Efficient Algorithms

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Lecture 3: Data Structures (Part I)
Stack, Queue, Heap, Priority Queue

Stack

A stack S consists of elements S[1 ... S. top]

- *S. top* points to the *most recently* inserted element
- S[1] points to the element at the bottom of the stack, i.e., the **oldest** element
- A stack exhibits LIFO behavior.
 - A new item is added to the top of the stack
 - Only the most recently item S[S, top] can be deleted or popped off the stack

Stack Operations

```
1: procedure STACKEMPTY(S)
```

- 2: if S.top == 0 then
- 3: return True
- 4: else
- 5: return False

```
1: procedure PUSH(S, x)
```

- S.top = S.top + 1
- 3: S[S.top] = x

```
1: procedure Pop(S)
```

- 2: if Stack-Empty(S) then
- 3: error "UNDERFLOW"
- 4: else
- 5: S.top = S.top 1
- 6: return S[S.top + 1]

The Time Complexity of Stack Operations

- Efficient operations in O(1) time:
 - PUSH, POP
 - TOP, EMPTY, SIZE
- Applications:
 - Tree Traversal and Backtracking
 - Evaluating arithmetic expressions
 - Parsing Grammar (CFG)
 - Implementation of Function Call Mechanism
- Implementation:
 - Array
 - Linked List

Queue

A queue *Q* exhibits *FIFO* behavior.

- Q. head points to the start of the queue
- Q. tail points to the end of the queue

You may think of a queue this way:

- The element pointed to by Q. head has the highest priority
- The element pointed to by Q. tail has the lowest priority

Initially, Q.head = Q.tail = 1, which means the queue is empty.

When Q.head = Q.tail + 1, the queue is full.

Queue Operations

```
1: procedure Enqueue(Q, x)

2: if Q.tail == Q.head then

3: error "OVERFLOW"

4: Q[Q.tail] = x

5: if Q.tail == Q.length then

6: Q.head = 1

7: else

8: Q.head = Q.head + 1
```

```
1: procedure Dequeue(Q)
     if Q.head == Q.tail then
2:
        error "UNDERFLOW"
3:
     x = Q[Q.head]
4:
     if Q.head == Q.length then
5:
        Q.head = 1
6:
     else
7:
        Q.head = Q.head + 1
8:
     return x
9:
```

The Enqueue and Dequeue operations take O(1) constant time.

Binary Heap

A binary heap (or simply heap) is an *array* which represents an *ordered* binary tree:

- all levels of a binary tree are filled except possibly for the last level, which is filled from left to right
 - This property is referred to as being a **Nearly Complete Binary Tree**.
- values stored at each node obey the MIN/MAX Heap Property, depending on which kind of heap the heap is.

Binary Heap

In a binary heap,

A[1] is the root of the binary tree

Given the index i of a node, we can compute the indices of:

- the parent
- the left child
- the right child

Parent-Child Relationship

```
1: procedure Parent(i)
```

2: return $\lfloor \frac{i}{2} \rfloor$

```
1: procedure Left(i) 1: procedure Right(i)
```

2: return 2i 2: return 2i+1

***Assume array indexing starts at 0.

The Max Heap Property

For every node *i* other than the root, the value of a node is at most the value of its parent

$$A[Parent(i)] \ge A[i]$$

Therefore, the **maximum value** is stored at the root A[1].

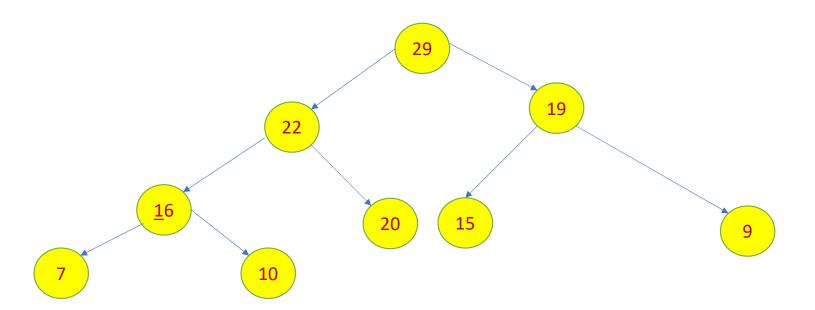
For a *min heap*, the *min heap property* is the opposite:

$$A[Parent(i)] \leq A[i]$$

***From now on, we will talk about only the max heap.

The Max Heap Property

Is this array a max heap [29,22,19,16,20,15,9,7,10]?



Definition of the Height of a Tree

Definition I:

The height of a node is the number of edges on the longest simple path from that node to a leaf.

Definition II:

The height of a tree is the height of the root.

Definition of the Height of a Tree

Since a **binary heap** can be viewed as a **nearly complete** binary tree, the **height** h of the heap is

$$h = \Theta(\log n)$$

, where n is the number of elements in the heap.

We will prove that some *basic operations* on any binary heap run in time proportional to *the height of the heap* h.

Therefore, the time complexity $T_{Op}(n)$ of these basic operations is $O(\log n)$.

How to prove $h = \Theta(\log n)$

First, we must show that the minimum and the maximum number of elements n in a heap of height h are

$$2^h$$
 and $2^{h+1} - 1$, respectively.

In other words,

$$2^h \le n \le 2^{h+1} - 1$$

Then, we must show that an n-element heap has height $\lfloor \log_2 n \rfloor$, which means $h = \Theta(\log n)$.

Max-Heapify

Suppose there is a binary heap rooted at node i.

Assumption: If there will be a violation of the max heap property within this tree, it can only happen at node i. In other words, both trees rooted at Left(i) and Right(i) obey the max heap property.

We can fix this violation using *Max-Heapify* shown on the right.

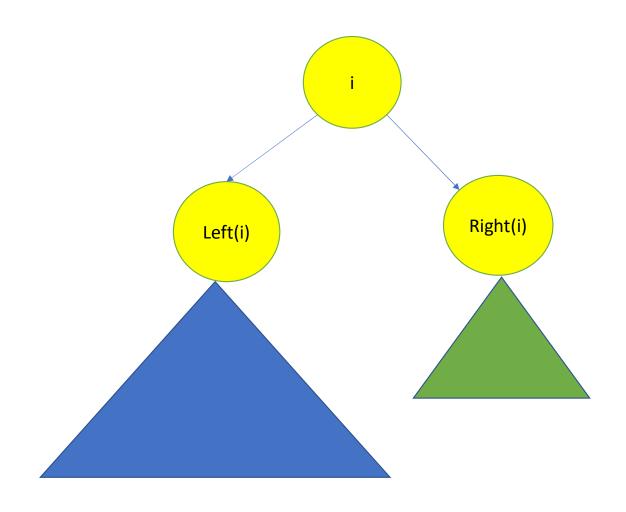
```
1: procedure Max-Heapify(A, i)
 2:
       l = Left(i)
       r = Right(i)
 3:
       if l \leq A.HeapSize \wedge A[l] > A[i] then
           largest = l
 5:
       else
 6:
          largest = i
 7:
       if r \leq A.HeapSize \wedge A[r] > A[i] then
 8:
           largest = r
9:
       if largest \neq i then
10:
           A[i] \iff A[largest]
11:
           Max-Heapify(A, largest)
12:
```

Max-Heapify

Suppose there is a binary heap rooted at node i.

Assumption: If there will be a violation of the max heap property within this tree, it can only happen at node i. In other words, both trees rooted at Left(i) and Right(i) obey the max heap property.

We can fix this violation using *Max-Heapify* shown on the right.



Time Complexity of Max-Heapify

The **time complexity** T(n) of Max-Heapify on a tree of n elements rooted at a given node i is the height of the tree in **the worst case**.

$$T(n) = O(\log n)$$

Another way to prove this is to derive the running time T(n) as a recurrence relation in terms of the running time of the recursive call on a subtree rooted at one of the children of node i plus the work done at each level of a recursive call.

We can use Max-Heapify in a **bottom-up manner** to convert an array A[1...n] into a max heap as follows.

```
1: procedure Build-Max-Heapify(A)
```

- 2: A.HeapSize = A.Length
- 3: for $i = A.Length \rightarrow 1$ do
- 4: Max-Heapify(A, i)

But, can we do better?

We can use Max-Heapify in a **bottom-up manner** to convert an array A[1...n] into a max heap as follows.

```
1: procedure Build-Max-Heapify(A)
2: A.HeapSize = A.Length
3: for i = \left\lfloor \frac{A.Length}{2} \right\rfloor \rightarrow 1 do
4: Max-Heapify(A, i)
```

<u>Key Observation</u>: the elements in the subarray $A[[^n/_2] + 1, [^n/_2] + 2, ..., n]$ are all leaves of the tree.

<u>Claim</u>: The elements in the subarray $A[[^n/_2] + 1, [^n/_2] + 2, ..., n]$ are all leaves of the tree.

Proof: We will prove by contradiction.

Assume the node with index $\lfloor n/2 \rfloor + 1$ is not a leaf.

Therefore, it must have a left child whose index is

$$2(\lfloor n/2 \rfloor + 1) = 2\lfloor n/2 \rfloor + 2.$$

Proof: We know that

$$\lfloor n/2 \rfloor > n/2 - 1$$

 $2\lfloor n/2 \rfloor > n - 2$
 $2\lfloor n/2 \rfloor + 2 > n$

We have just found that the index of the left child is bigger than n, which is a contradiction to the fact that there are only n elements in the heap.

Therefore, the node with index $\lfloor n/2 \rfloor + 1$ is a leaf.

Therefore, the nodes with larger indices must also be leaves. ■

Although we have shown that A[[n/2] + 1, [n/2] + 2, ..., n] are **all leaves**,

how do we confirm that the node with index $\lfloor n/2 \rfloor$ is **not a leaf**?

***Left as homework (PS 3.2.3)

- Each call to Max-Heapify costs $O(\log n)$.
- Buld-Max-Heap makes $\lfloor n/2 \rfloor = O(\log n)$ such calls.
- The time complexity is $O(n \log n)$.
- This upper bound is correct, but it is not the tightest asymptotic claim we can make.
- We can make a tighter claim based on the following claim:

Claim:

A binary heap with n elements can have at most $\left\lceil \frac{n}{2^{h+1}} \right\rceil$ nodes of any height h.

Structural Induction on the Binary Heap

Claim:

A binary heap with n elements can have at most $\left|\frac{n}{2^{h+1}}\right|$ nodes of any height h.

Proof: We will prove by induction on the height h.

Base Case: h = 0

All the nodes at height h = 0 are the leaf nodes.

There are leaves $\left\lceil \frac{n}{2} \right\rceil$ (You will prove this in PS 3.2.4), which is $\leq \left\lceil \frac{n}{2^{0+1}} \right\rceil = \left\lceil \frac{n}{2} \right\rceil$.

We are done with the base case.

Induction Hypothesis: Assume true for any $0 \le h \le k-1$.

Inductive Step: Show true for h = k.

Let n_k be the number of nodes at height k in a tree T with n nodes.

Construct another tree T' by removing the leaves of T.

Therefore, T' has $n' = n - \left\lceil \frac{n}{2} \right\rceil = \left\lfloor \frac{n}{2} \right\rfloor$ nodes.

The nodes at height k in T will become the nodes at height k-1 in T'.

Let n'_{k-1} be the number of nodes at height k-1 in T'.

Therefore,
$$n_k = n'_{k-1} \le \left[\frac{n'}{2^{(k-1)+1}} \right]$$
 (I.H. at $k-1$ for n')

Inductive Step:

$$n_{k} = n'_{k-1} \leq \left\lceil \frac{n'}{2^{(k-1)+1}} \right\rceil$$

$$= \left\lceil \frac{n'}{2^{k}} \right\rceil$$

$$= \left\lceil \frac{n}{2} \right\rceil_{2^{k}}$$

$$\leq \left\lceil \frac{n}{2^{k}} \right\rceil \qquad (\left\lfloor \frac{n}{2} \right\rfloor \leq \frac{n}{2} \, \forall n \in \mathbb{R})$$

$$= \left\lceil \frac{n}{2^{k+1}} \right\rceil$$

We have just shown true for h = k that $n^k \leq \left\lceil \frac{n}{2^{k+1}} \right\rceil$.

- A binary heap with n elements can have at most $\left|\frac{n}{2^{h+1}}\right|$ nodes of any height h.
- Each Max-Heapify costs O(h) for a node of height h.
- We know that $0 \le h \le \lfloor \log_2 n \rfloor$.

The time complexity of Max-Build-Heap is bound from above by

$$\sum_{i=0}^{\lfloor \log_2 n \rfloor} \left[\frac{n}{2^{h+1}} \right] O(h) = O\left(\frac{n}{2} \sum_{i=0}^{\lfloor \log_2 n \rfloor} \frac{n}{2^h} \right) = O(n \sum_{i=0}^{\lfloor \log_2 n \rfloor} \frac{n}{2^h})$$

Observation:

$$\sum_{h=0}^{\infty} \frac{h}{2^h} = 2.$$

Therefore,
$$\sum_{i=0}^{\lfloor \log_2 n \rfloor} \left[\frac{n}{2^{h+1}} \right] O(h) = O(2n) = O(n)$$

Thus, we can build a max heap from an unordered array in *linear time* O(n).

Heap Sort

- First, we build a max heap from an unordered array A (Line 2).
- The maximum element is initially stored at the root A[1].
- We put the maximum into the correct position by swapping A[1] with A[n] (Line 4).
- We can now reduce the size of our max heap by decrementing the heap size by one (Line 5).
- We fix up the potentially violation at the root A[1] with Max-Heapify (Line 6).
- If we perform such a swap n-1 times, the array A will be sorted in increasing order.

```
1: procedure Heap-Sort(A)
2: Build-Max-Heap(A)
3: for i = A.Length \rightarrow 2 do
4: A[1] \iff A[i]
5: A.HeapSize = A.HeapSize - 1
6: Max-Heapify(A, 1)
```

The time complexity of Heap Sort

Analysis:

Build-Max-Heap costs $T_1(n) = O(n)$ time.

Each call to Max-Heapify costs $O(\log k)$ time for k = n, n - 1, ..., 2.

• The total cost of Max-Heapify
$$T_2(n)$$
 is
$$T_2(n) = \sum_{k=n}^2 O(\log k) = O\left(\sum_{k=1}^n \log k\right) = O(\log n!)$$

<u>Key Observation</u>: $\log n! \le \log n^n = n \log n \ \forall n \ge 1$

$$T_2(n) = O(\log n^n) = O(n\log n)$$

$$T(n) = T_1(n) + T_2(n) = O(n) + O(n\log n) = O(n\log n)$$

Priority Queue

One popular use of binary heaps is to implement a *priority queue*.

A *priority queue* is a data structure for maintaining a set S of elements, each of which is assigned a value called *key*.

A priority queues comes into **two variants**: **max** and **min** priority queue, depending on the type of the underlying binary heap.

***In this lecture, we will talk about the max priority queue.

Basic Operations

- *Maximum*(*S*) returns the element of *S* with the largest key.
- ExtractMax(S) removes and returns the element of S with the largest key.
- IncreaseKey(S, x, k) increases the value of element x's key to the new value k, which is assumed to be at least as large as x's current key value.
- Insert(S, x) inserts the element x into the set S.

Maximum

An element with the *largest key value* is stored at the *root* A[1]. The operation has a constant time complexity O(1).

1: **procedure** MAXIMUM(A)

2: return A[1]

Extract-Max

The time complexity of ExtractMax is $O(\log n)$ since it performs only constant time operations before it performs MaxHeapify on the root A[1], which costs $O(\log n)$.

- 1) Save the value of the root element (Line 4)
- 2) Swap the element at the root with the last leaf element. *(Line 5)*
- ***At this point, the max heap property might have been violated.
- 3) Decrease the size of the heap by one, which effectively discards the extracted max element *(Line 6)*
- 4) Fix up the heap by calling Max-Heapify on the root (Line 7)
- 5) Return the extracted element with the largest value (Line 8)

```
1: procedure EXTRACT-MAX(A)
2: if A.heapSize < 1 then
3: error "UNDERFLOW"
4: max = A[1]
5: A[1] = A[A.heapSize]
6: A.heapSize = A.heapSiz - 1
7: MAX-HEAPIFY(A, 1)
8: return max
```

Increase-Key

An index i is to point to the element A[i] whose key value we want to increase.

Key Assumption: The new key key value must be at least as large as the current key value of A[i]. Otherwise, it is an error. **(Lines 2 & 3)**

If the new key value is ok,

1) Assign A[i] the new key value key (Line 4)

***At this point the max heap property might have been violated.

2) Traverse a simple path from A[i] towards the root to find a proper place for the new key value (Lines 5&6&7)

```
1: procedure Increase-Key(A, i, key)

2: if A[i] > key then

3: error "INVALID - KEY_VALUE"

4: A[i] = key

5: while i > 1 \land A[Parent(i)] < A[i] do

6: A[i] \iff A[Parent(i)]

7: i = Parent(i)
```

The time complexity is determined by the length of the path traversed up the tree, which is $O(\log n)$.

Max-Heap-Insert

MaxHeapInsert takes as input the key of a new element key to be inserted into the max heap A.

- 1. Expand the max heap by incrementing the size by one (Line 1)
- 2. Add a new element with key value $-\infty$ (Line 2)
- 3. Call *IncreaseKey* to set the key value of the newly inserted element to *key* and make sure the max heap property is maintained (*Line 3*)
- 1: procedure Max-Heap-Insert(A, key)
- 2: A.heapSize = A.heapSize + 1
- 3: $A.heapSize = -\infty$
- 4: Increase-Key(A, A.heapSize, key)

The time complexity of MaxHeapInsert is $O(\log n)$ since it performs constant time work before it calls Increasekey, which runs in is $O(\log n)$ time.

Summary

We have covered the following data structures today:

- Stack
- Queue
- Heap
- Priority Queue

We have also illustrated a new variant of mathematical induction known as **structural induction**.

We will cover Part II of Data Structures in the next lecture.