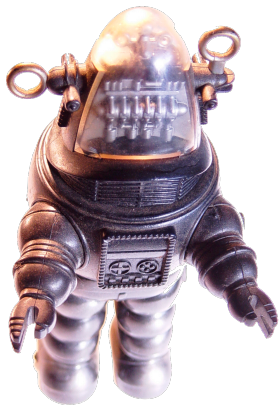
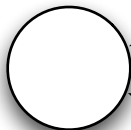


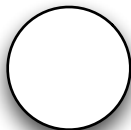
Hardware



Drivers

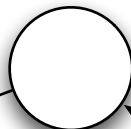


B-9

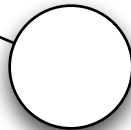


urg_laser

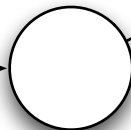
Interfaces



position2d



power



laser

Control

```
import robot
```

```
robot.connect()  
while True:  
    robot.observe()  
    robot.think()  
    robot.act()
```