

# 선형대수 4강 역행렬과 전치행렬

## 1.6. Inverse & Transpose

### • Inverse 역행렬

$$A_{n \times n} A^{-1} = A^{-1} A = I$$

→ Not all  $A$  has its inverse →  $\det(A) \neq 0$

1) The inverse ( $A^{-1}$ ) exists

iff Gauss elimination produces  $n$  pivots.

2) The inverse is **unique**!

3) If  $A^{-1}$  exists,  $Ax = b$ ,  $A^{-1}Ax = A^{-1}b$ .  
 $x \rightarrow$  unique!

4) Assume that there is a non-zero vector  $x$  such that

$$Ax = 0 \quad (b=0)$$

•  $x=0 \rightarrow$  trivial solution

$$A^{-1}0 = x = 0$$

→ then  $A^{-1}$  does **not** exist.

$$5) A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad A^{-1} = \frac{1}{\det A} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$\det \neq 0$

1) Diagonal Matrix

$$\begin{bmatrix} d_1 & & 0 \\ & d_2 & \\ 0 & & d_n \end{bmatrix} \quad \forall d_i \neq 0$$

( $\pi$ 는 짝수 곱)

$$\text{inverse} \rightarrow \begin{bmatrix} \frac{1}{d_1} & & 0 \\ & \frac{1}{d_2} & \\ 0 & & \frac{1}{d_n} \end{bmatrix}$$

2) The inverse comes in the reverse order.

$$(ABC)^{-1} = C^{-1}B^{-1}A^{-1}$$

•  $A^{-1}$ : Gauss-Jordan Method

$$AX = b$$

$$AB = A[b_1 \ b_2 \ \dots \ b_n] = [Ab_1 \ Ab_2 \ \dots \ Ab_n]$$

$$AA^{-1} = I, \quad A^{-1} = [x_1 \ x_2 \ \dots \ x_n]$$

$$[Ax_1 \ Ax_2 \ \dots \ Ax_n] = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix} \Rightarrow Ax_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, Ax_2 = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \dots$$

•  $A \xrightarrow{GE} U$

$$\underbrace{E_{32}E_{31}E_{21}}_{L^{-1}} A \rightarrow U \Rightarrow \cancel{U^{-1}} A^{-1} = U^{-1} L^{-1}$$

ex)  $A A^{-1} = I$

$$\left[ \begin{array}{ccc|ccc} 2 & 1 & 1 & 1 & 0 & 0 \\ 4 & -6 & 0 & 0 & 1 & 0 \\ -2 & 7 & 2 & 0 & 0 & 1 \end{array} \right]$$

↓

$$\left[ \begin{array}{ccc|ccc} 2 & 1 & 1 & 1 & 0 & 0 \\ 0 & -8 & -2 & -2 & 1 & 0 \\ 0 & 8 & 3 & 1 & 0 & 1 \end{array} \right]$$

↓

$$\left[ \begin{array}{ccc|ccc} 2 & 1 & 1 & 1 & 0 & 0 \\ 0 & -8 & -2 & -2 & 1 & 0 \\ 0 & 0 & 1 & -1 & 1 & 1 \end{array} \right]$$

$$\left[ \begin{array}{ccc|ccc} 2 & 1 & 0 & 2 & -1 & -1 \\ 0 & -8 & 0 & -4 & 3 & 2 \\ 0 & 0 & 1 & -1 & 1 & 1 \end{array} \right] \uparrow$$

↓

$$\left[ \begin{array}{ccc|ccc} 2 & 0 & 0 & \frac{3}{2} & \frac{5}{8} & \frac{3}{4} \\ 0 & -8 & 0 & -4 & 3 & 2 \\ 0 & 0 & 1 & -1 & 1 & 1 \end{array} \right]$$

↓

$$\left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & \frac{3}{4} & \frac{5}{16} & \frac{3}{8} \\ 0 & 1 & 0 & \frac{1}{2} & \frac{3}{8} & \frac{1}{4} \\ 0 & 0 & 1 & -1 & 1 & 1 \end{array} \right] \rightarrow I A^{-1}$$

## • Transpose 전치행렬

$$a_{ij} \xrightarrow{A^T} a_{ji}$$

$$\begin{cases} (A+B)^T = A^T + B^T \\ (A+B)^{-1} \neq A^{-1} + B^{-1} \end{cases}$$

$$\begin{cases} (AB)^T = B^T A^T \\ (AB)^{-1} = B^{-1} A^{-1} \end{cases}$$

$$(A^{-1})^T = (A^T)^{-1}$$

## • Symmetric Matrix 대칭행렬

$$A^T = A \quad a_{ij} = a_{ji}$$

• If  $A$  is symmetric and invertible,  
then  $A^{-1}$  is too.  $(A^{-1})^T = A^{-1}$

•  $A = LU = LDU$  ( $U$  pivot all 1)

$$A^T = A \text{ 대칭행렬}$$

$$\Rightarrow LDU = U^T D L^T$$

## • Correlation Matrix

$$R = A^T A = \begin{bmatrix} \equiv \\ \equiv \\ \equiv \end{bmatrix} \begin{bmatrix} | & | & | \end{bmatrix} = \begin{bmatrix} \cancel{x_1^T x_1} & \cancel{x_1^T x_2} & \dots & \cancel{x_1^T x_n} \\ \cancel{x_2^T x_1} & \dots & \dots & \cancel{x_2^T x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \cancel{x_n^T x_1} & \dots & \dots & \cancel{x_n^T x_n} \end{bmatrix}$$