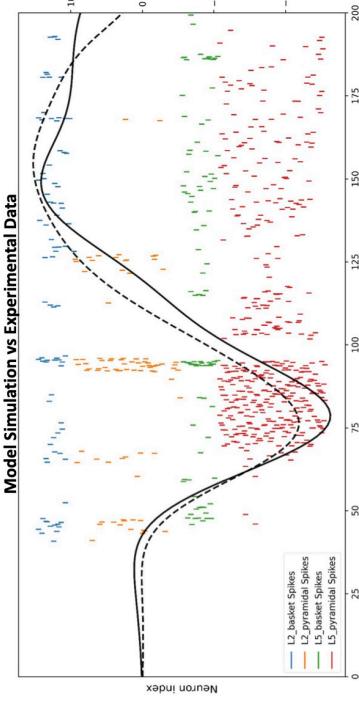


Figure 3 (Right): Model Simulation vs Experimental Data. (Top) Smoothed + Scaled data. (Middle) Original data. (Bottom) Aggregate (L2/3 + L5) data. ● HNN successfully reproduced VEPs, capturing major features of C1 and N1 components, using a sequence of feedforward–feedback–feedforward drives across cortical layers. ● Previous SEP (Jones, 2007) and AEP (Kohl, 2021) simulations (Figure 5, Left) show similar peak timings and orientations, which together with literature motivated the chosen sequence of thalamocortical drive. Parameters were tuned to closely match recorded dipoles, producing multiscale, layer-specific spiking patterns consistent with other studies. ● Ongoing studies are examining the corresponding LFP/CSD.

Discussion

- V1 ERPs were successfully modeled in HNN using a sequence of feedforward–feedback–feedforward drives across cortical layers.
- Multiscale simulations provide several targets for validation of model-based predictions.
- Layer-specific spiking predictions provide mechanistic insight into how different cortical layers contribute to the observed VEP.
- The commonalities with prior SI and A1 evoked response simulations suggest macroscale ERPs are constrained by commonalities in cortical structure and thalamocortical projection patterns, despite finer scale circuit difference.
- Findings suggest that early thalamic input, feedback modulation, and recurrent excitation together shape the major VEP components.

Contact / Funding

Contact:

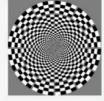
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Link to HNN Textbook

- <https://doi.org/10.1109/ACCESS.2023.3274053>
- [Poster PDF](https://doi.org/10.1109/ACCESS.2023.3274053)
- [QR code](https://doi.org/10.1109/ACCESS.2023.3274053)
- [Poster PDF](https://doi.org/10.1109/ACCESS.2023.3274053)



- [Inverso, S. et al. \(2016\). From evoked potentials to cortical currents: Resolving V1 and V2 components using rhythmic constrained source estimation without MRI. *Human Brain Mapping*.](https://doi.org/10.1109/ACCESS.2023.3274053)
- [Jaschinski, M. et al. \(2023\). HNN: core Python software for cellular and circuit-level interpretation of human MEG and EEG.](https://doi.org/10.1109/ACCESS.2023.3274053)
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