

# Efficient Algorithms

Ekkapot Charoenwanit

Electrical and Computer Engineering (ECE)

TGGS

KMUTNB

## Lecture 9: Graph Algorithms (Part I)

# Breadth-First Search (BFS)

## Problem Definition:

Given an *unweighted* graph  $G = (V, E)$ , find *a shortest path* from a given vertex  $s$  to every other vertex *reachable* from  $s$ .

## Key Idea:

BFS is a graph traversal algorithm that explores each vertex  $v \in V$  in the order of their distance from  $s$  (referred to as the *root*), where distance  $\delta(s, v)$  is defined as the *\*\*\* length \*\*\** of a shortest path from  $s$  to  $v$ .

*\*\*\*length = the number of edges*

# Breadth-First Search (BFS)

BFS is named so because it expands the *frontier* between *discovered* and *undiscovered* vertices *uniformly across the breadth* of the frontier.

In other words, the algorithm of BFS discovers all vertices at distance  $k$  before they discover any at distance  $k + 1$ .

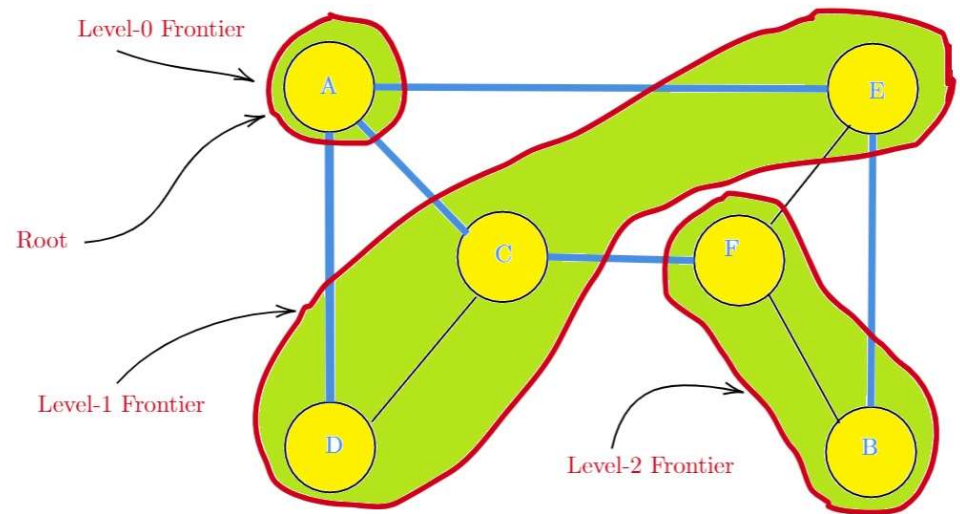
# Breadth-First Search (BFS): Example

BFS traverses the graph, starting from *A*.

*A* itself forms the level-0 frontier.

*C*, *D* and *E* form the level-1 frontier.

*B* and *F* form the level-2 frontier.

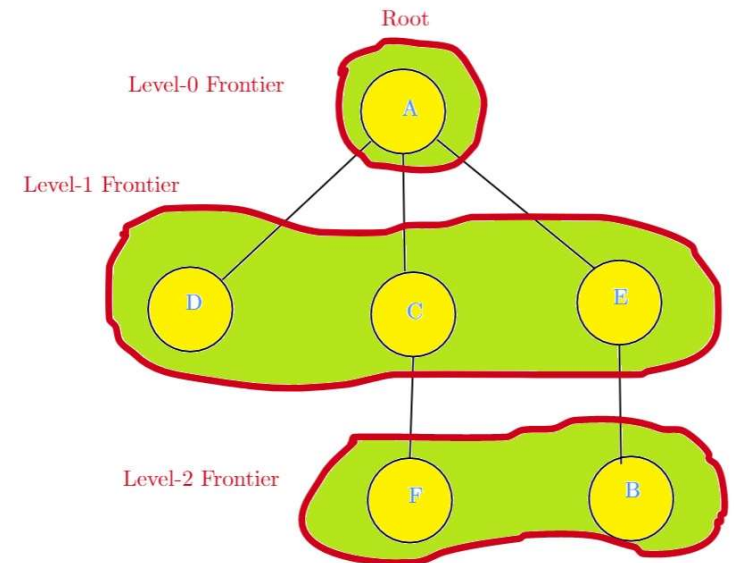


# Breadth-First Search (BFS): Example

Not only does BFS find a shortest path from  $A$  to every other vertex, but it also produces a **BFS tree**.

**Note:** BFS trees are not necessarily unique for all problem instances.

For this particular example, a different BFS tree would have been produced if  $E$  had been explored before  $C$ .



# Breadth-First Search (BFS): Color

BFS **colors** each vertex to keep track of its progress.

- **White** = undiscovered
- **Gray** = discovered and still in the frontier
- **Black** = discovered but not in the frontier any more

All vertices start out white (**Line 2**), except for the root, which starts out gray (**Line 5**).

BFS( $G, s$ )

```
1  for each vertex  $u \in G.V - \{s\}$ 
2       $u.color = \text{WHITE}$ 
3       $u.d = \infty$ 
4       $u.\pi = \text{NIL}$ 
5   $s.color = \text{GRAY}$ 
6   $s.d = 0$ 
7   $s.\pi = \text{NIL}$ 
8   $Q = \emptyset$ 
9  ENQUEUE( $Q, s$ )
10 while  $Q \neq \emptyset$ 
11      $u = \text{DEQUEUE}(Q)$ 
12     for each  $v \in G.Adj[u]$ 
13         if  $v.color == \text{WHITE}$ 
14              $v.color = \text{GRAY}$ 
15              $v.d = u.d + 1$ 
16              $v.\pi = u$ 
17             ENQUEUE( $Q, v$ )
18      $u.color = \text{BLACK}$ 
```

# Breadth-First Search (BFS): Distance

We initialize the **d-value** to  $\infty$  (**Line 3**), except for the **d-value** of the root  $s$ , which is set to 0 (**Line 6**).

## Note:

- For any vertex  $v$  reachable from  $s$ , its d-value will **converge** to  $\delta(s, v)$ .
- For any vertex  $v$  not reachable, its d-value will stay  $\infty$ .

BFS( $G, s$ )

```
1  for each vertex  $u \in G.V - \{s\}$ 
2       $u.color = \text{WHITE}$ 
3       $u.d = \infty$ 
4       $u.\pi = \text{NIL}$ 
5   $s.color = \text{GRAY}$ 
6   $s.d = 0$ 
7   $s.\pi = \text{NIL}$ 
8   $Q = \emptyset$ 
9  ENQUEUE( $Q, s$ )
10 while  $Q \neq \emptyset$ 
11      $u = \text{DEQUEUE}(Q)$ 
12     for each  $v \in G.Adj[u]$ 
13         if  $v.color == \text{WHITE}$ 
14              $v.color = \text{GRAY}$ 
15              $v.d = u.d + 1$ 
16              $v.\pi = u$ 
17             ENQUEUE( $Q, v$ )
18      $u.color = \text{BLACK}$ 
```



# Breadth-First Search (BFS): Parent

We initialize the *parent-value* of all vertices to *NIL* (*Line 4*).

**Note:**

- For any vertex  $v$  reachable from  $s$ , its parent-value will be set to some predecessor vertex  $u$ . (*Line 16*)
- For any vertex  $v$  not reachable, its parent-value will stay *NIL*.
- For the root  $s$ , its parent-value will stay *NIL*.

The resulting BFS tree can be constructed based on these parent values found.

BFS( $G, s$ )

```
1  for each vertex  $u \in G.V - \{s\}$ 
2       $u.color = \text{WHITE}$ 
3       $u.d = \infty$ 
4       $u.\pi = \text{NIL}$ 
5   $s.color = \text{GRAY}$ 
6   $s.d = 0$ 
7   $s.\pi = \text{NIL}$ 
8   $Q = \emptyset$ 
9  ENQUEUE( $Q, s$ )
10 while  $Q \neq \emptyset$ 
11      $u = \text{DEQUEUE}(Q)$ 
12     for each  $v \in G.Adj[u]$ 
13         if  $v.color == \text{WHITE}$ 
14              $v.color = \text{GRAY}$ 
15              $v.d = u.d + 1$ 
16              $v.\pi = u$ 
17             ENQUEUE( $Q, v$ )
18      $u.color = \text{BLACK}$ 
```

# Breadth-First Search (BFS)

BFS relies on a **FIFO queue**  $Q$  to generate frontiers in a **level-by-level** manner.

BFS operates as follows:

- it adds the root  $s$  to  $Q$ , which is initially empty
- It removes vertex  $u$  from the head of  $Q$  and scans its adjacency list  $Adj[u]$
- whenever the search discovers a white vertex  $v$  during the scanning of the adjacency list  $Adj[u]$ ,
  - it colors  $v$  gray and updates its distance
  - it also adds the edge  $(u, v)$  to the BFS tree by setting  $v.\pi$  to  $u$
  - it then adds  $v$  to  $Q$
- after  $Adj[u]$  is completely scanned, it colors  $u$  black
- the search continues as long as  $Q$  is not empty

BFS( $G, s$ )

```
1  for each vertex  $u \in G.V - \{s\}$ 
2       $u.color = \text{WHITE}$ 
3       $u.d = \infty$ 
4       $u.\pi = \text{NIL}$ 
5   $s.color = \text{GRAY}$ 
6   $s.d = 0$ 
7   $s.\pi = \text{NIL}$ 
8   $Q = \emptyset$ 
9  ENQUEUE( $Q, s$ )
10 while  $Q \neq \emptyset$ 
11      $u = \text{DEQUEUE}(Q)$ 
12     for each  $v \in G.Adj[u]$ 
13         if  $v.color == \text{WHITE}$ 
14              $v.color = \text{GRAY}$ 
15              $v.d = u.d + 1$ 
16              $v.\pi = u$ 
17             ENQUEUE( $Q, v$ )
18      $u.color = \text{BLACK}$ 
```

# Breadth-First Search (BFS): Analysis

We use *aggregate analysis* as follows.

After initialization, no vertices are colored white a second time.

This ensures that each vertex is enqueued at most once (*Line 17*), and hence dequeued at most once as a consequence.

∴ The while loop executes at most  $|V|$  iterations.

The operations of enqueueing and dequeuing cost  $O(1)$  time.

The total time devoted to queue operations is  $O(V)$ .

BFS( $G, s$ )

```
1  for each vertex  $u \in G.V - \{s\}$ 
2       $u.color = \text{WHITE}$ 
3       $u.d = \infty$ 
4       $u.\pi = \text{NIL}$ 
5   $s.color = \text{GRAY}$ 
6   $s.d = 0$ 
7   $s.\pi = \text{NIL}$ 
8   $Q = \emptyset$ 
9  ENQUEUE( $Q, s$ )
10 while  $Q \neq \emptyset$ 
11      $u = \text{DEQUEUE}(Q)$ 
12     for each  $v \in G.Adj[u]$ 
13         if  $v.color == \text{WHITE}$ 
14              $v.color = \text{GRAY}$ 
15              $v.d = u.d + 1$ 
16              $v.\pi = u$ 
17             ENQUEUE( $Q, v$ )
18      $u.color = \text{BLACK}$ 
```

# Breadth-First Search (BFS): Analysis

BFS scans the adjacency list of each dequeued vertex at most once

Therefore, the total time spent on examining adjacent vertices is  $O(E)$ .

The total running time is  $O(V + E)$ .

**Note:** For undirected graphs, the number of inspections is  $2E$ .

For directed graphs, the number of inspections is  $E$ .

BFS( $G, s$ )

```
1  for each vertex  $u \in G.V - \{s\}$ 
2       $u.color = \text{WHITE}$ 
3       $u.d = \infty$ 
4       $u.\pi = \text{NIL}$ 
5   $s.color = \text{GRAY}$ 
6   $s.d = 0$ 
7   $s.\pi = \text{NIL}$ 
8   $Q = \emptyset$ 
9  ENQUEUE( $Q, s$ )
10 while  $Q \neq \emptyset$ 
11      $u = \text{DEQUEUE}(Q)$ 
12     for each  $v \in G.Adj[u]$ 
13         if  $v.color == \text{WHITE}$ 
14              $v.color = \text{GRAY}$ 
15              $v.d = u.d + 1$ 
16              $v.\pi = u$ 
17             ENQUEUE( $Q, v$ )
18      $u.color = \text{BLACK}$ 
```

# Breadth-First Search (BFS): Correctness

**Lemma 1:** Let  $G = (V, E)$  be a directed or undirected graph, and let  $s$  be an arbitrary vertex. Then, for any edge  $(u, v) \in E$ ,

$$\delta(s, v) \leq \delta(s, u) + 1$$

**Proof:**

**Case 1:** If  $u$  is reachable from  $s$ , so is  $v$  since there is at least the path from  $s$  to  $u$  followed by the edge  $(u, v)$ .

In this case, a shortest from  $s$  to  $v$  cannot be longer than a shortest path from  $s$  to  $u$  followed by the edge  $(u, v)$ .

Then,  $\delta(s, v) \leq \delta(s, u) + 1$  holds.

# Breadth-First Search (BFS): Correctness

**Case II:** If  $u$  is not reachable from  $s$ , then  $\delta(s, u) = \infty$ .

If  $v$  is reachable from  $s$ ,  $\delta(s, v)$  is a finite number.

Then,  $\delta(s, v) \leq \delta(s, u) + 1$  holds.

If  $v$  is not reachable from  $s$ ,  $\delta(s, v) = \infty$ .

Then,  $\delta(s, v) \leq \delta(s, u) + 1$  still holds. ■

**Note:**  $\delta(s, v) \leq \delta(s, u) + 1$  is a special case of the **triangle inequality**  $\delta(s, v) \leq \delta(s, u) + w(u, v)$  used in the process of **edge relaxation** in shortest-path algorithms for **weighted** graphs we will be studying.

# Breadth-First Search (BFS): Correctness

**Lemma II:** Let  $G = (V, E)$  be a directed or undirected graph, and suppose that BFS is run on  $G$  with a given source vertex  $s$ . Then, upon termination, for all  $v \in V$ ,  $v.d \geq \delta(s, v)$ .

**Proof:** We will prove by induction that this property holds prior to the start of each iteration.

**Base Case:** Prior to the  $1^{th}$  iteration,

$$v.d = \infty \text{ for all } v \neq s \rightarrow v.d \geq \delta(s, v)$$

$$s.d = 0 \text{ and } \delta(s, s) = 0 \rightarrow s.d \geq \delta(s, s)$$

**Induction Hypothesis:** Assume true for any  $k^{th}$  iteration.

# Breadth-First Search (BFS): Correctness

**Inductive Step:** We will show true for the  $k + 1^{th}$  iteration.

Suppose a vertex  $u \in V$  is dequeued at  $k + 1^{th}$  iteration.

For all  $v \in Adj[u]$  that are white,

$$\delta(s, v) \leq \delta(s, u) + 1 \quad \text{[Lemma 1]} \quad \text{-----(1)}$$

$$u.d \geq \delta(s, u) \quad \text{[I.H.]} \quad \text{-----(2)}$$

$$u.d + 1 \geq \delta(s, u) + 1 \quad \text{[Adding 1 on both sides of (2)]} \quad \text{-----(3)}$$

$$\delta(s, v) \leq u.d + 1 \quad \text{[Transitivity of (1) and (3)]} \quad \text{-----(4)}$$

$$v.d = u.d + 1 \quad \text{[Line 15]} \quad \text{-----(5)}$$

$$\delta(s, v) \leq v.d \quad \text{[Substituting (5) into (4)]}$$

For all the other  $v$  (including  $u$ ),

$$\delta(s, v) \leq v.d \quad \text{[I.H.]}$$





# Breadth-First Search (BFS): Correctness

## Lemma III:

Suppose during the execution of BFS, the queue  $Q$  contains the vertices  $\langle v_1, v_2, \dots, v_r \rangle$ , where  $v_1$  is the head of  $Q$  and  $v_r$  is the tail.

Then, the following loop invariant properties hold prior to the start of each queue operation:

(P1)  $v_r.d \leq v_1.d + 1$

(P2)  $v_i.d \leq v_{i+1}.d$  for all  $i = 1, 2, \dots, r - 1$ .

Proof: We will prove by induction on **the number of queue operations**.

Base Case: Initially,  $Q$  contains only the root  $s$ .

In other words,  $v_1 = v_r = s$ .

**P1** holds since  $s.d \leq s.d + 1$ .

**P2** vacuously holds.

# Breadth-First Search (BFS): Correctness

**Induction Hypothesis:** Assume true for prior to any queue operation.

**Inductive Step:** We will show that the invariant still holds prior to the next queue operation.

Since there are two kinds of queue operations, namely, **enqueue** and **dequeue**, we shall consider the following **two cases** separately:

**Case I:** Suppose  $Q = \langle v_1, v_2, \dots, v_r \rangle$  and  $v_1$  is the head. Hence,  $v_1$  is dequeued and  $v_2$  becomes the head and  $Q = \langle v_2, \dots, v_r \rangle$ .

We will have to show **IH** is reestablished at the start of the next operation:

**P1**  $v_r.d \leq v_2.d + 1$

**P2**  $v_2.d \leq v_3.d \leq \dots \leq v_r.d$

# Breadth-First Search (BFS): Correctness

If  $Q$  becomes empty, **P1** and **P2** vacuously hold.

Otherwise,

$$v_1.d \leq v_2.d \quad \text{[I.H.(P2)]} \quad \text{-----(1)}$$

$$v_1.d + 1 \leq v_2.d + 1 \quad \text{[Adding 1 on both sides of (1)]} \quad \text{-----(2)}$$

$$v_r.d \leq v_1.d + 1 \quad \text{[I.H.(P1)]} \quad \text{-----(3)}$$

$$v_r.d \leq v_2.d + 1 \quad \text{[Transitivity of (2) and (3)]}$$

**P1** still holds right after a **dequeue** operation.

**P2** still holds since the values of  $v_2.d, v_3.d, \dots, v_r.d$  are not affected.

Then, **P1 & P2** hold after a dequeue operation.

# Breadth-First Search (BFS): Correctness

**Case II:** Suppose  $Q = \langle v_1, v_2, \dots, v_r \rangle$ , and  $v = v_{r+1}$  is added and becomes the tail.

Then,  $Q = \langle v_1, \dots, v_r, v_{r+1} \rangle$ . We will have to show

**P1**  $v_{r+1}.d \leq v_1.d + 1$

**P2**  $v_1.d \leq v_2.d \leq \dots \leq v_{r+1}.d$

Let's consider what happens in the code.

$v$  is enqueued (**Line 17**) as part of the scanning of the adjacency list of some vertex  $u = v_0$  that has just been dequeued by **Line 11**. ( $v_0$  is not in  $Q$  anymore.)

$$v_0.d \leq v_1.d \quad [\text{I.H. (P2)}] \quad \text{-----(1)}$$

$$v_0.d + 1 \leq v_1.d + 1 \quad [\text{Adding 1 on both sides of (1)}] \quad \text{-----(2)}$$

$$v_0.d + 1 = v_{r+1}.d \quad [\text{Line 15}] \quad \text{-----(3)}$$

$$v_{r+1}.d \leq v_1.d + 1$$

Thus, **P1** holds.

# Breadth-First Search (BFS): Correctness

## Case II:

$$v_r.d \leq v_0.d + 1 \quad [\text{I.H.}(P1)] \quad \text{-----}(1)$$

$$v_r.d \leq v_{r+1}.d \quad [\text{Line 15: } v_{r+1}.d = v_0.d + 1] \quad \text{-----}(2)$$

**P2** holds since the values of  $v_1.d, v_2.d, \dots, v_r.d$  are not affected so the inequalities  $v_1.d \leq v_2.d \leq \dots \leq v_r.d$  still hold, and  $v_r.d \leq v_{r+1}.d$  additionally holds.

Then, **P1 & P2** hold after an enqueue operation.

This proves the lemma. ■

**Immediate Implication:** The lemma immediately implies that the **d-values** at the time that vertices are **enqueued** are **monotonically increasing over time**.

# Breadth-First Search (BFS): Correctness

**Theorem:** Let  $G = (V, E)$  be a directed or undirected graph, and suppose that BFS is run on  $G$  with a given source vertex  $s$ .

(**Claim I**) Then, during its execution, BFS discovers every vertex  $v \in V$  that is reachable from  $s$ , and, upon termination,  $v.d = \delta(s, v)$  for all  $v \in V$ .

(**Claim II**) Moreover, for any vertex  $v \neq s$  that is reachable from  $s$ , one of the shortest paths from  $s$  to  $v$  is a shortest path from  $s$  to  $v.\pi$  followed by the edge  $(v.\pi, v)$ .

**Proof:**

**Claim I:** We will first show that  $v.d = \delta(s, v)$  for all  $v \in V$ .

Assume for the purpose of contradiction some vertex  $v$  receives a value not equal to its shortest-path distance.

Let  $v$  be the vertex with the minimum  $\delta(s, v)$  that receives such an incorrect value of  $v.d$ ; clearly,  $v \neq s$  since  $s.d$  is correctly initialized to zero (**Line 6**).

That is,

$$v.d \neq \delta(s, v).$$

# Breadth-First Search (BFS): Correctness

$$v.d \geq \delta(s, v) \quad [\text{Lemma II}] \quad \text{-----}(1)$$

$$v.d > \delta(s, v) \quad [ (1) \ \& \ \text{Assumption } v.d \neq \delta(s, v)] \quad \text{-----}(2)$$

Let  $u$  be the vertex immediately preceding  $v$  on a shortest path from  $s$  to  $v$ .

$$\delta(s, v) = \delta(s, u) + 1$$

$$\delta(s, u) < \delta(s, v)$$

We chose  $v$  such that  $v$  is the vertex with the minimum distance that received an incorrect value of  $v.d$ ; any vertex  $u$  preceding  $v$  on the corresponding shortest path must have received the correct value.

$$u.d = \delta(s, u)$$

Putting these properties together,

$$v.d > \delta(s, v)$$

$$= \delta(s, u) + 1$$

$$= u.d + 1$$

$$v.d > u.d + 1$$

-----(\*)

# Breadth-First Search (BFS): Correctness

Consider the time when BFS chooses to dequeue  $u$  from  $Q$  in **Line 11**.

At this time,  $v$  is either white, gray or black. We will show that, in all the three cases, we will arrive at a contradiction to **(\*)**.

**Case I:**  $v$  is white.

$$v.d = u.d + 1 \quad [\text{Line 15}]$$

Hence, we arrive at a contradiction to **(\*)**.

**Case II:**  $v$  is black;  $v$  has been dequeued.

Then, 
$$v.d \leq u.d \quad [\text{Lemma III}]$$

Hence, we arrive at a contradiction to **(\*)**.



# Breadth-First Search (BFS): Correctness

**Case III:**  $v$  is gray;

$v$  was gray upon dequeuing some vertex  $w$ , which was removed from  $Q$  earlier than  $u$ .

Then  $v$  was marked  $v.d = w.d + 1$  [Line 15] -----(1)

$w.d \leq u.d$  [Lemma III] -----(2)

$w.d + 1 \leq u.d + 1$  [Adding 1 on both sides of (2)] -----(3)

$v.d \leq u.d + 1$  [Transitivity of (1) and (3)]

Hence, we arrive at a contradiction to (\*).

Therefore, such a vertex with  $v.d \neq \delta(s, v)$  does not exist.

**Claim I**  $v.d = \delta(s, v)$  for all  $v \in V$  holds. ■

# Breadth-First Search (BFS): Correctness

**Claim II:** we will show, for any vertex  $v \neq s$  that is reachable from  $s$ , one of the shortest paths from  $s$  to  $v$  is a shortest path from  $s$  to  $v.\pi$  followed by the edge  $(v.\pi, v)$ .

Observe that If  $v.\pi = u$ ,

$$v.d = u.d + 1 \quad \text{[Lines 15 \& 16]}$$

This means if there is a path from  $s$  to  $v$ , we can obtain a shortest path from  $s$  to  $v$  by taking a shortest path from  $s$  to  $v.\pi$  followed by the edge  $(v.\pi, v)$ . ■

# Depth-First Search (DFS)

## Problem Definition:

Given an **unweighted** graph  $G = (V, E)$ , find **a path** from a given vertex  $s$  to every other vertex **reachable** from  $s$ .

## Key Idea:

DFS is a graph traversal algorithm that explores all outgoing edges of the most recently visited vertex  $v$ . Once all of  $v$ 's outgoing edges have been explored, the algorithm **backtracks** to explore edges leaving the vertex from which  $v$  was discovered.

# Depth-First Search (DFS) : Parent

As in BFS, whenever DFS discovers a vertex  $v$  during a scan of its adjacency list of the most recently discovered vertex  $u$ , it records this event by setting  $v.\pi = u$ .

Unlike BFS whose predecessor subgraph forms a tree, the predecessor subgraph produced by DFS forms a **forest** (multiple trees), because the search may be repeated from **multiple sources**.

We can define the **predecessor subgraph** of DFS as follows:

$$\begin{aligned} G_\pi &= (V, E_\pi) \\ E_\pi &= \{(v.\pi, v) : v \in V \wedge v.\pi \neq \text{NIL}\} \end{aligned}$$

We call the edges  $(v.\pi, v)$  in  $E_\pi$  **tree edges**.

# Depth-First Search (DFS): Color

DFS relies on a similar *vertex-coloring scheme* to that of BFS as follows:

- Initially, each vertex is white.
- It becomes gray when it is discovered during the search.
- Eventually, it becomes black when it is finished, i.e., when its adjacency list is completely explored.

This coloring scheme can also ensure that each vertex ends up in *exactly one* DFS tree so that all the resulting DFS trees are *disjoint*.

# Depth-First Search (DFS) : Timestamp

Associated with each vertex  $v$  are **two timestamps**  $v.d$  and  $v.f$ :

- The first timestamp  $v.d$  records when  $v$  is first **discovered** and **grayed**.
- The second timestamp  $v.f$  records when DFS finishes exploring  $v$ 's adjacency list and **blackens**  $v$ .

These timestamps are helpful in reasoning about the behavior and correctness of DFS.

## Depth-First Search (DFS) : Color and Timestamp

Timestamps can be implemented using *integers* between 1 and  $2|V|$ .

For every vertex  $v$ ,

$$v.d < v.f$$

$v$  is white before  $v.d$ , gray between  $v.d$  and  $v.f$  and black after  $v.f$ .

# Depth-First Search (DFS) : Pseudocode

DFS( $G$ )

```
1  for each vertex  $u \in G.V$ 
2       $u.color = \text{WHITE}$ 
3       $u.\pi = \text{NIL}$ 
4   $time = 0$ 
5  for each vertex  $u \in G.V$ 
6      if  $u.color == \text{WHITE}$ 
7          DFS-VISIT( $G, u$ )
```

DFS-VISIT( $G, u$ )

```
1   $time = time + 1$                                 // white vertex  $u$  has just been discovered
2   $u.d = time$ 
3   $u.color = \text{GRAY}$ 
4  for each  $v \in G.Adj[u]$                             // explore edge  $(u, v)$ 
5      if  $v.color == \text{WHITE}$ 
6           $v.\pi = u$ 
7          DFS-VISIT( $G, v$ )
8   $u.color = \text{BLACK}$                                 // blacken  $u$ ; it is finished
9   $time = time + 1$ 
10  $u.f = time$ 
```



# Depth-First Search (DFS) : Pseudocode

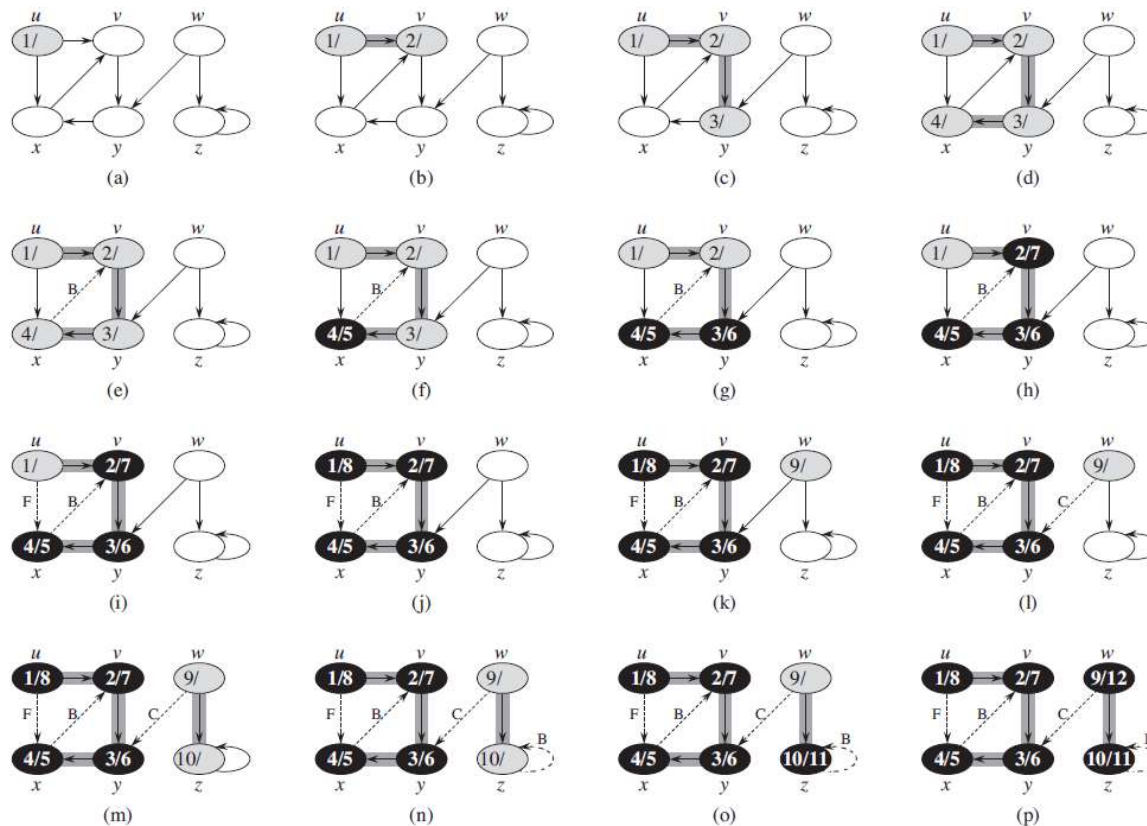
*DFS* works as follows:

- All vertices are initially painted white with their parent values set to *NIL*.
- The **global time counter** is reset.
- DFS checks each vertex  $u$  and explores  $v$  using *DFS – Visit*( $G, u$ ) if  $u$  is white
- Every time *DFS – Visit*( $G, u$ ) is called,  $u$  becomes the root of a new tree.
- When DFS returns, all vertices  $u$  are assigned with  $u.d$  and  $u.f$

*DFS – Visit* works as follows:

- In each call *DFS – Visit*( $G, u$ ),  $u$  is initially white
- Increment the global time counter and record it as the discovery time of  $u$
- $u$  is then painted gray
- $u$ 's adjacency list is recursively explored
  - For each  $v \in Adj[u]$  and  $v$  is white, explore  $v$
- After all edges leaving  $u$  are explored, blacken it increment the time counter and record it as the finishing time of  $u$

# Depth-First Search (DFS) : Example



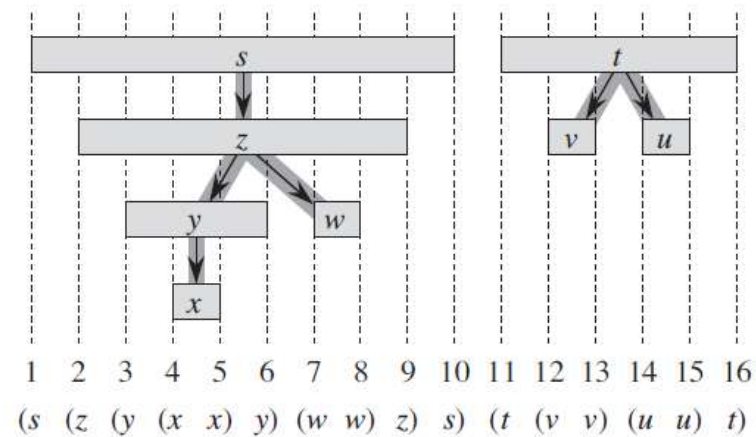
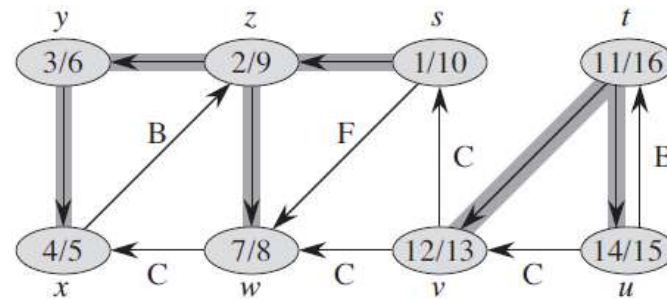
## Depth-First Search (DFS) : Parenthesis Structure

In DFS, discovery and finishing times exhibit ***parenthesis structure***.

In other words, if we represent the discovery of a vertex  $u$  with a ***left parenthesis*** ( $u$  and represent its finishing time with a ***right parenthesis***  $u$ ).

Then, the history of discovering and finishing all vertices makes a ***well-form expression*** in that the parentheses are ***properly nested***.

# Depth-First Search (DFS) : Parenthesis Structure



# Depth-First Search (DFS) : Parenthesis Structure

**Parenthesis Theorem:** In any depth-first search of a directed or undirected graph  $G = (V, E)$ , for any two vertices  $u$  and  $v$ , exactly one of the following conditions holds.

- The intervals  $[u.d, u.f]$  and  $[v.d, v.f]$  are entirely disjoint, and neither  $u$  nor  $v$  is a descendant of the other in the resulting DFS forest.
- The interval  $[u.d, u.f]$  is contained entirely in the interval  $[v.d, v.f]$ ,  $u$  is a descendant of  $v$  in a DFS tree.
- The interval  $[v.d, v.f]$  is contained entirely in the interval  $[u.d, u.f]$ ,  $v$  is a descendant of  $u$  in a DFS tree.

# Depth-First Search (DFS) : Parenthesis Structure

**Lemma (Nesting of Descendants' Intervals):** Vertex  $v$  is a proper descendant of vertex  $u$  in the DFS forest for a directed or undirected graph  $G = (V, E)$  if and only if  $u.d < v.d < v.f < u.f$ .

**Proof:** The lemma follows Immediately from ***Parenthesis Theorem***. ■

# Depth-First Search (DFS) : Parenthesis Structure

**White-path Theorem:** In a DFS forest of a directed or an undirected graph  $G = (V, E)$ , vertex  $v$  is a descendant of vertex  $u$  if and only if at the time  $u.d$  that the search discovers  $u$ , there is a **white path** from  $u$  to  $v$  consisting entirely of white vertices.

**Proof:**

$\Rightarrow$ : If  $u = v$ , then the path from  $u$  to  $v$  contains just  $u$ , which is still white when we set the value of  $u.d$ .

Now suppose  $v$  is a proper descendant of  $u$ .

$$u.d < v.d$$

**[Nesting of Descendants' Intervals]**

Then,  $v$  is white at time  $u.d$ .

Since  $v$  can be any descendant of  $u$ , all vertices on the unique path from  $u$  to  $v$  are white at time  $u.d$ .

# Depth-First Search (DFS) : Parenthesis Structure

$\Leftarrow$ : Suppose there is a path from of white vertices from  $u$  to  $v$  at time  $u.d$ , but **FPOC**,  $v$  does not become a descendant of  $u$  in the resulting DFS tree.

Assume wlog that the other vertices than  $v$  along the path become a descendant of  $u$ .

Let vertex  $w$  be a predecessor of  $v$  on that path so  $w$  is a descendant of  $u$  ( $u$  and  $w$  may be the same vertex).

Then,  $w.f \leq u.f$  [**Nesting of Descendants' Intervals**]

Because  $v$  must be discovered after  $u$  is discovered, but before  $w$  is finished, we have

$$u.d < v.d < w.f \leq u.f$$

**Parenthesis Theorem** implies that the interval  $[v.d, v.f]$  is entirely contained within  $[u.d, u.f]$ .

Hence,  $v$  is a descendant of  $u$  after all by **Nesting of Descendants' Intervals**. ■



# Depth-First Search (DFS) : Edge Classification

Another property of DFS is that the search can be used to **classify** the edges in the input graph  $G = (V, E)$ .

The type of each edge can provide information about the graph.

We can define **four** edge types in terms of the DFS forest  $G_\pi$  produced by DFS on  $G$  as follows:

- **Tree edges** are edges in  $G_\pi$ . Edge  $(u, v)$  is a tree edge if  $v$  was first discovered by exploring  $(u, v)$ .
- **Back edges** are those edges  $(u, v)$  connecting a vertex  $u$  to an ancestor  $v$  in a DFS tree.
- **Forward edges** are those non-tree edges connecting a vertex  $u$  to a descendant  $v$  in a DFS tree.
- **Cross edges** are all other edges that go between vertices that are not **ancestor-descendant-related**.

# Depth-First Search (DFS) : Edge Classification

The DFS algorithm has enough information to classify some edges as it encounters them.

The key idea is that when we first explore an edge  $(u, v)$ , the color of vertex  $v$  tells us something about the edge:

- **White** indicates a **tree edge**
- **Gray** indicates a **back edge**
- **Black** indicates a **forward** or a **cross edge**

To distinguish between forward and cross edges,

$(u, v)$  is a forward edge if  $u.d < v.d$

$(u, v)$  is a cross edge if  $u.d > v.d$

**\*\*\*In undirected graphs, there are only two types of edges, namely, tree and back edges.**

# Depth-First Search (DFS) : Edge Classification

**Theorem:** In a DFS tree of an undirected graph  $G = (V, E)$ , every edge of  $G$  is either a tree edge or a back edge.

**Proof:** Let  $(u, v)$  be an arbitrary edge of  $G$  and suppose wlog that  $u.d < v.d$ .

The search must discover and finish  $v$  before it finishes  $u$  while  $u$  is still gray, since  $v$  is on  $u$ 's adjacency list.

If the first time that the search explores  $(u, v)$ , it is in the direction from  $u$  to  $v$ , then  $v$  is undiscovered (white). Otherwise, the search would have explored the search already in the opposite direction from  $v$  to  $u$ .

Thus,  $(u, v)$  becomes a tree edge.

If the search explores  $(u, v)$  first in the direction from  $v$  to  $u$ , then  $(u, v)$  is a back edge, since  $u$  is still gray at the time the edge is first explored. ■

# Topological Sorting

DFS can be used to perform a **topological sort** of a **directed acyclic graph (DAG)**.

**Definition:** A topological sort of a DAG  $G = (V, E)$  is a linear (partial) ordering of all its vertices such that  $G$  contains an edge  $(u, v)$ , then  $u$  appears before  $v$  in that ordering.

TOPOLOGICAL-SORT( $G$ )

- 1 call DFS( $G$ ) to compute finishing times  $v.f$  for each vertex  $v$
- 2 as each vertex is finished, insert it onto the front of a linked list
- 3 **return** the linked list of vertices

**Note:** If a graph is not a DAG, such a linear ordering cannot be constructed among all vertices.

# Directed Acyclic Graph

**Lemma:** If there is a back edge if and only if  $G$  contains a cycle.

**Proof:**

$\Rightarrow$ : If there is a back edge  $(u, v)$ , that means there is a path from  $v$  to  $u$ .

Thus, the back edge  $(u, v)$  completes a cycle.

$\Leftarrow$ : Suppose  $G$  contains a cycle  $c$ .

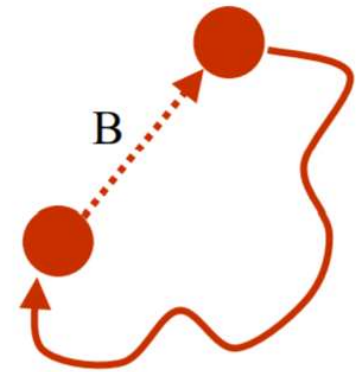
Let  $v$  be the first vertex to be discovered in the cycle  $c$ .

Let  $(u, v)$  be the preceding edge in the cycle  $c$ .

Thus, when  $v$  is discovered, all the other vertices in  $c$  are still white.

By the **White-path Theorem**,  $u$  becomes a descendant of  $v$ .

Therefore,  $(u, v)$  is a back edge. ■



# Directed Acyclic Graph

**Lemma:** If there is a back edge if and only if  $G$  contains a cycle.  $[p \leftrightarrow q]$

This is logically equivalent to:

**Lemma:** DFS yields no back edge if and only if  $G$  is a DAG.  $[\neg p \leftrightarrow \neg q]$

# Summary

In this lecture, we have covered the topic of *graph traversal techniques* and their applications:

- Breadth-First Search (BFS)
  - BFS Trees
  - Shortest Paths in Unweighted Graphs
- Depth-First Search (DFS)
  - DFS Trees
  - Edge Classifications
  - Topological Sort
  - Directed Acyclic Graph

In the next lecture, we will cover *Single-Source Shortest Path Problems*.