

PLATFORM

Platformio

- Apakah itu?

- PlatformIO is an open source ecosystem for IoT development
- Cross-platform IDE and unified debugger.
- Remote unit testing and firmware updates
(<http://platformio.org/>)

- Spesifikasi

- **Cross-platform** build system without external dependencies to the OS software: 400+ embedded boards, 15+ development platforms, 10+ frameworks
- C/C++ Intelligent Code Completion and Smart Code Linter for rapid professional development
- Multi-projects workflow with multiple panes and Themes support with dark and light colors
- Built-in Terminal with PlatformIO Core and powerful Serial Port Monitor

Platformio

- **Kebutuhan Sistem**

- OS : Windows, macOS, Linux, FreeBSD, Linux ARMv6+
- Python Interpreter : Python 3.5 above
- CLang Interpreter : 3.9.1 version

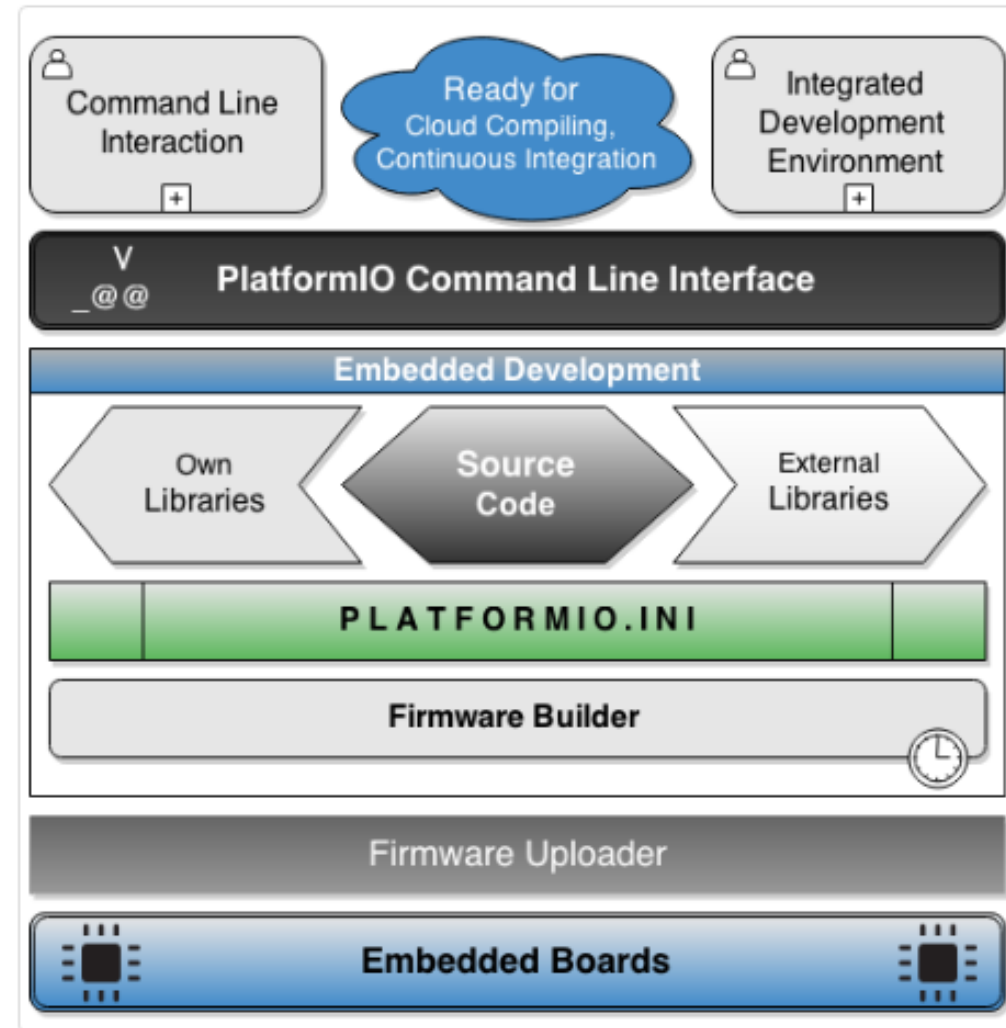
- **PERINGATAN**

**MATIKAN SEMUA ANTIVIRUS DAN FIREWALL SEBELUM MEMULAI INSTALASI
SEMUA PROGRAM RUN AS ADMINISTRATOR**

Embedded Development. Easier Than Ever.

PlatformIO is well suited for embedded development and has pre-configured settings for the most popular [Embedded Boards](#).

- ✓ **Colourful** command-line output
- ✓ **IDE Integration** with *Cloud9*, *Codeanywhere*, *Eclipse Che*, *Atom*, *CLion*, *CodeBlocks*, *Eclipse*, *Emacs*, *NetBeans*, *Qt Creator*, *Sublime Text*, *Vim*, *Visual Studio*
- ✓ Cloud compiling and **Continuous Integration** with *AppVeyor*, *Circle CI*, *Drone*, *Shippable*, *Travis CI*
- ✓ Built-in **Serial Port Monitor** and configurable **build -flags/-options**
- 👍 Pre-built toolchains, **frameworks** for the popular **development platforms**



The screenshot displays the PlatformIO IDE interface with several key components:

- Left Sidebar:** Contains navigation icons for Home, Check, Run, Trash, Bugs, Recent, Extensions, and Settings.
- Project Explorer:** Shows the file structure of the 'PlatformIO' project, including 'lib', 'src', and 'platformio.ini'.
- Code Editor:**
 - The top editor shows `blink.cpp` with C++ code. A blue callout bubble labeled "Intelligent Code Completion" points to the `Serial.begin` method.
 - The bottom editor shows `wiring_digital.c` with C code. A blue callout bubble labeled "Smart Code Linter" points to a line of code.
- Right Sidebar:**
 - Watch Variables:** A table showing expressions, watchpoint (WP) status, and values.

Expression	WP	Value
Serial		{...}
HardwareSerial	<input type="checkbox"/>	{...}
sercom		0x200007
sercom		0x42001c
I2CM		{...}
I2CS		{...}
SPI		{...}
USART		{...}
rxBuffer		{...}
_aucBuffer		[64]
_jHead	<input type="checkbox"/>	0
_jTail	<input type="checkbox"/>	0
uc_pinRX	<input checked="" type="checkbox"/>	36 '\$'
uc_pinTX	<input checked="" type="checkbox"/>	35 '#'
uc_padRX	<input type="checkbox"/>	SERCOM_
uc_padTX	<input type="checkbox"/>	SERCOM_
LED_BU	<input type="checkbox"/>	
 - Breakpoints:** Shows a breakpoint set at `in loop() at blink.cpp:22`.
 - Call Stacks:** Shows the current thread stack, including `#0 in digitalWrite() at wiring_digital.c:82`.
- Bottom Status Bar:** Displays the current file (`src/blink.cpp`), line numbers (`1 1 0`), time (`15:14`), and the current execution point (`#0 in digitalWrite() at wiring_digital.c:82`).

Platformio + Atom Editor

1. Install Python 3.7.9 (32bit atau 64bit sesuaikan OS Anda)
<https://www.python.org/downloads/release/python-379/>
2. Install CLang 3.9.1 (Install di path tanpa spasi. Restart PC Anda)
<http://releases.llvm.org/download.html>

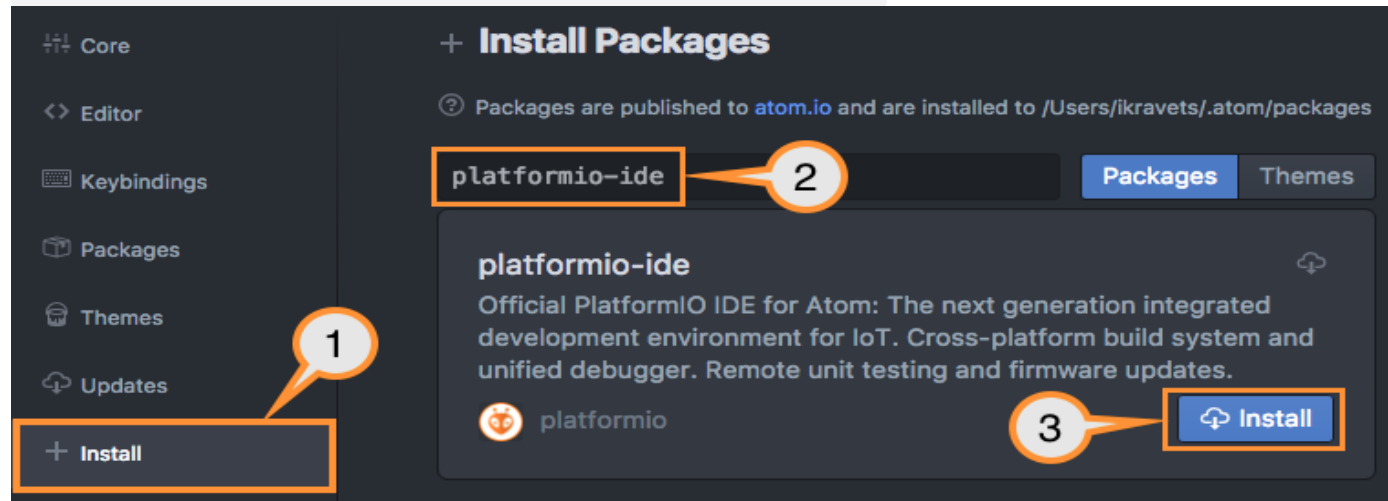
Platformio + Atom Editor

3. Install Atom Editor. Pilih portable version saja

<https://github.com/atom/atom/releases/download/v1.54.0/atom-windows.zip>

4. Install Platformio

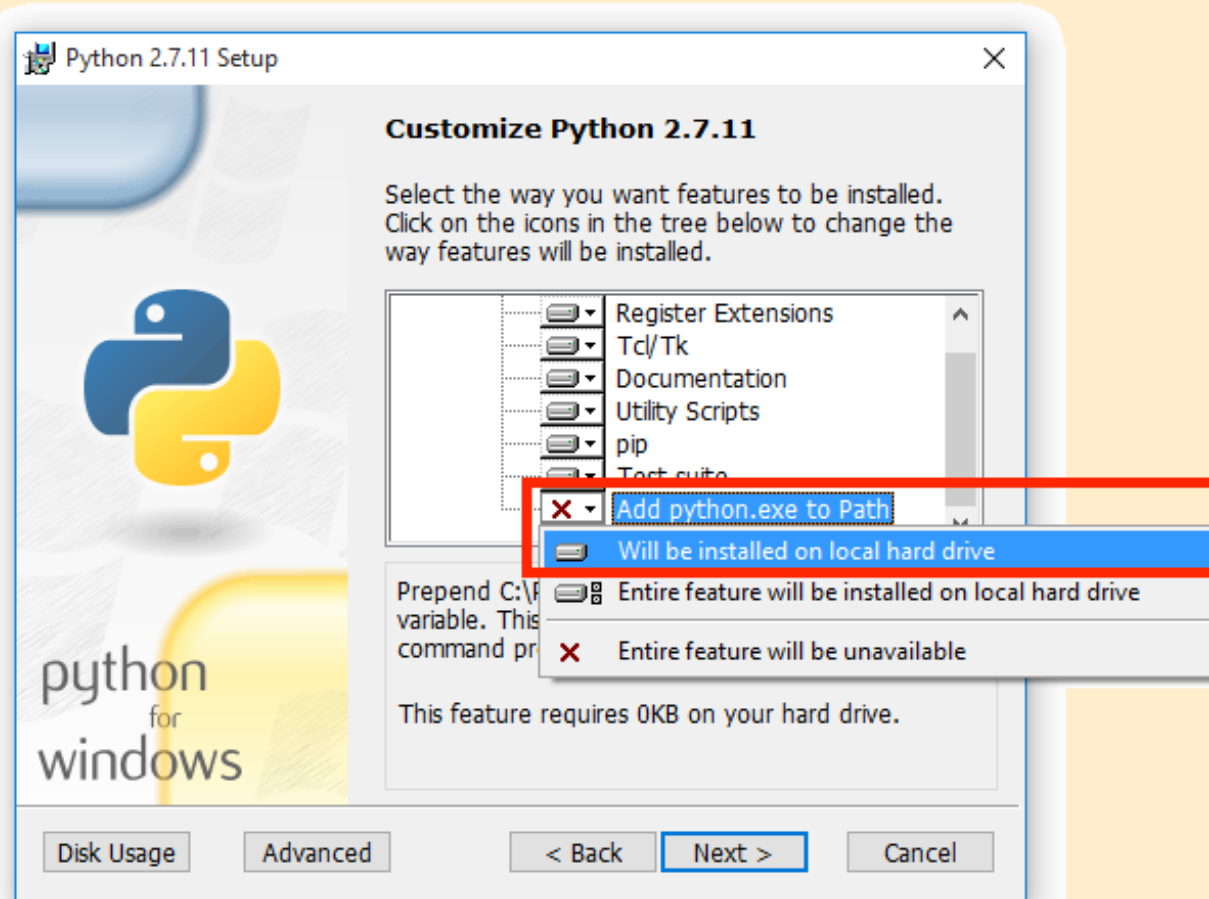
Menu: File > Settings > Install



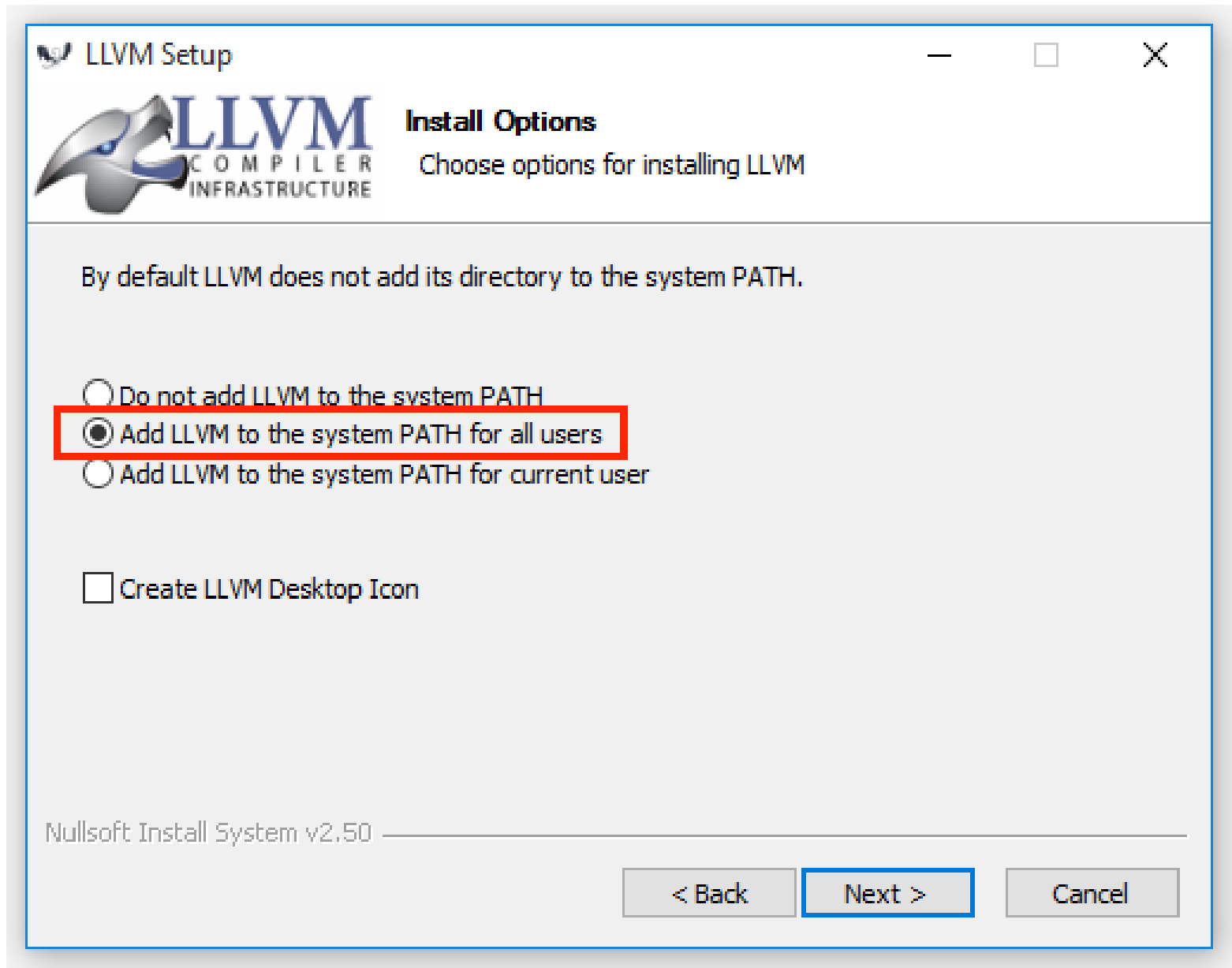
Jangan lupa ini!

Attention

Windows Users: Please [Download the latest Python 2.7](#) and install it. **DON'T FORGET** to select `Add python.exe to Path` feature on the "Customize" stage, otherwise Python Package Manager `pip` command will not be available.



Jangan lupa ini!



Driver CP2102

1. Download dan *install* dari :

<https://www.silabs.com/products/development-tools/software/usb-to-uart-bridge-vcp-drivers>

Driver CH340G

1. Download dan *install* dari :

<https://kelasrobot.com/cara-install-usb-driver-ch340g-ch340-untuk-arduino/>

[https://www.dropbox.com/s/q0u00s6yd4bhw8w/USB Driver CH340G.rar?dl=0](https://www.dropbox.com/s/q0u00s6yd4bhw8w/USB%20Driver%20CH340G.rar?dl=0)

SDK ARDUINO ESP8266 PLATFORMIO

- Proses instalasinya lama banget,hehehehe....
- Instruktur akan memberikan file SDK dalam format **zip**
- Ekstrak ke folder di PC Anda. **Nama folder tidak boleh ada spasi!!!**
- Misal : **D:\PIO**

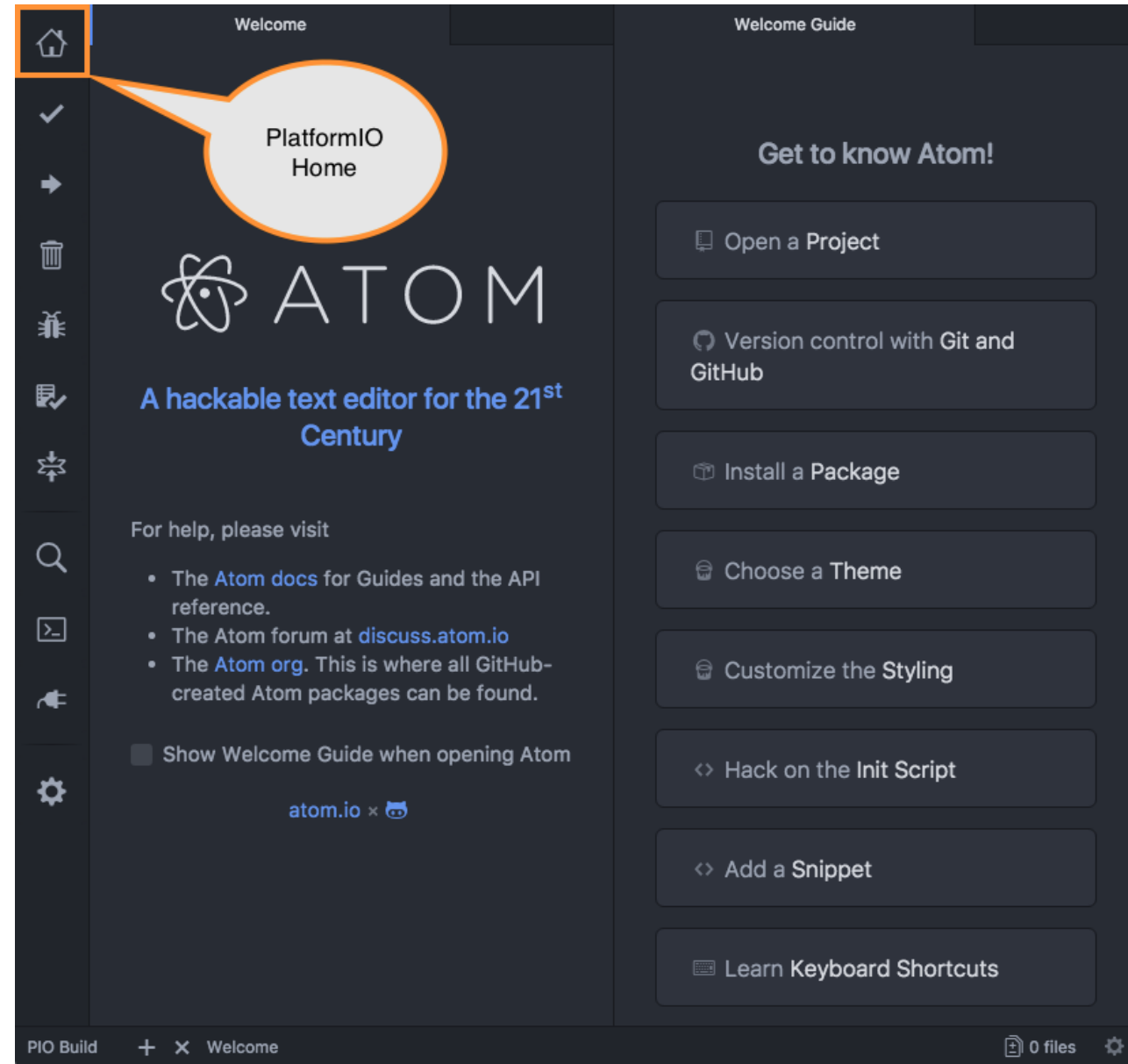






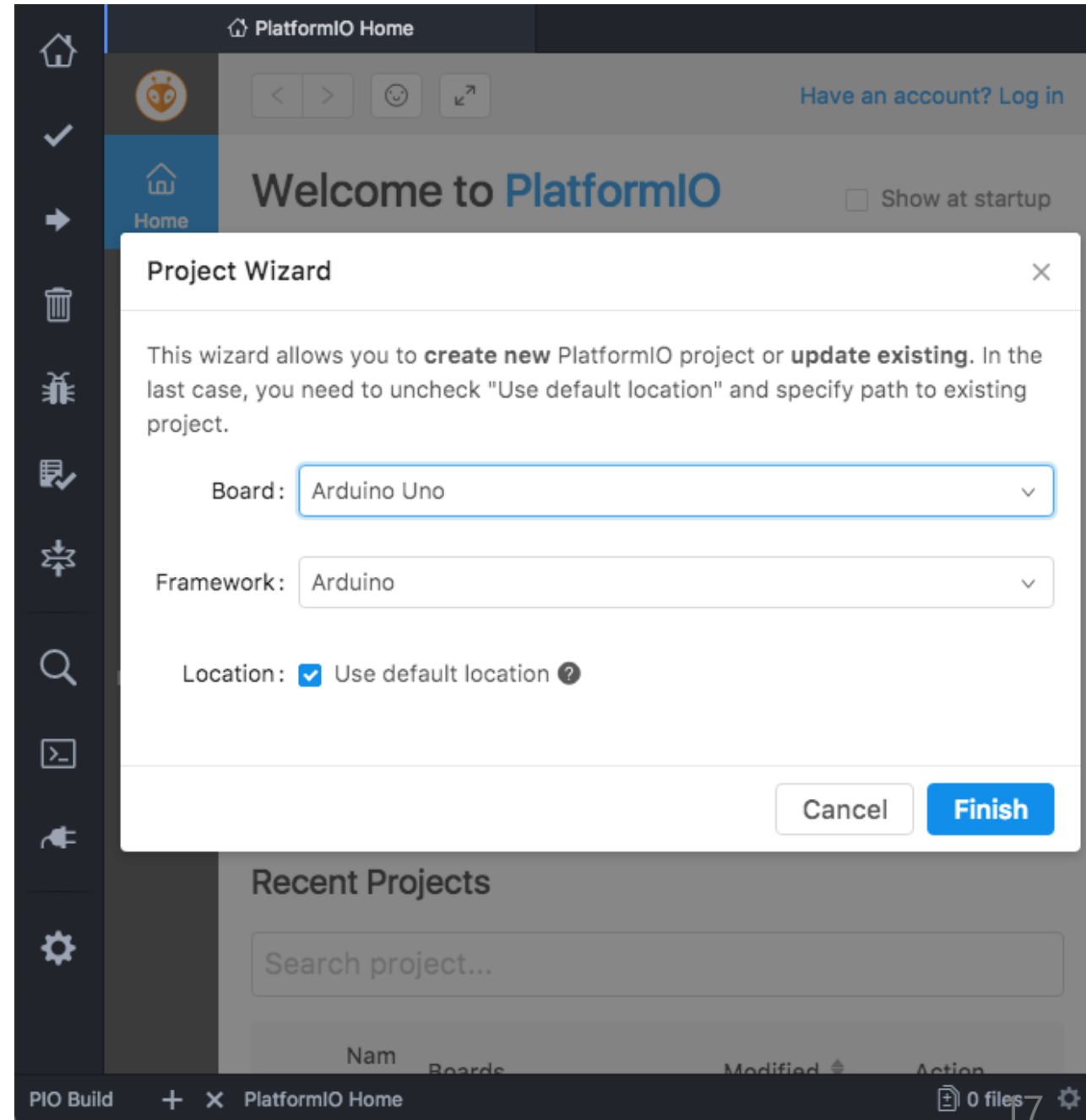
Platformio Quick Start

1. Jalankan Atom, Platformio akan mulai terbuka. Harap bersabar bagi yang *low spec* PC



Platformio Quick Start

2. Klik **New Project**, pilih nama modulnya (Nodemcu v1.0), dan finish
3. Tunggu sampai selesai instalasi SDK-nya dan software pendukungnya. **SANGAT LAMA KETIKA PERTAMA KALI**. Silakan ngopi dulu ^_^



Platformio Quick Start

4. Buat file baru di folder `src` , misal : *main.cpp*

```
/**
 * Blink
 *
 * Turns on an LED on for one second,
 * then off for one second, repeatedly.
 */
#include <Arduino.h>

// Set LED_BUILTIN if it is not defined by Arduino framework
// #define LED_BUILTIN 13

void setup()
{
    Serial.begin(57600);

    // initialize LED digital pin as an output.
    pinMode(LED_BUILTIN, OUTPUT);
}
```

```
void loop()
{
    // turn the LED on (HIGH is the voltage level)
    digitalWrite(LED_BUILTIN, HIGH);

    // wait for a second
    delay(1000);

    // turn the LED off by making the voltage LOW
    digitalWrite(LED_BUILTIN, LOW);

    // wait for a second
    delay(1000);

    Serial.println(millis());
}
```

Project

170905-185203-un

lib

src

G+ main.cpp

platformio.ini

G+ main.cpp

```
1  /**
2   * Blink
3   *
4   * Turns on an LED on for one second,
5   * then off for one second, repeatedly.
6   */
7   #include "Arduino.h"
8
9   // Set LED_BUILTIN if it is not defined by Arduino
10  // #define LED_BUILTIN 13
11
12  void setup()
13  {
14      // initialize LED digital pin as an output.
15      pinMode(LED_BUILTIN, OUTPUT);
16  }
17
18  void loop()
19  {
20      // turn the LED on (HIGH is the voltage level)
21      digitalWrite(LED_BUILTIN, HIGH);
22
23      // wait for a second
24      delay(1000);
25
26      // turn the LED off by making the voltage level
```

PIO Build

+ X src/main.cpp

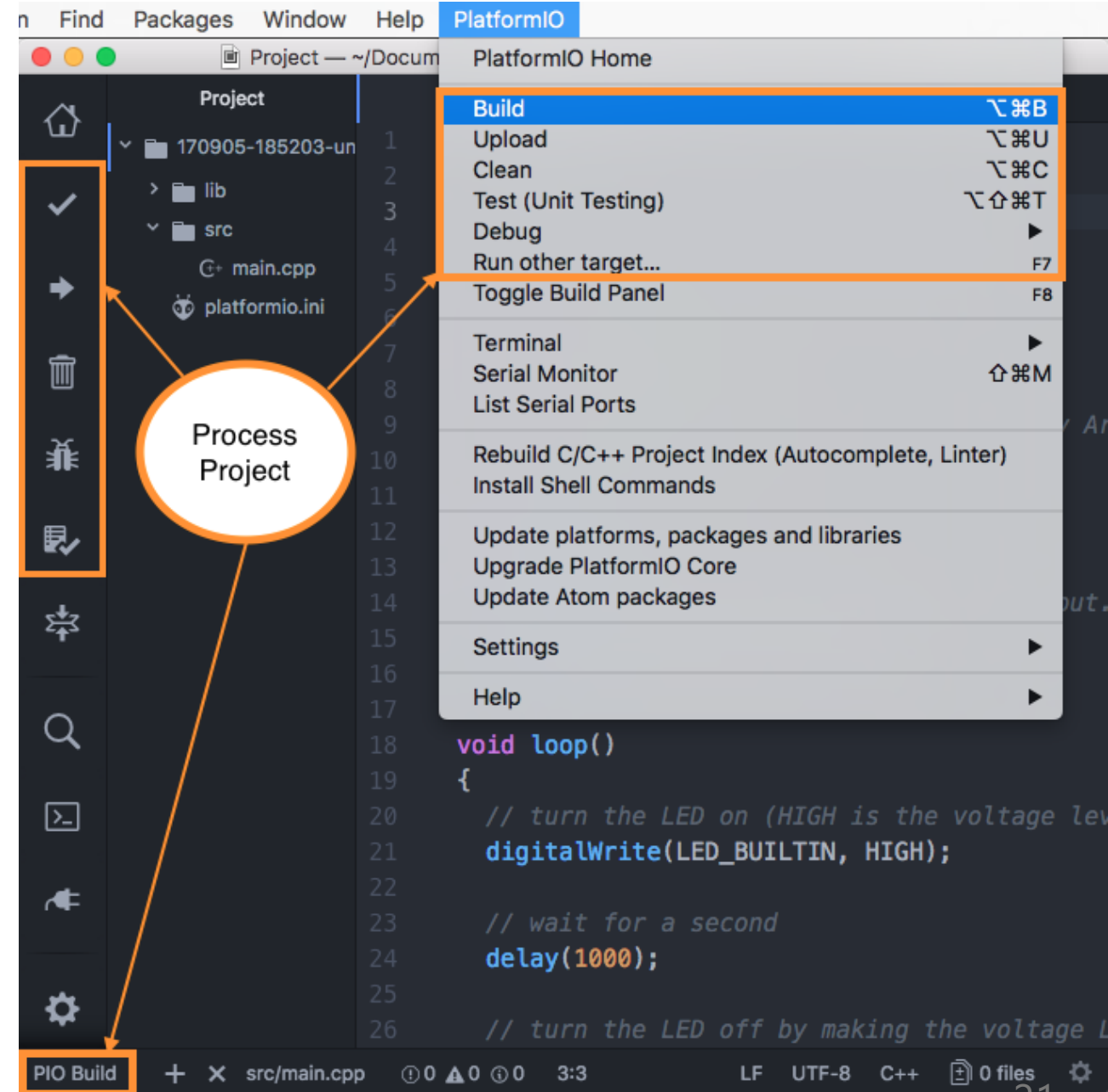
0 0 0 0 3:3

LF UTF-8 C++

0 files

Platformio Quick Start

5. Kompile dan upload kode di atas via menu **Build, Upload**



Platformio Quick Start

The screenshot displays the PlatformIO IDE interface. On the left, a sidebar contains icons for home, build, upload, delete, debug, test, search, terminal, and settings. The 'Project' panel shows a folder named '170905-185203-un' with files 'src', 'main.cpp', and 'platformio.ini'. A blue button labeled 'PlatformIO: Build' is highlighted. The main editor shows the code for 'main.cpp' with the following content:

```
1  /**
2   * Blink
3   *
4   * Turns on an LED on for one second,
5   * then off for one second, repeatedly.
6   */
7  #include "Arduino.h"
8
9  // Set LED_BUILTIN if it is not defined by Arduino
10 // #define LED_BUILTIN 13
11
12 void setup()
13 {
14   // Initialize the LED_BUILTIN pin as an output
15   pinMode(LED_BUILTIN, OUTPUT);
16 }
```

Below the editor, the 'platformio run' output is shown, indicating a successful build. The output includes the following information:

```
platformio run 5.0 s
AVR Memory Usage
-----
Device: atmega328p

Program:      928 bytes (2.8% Full)
(.text + .data + .bootloader)

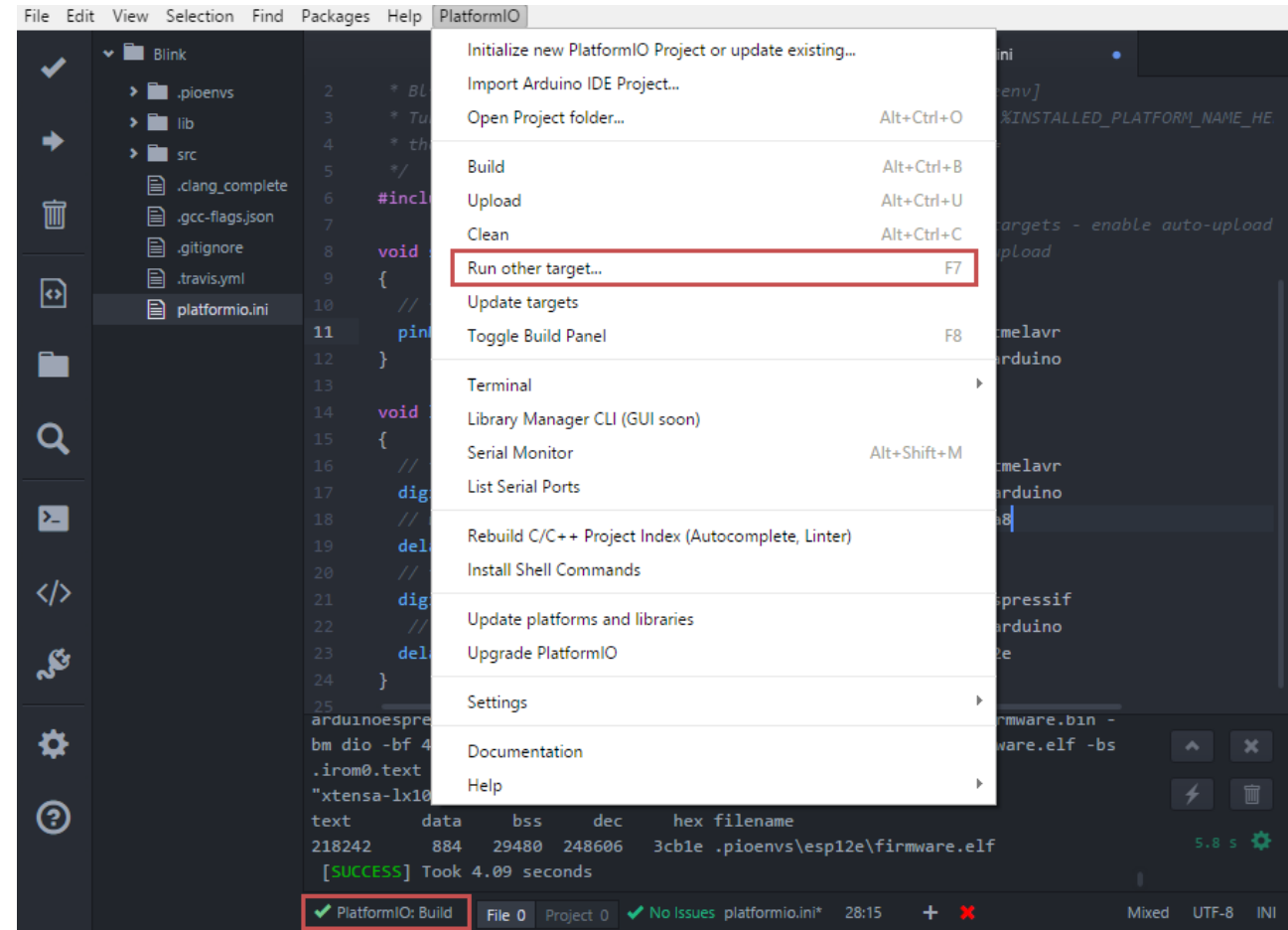
Data:         9 bytes (0.4% Full)
(.data + .bss + .noinit)

===== [SUCCESS] Took 4.01 seconds
```

The status bar at the bottom shows 'PIO Build' in green, followed by icons for file operations and a status bar with 'src/main.cpp', '3:3', 'LF', 'UTF-8', 'C++', and '0 files'.

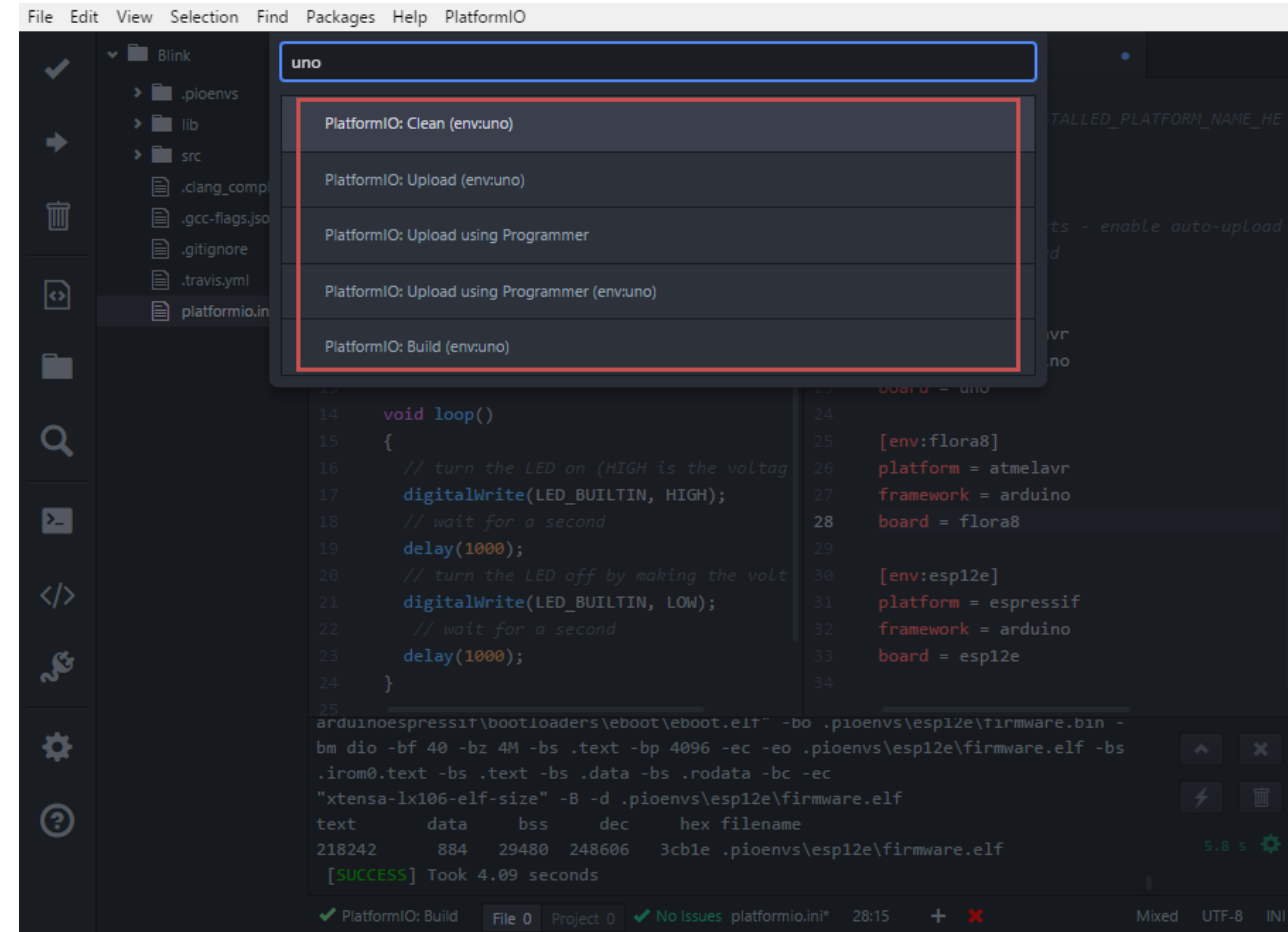
Platformio Quick Start

6. Untuk target dan opsi lainnya
maka tekan tombol **F7**



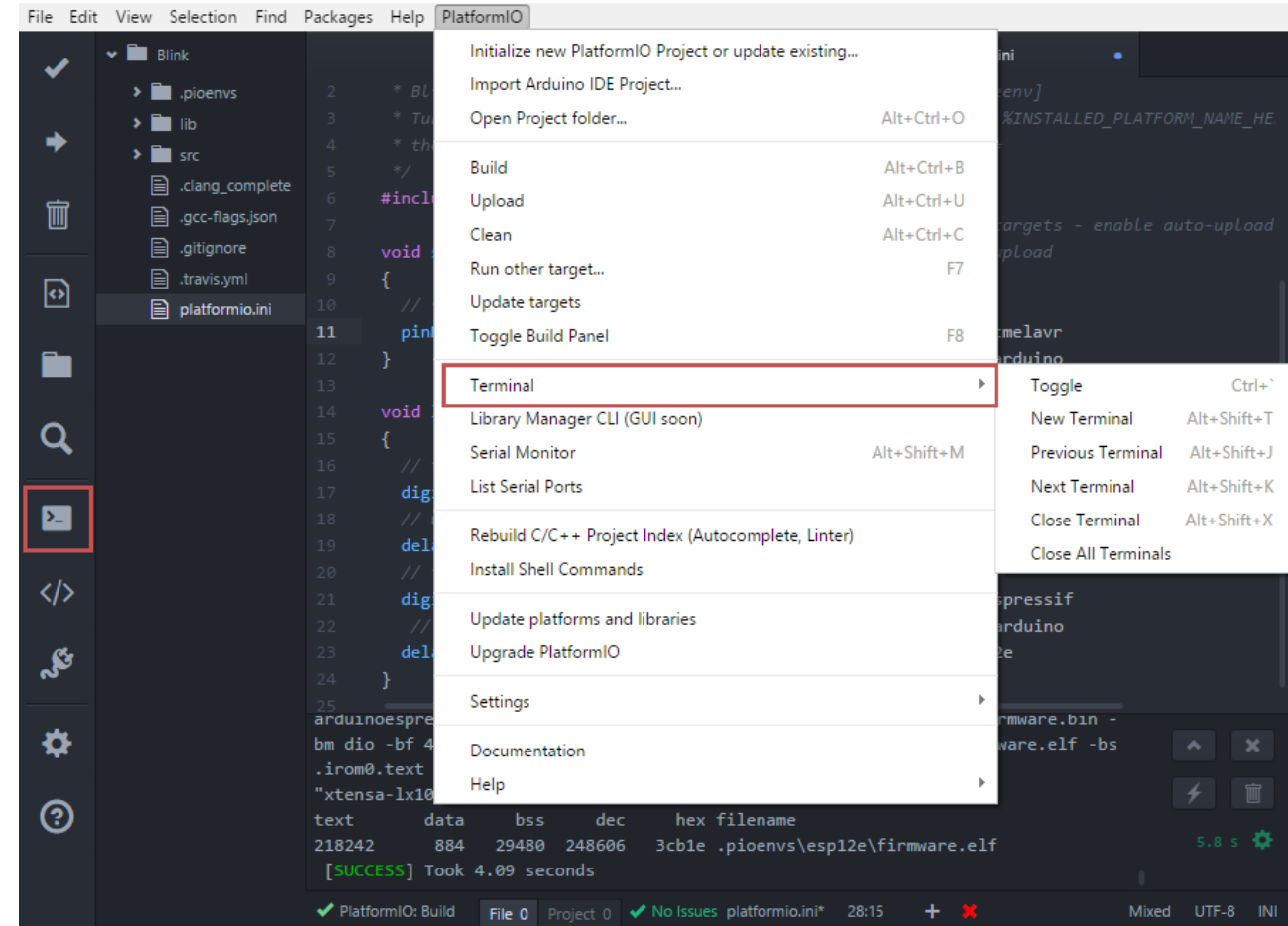
Platformio Quick Start

7. Pilih dan jalankan sesuai keinginan Anda. Ini di versi baru tidak muncul kalau di Atom 😞

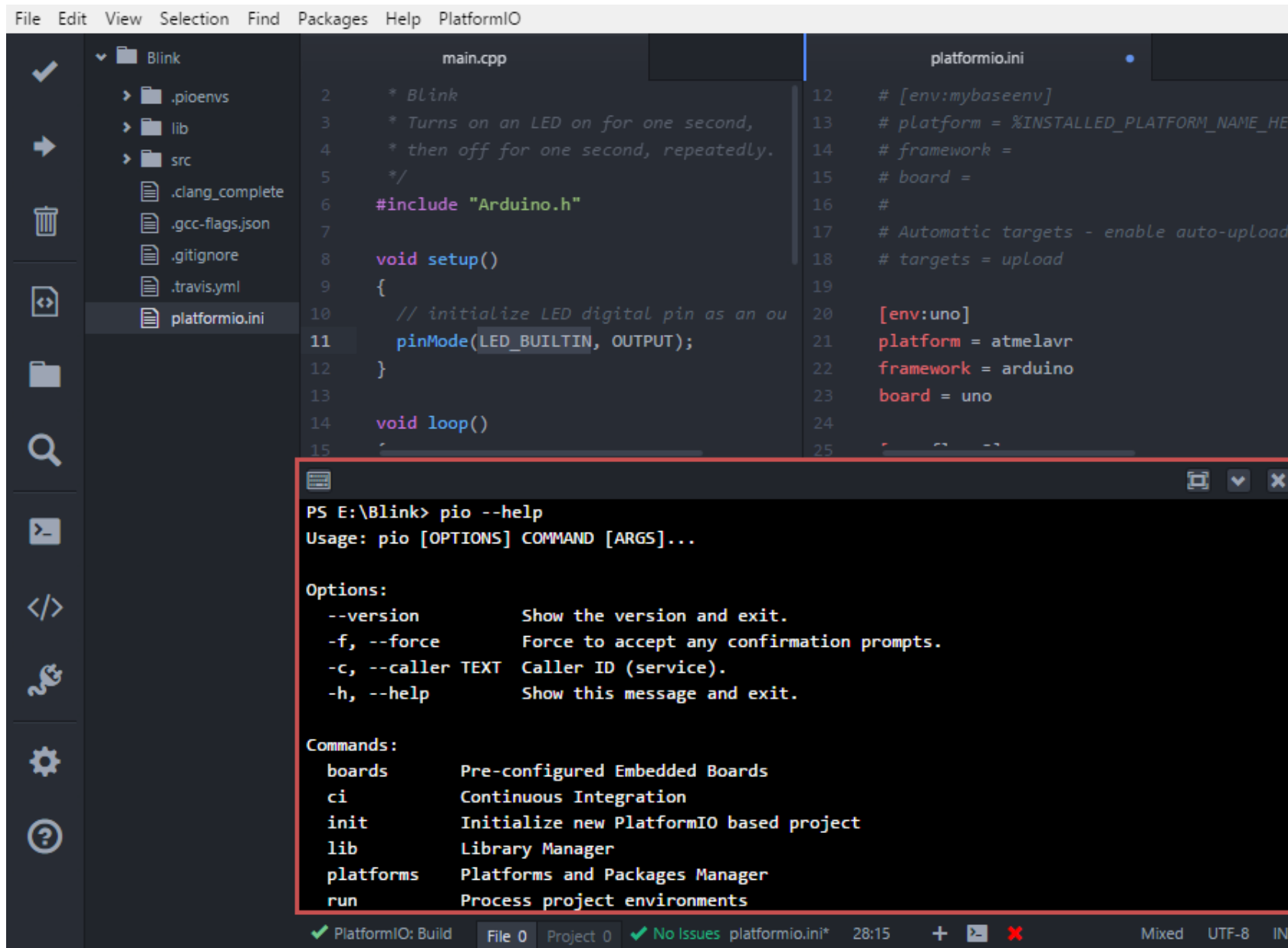


Platformio Quick Start

8. Untuk kebutuhan yang lebih
maka menggunakan **Terminal**



Platformio Quick Start



The screenshot displays the PlatformIO IDE interface. The left sidebar shows a project named 'Blink' with a file explorer containing folders like '.pioenvs', 'lib', and 'src', and files like '.clang_complete', '.gcc-flags.json', '.gitignore', '.travis.yml', and 'platformio.ini'. The main editor area shows two files: 'main.cpp' and 'platformio.ini'. The 'main.cpp' file contains a simple Blink sketch. The 'platformio.ini' file contains configuration for the 'uno' board. A terminal window is open at the bottom, showing the command 'pio --help' and its output, which lists various options and commands available in the PlatformIO CLI.

```
File Edit View Selection Find Packages Help PlatformIO
```

```
main.cpp
2  * Blink
3  * Turns on an LED on for one second,
4  * then off for one second, repeatedly.
5  */
6  #include "Arduino.h"
7
8  void setup()
9  {
10     // initialize LED digital pin as an ou
11     pinMode(LED_BUILTIN, OUTPUT);
12 }
13
14 void loop()
15 {
```

```
platformio.ini
12 # [env:mybaseenv]
13 # platform = %INSTALLED_PLATFORM_NAME_HE
14 # framework =
15 # board =
16 #
17 # Automatic targets - enable auto-upload
18 # targets = upload
19
20 [env:uno]
21 platform = atmelavr
22 framework = arduino
23 board = uno
24
25
```

```
PS E:\Blink> pio --help
Usage: pio [OPTIONS] COMMAND [ARGS]...

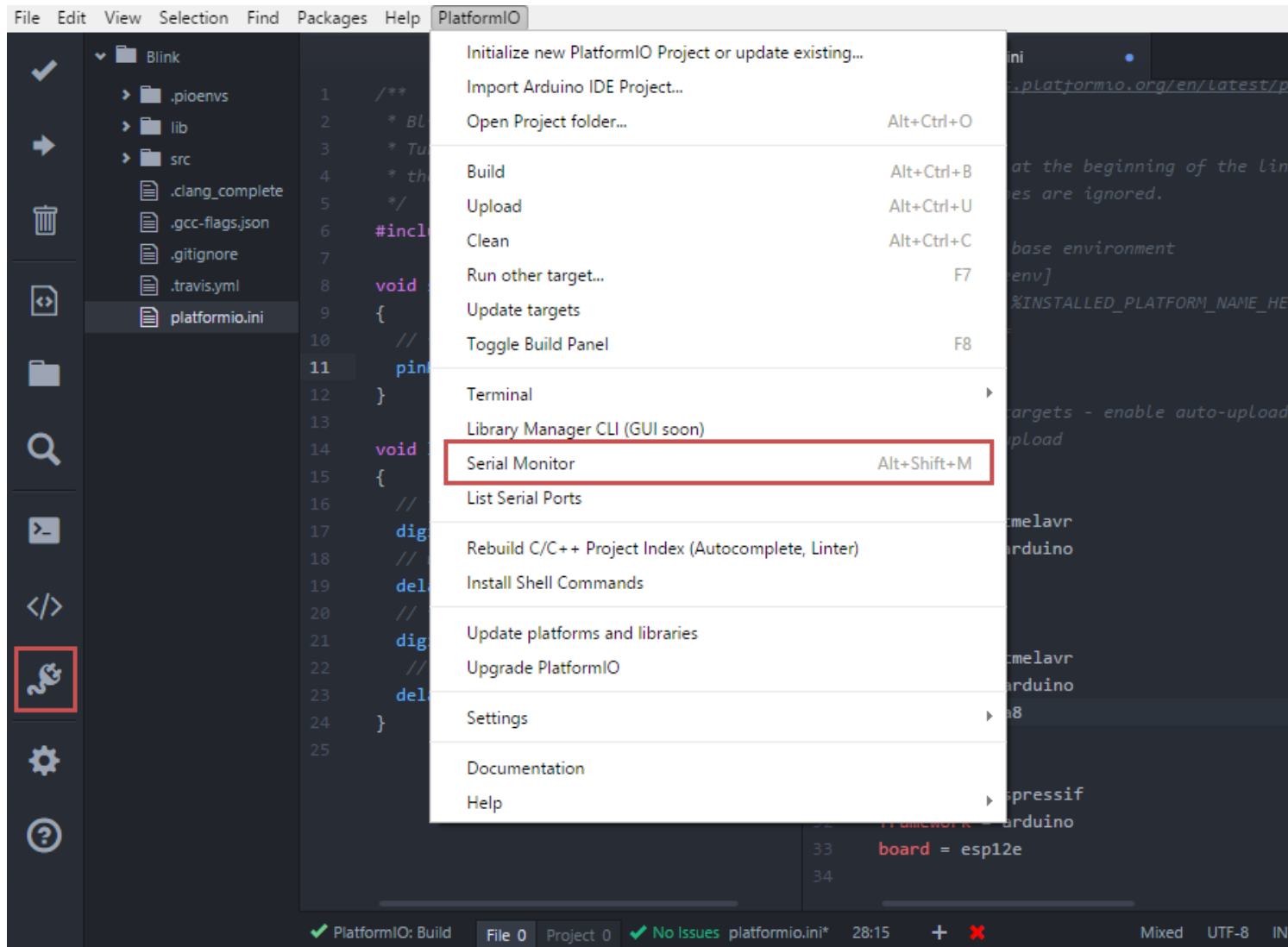
Options:
  --version          Show the version and exit.
  -f, --force        Force to accept any confirmation prompts.
  -c, --caller TEXT  Caller ID (service).
  -h, --help         Show this message and exit.

Commands:
  boards      Pre-configured Embedded Boards
  ci          Continuous Integration
  init        Initialize new PlatformIO based project
  lib         Library Manager
  platforms   Platforms and Packages Manager
  run         Process project environments
```

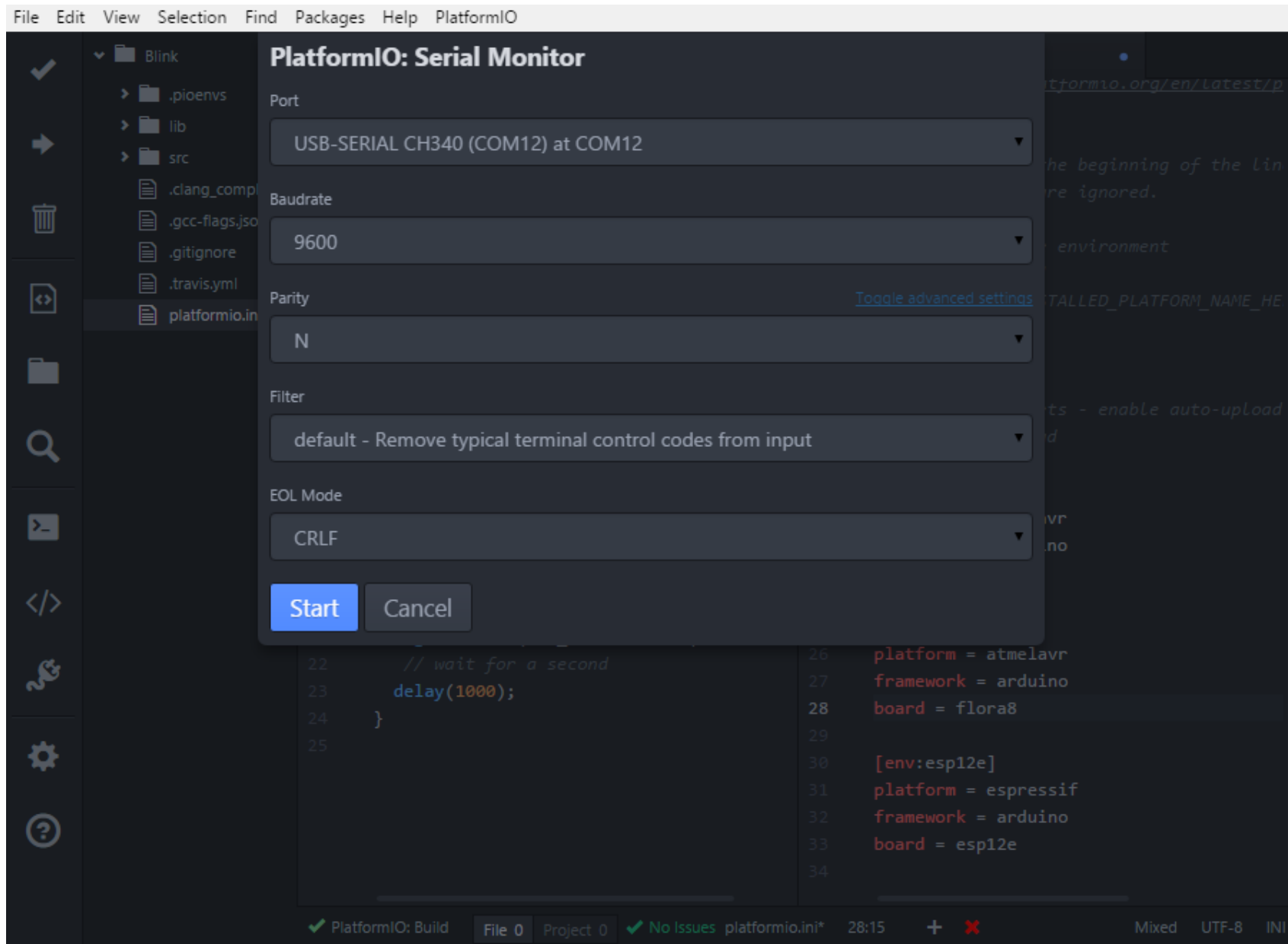
PlatformIO: Build | File 0 | Project 0 | No Issues platformio.ini* | 28:15 | Mixed UTF-8 | INI

Platformio Quick Start

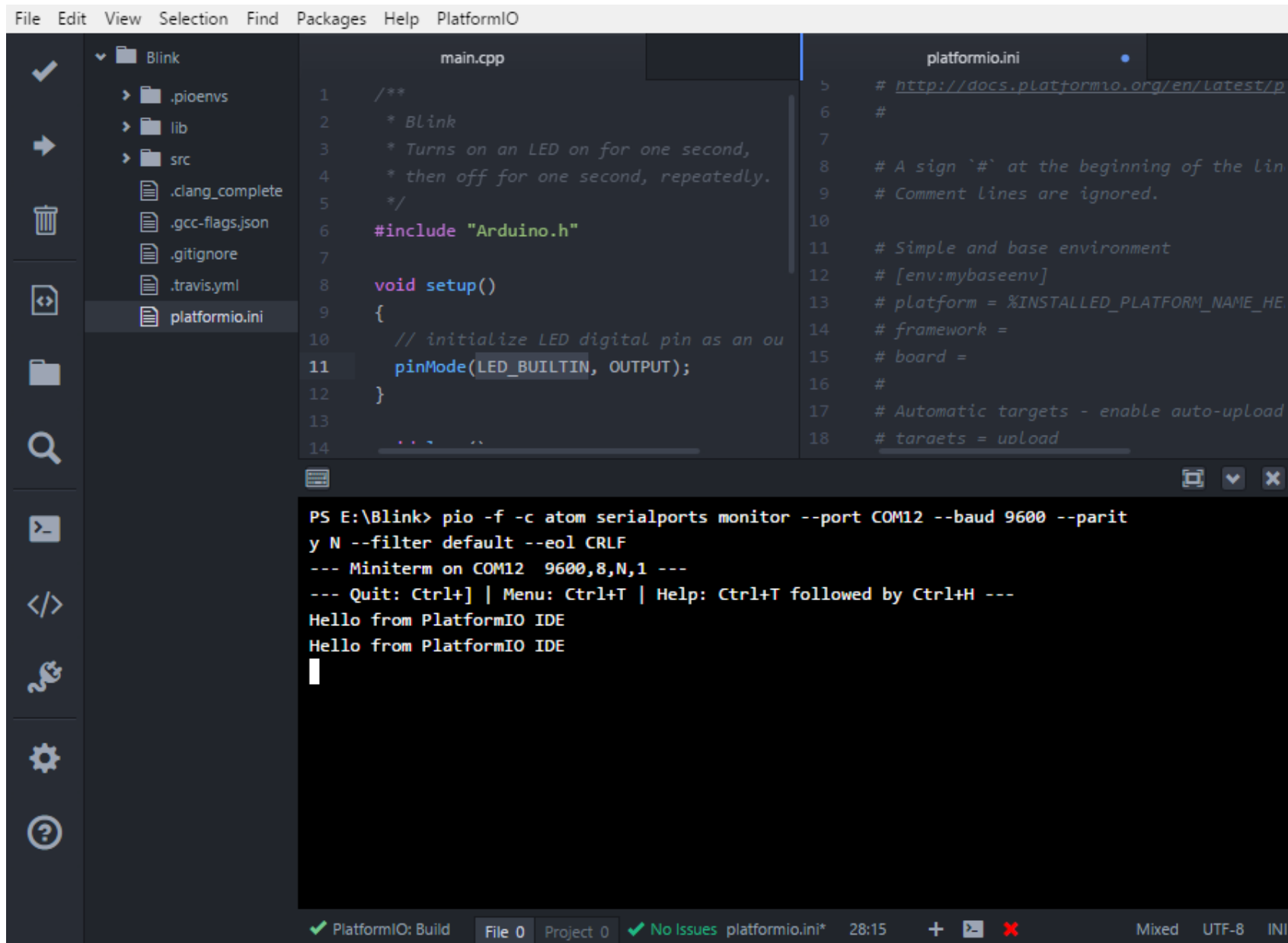
9. Debug program Anda menggunakan Serial Port Monitor



PlatformIO Quick Start



Platformio Quick Start



```
File Edit View Selection Find Packages Help PlatformIO

Blink
├── .pioenvs
├── lib
├── src
│   ├── .clang_complete
│   ├── .gcc-flags.json
│   ├── .gitignore
│   ├── .travis.yml
│   └── platformio.ini
└── ...

main.cpp
1  /**
2   * Blink
3   * Turns on an LED on for one second,
4   * then off for one second, repeatedly.
5   */
6  #include "Arduino.h"
7
8  void setup()
9  {
10     // initialize LED digital pin as an output
11     pinMode(LED_BUILTIN, OUTPUT);
12 }
13
14 ...

platformio.ini
5  # http://docs.platformio.org/en/latest/
6  #
7
8  # A sign '#' at the beginning of the line
9  # Comment lines are ignored.
10
11 # Simple and base environment
12 # [env:mybaseenv]
13 # platform = %INSTALLED_PLATFORM_NAME_HERE
14 # framework =
15 # board =
16 #
17 # Automatic targets - enable auto-upload
18 # targets = upload

PS E:\Blink> pio -f -c atom serialports monitor --port COM12 --baud 9600 --parity N --filter default --eol CRLF
--- Miniterm on COM12 9600,8,N,1 ---
--- Quit: Ctrl+] | Menu: Ctrl+T | Help: Ctrl+T followed by Ctrl+H ---
Hello from PlatformIO IDE
Hello from PlatformIO IDE

```

Platformio Core

1. Buka Atom Platformio
2. Buka **Terminal** menggunakan **CTRL+`**
3. Cek info *board* yang dipakai : `pio boards nodemcu` or `pio boards esp32doit`
4. Inisialisasi *project*-nya : `pio init --board uno --board nodemcuv1.0 --board esp32doit-devkit-v1`
5. Konfigurasi **platformio.ini** untuk kustomisasi opsi lebih lanjut

Platformio Core

platformio.ini

```
; PlatformIO Project Configuration File
;
; Build options: build flags, source filter
; Upload options: custom upload port, speed and extra flags
; Library options: dependencies, extra library storages
; Advanced options: extra scripting
;
; Please visit documentation for the other options and examples
; http://docs.platformio.org/page/projectconf.html
[platformio]
default_envs = iot_esp8266
core_dir = D:\PIO\.platformio

; if you want add aonther library folder
; lib_extra_dirs = K:\2009\WORK\PROJECT\PlatformIO_Library\
```

```
[env:iot_esp8266]
platform = espressif8266
board = nodemcu2
framework = arduino
; 4M (1M SPIFFS)
build_flags = -Wl,-Tesp8266.flash.4m1m.ld

; 4M (3M SPIFFS)
; build_flags = -Wl,-Tesp8266.flash.4m.ld -lc

; make sure the library search it deep enough
lib_ldf_mode = deep+

; customize upload port
; upload_port = COM4
; upload_speed = 480600

; src_filter = -<test/>
; src_filter = +<*> -<arduino> -<test>
```



```
; you environment, name it as you wish, no space
[env:esp32dev]
; platform used
platform = espressif32
; platform = espressif32@0.11.1
; platform = https://github.com/platformio/
;           platform-espressif32.git

; framework use for this environment
; depend on your board and platform
framework = arduino

; Board name used
board = esp32doit-devkit-v1

; http://docs.platformio.org/en/latest/projectconf/
; section_env_library.html
; how the platformio search for Library
; deep+ is the most advance and
; complete for auto search Library
lib_ldf_mode = deep+
```

```
; which library you want to ignore or exclude from compilation
; lib_ignore = ESPAsync

; which library you want to use specifically for this environment
; lib_deps = DHT

; how the library is automagically choose,
; which one is going to be compiled,
; which one is not
; by default soft mode,
; platformio will ignore library which is
; not meant for the framework
; lib_compat_mode = soft

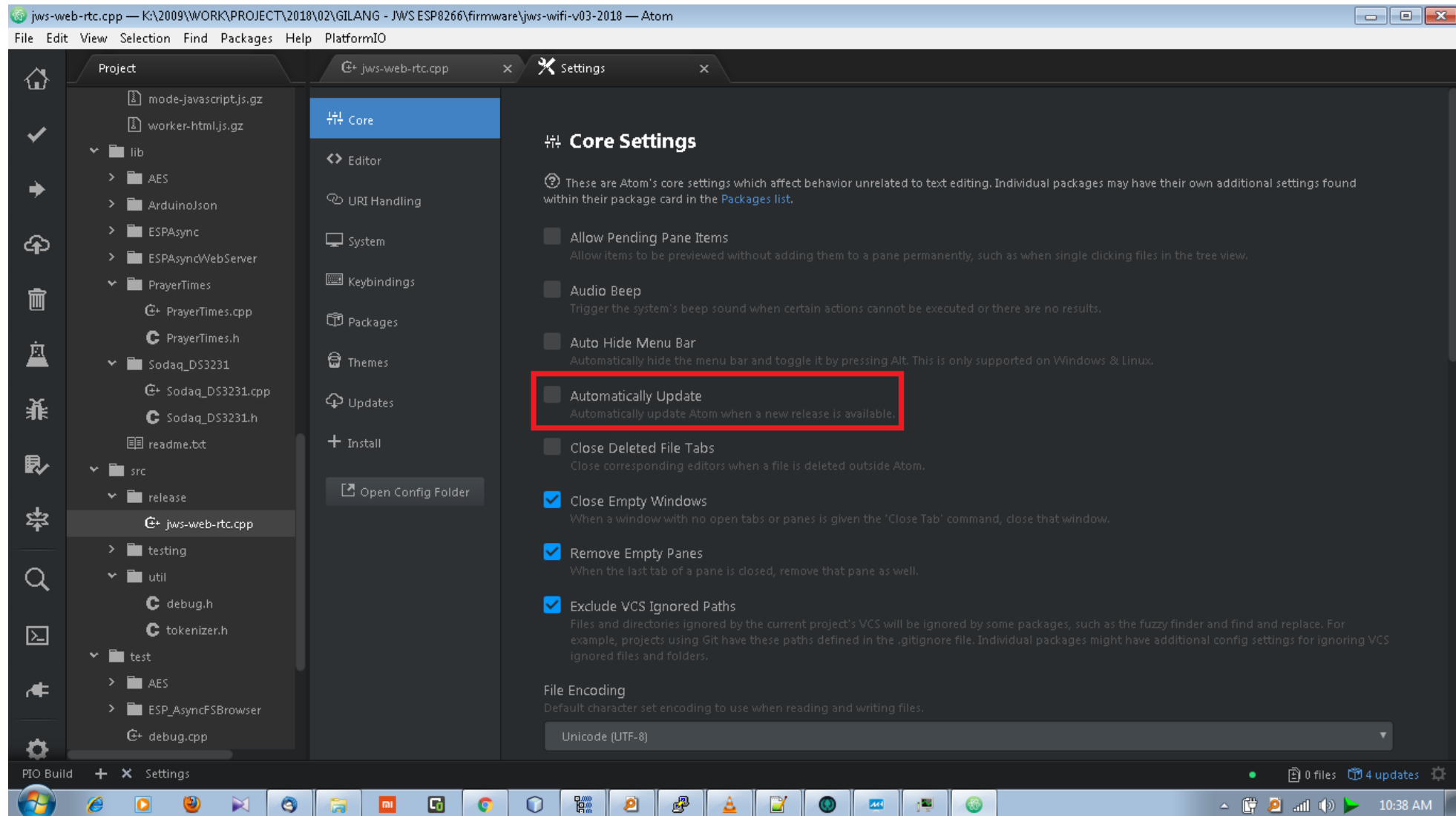
; if you got many folder inside src, then this will filter
; which one you want to include(+) or exclude(-)
; src_filter = +<*> -<release>

; add custom build flags
; -fexceptions needed if you want to use BLE
; build_flags = -fexceptions

; customize upload port, if needed
; upload_port = COM4
; upload_speed = 115200
```

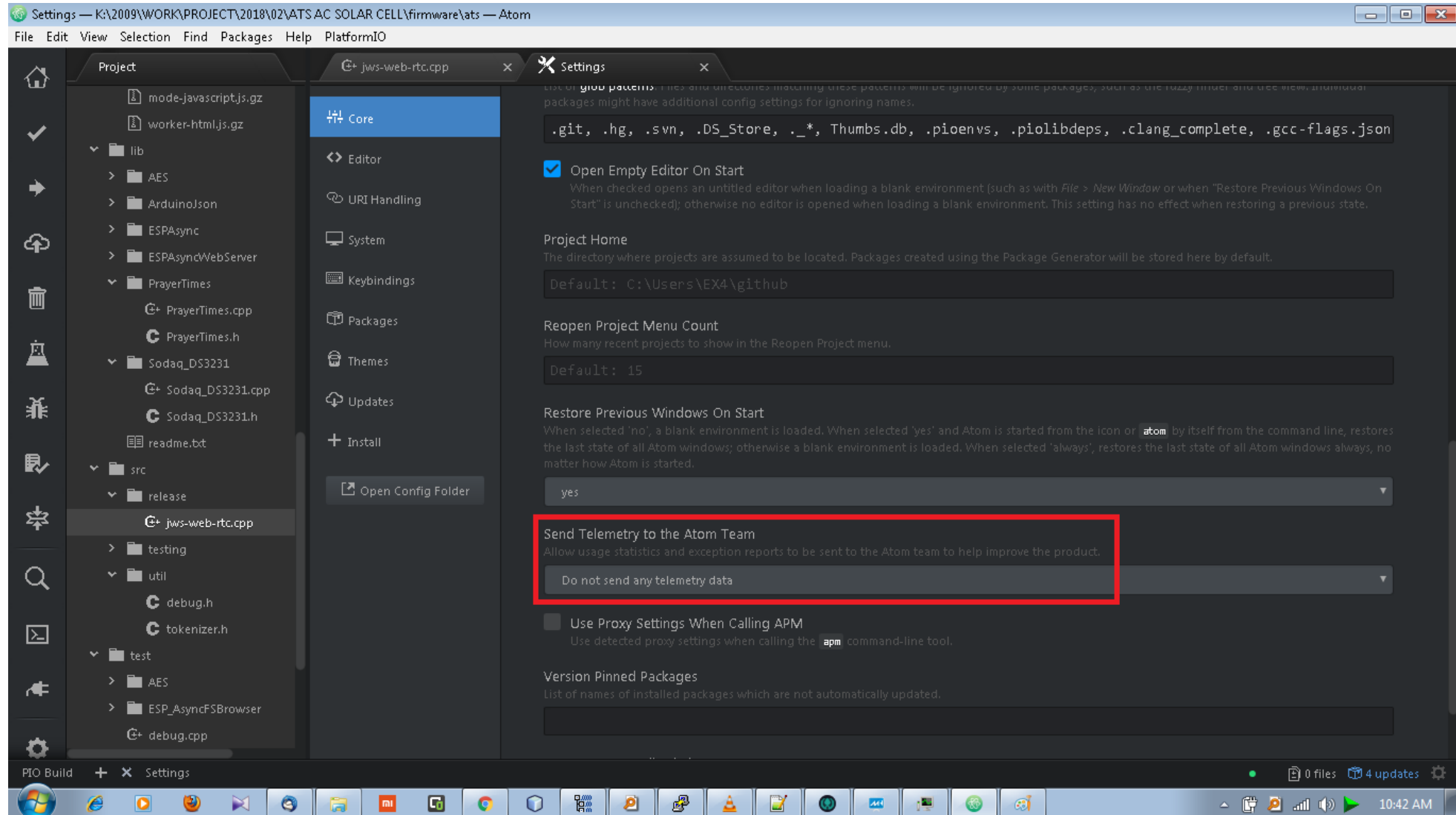
Platformio Tips

- Disable auto update -- Sangat menyebalkan



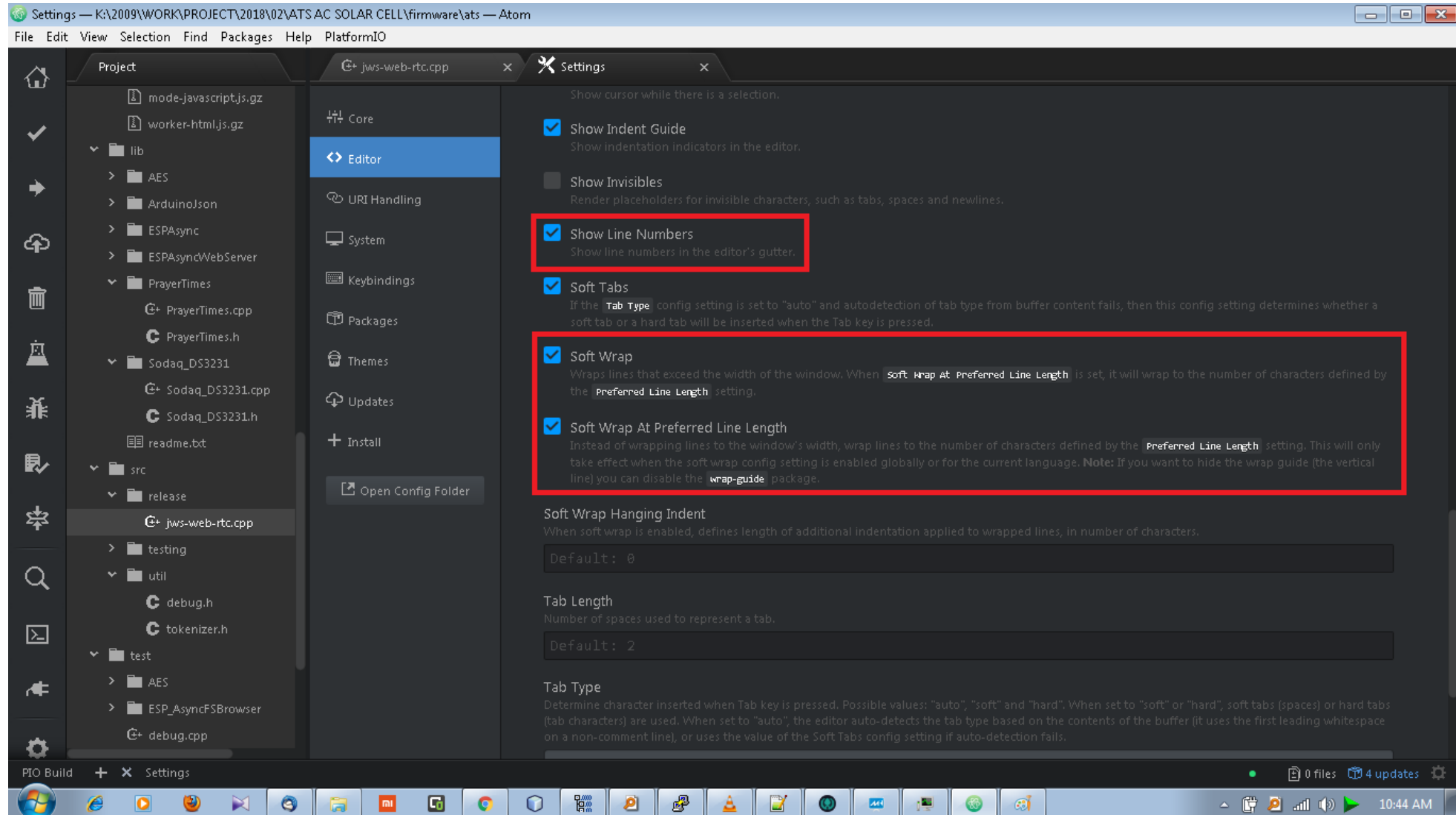
Platformio Tips

- Disable Telemetry -- Makan *bandwitdh* jaringan



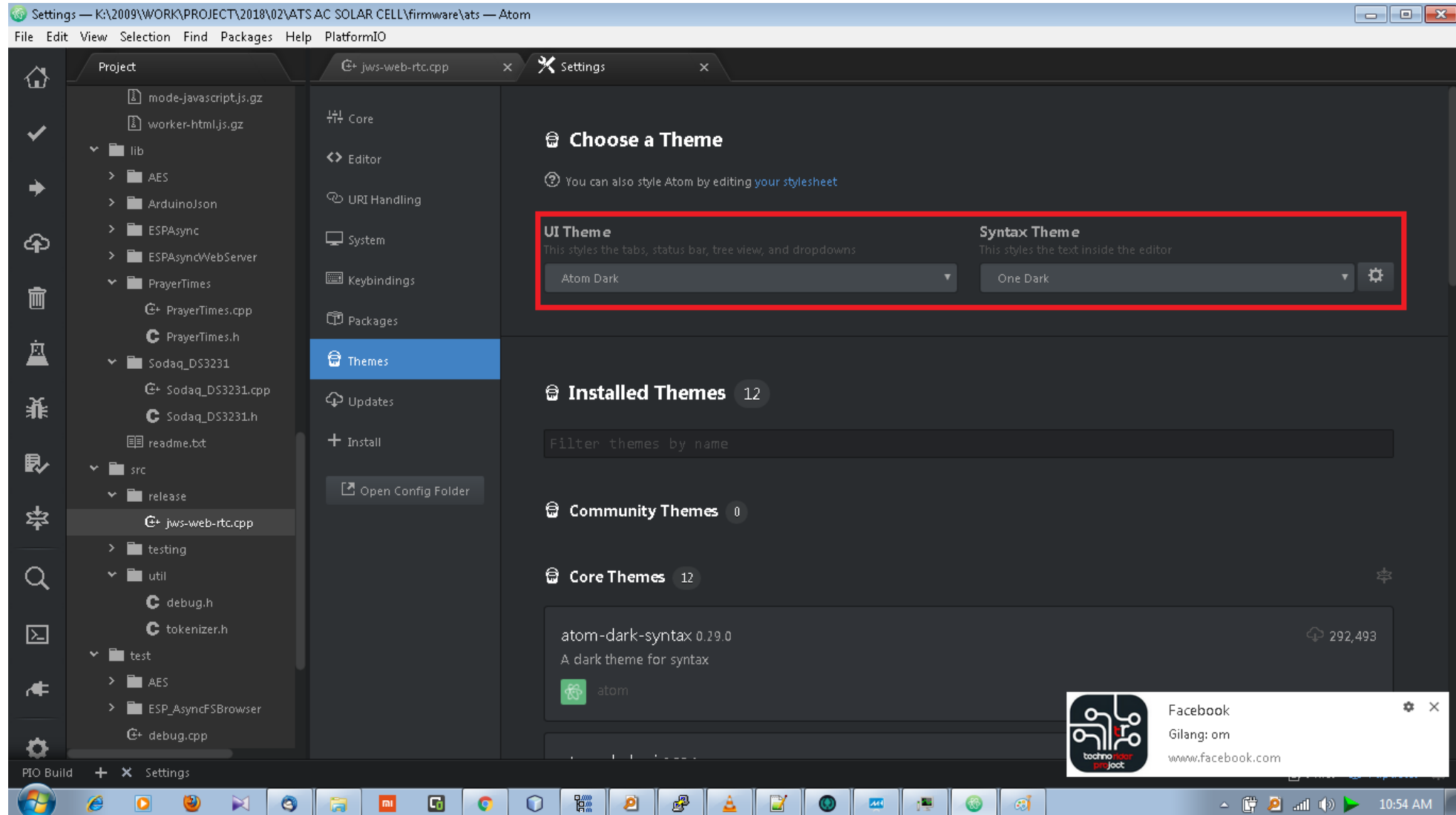
Platformio Tips

- Aktifkan nomor baris dan opsi wrap text -- Informatif



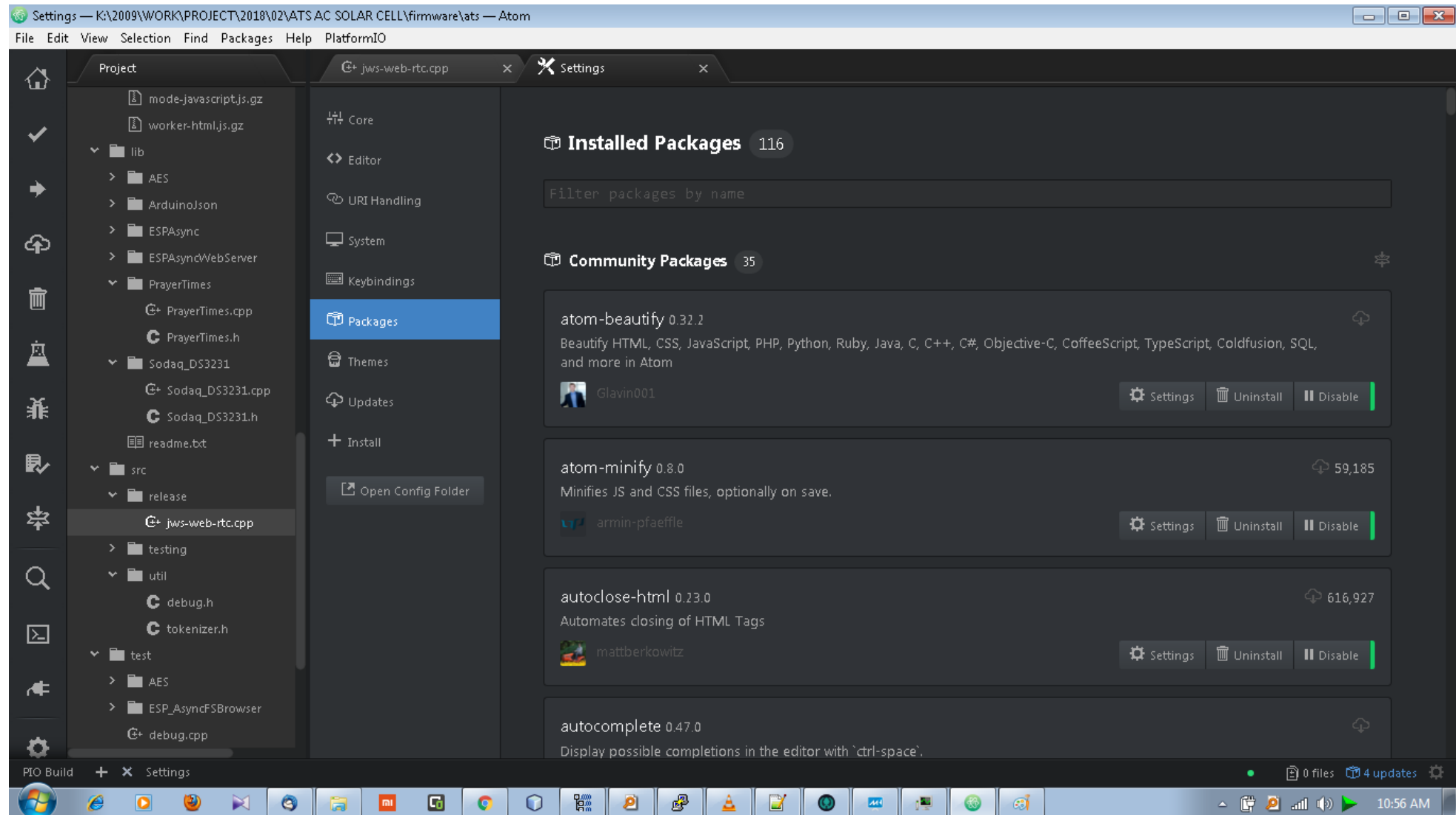
Platformio Tips

- Pilih theme yang adem di mata -- Bikin ga lelah mata



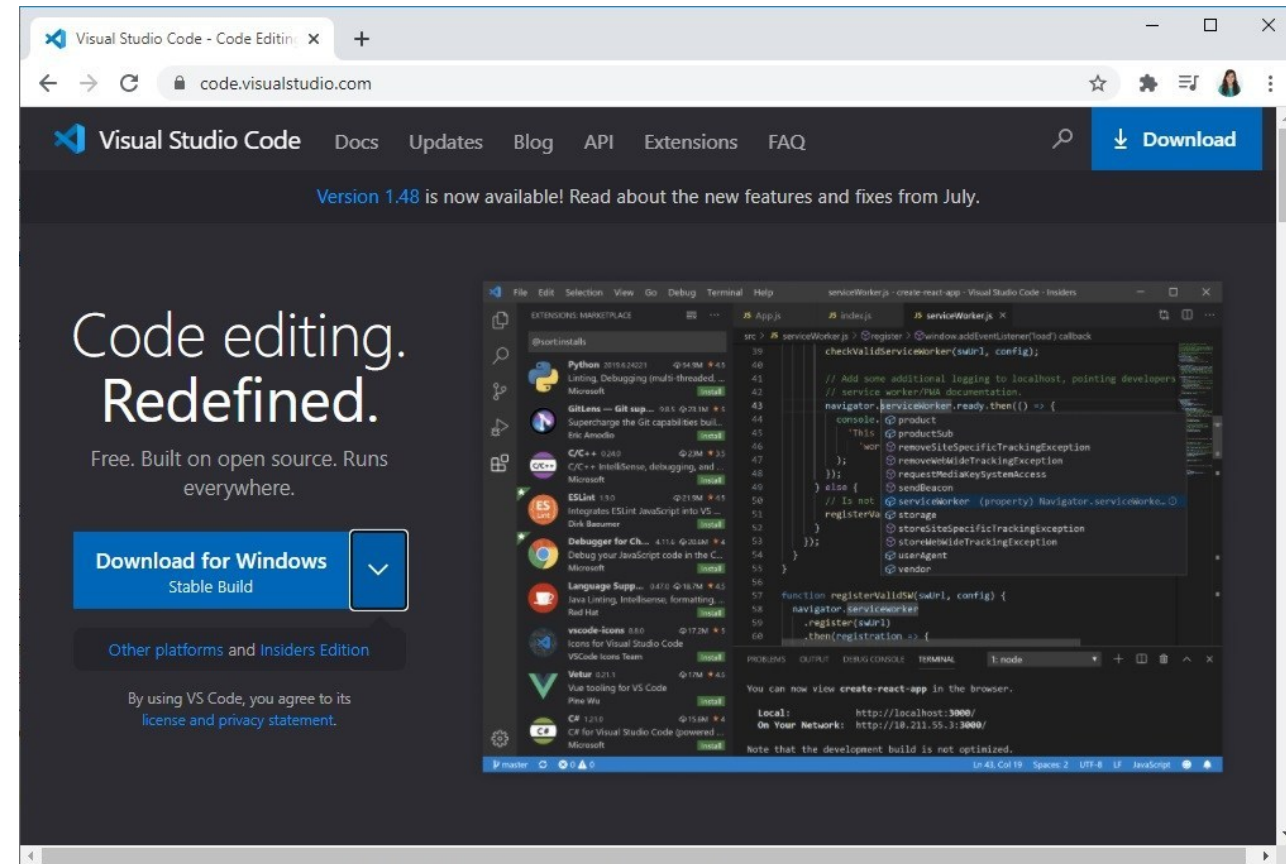
Platformio Tips

- Tambahkan beberapa modul Atom -- Lebih produktif
 - atom-beautify, dockblockr, minimap



Visual Studio Code

- Download versi portable dan ekstrak ke folder tanpa spasi :
<https://code.visualstudio.com/download>
<https://code.visualstudio.com/sha/download?build=stable&os=win32-archive>
- Pastikan Python 3.5 ke atas sudah terinstall



PlatformIO Extension

- Run VS Code As Administrator
- Klik Extensions icon atau tekan **Ctrl+Shift+X**
- Cari **PlatformIO IDE**
- Klik install dan silakan tunggu
- Setelah selesai, pastikan PlatformIO Extension sudah aktif

FileEditSelectionViewGoRunTerminalHelp

Extension: PlatformIO IDE - Visual Studio Code

EXTENSIONS: MARKETPLACE

platformio ide

PlatformIO IDE 1.10.0

Development environment for Embedded, IoT, Arduino, ARM microcontrollers

PlatformIO

Install

Bash IDE 1.11.0

A language server for Bash

Mads Hartmann

Install

IntelliJ IDEA Keybindings 0.2.41

Port of IntelliJ IDEA Keybindings, including IntelliJ IDEA, PyCharm, and WebStorm

Keisuke Kato

Install

COMP2300 IDE 2.0.9

PlatformIO IDE modified for COMP2300

comp2300-anu

Install

Java IDE 0.1.1

To make the vscode work as Eclipse or IntelliJ

JavaHub

Install


Serverless IDE 0.5.26

Enhanced support for AWS SAM, CloudFormation, and Serverless Framework

ThreadHeap

Install

Extension: PlatformIO IDE



PlatformIO IDE

platformio.platformio-ide

PlatformIO | 1,045,617 | ★★★★★ | Repository

Development environment for Embedded, IoT, Arduino, ARM microcontrollers

Install

Details

Feature Contributions

Changelog

Dependencies

PlatformIO IDE for VSCode

A new generation toolset for embedded C/C++ development

PlatformIO is a new generation ecosystem for embedded development.

- Open source, maximum permissive Apache 2.0 license
- Cross-platform IDE and Unified Debugger

0 0

42


File Edit Selection View Go Run Terminal Help Extension: PlatformIO IDE - Visual Studio Code

EXTENSIONS Search Extensions in Marketplace

INSTALLED 2

C/C++ 0.29.0
C/C++ IntelliSense, debugging, and c...
Microsoft

PlatformIO IDE 1.10.0
Development environment for Embed...
PlatformIO ✓ Enabled

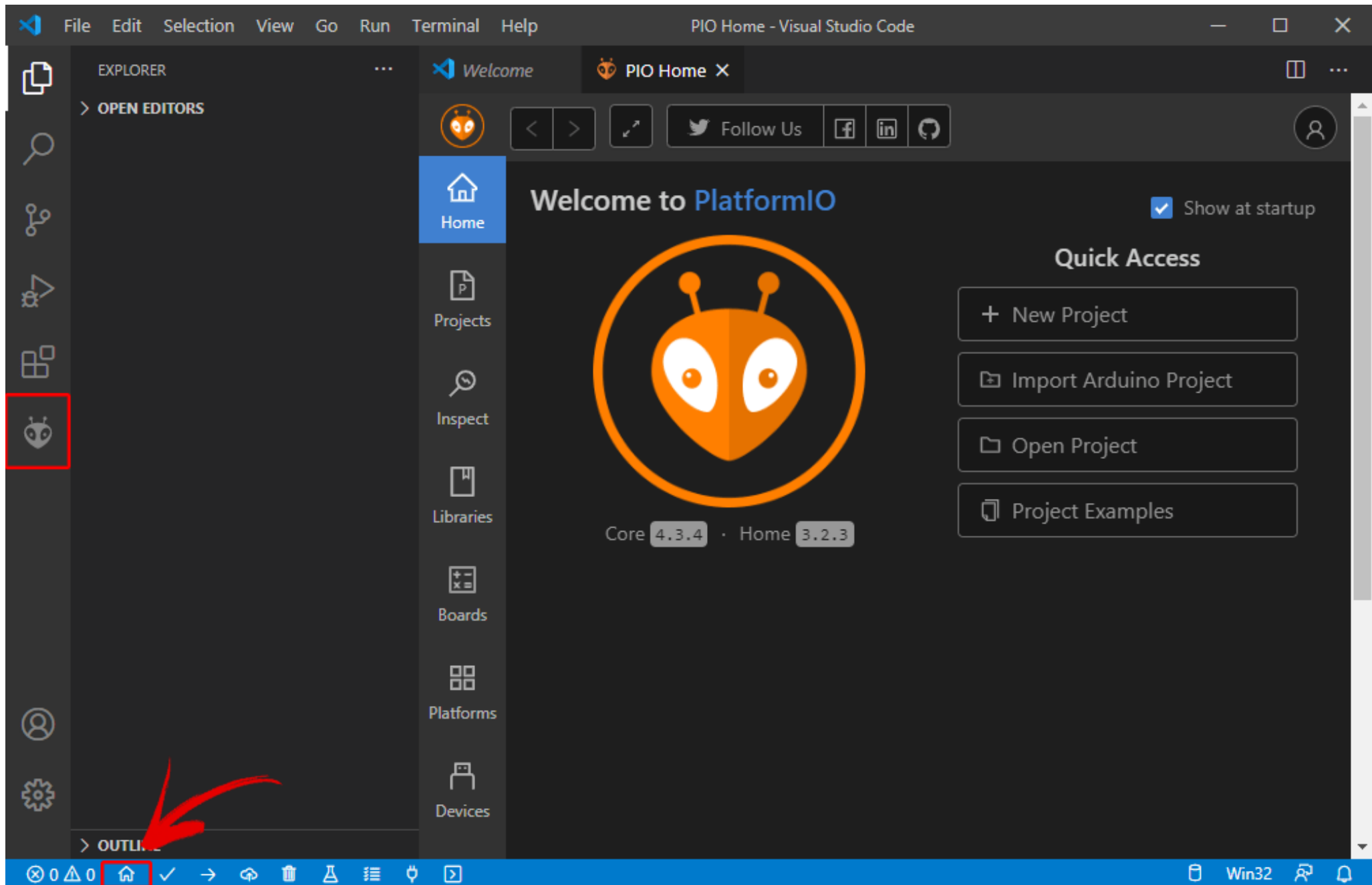
 **PlatformIO IDE** platformio.platformio-ide

PlatformIO | 1,045,744 | ★★★★★ | Repository | Lic

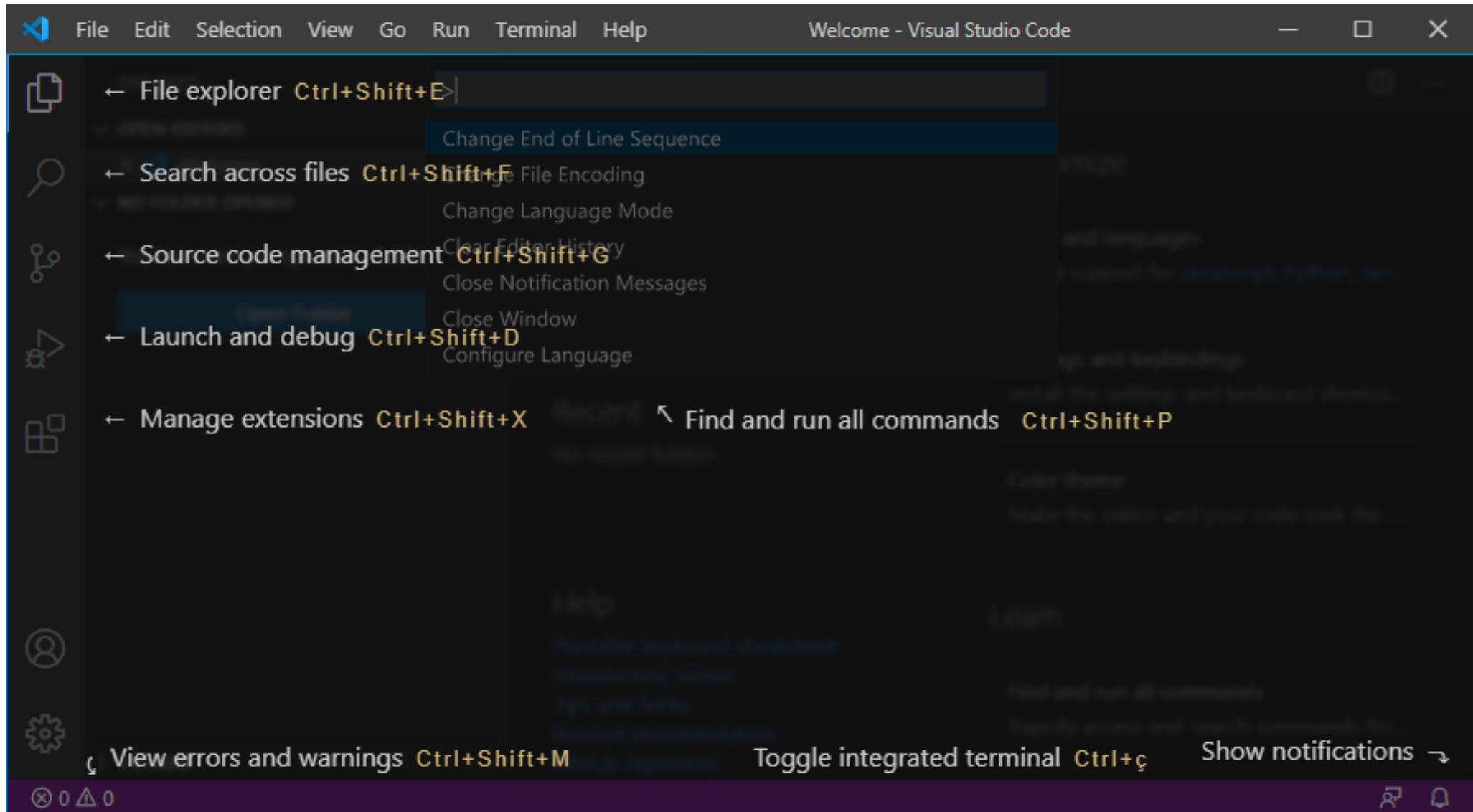
Development environment for Embedded, IoT, Arduino, ARM mbed, Esp...

✓ Enabled Disable Uninstall This extension is enabled globally.

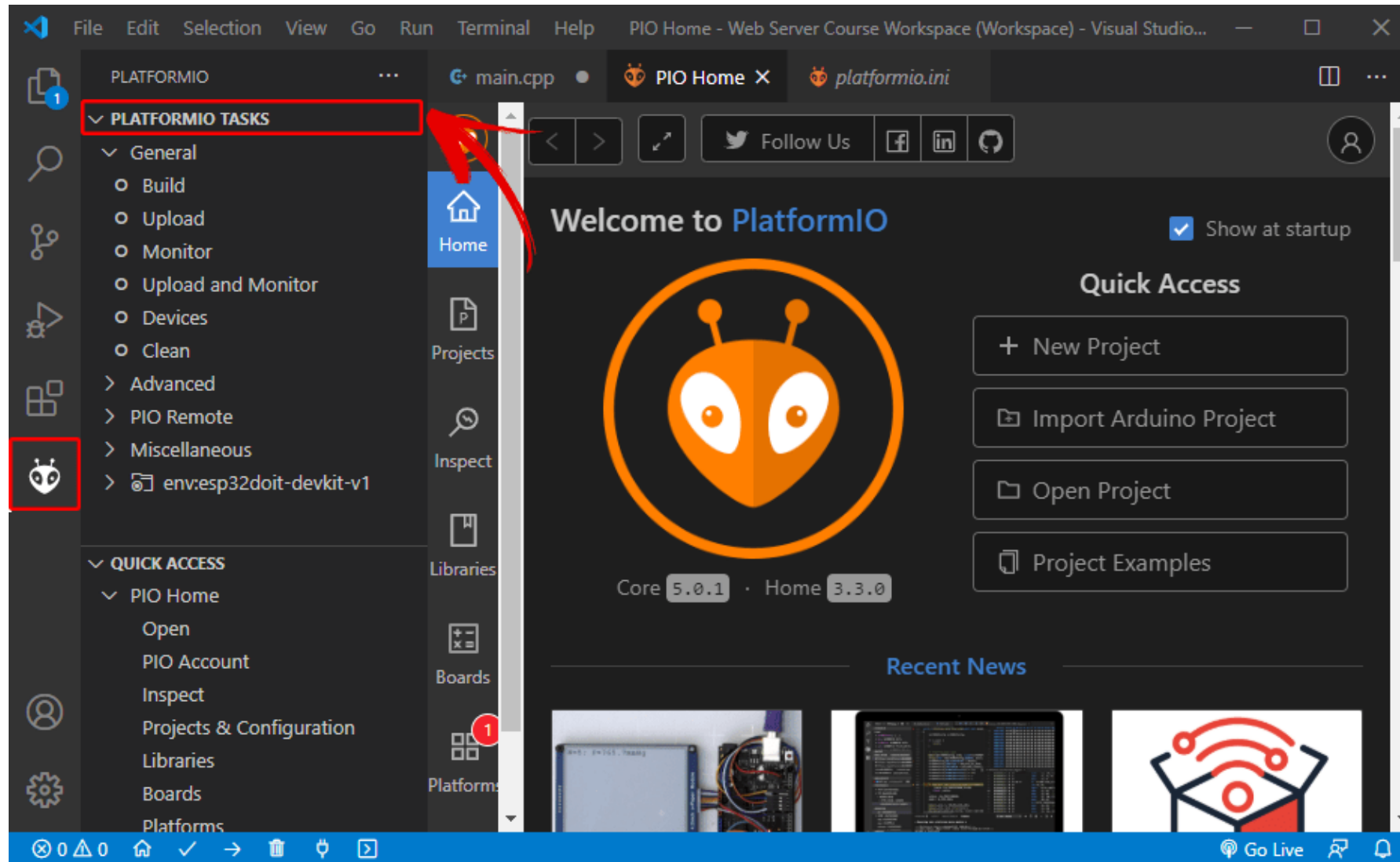
Details Feature Contributions Changelog Dependencies

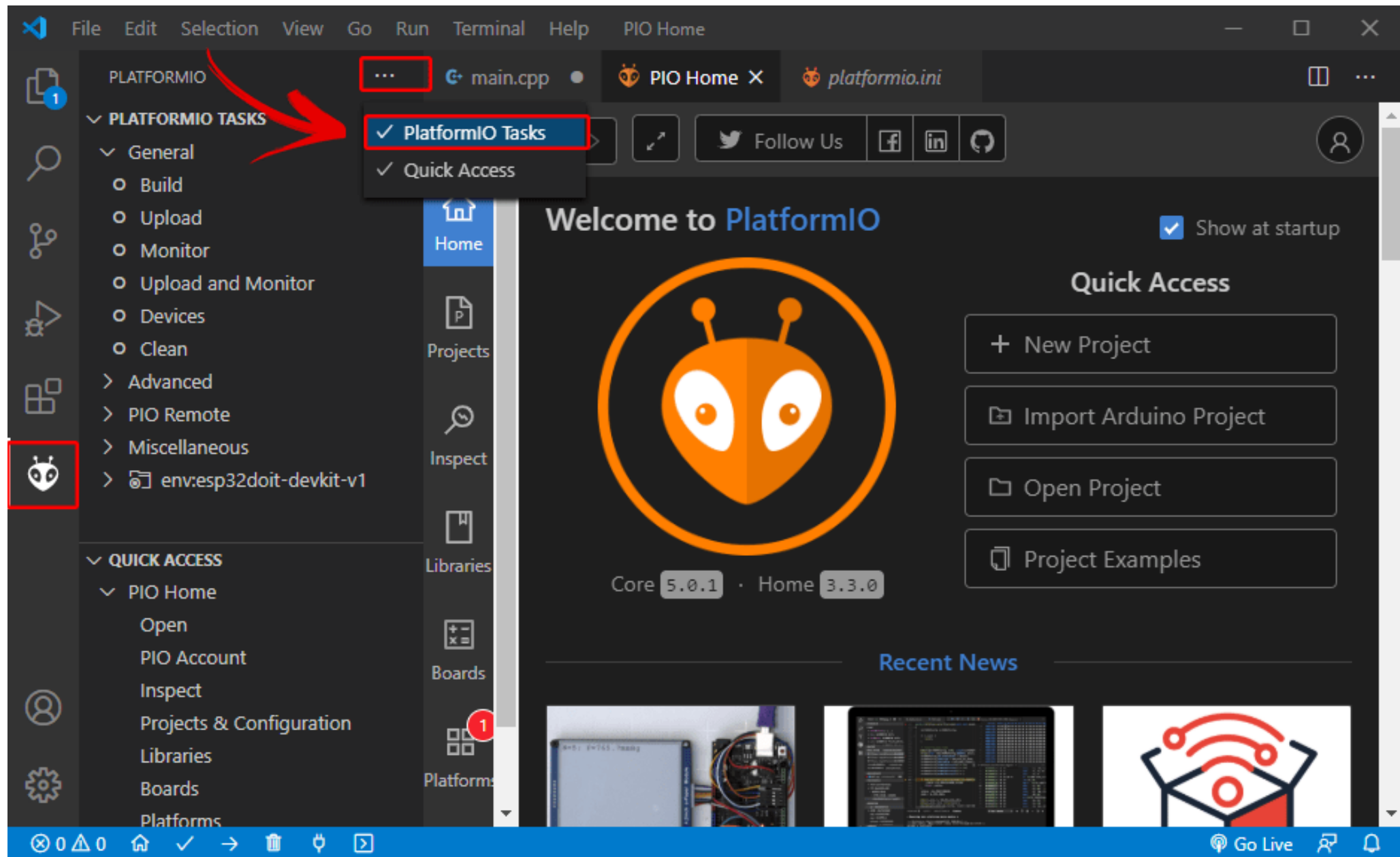


Interface



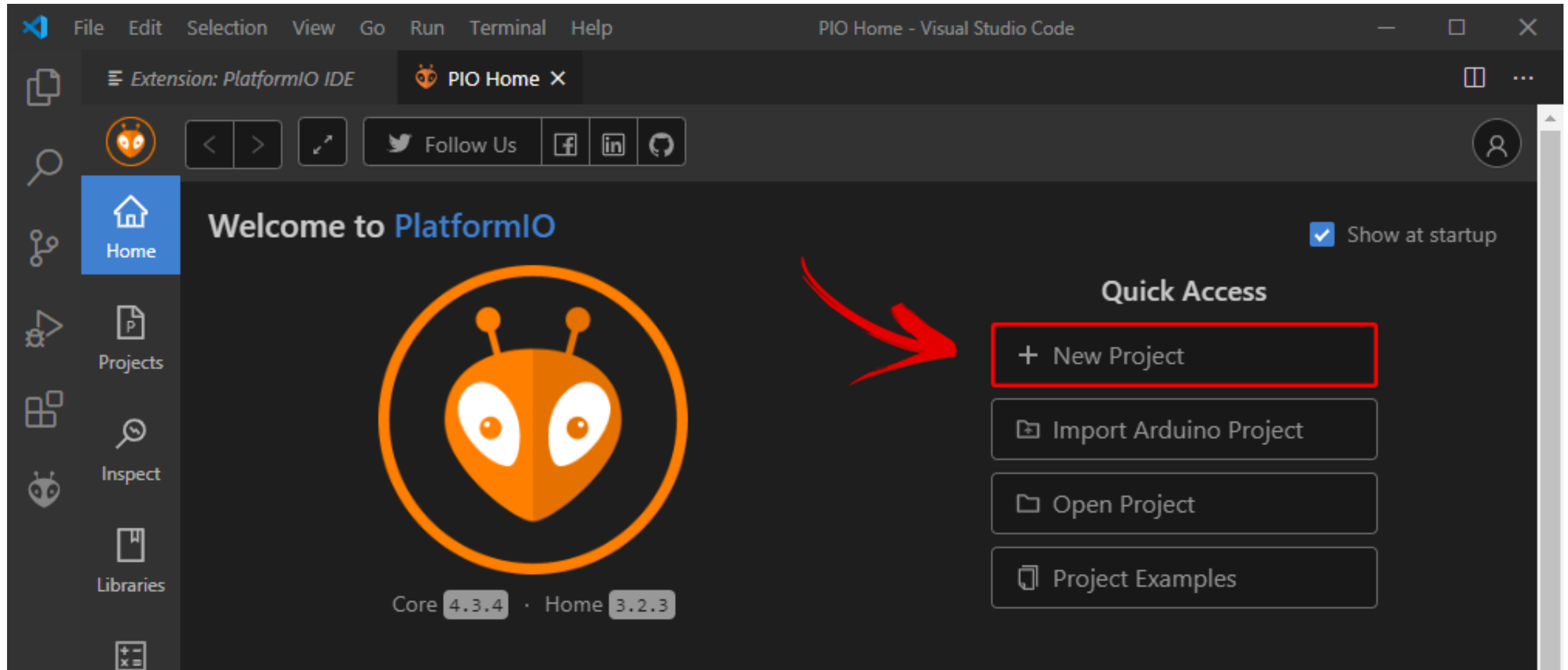
PIO Task





Project

1. Klik +New Project dari PIO Home
2. Pilih board Anda, misal Wemos D1 Mini
3. Jangan centang **Use default location**. Pilih Folder Anda sendiri
4. Klik **Finish*



Project Wizard




This wizard allows you to **create new** PlatformIO project or **update existing**. In the last case, you need to uncheck "Use default location" and specify path to existing project.

Name:

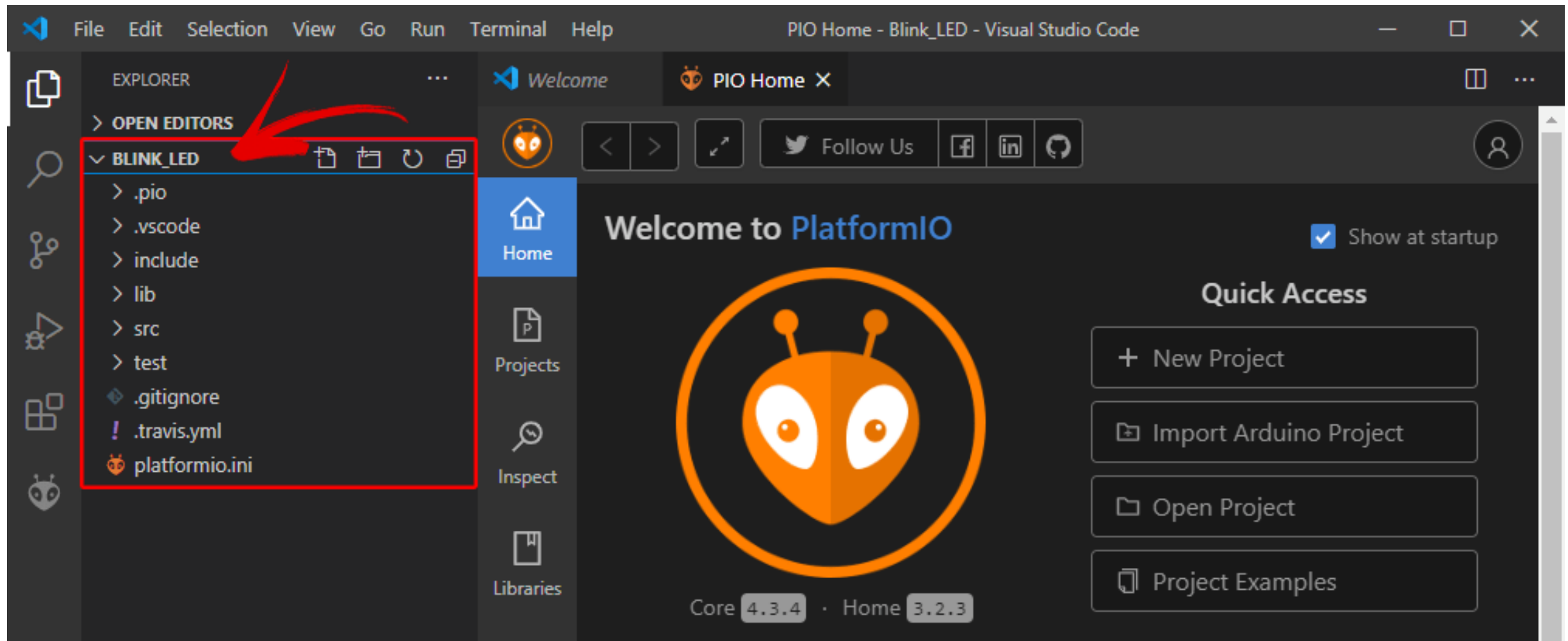
Board:

Framework:

Location: ☒ Use default location 

Cancel

Finish



Kompilasi Program

Klik kanan folder **src** dan buat file baru misal **main.cpp**. Isikan dengan kode berikut ini :

```
#include <Arduino.h>

#define LED LED_BUILTIN

void setup() {
    Serial.begin(115200);
    pinMode(LED, OUTPUT);
}

void loop() {
    digitalWrite(LED, HIGH);
    Serial.println("LED is on");
    delay(1000);
    digitalWrite(LED, LOW);
    Serial.println("LED is off");
    delay(1000);
}
```

Build dan Upload

1. Klik pilihan **Build** untuk melakukan kompilasi program Anda
2. Klik **Upload** untuk memprogram board Anda. Pastikan board Anda sudah dikenali di Device Manager

Visual Studio Code interface showing the PlatformIO extension and a C++ file named `main.cpp`.

Left Panel (PlatformIO):

- PROJECT TASKS
 - General
 - Build
 - Upload (highlighted with a red box)
 - Monitor
 - Upload and Monitor
 - Devices
 - Clean
 - Advanced
 - Remote Development
 - Miscellaneous
 - env:esp32doit-devkit-v1
- QUICK ACCESS
 - (highlighted with a red box and a red arrow pointing to it)

Main Editor (main.cpp):

```
Blink_LED > src > main.cpp > loop()
1  #include <Arduino.h>
2
3  #define LED 2
4
5  void setup() {
6      // put your setup code here, to run once:
7      Serial.begin(115200);
8      pinMode(LED, OUTPUT);
9  }
10
11 void loop() {
12     // put your main code here, to run repeatedly:
13     digitalWrite(LED, HIGH);
14     Serial.print("LED is on");
15     delay(1000);
16     digitalWrite(LED, LOW);
17 }
```

Bottom Status Bar:

- Ln 19, Col 2 Spaces: 2 UTF-8 CRLF C++ Go Live Win32

File Edit Selection View Go Run Terminal Help main.cpp - Visual Stu...

PLATFORMIO ...

PROJECT TASKS

- General
 - Build
 - Upload
 - Monitor
 - Upload and Monitor
 - Devices
 - Clean
- Advanced
- Remote Development
- Miscellaneous
- env:esp32doit-d...

main.cpp X

Blink_LED > src > main.cpp > loop()

```
1 #include <Arduino.h>
2
3 #define LED 2
4
5 void setup() {
6     // put your setup code here, to run once:
7     Serial.begin(115200);
8     pinMode(LED, OUTPUT);
9 }
10
11 void loop() {
12     // put your main code here, to run repeatedly:
13     digitalWrite(LED, HIGH);
14     Serial.print("LED is on");
15     delay(1000);
16     digitalWrite(LED, LOW);
17     Serial.print("LED is off");
```

PROBLEMS OUTPUT DEBUG CONSOLE TERMINAL 2: Task - PlatformIO: Up

Wrote 216752 bytes (109861 compressed) at 0x00010000 in 2.7 seconds (effective 631.3 kbit/Hash of data verified.

Leaving...
Hard resetting via RTS pin...

===== [SUCCESS] Took 30.85 seconds =====

Terminal will be reused by tasks, press any key to close it.

QUICK ACCESS

Ln 19, Col 2 Spaces: 2 UTF-8 CRLF C++ Go Live Win32

File Edit Selection View Go Run Terminal Help

main.cpp - Visual Stu...

PLATFORMIO ...

PROJECT TASKS

- General
 - Build
 - Upload
 - Monitor
 - Upload and Monitor
 - Devices
 - Clean
- Advanced
- Remote Development
- Miscellaneous
- env:esp32doit-d...

main.cpp x platformio.ini


Blink_LED > src > main.cpp > loop()

```
1 #include <Arduino.h>
2
3 #define LED 2
4
5 void setup() {
6     // put your setup code here, to run once:
7     Serial.begin(115200);
8 }
```

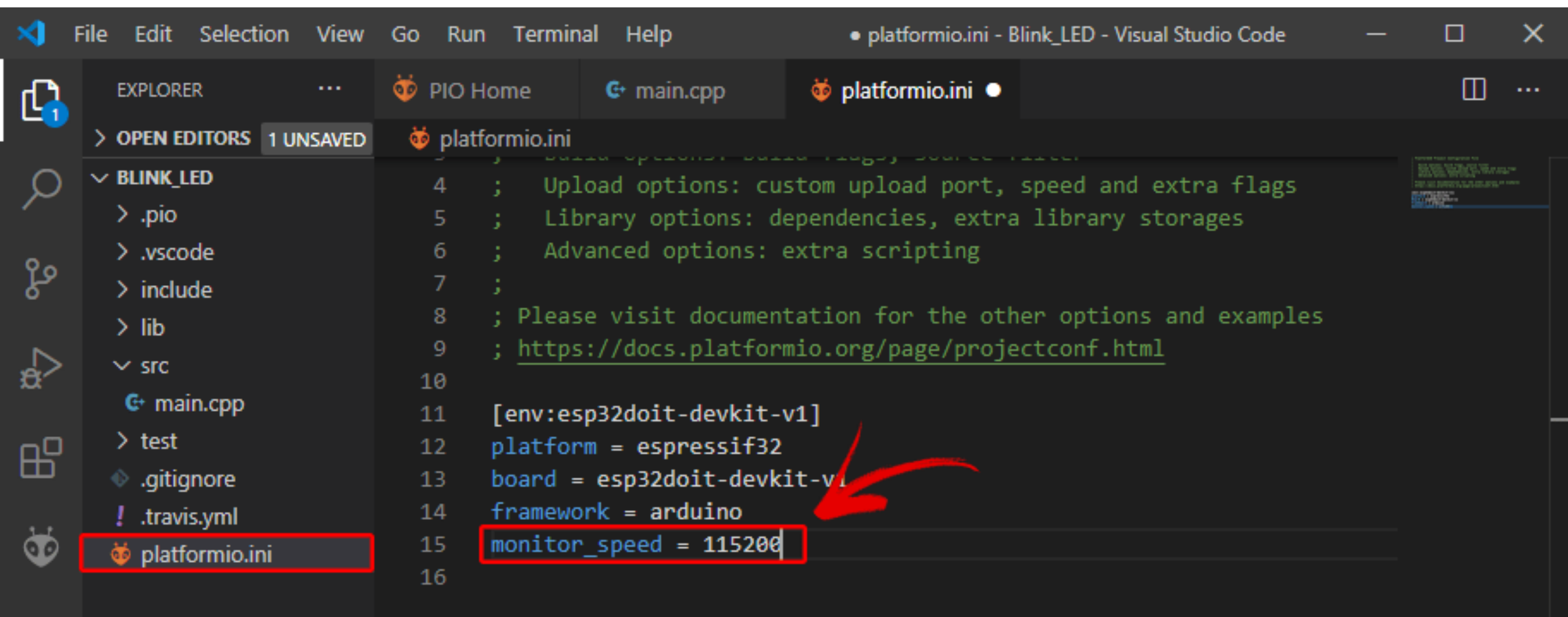
PROBLEMS OUTPUT DEBUG CONSOLE TERMINAL

3: Task - PlatformIO: Mc

LED is on
LED is off
LED is on
LED is off
LED is on
LED is off
LED is on
LED is off
LED is on

0 0 1 ✓ →  ↩

Ln 13, Col 27 Spaces: 2 UTF-8 CRLF C++ Go Live Win32



Instalasi Library

- Bisa secara manual (saya sarankan manual saja)
- Menggunakan library manager PIO

FileEditSelectionViewGoRunTerminalHelpPIO Home - Untitled (Workspace) - Visual Studio Code

PIO Home X

PIO Home

Home

Projects

Inspect

Libraries

Boards

Platforms

Devices

<>

Registry

Installed

Built-in

Updates

BME280

tft display

dht*

header:RH_ASK.h

keyword:mqtt

framework:mbed

platform:espressif8266

more...

Libraries

66

Adafruit BME280 Library

by Adafruit

2,462

3

Arduino

Arduino library for BME280 sensors. Arduino library for BME280 humidity and pressure sensors.

sensors

Infineon XMC, Kendryte K210, GigaDevice GD32V, ASR Microelectronics ASR605x, Atmel AVR, Atmel SAM, Espressif 8266, Intel ARC32, Microchip PIC32, Nordic nRF51, ST STM32, Teensy, TI MSP430, TI TIVA, Espressif 32, Nordic nRF52, ST STM8, Atmel megaAVR

BME280_Light

by Tomasz 'Zen' Napierala

416

1


Arduino

Lightweight and minimal BME280 temperature, humidity and barometric pressure sensos implementation for Arduino


00

59

 Registry

 Installed

 Built-in

 Updates

Adafruit BME280 Library by Adafruit

Arduino library for BME280 sensors. Arduino library for BME280 humidity and pressure sensors.

Installation

2.1.0 released about a month ago 

 Add to Project

| [More info](#)

Add project dependency



adafruit/Adafruit BME280 Library@^2.1.0

Projects\Blink_LED



You can manage your projects in the "Projects" section: create a new or add existing.

Information

> Registry and Specification

> External resources

Cancel

Add

Visual Studio Code interface showing the PlatformIO configuration file (`platformio.ini`) in the Explorer and the main editor.

EXPLORER

- WEB ...
- Blink_LED
 - .pio
 - .vscode
 - Example
 - include
 - lib
 - src
 - main.cpp
 - test
 - .gitignore
 - .travis.yml
 - platformio.ini**
- OUTLINE

platformio.ini

```
6 ; Advanced options: extra scripting
7 ;
8 ; Please visit documentation for the other options and examples
9 ; https://docs.platformio.org/page/projectconf.html
10
11 [env:esp32doit-devkit-v1]
12 platform = espressif32
13 board = esp32doit-devkit-v1
14 framework = arduino
15 monitor_speed = 115200
16 lib_deps = adafruit/Adafruit BME280 Library@^2.1.0
17
```

A red arrow points to the `lib_deps` line, and a red box highlights the text `lib_deps = adafruit/Adafruit BME280 Library@^2.1.0`.

Ln 17, Col 1 Spaces: 4 UTF-8 CRLF Ini Go Live

Adafruit BME280 Library by Adafruit

Arduino library for BME280 sensors. Arduino library for BME280 humidity and pressure sensors.

Installation

2.1.0 released about a month ago ▾

⬇️ Add to Project | [More info](#)

📄 Examples

🔗 Installation

📄 Headers

🕒 Changelog

Library Dependencies platformio.ini

The PlatformIO Registry is fully compatible with [Semantic Versioning](#) and its "version" scheme `<major>.<minor>.<patch>`. You can declare library dependencies in "platformio.ini" configuration file using [lib_deps](#) option.

; platformio.ini - project configuration file

[env:my_build_env]

platform = infineonxmc

framework = arduino

lib_deps =

RECOMMENDED

Accept new functionality in a backwards compatible manner and patches

adafruit/Adafruit BME280 Library @ ^2.1.0

Accept only backwards compatible bug fixes

(any version with the same major and minor versions, and an equal or greater patch version)

adafruit/Adafruit BME280 Library @ ~2.1.0

The exact version

adafruit/Adafruit BME280 Library @ 2.1.0

Kenapa ATOM / VSCODE???

- Deteksi port serial otomatis
- Autocomplete
- Error Highlight
- Multiple tabs
- Code folding
- Advance code navigation

THANK YOU VERY MUCH

