Marching Triangles

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Outline

- Review
- Goal
- Interpolation
- Implementation
- Inductive triangulation

Notation

Throughout:

We represent scalars by italics/Greek letters:

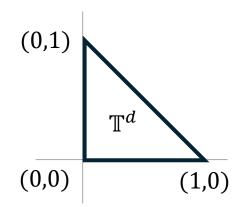
$$a, \alpha \in \mathbb{R}$$

We represent vectors/matrices with bold letters:

$$\mathbf{v} \in \mathbb{R}^d$$
 and $\mathbf{M} \in \mathbb{R}^{d \times d}$

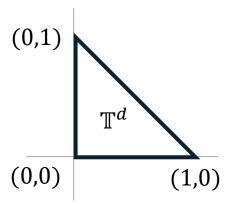
We represent vector/matrix coefficients with italics letters:

$$(\mathbf{v})_i \equiv v_i \in \mathbb{R}$$
 and $(\mathbf{M})_{ij} \equiv M_{ij} \in \mathbb{R}$



Definition:

The *d*-dimensional *unit-right-simplex*
$$\mathbb{T}^d \subset \mathbb{R}^d$$
 is the simplex through: $\{(0,0,\dots,0,0),(1,0,\dots,0,0),(0,1,\dots,0,0),\dots,(0,0,\dots,1,0),(0,0,\dots,0,1)\}$ $\mathbb{T}^d = \{\mathbf{x} = \{x_1,\dots,x_d\} \in \mathbb{R}^d \, | \, 0 \leq x_i \leq 1, \, \sum_{i=1}^d x_i \leq 1 \}$



Definition:

The *d*-dimensional *unit-right-simplex* $\mathbb{T}^d \subset \mathbb{R}^d$ is the simplex: $\mathbb{T}^d = \{\mathbf{x} = \{x_1, ..., x_d\} \in \mathbb{R}^d | 0 \le x_i \le 1, \ \sum_{i=1}^d x_i \le 1\}$

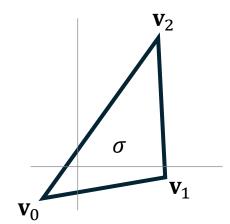
Fact:

Given a set of $\{f_0, ..., f_d\} \in \mathbb{R}$ values at the corners of the simplex, there is a unique affine function which evaluates to those values at the corners.

Proof:

Set $f: \mathbb{R}^d \to \mathbb{R}$ to be the function:

$$f(\mathbf{p}) = f_0 + \langle \mathbf{p}, \mathbf{v}_f \rangle$$
 with $\mathbf{v}_f = (f_1 - f_0, ..., f_d - f_0)^{\mathsf{T}}$



Definition:

A d-dimensional $simplex \sigma \subset \mathbb{R}^d$ is the convex hull of d+1 points* $\{\mathbf{v}_0, ..., \mathbf{v}_d\} \subset \mathbb{R}^d$

Fact:

There is a unique affine map $\phi_{\sigma} : \mathbb{R}^d \to \mathbb{R}^d$ taking the unit-right-simplex to σ .

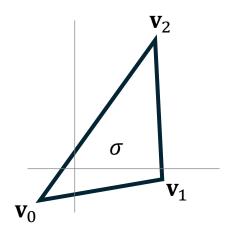
Proof:

Set ϕ_{σ} to be the map:

$$\phi_{\sigma}(\mathbf{p}) = \mathbf{v}_0 + (\mathbf{v}_1 - \mathbf{v}_0) \cdots |\mathbf{v}_d - \mathbf{v}_0| \cdot \mathbf{p}$$

^{*}Throughout will be assuming that geometry is "in general position"

$$\phi_{\sigma}(\mathbf{p}) = \mathbf{v}_0 + (\mathbf{v}_1 - \mathbf{v}_0) \cdots |\mathbf{v}_d - \mathbf{v}_0| \cdot \mathbf{p}$$



Definition:

Given a point $\mathbf{p} \in \mathbb{R}^d$, the point

$$\mathbf{p}^{\sigma} = \phi_{\sigma}^{-1}(\mathbf{p})$$

is the barycentric coordinates of **p** with respect to the simplex σ .

Fact:

The barycentric coordinates $\mathbf{p}^{\sigma} = \phi_{\sigma}^{-1}(\mathbf{p})$ satisfy: $\mathbf{p} = \mathbf{v}_0 \cdot (1 - p_1^{\sigma} - \dots - p_d^{\sigma}) + \mathbf{v}_1 \cdot p_1^{\sigma} + \dots + \mathbf{v}_d \cdot p_d^{\sigma}$

Review: barycentric coordinates

Example:

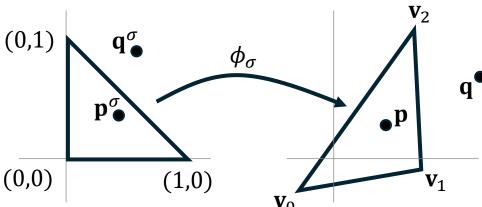
Given a d-dimensional simplex $\sigma \subset \mathbb{R}^d$ point $\mathbf{p} \in \mathbb{R}^d$, check if $\mathbf{p} \in \sigma$.

• Compute the barycentric coordinates of **p**:

$$\mathbf{p}^{\sigma} = \phi_{\sigma}^{-1}(\mathbf{p})$$

• Check if the barycentric coordinates are in the unit-right-simplex \mathbb{T}^d :

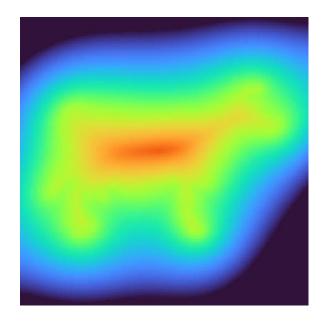
$$0 \le p_i^{\sigma} \le 1$$
 and $\sum_{i=1}^{a} p_i^{\sigma} \le 1$



Goal (analytic)

Input:

- A real-valued function, $g:[0,1]^2 \to \mathbb{R}$
- A real level-set-value, $\alpha \in \mathbb{R}$



Goal (analytic)

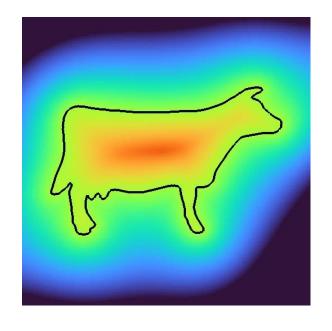
Input:

- A real-valued function, $g:[0,1]^2 \to \mathbb{R}$
- A real level-set-value, $\alpha \in \mathbb{R}$

Output:

• The α level-set of g:

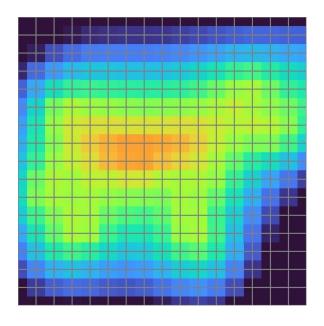
$$g^{-1}(\alpha) = \{ \mathbf{p} \in [0,1]^2 | g(\mathbf{p}) = \alpha \}$$



Goal (discrete)

Input:

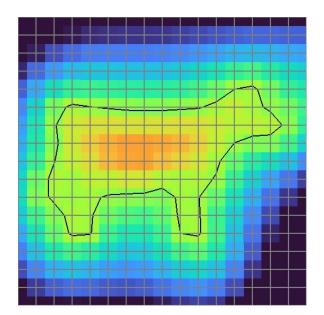
- A regular real-valued 2D grid, $g \in \mathbb{R}^{N \times N}$, with values at corners
- A real level-set-value, $\alpha \in \mathbb{R}$



Goal (discrete)

Input:

- A regular real-valued 2D grid, $g \in \mathbb{R}^{N \times N}$, with values at corners
- A real level-set-value, $\alpha \in \mathbb{R}$

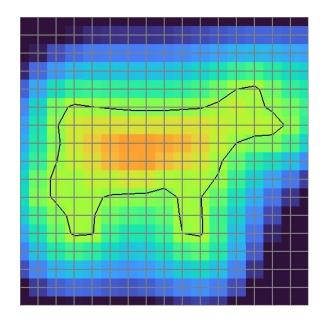


Output:

- A piecewise-linear curve corresponding to the α level-set of g.
 - A set of vertices, $V = \{\mathbf{v}_1, \dots, \mathbf{v}_n\} \subset \mathbb{R}^2$
 - Set of edges $E \subset \{1, ..., n\} \times \{1, ..., n\}$

Approach

- Interpolate the function's values from the corners.
- Independently extract the level-set from each cell.



Observation:

• If the interpolated function is continuous, the per-cell level-sets will match seamlessly.

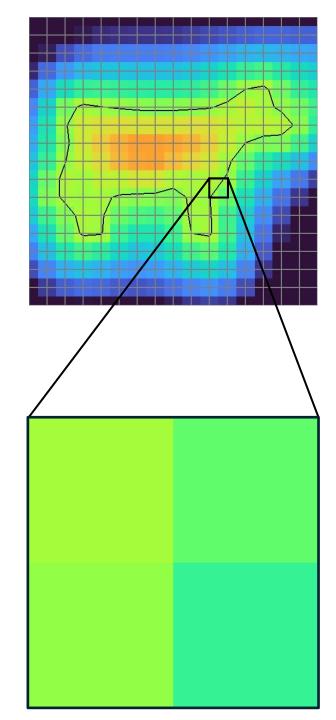
Challenge:

How to interpolate from corners?

Q: How to interpolate from corners?

A: Nearest interpolation

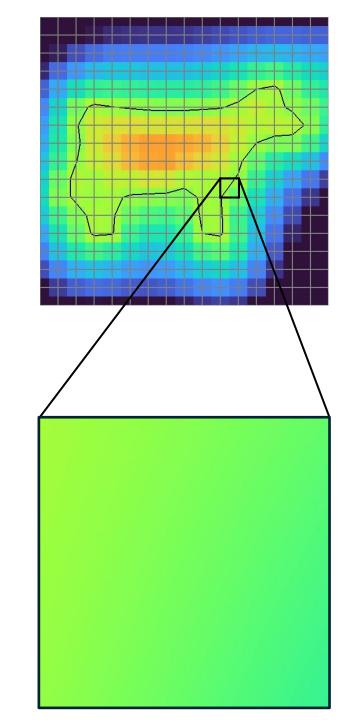
✗ Not continuous



Q: How to interpolate from corners?

A: Bi-linear interpolation

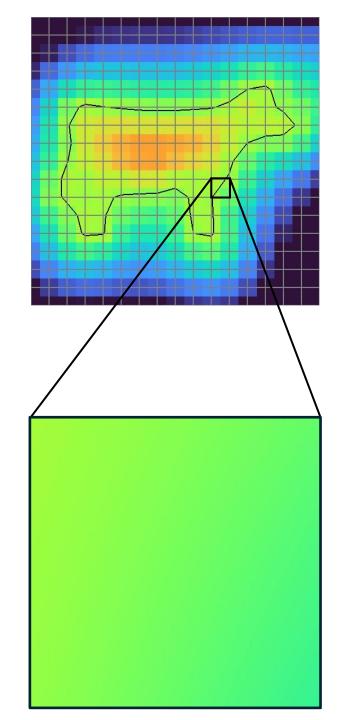
$$f(x,y) = (1-x) \cdot (1-y)f_{00} + (1-x) \cdot y \cdot f_{01} + x \cdot (1-y) \cdot f_{10} + x \cdot y \cdot f_{11}$$



Q: How to interpolate from corners?

A: Bi-linear interpolation

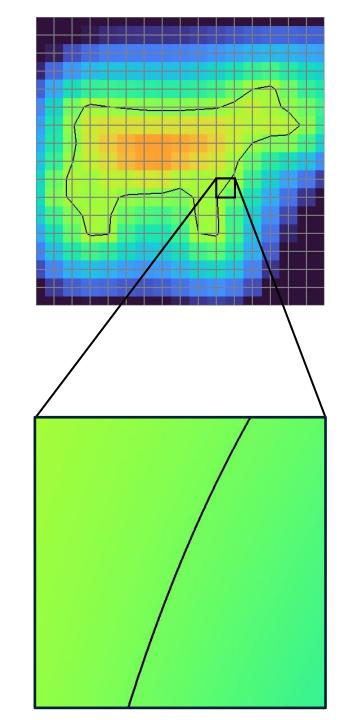
✓ Continuous



Q: How to interpolate from corners?

A: Bi-linear interpolation

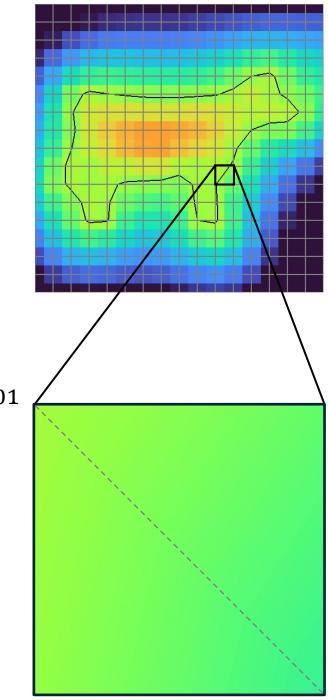
- ✓ Continuous
- Level-sets are curved (the level-set gets more complex as the dimension of the domain is increased)



Q: How to interpolate from corners?

A: Add a diagonal and linearly interpolate within each triangle

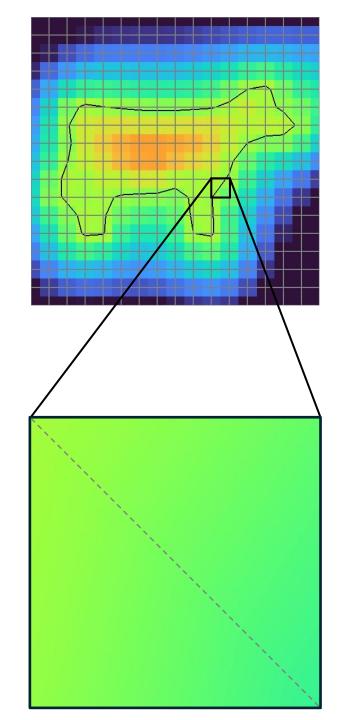
$$f(x,y) = (1 - x - y) \cdot f_{00} + x \cdot f_{10} + y \cdot f_{01}$$



Q: How to interpolate from corners?

A: Add a diagonal and linearly interpolate within each triangle

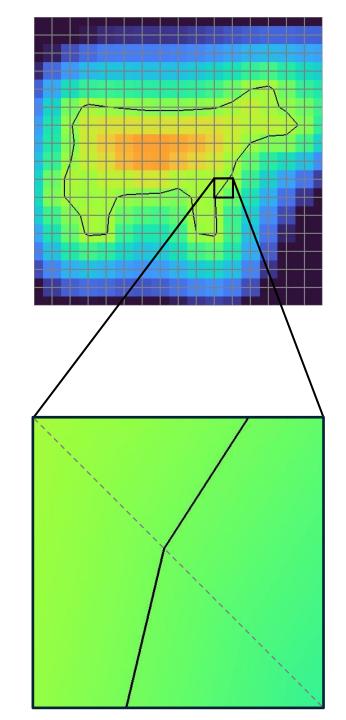
✓ Continuous



Q: How to interpolate from corners?

A: Add a diagonal and linearly interpolate within each triangle

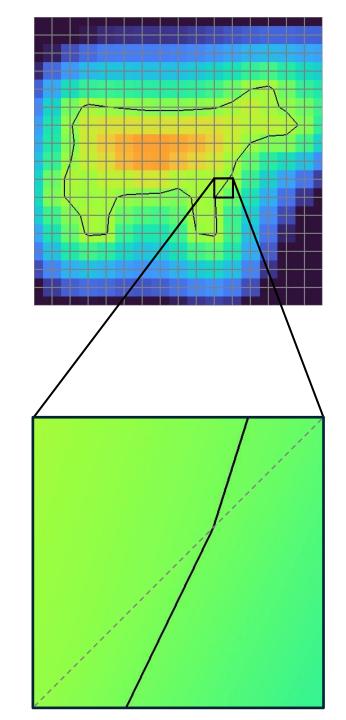
- ✓ Continuous
- ✓ Level-sets are straight



Q: How to interpolate from corners?

A: Add a diagonal and linearly interpolate within each triangle

- ✓ Continuous
- ✓ Level-sets are straight
- * Diagonal choice is arbitrary



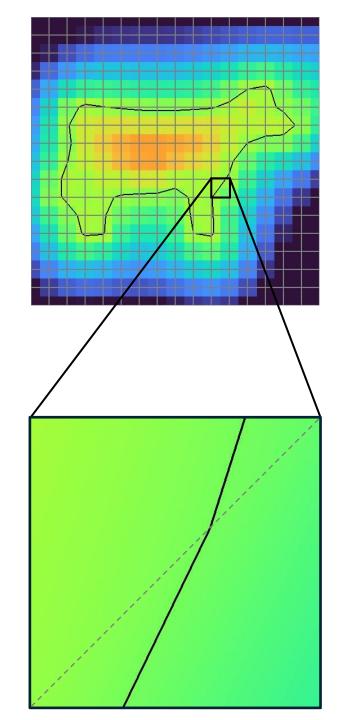
Q: How to interpolate from corners?

A: Add a diagonal and linearly interpolate within each triangle

- ✓ Continuous
- ✓ Level-sets are straight
- ➤ Diagonal choice is arbitrary

Note:

The functions will be continuous along the shared edge between edge-adjacent triangles.

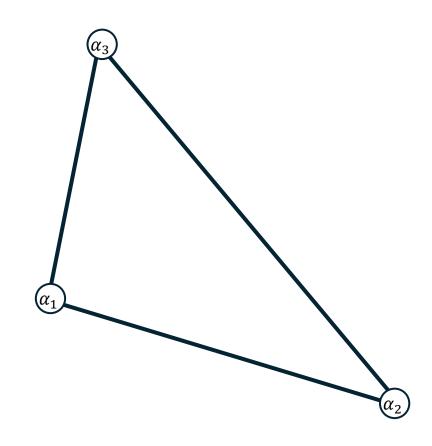


Input:

- A triangle $(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3)$, with $\mathbf{v}_i \in \mathbb{R}^2$
- Values $(\alpha_1, \alpha_2, \alpha_3)$, with $\alpha_i \in \mathbb{R}$
- A level-set-value $\alpha \in \mathbb{R}$

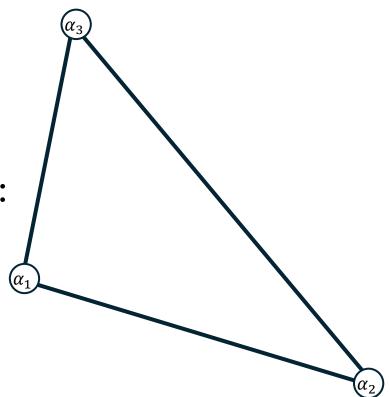
Output:

• The geometry of the α level-set within the triangle



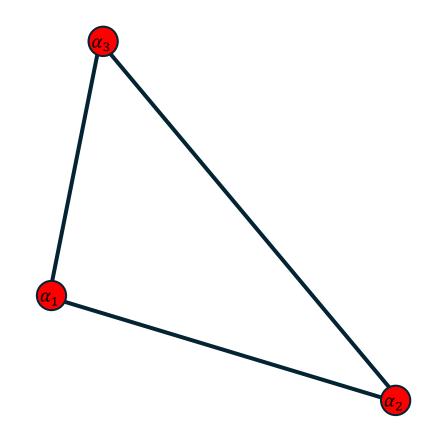
Assuming general position, there are four cases:

- α_1 , α_2 , $\alpha_3 > \alpha$
- α_{i+1} , $\alpha_{i+2} > 0$ and $\alpha_i < \alpha$
- $\alpha_i > \alpha$ and α_{i+1} , $\alpha_{i+2} < \alpha$
- α_1 , α_2 , $\alpha_3 < \alpha$



$$\alpha_1, \alpha_2, \alpha_3 > \alpha$$
:

• The lpha level-set does not pass through the triangle



$$\alpha_{i+1}$$
, $\alpha_{i+2} > \alpha$ and $\alpha_i < \alpha$:

• There is an lpha level-set-vertex along edge $\overline{\mathbf{v}_i\mathbf{v}_{i+1}}$



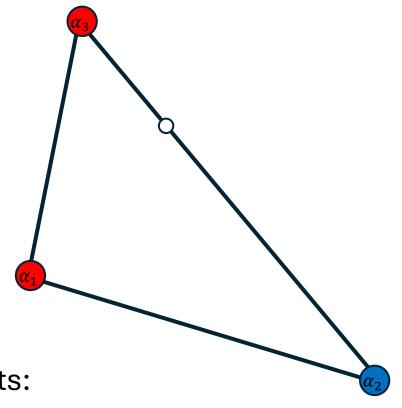
• The vertex is the weighted average of the end-points:

$$\mathbf{v} = (1 - s) \cdot \mathbf{v}_i + s \cdot \mathbf{v}_{i+1}$$

• The weights are the same that make the weighted average of end-point values equal the level-set-value:

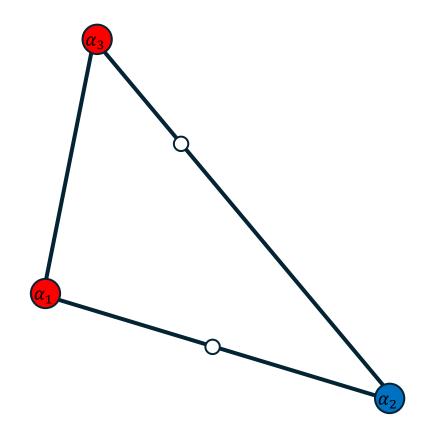
$$\alpha = (1 - s) \cdot \alpha_i + s \cdot \alpha_{i+1}$$

$$s = \frac{\alpha - \alpha_i}{\alpha_{i+1} - \alpha_i}$$



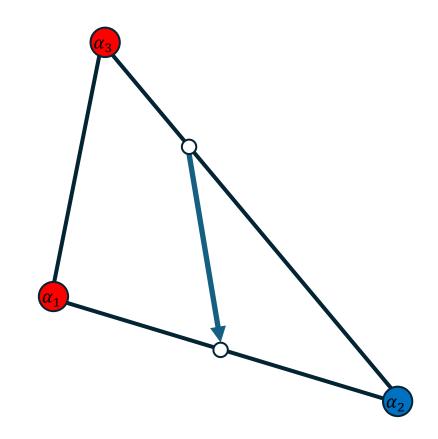
$$\alpha_{i+1}, \alpha_{i+2} > \alpha$$
 and $\alpha_i < \alpha$:

- There is an lpha level-set-vertex along edge $\overline{\mathbf{v}_i\mathbf{v}_{i+1}}$
- There is an lpha level-set-vertex along edge $\overline{\mathbf{v}_i\mathbf{v}_{i+2}}$



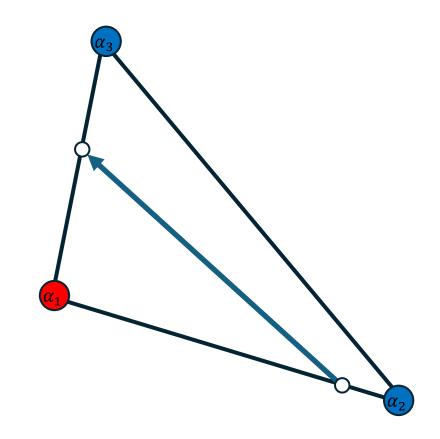
$$\alpha_{i+1}$$
, $\alpha_{i+2} > \alpha$ and $\alpha_i < \alpha$:

- There is an lpha level-set-vertex along edge $\overline{\mathbf{v}_i\mathbf{v}_{i+1}}$
- There is an lpha level-set-vertex along edge $\overline{\mathbf{v}_i\mathbf{v}_{i+2}}$
- There is an α level-set-edge connecting the level-set-vertices



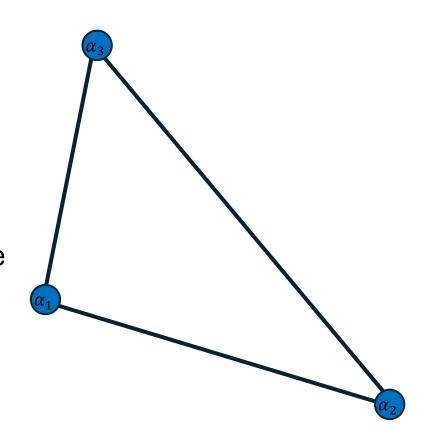
 $\alpha_i > \alpha$ and α_{i+1} , $\alpha_{i+2} < \alpha$:

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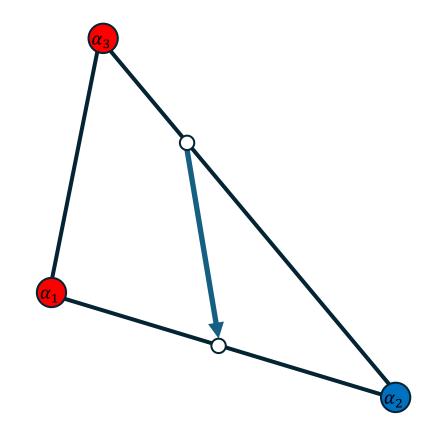
$$\alpha_1, \alpha_2, \alpha_3 < \alpha$$
:

• The α level-set does not pass through the triangle



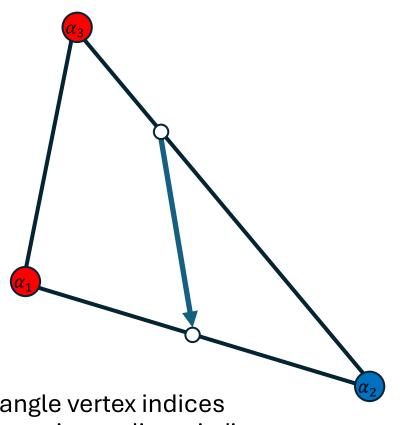
Technical details:

• Represent the geometry by having edges store vertex **indices**, not positions.



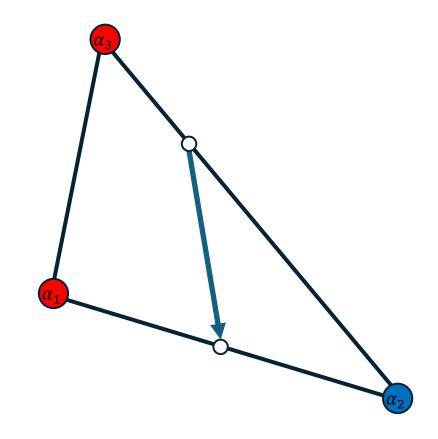
Technical details:

- Avoid generating the same level-set-vertex twice (once for each triangle adjacent to the edge)
 - Triangle vertices are at the corners of the grid
 - ⇒ Linearize the triangle vertex indices
 - A level-set-vertex is defined by a pair of triangle vertices
 - ⇒ Represent a level-set-vertex by a pair of (linearized) triangle vertex indices
 - \Rightarrow Use an associative array (e.g. std::map) to map level-set-vertices to linear indices.



Technical details:

• Orient the edges consistently (e.g. so that the corners values less than α are always on the left)

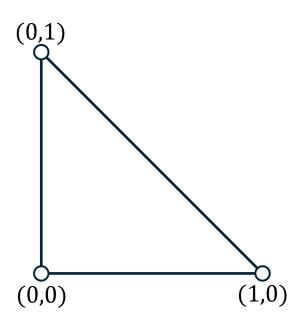


Technical details:

- Perform the calculation over the unit-right-simplices

 ⇒ Gives the position of the vertices in barycentric coordinates
- Transform barycentric coordinates to world coordinates



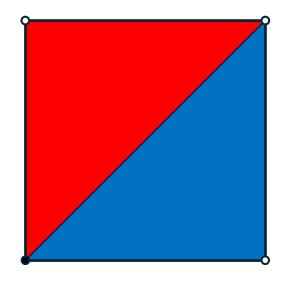


By induction:

Decompose a d-dimensional into d! d-dimensional simplices.

Base case d = 2:

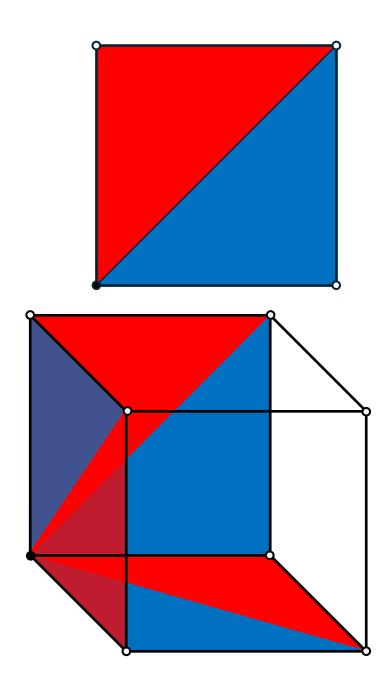
- Triangulate the square by adding the diagonal from the origin to the opposite corner
 - \Rightarrow 2-dimensional cube \rightarrow 2! simplices



Base case d=2:

- Triangulate the square by adding the diagonal from the origin to the opposite corner
 - \Rightarrow 2-dimensional cube \rightarrow 2! simplices

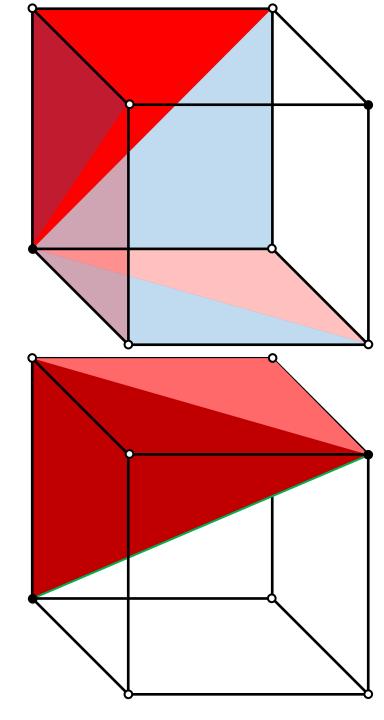
- ullet Triangulate the d faces incident on the origin
 - \Rightarrow d! (d-1)-dimensional simplices



Base case d=2:

- Triangulate the square by adding the diagonal from the origin to the opposite corner
 - \Rightarrow 2-dimensional cube \rightarrow 2! simplices

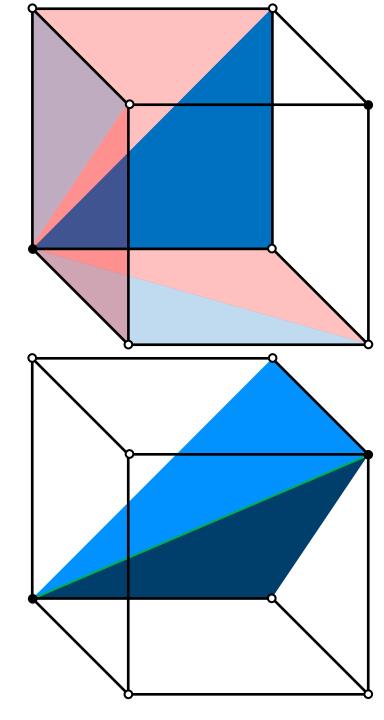
- ullet Triangulate the d faces incident on the origin
- Fuse each (d-1)-dimensional simplex with the point antipodal from the origin



Base case d=2:

- Triangulate the square by adding the diagonal from the origin to the opposite corner
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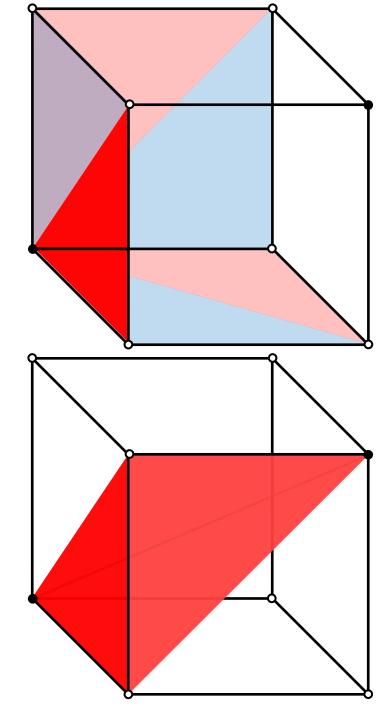
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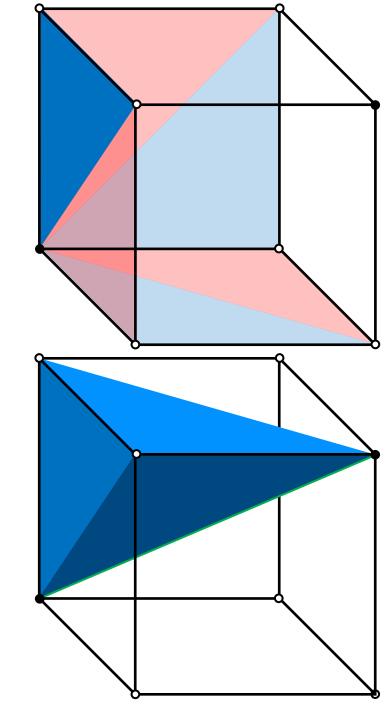
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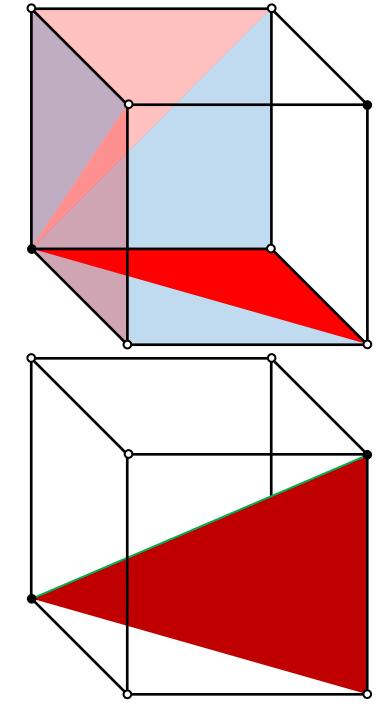
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Base case d=2:

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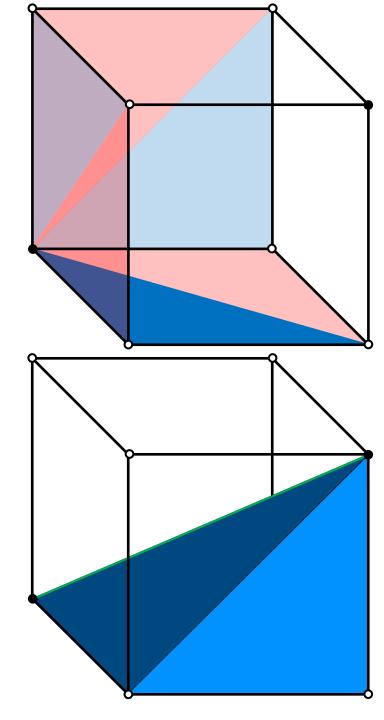
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Base case d=2:

- Triangulate the square by adding the diagonal from the origin to the opposite corner
 - \Rightarrow 2-dimensional cube \rightarrow 2! simplices

- ullet Triangulate the d faces incident on the origin
- Fuse each (d-1)-dimensional simplex with the point antipodal from the origin
 - \Rightarrow d-dimensional cell \rightarrow d! simplices

