# ECE421 – Introduction to Machine Learning

# Assignment 2

## **Neural Networks**

Hard Copy Due: Friday, March 6 @ 3:00 PM, at BA3128 Code Submission Due: Friday, March 6 @ 5:00 PM, on Quercus

## **General Notes:**

- Attach this cover page to your hard copy submission
- Please post assignment related questions on Piazza.

Please check section to which you would like the assignment returned.

## **Tutorial Sections:**

☐ Tutorial 1: Thursdays 3-5pm (SF2202)
☐ Tutorial 2: Thursdays 3-5pm (GB304)
☐ Tutorial 3: Tuesdays 10-12 (SF2202)
☐ Tutorial 4: Fridays 9-11 (BA1230)

Group Members			
Name	Student ID		

## 0 Setup

[1]: # ignore all future warnings

```
from warnings import simplefilter
simplefilter(action='ignore', category=FutureWarning)

[2]: # importing tensorflow
try:
    import google.colab
    import tensorflow as tf
    %tensorflow_version 1.13
except:
    import tensorflow as tf
    assert tf.__version__ == "1.13.1"
```

```
[3]: # imports
import numpy as np
import matplotlib.pyplot as plt
from tensorflow.keras import layers, models
```

import tensorflow.python.util.deprecation as deprecation

# ignore tensorflow depreciation warnings

deprecation.\_PRINT\_DEPRECATION\_WARNINGS = False

## 0.1 Visualizing the Dataset

```
[4]: # given by the assignment
def loadData():
    with np.load("notMNIST.npz") as data:
        Data, Target = data ["images"], data["labels"]
        np.random.seed(521)
        randIndx = np.arange(len(Data))
        np.random.shuffle(randIndx)
        Data = Data[randIndx]/255.
        Target = Target[randIndx]
        trainData, trainTarget = Data[:15000], Target[:15000]
        validData, validTarget = Data[15000:16000], Target[15000:16000]
        testData, testTarget = Data[16000:], Target[16000:]
        return trainData, validData, testData, trainTarget, validTarget, testTarget
```

```
[5]: trainData, validData, testData, trainTarget, validTarget, testTarget = loadData()

print(f"Training Data: {trainData.shape}\tTraining tagets: {trainTarget.shape}")

print(f"Validation Data: {validData.shape}\tValidation tagets: {validTarget.

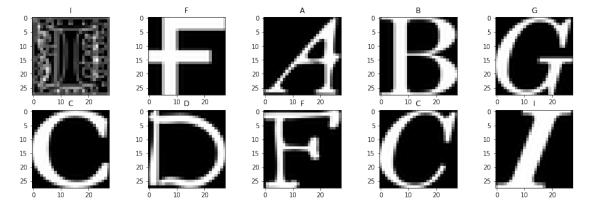
→shape}")

print(f"Testing Data: {testData.shape}\tTesting tagets:{testTarget.shape}")
```

Training Data: (15000, 28, 28) Training tagets: (15000,)
Validation Data: (1000, 28, 28) Validation tagets: (1000,)
Testing Data: (2724, 28, 28) Testing tagets: (2724,)

```
[6]: def plot(image, target, ax=None):
    ax = plt.gca() if ax == None else ax
    ax.imshow(image, cmap=plt.cm.gray)
    target_names = ['A', 'B', 'C', 'D', 'E', 'F', 'G', 'H', 'I', 'J']
    ax.set_title(target_names[target])
    # targets interger encoded from 0 to 9 corresponding to 'A' to 'J', □
    →respectively
```

```
[7]: fig, axis = plt.subplots(2, 5, figsize=(16, 5))
for ax in axis.reshape(-1):
    r = np.random.randint(trainData.shape[0])
    plot(trainData[r], trainTarget[r], ax=ax)
plt.show()
```



#### 0.2 Useful Functions

Some useful functions that will be used throughout the assignment such as getting random weights, getting the accuracy of a batch, making the loss and accuracy plots look nice, and global variables used throughout the code

```
[8]: # given by the assignment
def convertOneHot(trainTarget, validTarget, testTarget):
    newtrain = np.zeros((trainTarget.shape[0], 10))
    newvalid = np.zeros((validTarget.shape[0], 10))
    newtest = np.zeros((testTarget.shape[0], 10))
    for item in range(0, trainTarget.shape[0]):
        newtrain[item][trainTarget[item]] = 1
    for item in range(0, validTarget.shape[0]):
        newvalid[item][validTarget[item]] = 1
    for item in range(0, testTarget.shape[0]):
        newtest[item][testTarget[item]] = 1
    return newtrain, newvalid, newtest
```

```
[9]: def accuracy(y_pred, y):
    if y_pred.shape != y.shape:
        raise ValueError(f"prediction dimension {y_pred.shape} and label
        →dimensions {y.shape} don't match")
    return np.sum(y_pred.argmax(axis=1) == y.argmax(axis=1)) / y.shape[0]
```

```
[10]: def plot_loss(x, train_loss=None, valid_loss=None, test_loss=None, title=None,
       \rightarrowax=None):
          ax = plt.gca() if ax == None else ax
          if train_loss != None:
              ax.plot(x, train_loss, label="Training Loss")
          if valid_loss != None:
              ax.plot(x, valid loss, label="Validation Loss")
          if test_loss != None:
              ax.plot(x, test_loss, label="Testing Loss")
          ax.set_title("Loss" if title == None else title)
          ax.set_xlabel("Iterations")
          ax.set_xlim(left=0)
          ax.set_ylabel("Loss")
          ax.set_ylim(bottom=0)
          ax.legend(loc="upper right")
      def plot_accuracy(x, train_accuracy=None, valid_accuracy=None,_
       →test_accuracy=None, title=None, ax=None):
          ax = plt.gca() if ax == None else ax
          if train_accuracy != None:
```

```
ax.plot(x, train_accuracy, label="Training Accuracy")
    if valid_accuracy != None:
        ax.plot(x, valid_accuracy, label="Validation Accuracy")
    if test_accuracy != None:
        ax.plot(x, test_accuracy, label="Testing Accuracy")
    ax.set_title("Accuracy" if title == None else title)
    ax.set xlabel("Iterations")
    ax.set_xlim(left=0)
    ax.set ylabel("Accuracy")
    ax.set_yticks(np.arange(0, 1.1, step=0.1))
    ax.grid(linestyle='-', axis='y')
    ax.legend(loc="lower right")
def display statistics(train loss=None, train acc=None, valid loss=None,
→valid_acc=None,
                       test loss=None, test acc=None, num=True, plot=True):
    tl = "-" if train loss is None else round(train loss[-1], 4)
    ta = "-" if train acc is None else round(train acc[-1]*100, 2)
    vl = "-\t" if valid_loss is None else round(valid_loss[-1], 4)
    va = "-" if valid_acc is None else round(valid_acc[-1]*100, 2)
    sl = "-\t\t" if test_loss is None else round(test_loss[-1], 4)
    sa = "-" if test_acc is None else round(test_acc[-1]*100, 2)
    if num:
        print(f"Training loss: {tl}{'':.20s}\t\tTraining acc: {ta}{'%' if ta !=_u
 →'-' else ''}")
        print(f"Validation loss: {vl}{'':.20s}\t\tValidation acc: {va}{'%' if⊔
→va != '-' else ''}")
        print(f"Testing loss: {sl}{'':.20s}\t\tTesting acc: {sa}{'%' if sa !=_\( \)
→'-' else ''}")
    if plot:
        fig, ax = plt.subplots(1, 2, figsize=(18, 6))
        plot_loss(np.arange(0, len(train_loss), 1), train_loss, valid_loss, u
 →test_loss, ax=ax[0])
        plot_accuracy(np.arange(0, len(train_loss), 1), train_acc, valid_acc,_u
 \rightarrowtest_acc, ax=ax[1])
        plt.show()
        plt.close()
```

[11]:

## 1 Neural Networks using Numpy

## 1.1 Helper Functions

```
[12]: def relu(x):
          return np.maximum(0, x)
      # applies softmax to a single vector
      def softmax(x):
          return np.exp(x) / np.exp(x).sum()
      # applies softmax to a batch
      # (more efficient than having a loop and calling the above function)
      def softmax_batch(X):
          return np.exp(X) / np.exp(X).sum(axis=1, keepdims=True)
[13]: def computeLayer(X, W, b):
          return X @ W.T + b
[14]: # note: target is one-hot encoded
      def averageCE(target, prediction):
         return -(target * np.log(prediction+TINY)).sum(axis=1).mean()
      def gradCE(target, predication):
          return predication - target
```

## 1.2 Backpropagation Derivation

The code application of the following derivation is given in the next section.

## Derivative of Softmax

$$\begin{split} p_i &= \mathtt{softmax}(\mathbf{o})_i = \frac{e^{o_i}}{\sum_{k=1}^K e^{o_k}} \\ & \text{if } i \neq j \\ & \frac{\partial p_j}{\partial o_i} = \frac{0 \cdot \sum_{k=1}^K e^{o_k} - e^{o_i} \cdot e^{o_j}}{\left(\sum_{k=1}^K e^{o_k}\right)^2} = \boxed{-p_i \cdot p_j} \\ & \text{if } i = j \\ & \frac{\partial p_j}{\partial o_i} = \frac{e^{o_i} \cdot \sum_{k=1}^K e^{o_k} - e^{o_i} \cdot e^{o_j}}{\left(\sum_{k=1}^K e^{o_k}\right)^2} = \boxed{(1-p_j) \cdot p_i} \end{split}$$

### Derivative of Softmax + Cross Entropy Loss

$$L_{CE}(\mathbf{y}, \mathbf{p}) = -\sum_{k=1}^{K} y_k \log p_k$$

$$\frac{\partial L_{CE}}{\partial o_i} = -\sum_{k=1}^K \frac{y_k}{p_k} \cdot \frac{\partial p_k}{\partial o_i} = -y_i(1-p_i) - \sum_{k \neq i} \frac{y_k}{p_k} \cdot (-p_k p_i) = -y_i + y_i p_i + \sum_{k \neq i} y_k p_i = -y_i + p_i \cdot \sum_{k=1}^K y_k = p_i - y_i$$

In Vector Form: 
$$\boxed{\frac{\partial L_{CE}}{\partial \mathbf{o}} = \mathbf{p} - \mathbf{y}}$$

### Remaining Backpropogation

$$\mathbf{o} = W_o \mathbf{g} + \mathbf{b}_o$$

$$\frac{\partial L}{\partial W_o} = \frac{\partial L}{\partial \mathbf{o}} \cdot \left(\frac{\partial \mathbf{o}}{\partial W_o}\right)^T = \frac{\partial L}{\partial \mathbf{o}} \cdot \mathbf{g}^T \qquad \qquad \frac{\partial L}{\partial \mathbf{b}_o} = \frac{\partial L}{\partial \mathbf{o}} \cdot \left(\frac{\partial \mathbf{o}}{\partial \mathbf{b}_o}\right)^T = \frac{\partial L}{\partial \mathbf{o}}$$

$$g_i = \mathtt{ReLU}(h_i) = \mathtt{max}(h_i, 0)$$

$$\frac{\partial L}{\partial h_i} = \frac{\partial L}{\partial g_i} \cdot \frac{\partial g_i}{\partial h_i} = \begin{cases} \frac{\partial L}{\partial g_i} & \text{if } h_i > 0\\ 0 & \text{if } h_i < 0 \end{cases}$$

$$\mathbf{h} = W_h \mathbf{x} + \mathbf{b}_h$$

$$\frac{\partial L}{\partial W_h} = \frac{\partial L}{\partial \mathbf{h}} \cdot \left(\frac{\partial \mathbf{h}}{\partial W_h}\right)^T = \frac{\partial L}{\partial \mathbf{h}} \cdot \mathbf{x}^T \qquad \qquad \frac{\partial L}{\partial \mathbf{b}_h} = \frac{\partial L}{\partial \mathbf{h}} \cdot \left(\frac{\partial \mathbf{h}}{\partial \mathbf{b}_h}\right)^T = \frac{\partial L}{\partial \mathbf{h}}$$

### 1.3 Learning

```
[16]: class mini NN(object):
          11 11 11
          Network Structure:
              input: x
              hidden: h = W_h * x + b_h
                      g = ReLU(h)
              output: o = W_o * g + b_o
                      p = softmax(o)
          n n n
          def __init__(self, D, F, K):
              # D, F, and K are the number of neurons in the input, hidden, and
       \rightarrow output layers
              self.D, self.F, self.K = D, F, K
              self.init_weights()
          def init_weights(self):
              # getting random parameters using Xaiver initialization scheme
              self.W_h = np.random.normal(0, np.sqrt(2.0/(self.D+self.F)), (self.F,_
       ⇒self.D))
              self.b_h = np.random.normal(0, np.sqrt(2.0/(self.D+self.F)), self.F)
              self.W_o = np.random.normal(0, np.sqrt(2.0/(self.F+self.K)), (self.K,_
       \rightarrowself.F))
              self.b_o = np.random.normal(0, np.sqrt(2.0/(self.F+self.K)), self.K)
          def feedforward(self, X):
              # python can dynamically create attributes
              self.H = computeLayer(X, self.W h, self.b h)
              self.G = relu(self.H)
              self.0 = computeLayer(self.G, self.W_o, self.b_o)
              self.P = softmax_batch(self.0)
              return self.P
          def backpropagation(self, X, y):
              # This function assumes that feedforward was called before,
              # which instantiates the needed activations
              # output layer activations
              dL_do = gradCE(y, self.P)
              # output layer parameters
              dL_dWo = dL_do.T @ self.G
              dL_dbo = dL_do
```

```
# hidden layer activations
    dL_dg = dL_do @ self.W_o
    dL_dh = dL_dg.copy()
    dL_dh[self.H <= 0] = 0
    # hidden layer parameters
    dL_dWh = dL_dh.T @ X
    dL_dbh = dL_dh
    return dL_dWo , dL_dbo.sum(axis=0), dL_dWh, dL_dbh.sum(axis=0)
def train(self, X, y, epochs=200, gamma=0.99, alpha=1e-5, F=None,
          validData=None, validTarget=None, testData=None, testTarget=None):
    # initializations
    self.F = self.F if F is None else F
    self.init_weights()
    train_loss, train_acc = [], []
    valid_loss, valid_acc = [], []
    test_loss, test_acc = [], []
    v_Wo, v_Wh = 0, 0
    for e in range(epochs):
        # getting predictions
        p = self.feedforward(X)
        train_loss.append( averageCE(p, y) )
        train_acc.append( accuracy(p, y) )
        # getting gradients
        dL_dWo, dL_dbo, dL_dWh, dL_dbh = self.backpropagation(X, y)
        # updating parameters
        v_Wo = gamma * v_Wo + alpha * dL_dWo
        self.W_o -= v_Wo
        self.b_o -= alpha * dL_dbo
        v_Wh = gamma * v_Wh + alpha * dL_dWh
        self.W_h -= v_Wh
        self.b_h -= alpha * dL_dbh
        # calculating statistics
        if not validData is None and not validTarget is None:
            p = self.feedforward(validData)
```

```
valid_loss.append(averageCE(p, validTarget))
    valid_acc.append(accuracy(p, validTarget))
    if not testData is None and not testTarget is None:
        p = self.feedforward(testData)
        test_loss.append(averageCE(p, testTarget))
        test_acc.append(accuracy(p, testTarget))

statistics = (train_loss, train_acc)
    if not validData is None and not validTarget is None:
        statistics += (valid_loss, valid_acc, )
    if not testData is None and not testTarget is None:
        statistics += (test_loss, test_acc,)
    return statistics
```

```
[17]: # For investigation, analyze how long each hyperparameter set takes to train
import time

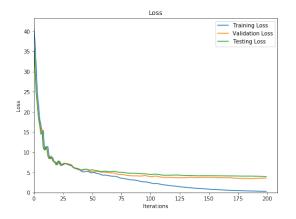
X, y = trainData.reshape(N, d), newtrain
F = 1000 # hidden unit size
model = mini_NN(d, F, K)

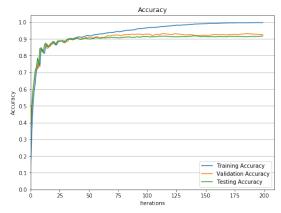
start = time.time()
statistics = model.train(X, y, epochs=200, gamma=0.99, alpha=1e-5, **VTDatasets)
end = time.time()

display_statistics(*statistics)
print(f"Time is {end - start}.")
```

Training loss: 0.2957 Training acc: 99.73%

Validation loss: 3.6131 Validation acc: 92.6% Testing loss: 3.9853 Testing acc: 91.74%





Time is 372.057715177536.

## 1.4 Hyperparameter Investigation

The following hyperparameter search was done on google colab using code similar to the snippet above, but with the corresponding hyperparameters changed.

#### 1.4.1 Number of Hidden Units

Number of hidden units: 100

Statistic	Value	Statistic	Value
Training loss:	4.6824	Training acc:	92.31%
Validation loss:	5.5578	Validation acc:	89.8%
Testing loss:	5.7423	Testing acc:	89.46%
Training Time(s):	42.705		

**Comments**: Accuracy seems to have converged by 50 iterations. Training this network with 100 hidden units was the fastest of the three. This is likely because there were very few parameters to optimize.

Number of hidden units: 500

Value	Statistic	Value
0.7009	Training acc:	99.36%
3.894	Validation acc:	91.9%
4.1808	Testing acc:	91.19%
176.361		
	0.7009 3.894 4.1808	0.7009 Training acc: 3.894 Validation acc: 4.1808 Testing acc:

Comments: Accuracy seems to have converged by 50 iterations. Training this network with 500 hidden units was slower than with 100 units, but the validation/testing accuracies showed slight improvement. Further, Training loss and training accuracy near perfection. Since this trend is not matched by validation/testing accuracies, we see that the network is overfitting as it is learning the training examples too well.

Number of hidden units: 2000

Statistic	Value	Statistic	Value
Training loss: Validation loss: Testing loss: Training Time(s):	0.2303 3.3766 3.8814 645.494	Training acc: Validation acc: Testing acc:	99.82% 93.0% 91.85%

Comments: Accuracy seems to have convered by 50 iterations. Training this network with 2000 hidden units was considerably slower than both other networks, depite nearly identical validation/testing accuracies. Training loss and training accuracy are essentially perfect by the end of 200 epochs. Since this trend is not matched by validation/testing accuracies, we see that the

network is overfitting considerably. It has essentially memorized the training examples, but can not generalize as well (beyond the performance attained by smaller networks) to validation/testing data.

General comments: Also, the small bump and incresae in loss before once again decreasing suggest that the parameters went through a local minimum before converging. Momentum likely helped it converge faster as it doesn't appear to have gotten stuck in the local min. The smaller networks trained considerably faster, but had lower accuracy (even though the difference was very small). The larger networks clearly overfit the training data; this indicates that they are too complex for their classification tasks and/or the input data should be improved.

## 1.4.2 Early Stopping

From the plots, we observe that training should have stopped at an early stopping point of 50 iterations. Beyond this point, there is very little improvement in either validation/testing losses or accuracies.

## 2 Neural Networks in Tensorflow

## 2.1 Model implementation

```
[0]: # training params
     learning_rate = 0.0001
     epochs = 50
     batch size = 32
     # create model
     model = models.Sequential()
     model.add(layers.InputLayer(input shape=(28, 28,1))) # input layer
     model.add(layers.Conv2D(
                                                             # conv layer
             filters=32,
             strides=(1,1),
             kernel_size=[3, 3],
             padding="same",
             activation='relu',
             kernel_initializer=tf.contrib.layers.xavier_initializer(uniform=False)))
     model.add(layers.BatchNormalization())
                                                            # batch norm
     model.add(layers.MaxPooling2D((2, 2)))
                                                             # max pooling
     model.add(layers.Flatten())
                                                             # flatten
     model.add(layers.Dense(784, activation='relu'))
                                                             # fully-connected 784
     model.add(layers.Dense(10))
                                                             # fully-connected 10
                                                             # softmax output
     model.add(layers.Softmax())
     # compile model w/ Adam optimizer + cross entropy loss
     model.compile(optimizer=tf.keras.optimizers.Adam(lr=learning_rate),
                   loss=tf.keras.losses.CategoricalCrossentropy(from_logits=True),
                   metrics=['accuracy'])
```

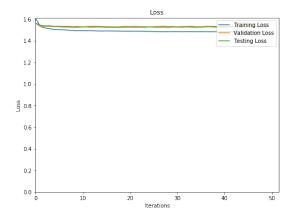
## 2.2 Model Training

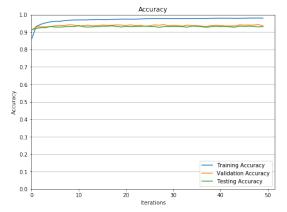
```
[]: # callback to test after each epoch
     class TestCallback(tf.keras.callbacks.Callback):
         def __init__(self, test_data):
             self.test_data = test_data
             self.test_acc = []
             self.test_loss = []
         def on epoch end(self, epoch, logs=None):
             # perform a test per epoch
             x, y = self.test_data
             loss, acc = self.model.evaluate(x, y, verbose=0, batch_size=32)
             self.test_loss.append(loss)
             self.test acc.append(acc)
             # append to returned dictionary
             logs["test_loss"] = self.test_loss
             logs["test_acc"] = self.test_acc
[0]: # training
     history = model.fit(trainData, train_labels,
                         validation_data = (validData, valid_labels),
                         epochs=epochs,
                         batch_size=batch_size,
                         callbacks=[TestCallback((testData, test_labels))],
                         verbose=0, # 0 = silent, 1 = per epoch
                         shuffle=True)
     # display statistics
     train_acc, train_loss = history.history["acc"], history.history["loss"]
     val_acc, val_loss = history.history["val_acc"], history.history["val_loss"]
     test_acc, test_loss = history.history["test_acc"][0], history.
     ⇔history["test_loss"][0]
     display_statistics(train_loss=train_loss, train_acc=train_acc,
                        valid_loss=val_loss, valid_acc=val_acc,
```

Training loss: 1.4814 Training acc: 97.97%

Validation loss: 1.5248 Validation acc: 93.5% Testing loss: 1.5293 Testing acc: 93.06%

test\_loss=test\_loss, test\_acc=test\_acc)





## 2.3 Hyperparameter Investigation

### 2.3.1 L2 Regularization

```
[0]: # training params
     learning_rate = 0.0001
     epochs = 50
     batch_size = 32
     # test all weight decays [0.01, 0.1, 0.5]
     for scale in [0.01, 0.1, 0.5]:
         print("\nL2 Normalization with {}\n".format(scale))
         # create model
         model = models.Sequential()
         model.add(layers.InputLayer(input_shape=(28, 28,1))) # input layer
         model.add(layers.Conv2D(
                                                                 # conv layer
               filters=32,
               strides=(1,1),
               kernel_size=[3, 3],
               padding="same",
               activation='relu',
               kernel_initializer=tf.contrib.layers.
      →xavier_initializer(uniform=False)))
         model.add(layers.BatchNormalization())
                                                                # batch norm
         model.add(layers.MaxPooling2D((2, 2)))
                                                                 # max pooling
         model.add(layers.Flatten())
                                                                 # flatten
         model.add(layers.Dense(784,
                             activation='relu',
                             kernel regularizer=tf.contrib.layers.
     →12_regularizer(scale=scale)))
                                                                      #⊔
     → fully-connected 784 w/ ReLu
         model.add(layers.Dense(10))
                                                                 # fully-connected 10
         model.add(layers.Softmax())
                                                                 # softmax output
         # compile model w/ Adam optimizer + cross entropy loss
         model.compile(optimizer=tf.keras.optimizers.Adam(lr=learning_rate),
                     loss=tf.keras.losses.CategoricalCrossentropy(from_logits=True),
                     metrics=['accuracy'])
         # train
         history_1 = model.fit(trainData, train_labels,
                           validation_data = (validData, valid_labels),
                           epochs=epochs,
                           batch_size=batch_size,
                           callbacks=[TestCallback((testData, test_labels))],
                           verbose=0, # 0 = silent, 1 = per epoch
```

```
shuffle=True)

# display statistics

train_acc, train_loss = history.history["acc"], history.history["loss"]

val_acc, val_loss = history.history["val_acc"], history.history["val_loss"]

test_acc, test_loss = history.history["test_acc"][0], history.

→history["test_loss"][0]

display_statistics(train_loss=train_loss, train_acc=train_acc,

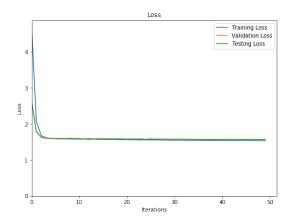
valid_loss=val_loss, valid_acc=val_acc,

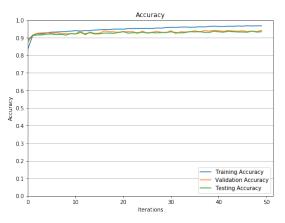
test_loss=test_loss, test_acc=test_acc)
```

#### L2 Normalization with 0.01

Training loss: 1.5349 Training acc: 96.81%

Validation loss: 1.5601 Validation acc: 94.2% Testing loss: 1.5696 Testing acc: 93.43%

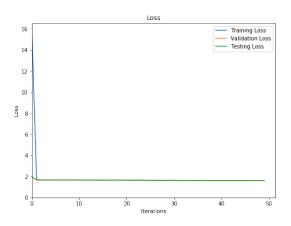


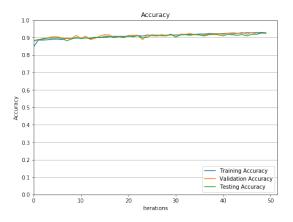


#### L2 Normalization with 0.1

Training loss: 1.6037 Training acc: 92.77%

Validation loss: 1.6033 Validation acc: 92.6% Testing loss: 1.6058 Testing acc: 92.44%

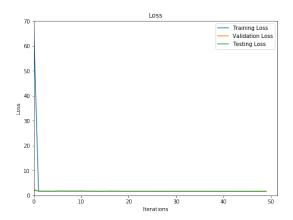


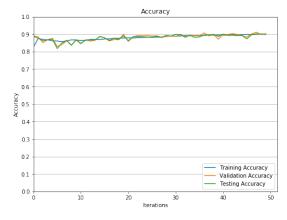


## L2 Normalization with 0.5

Training loss: 1.6729 Training acc: 90.07%

Validation loss: 1.6705 Validation acc: 90.3% Testing loss: 1.6746 Testing acc: 89.83%





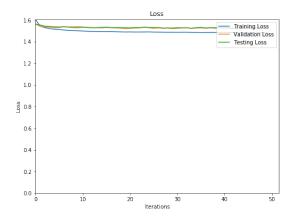
#### 2.3.2 Dropout

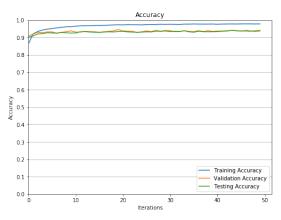
```
[0]: # training params
     learning_rate = 0.0001
     epochs = 50
     batch_size = 32
     # for rate in [0.9, 0.75, 0.5]:
     for rate in [0.1, 0.25, 0.5]:
         print("\nDropout with probability {}\n".format(rate))
         # create model
         model = models.Sequential()
         model.add(layers.InputLayer(input_shape=(28, 28,1)))
                                                               # input layer
         model.add(layers.Conv2D(
                                                                # conv layer
               filters=32,
               strides=(1,1),
               kernel_size=[3, 3],
               padding="same",
               activation='relu',
               kernel_initializer=tf.contrib.layers.
     →xavier_initializer(uniform=False)))
         model.add(layers.BatchNormalization())
                                                               # batch norm
         model.add(layers.MaxPooling2D((2, 2)))
                                                               # max pooling
         model.add(layers.Flatten())
                                                                # flatten
         model.add(layers.Dense(784))
                                                               # fully-connected 784
         model.add(layers.Dropout(rate=rate))
                                                               # dropout
                                                                # Relu activation
         model.add(layers.ReLU())
         model.add(layers.Dense(10))
                                                                # fully-connected 10
         model.add(layers.Softmax())
                                                                # softmax output
         # compile model w/ Adam optimizer + cross entropy loss
         model.compile(optimizer=tf.keras.optimizers.Adam(lr=learning_rate),
                     loss=tf.keras.losses.CategoricalCrossentropy(from_logits=True),
                     metrics=['accuracy'])
         # train
         history_2 = model.fit(trainData, train_labels,
                           validation_data = (validData, valid_labels),
                           epochs=epochs,
                           batch_size=batch_size,
                           callbacks=[TestCallback((testData, test_labels))],
                           verbose=0, # 0 = silent, 1 = per epoch
                           shuffle=True)
         # display stats
         train_acc, train_loss = history.history["acc"], history.history["loss"]
         val_acc, val_loss = history.history["val_acc"], history.history["val_loss"]
```

### Dropout with probability 0.1

Training loss: 1.4831 Training acc: 97.81%

Validation loss: 1.5229 Validation acc: 93.7% Testing loss: 1.5219 Testing acc: 93.98%

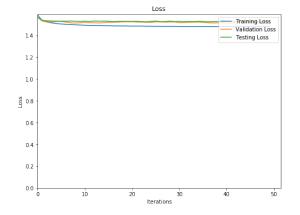


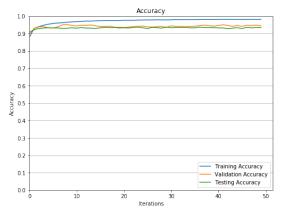


### Dropout with probability 0.25

Training loss: 1.4794 Training acc: 98.19%

Validation loss: 1.5156 Validation acc: 94.4% Testing loss: 1.527 Testing acc: 93.36%





## Dropout with probability 0.5

Training loss: 1.4803 Training acc: 98.09%

Validation loss: 1.5206 Validation acc: 94.0% Testing loss: 1.5238 Testing acc: 93.69%

