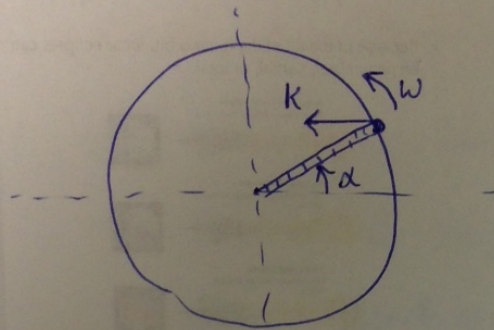


Homework 5

The way I am looking at this problem ...



$\alpha \rightarrow$ the angle

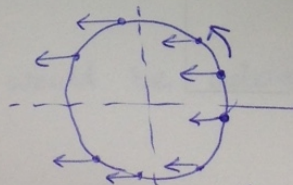
$\omega \rightarrow$ angular velocity

\rightarrow at each step, the force \vec{K} is applied on the rotator.

The direction of the force is always horizontal and its component that is perpendicular to the rod, changes the velocity.

For the simplicity, I assume that $\alpha_0 = 0$

if ω_0 is small \Rightarrow
Compared to \underline{K} .



* The number of kick at the top of the circle and at the bottom are almost the same.

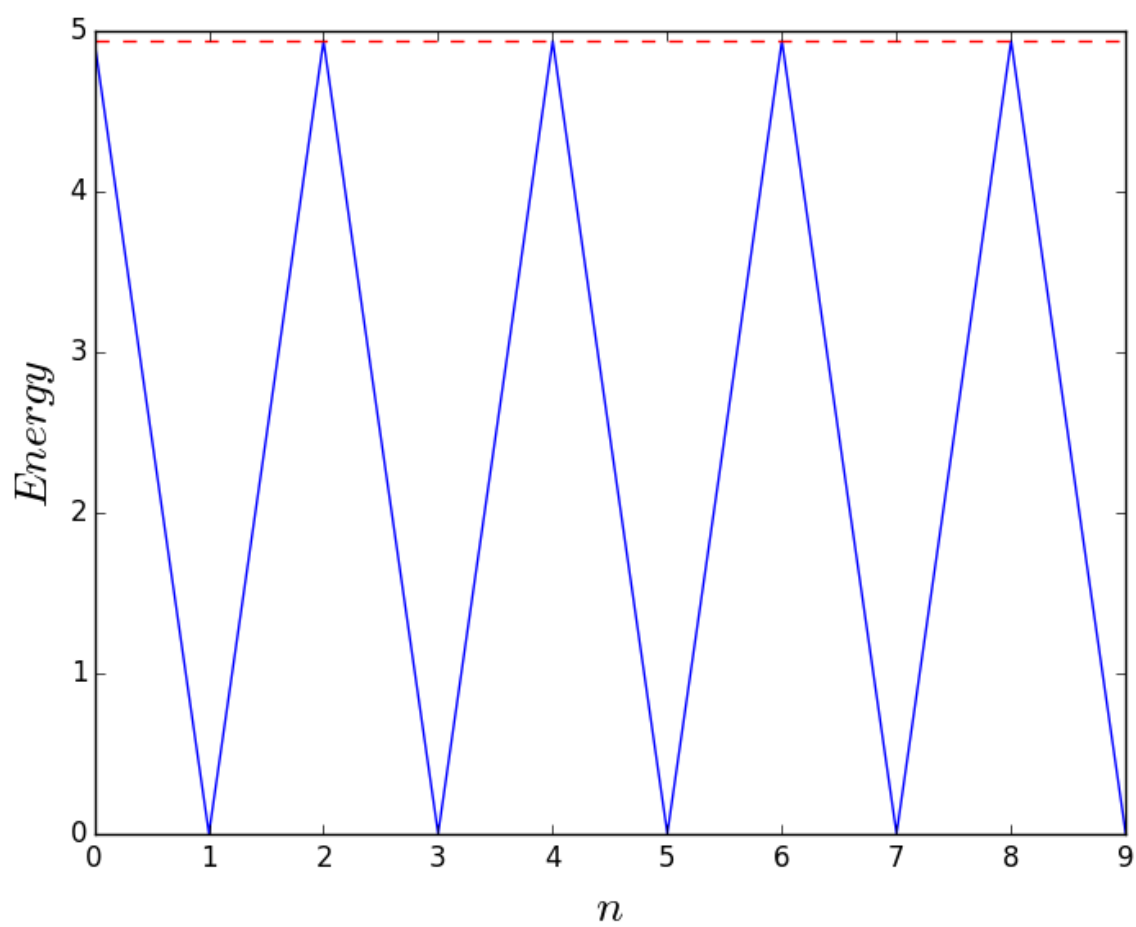
* Therefore the effect of the kick is canceled out and in average, the rotator does not gain any energy.

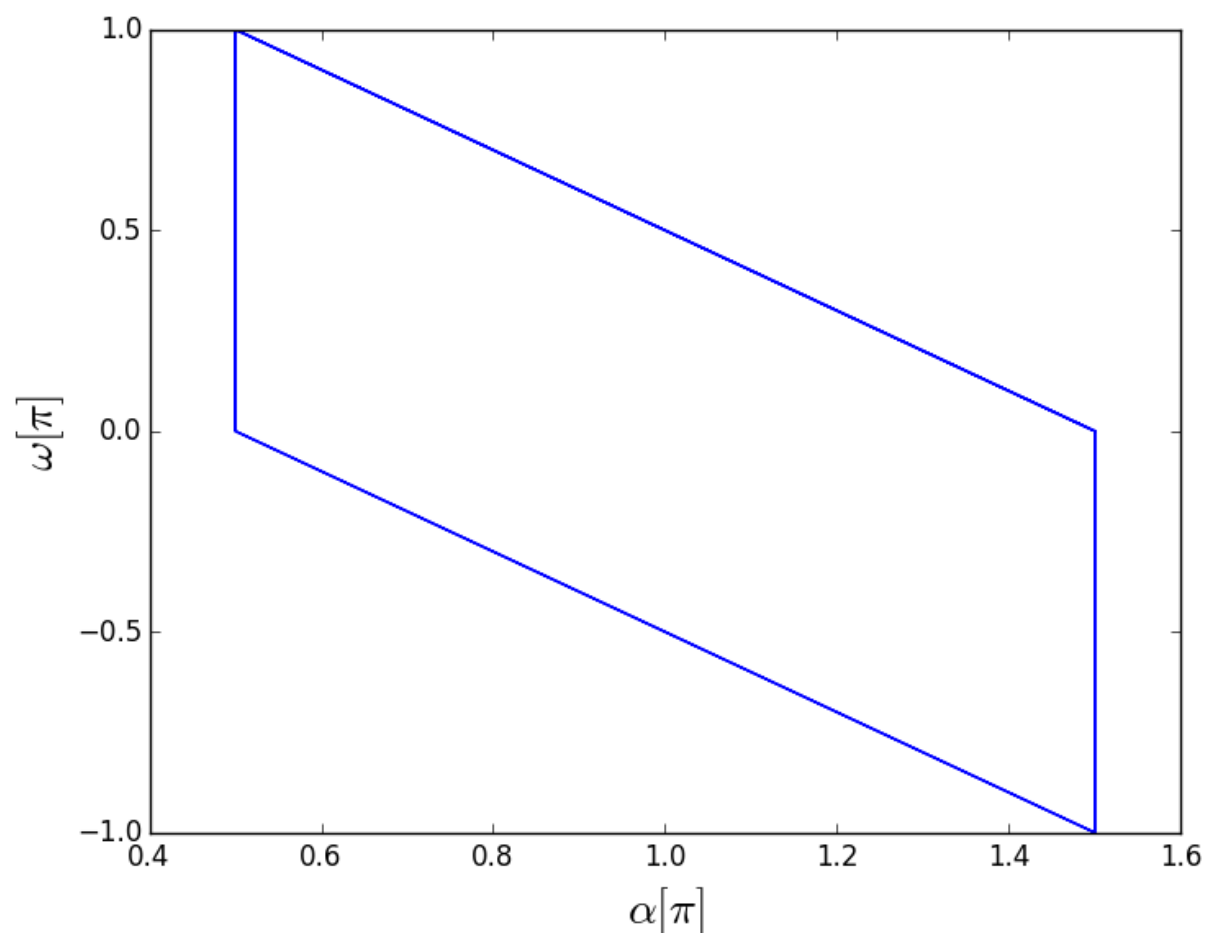
* Interesting

$$\left\{ \begin{array}{l} \text{If } \omega_0 = \pi, \alpha_0 = \frac{\pi}{2}, K = \pi \\ \alpha_1 = \frac{\pi}{2} + \pi = \frac{3\pi}{2}; \omega_1 = \pi - \pi = 0 \\ \alpha_2 = \frac{3\pi}{2} + \pi \equiv \frac{\pi}{2}; \omega_2 = \pi \end{array} \right.$$

\Rightarrow energy does not change.

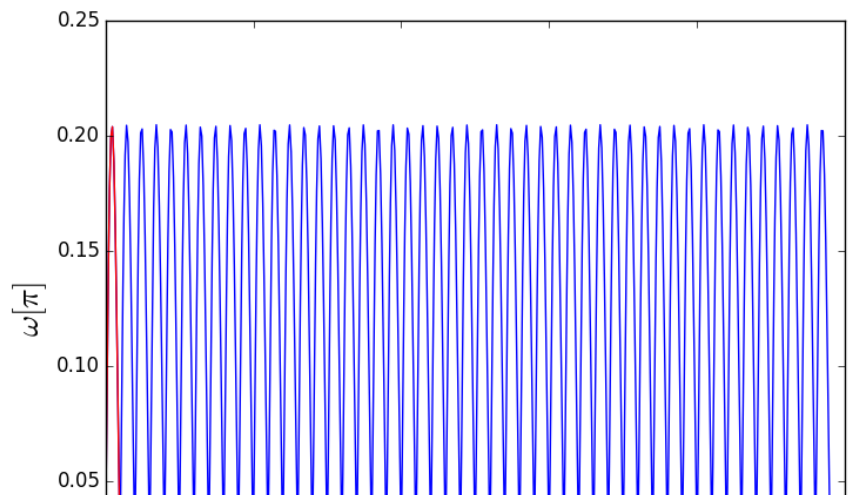
Here is the phase diagrams, and the energy diagram for this particular problem. Energy is constant and the red dashed-line line shows its value.





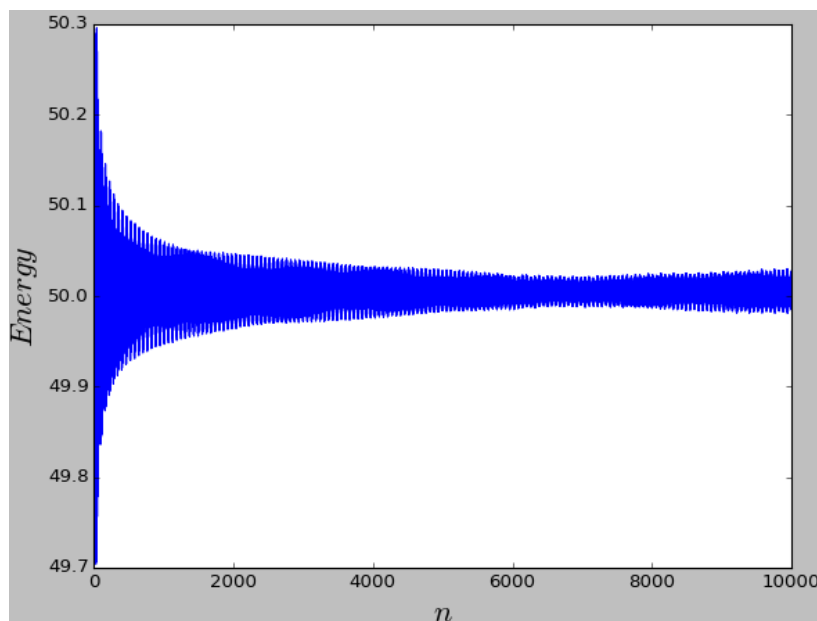
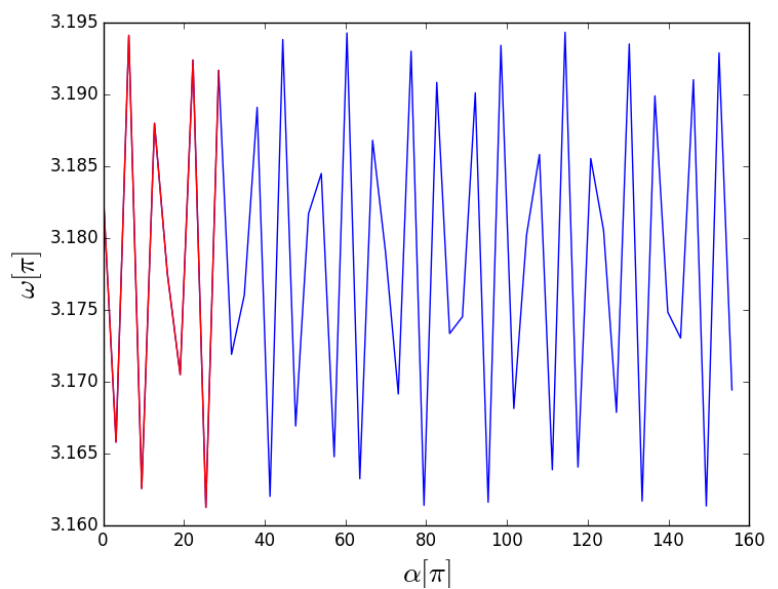
```
w[0] = 0.1      # velocity
a[0] = 0        # location
K = 0.1
```

This is the phase diagram. The red part shows the initial condition. As I mentioned earlier, if K is small, the solution is periodic and it is not chaotic.



```
w[0] = 10       # velocity
a[0] = 0        # location
K = 0.1
```

Even if $w[0]$ is big, the solution is integrable.



Left plot shows the ensemble average of energy when $w_0=10$ but $\alpha_0 \in [0:2\pi]$. As seen, the energy is fairly constant ($\sim 50 = 0.5 \cdot 10^2$), since kicking force is small.

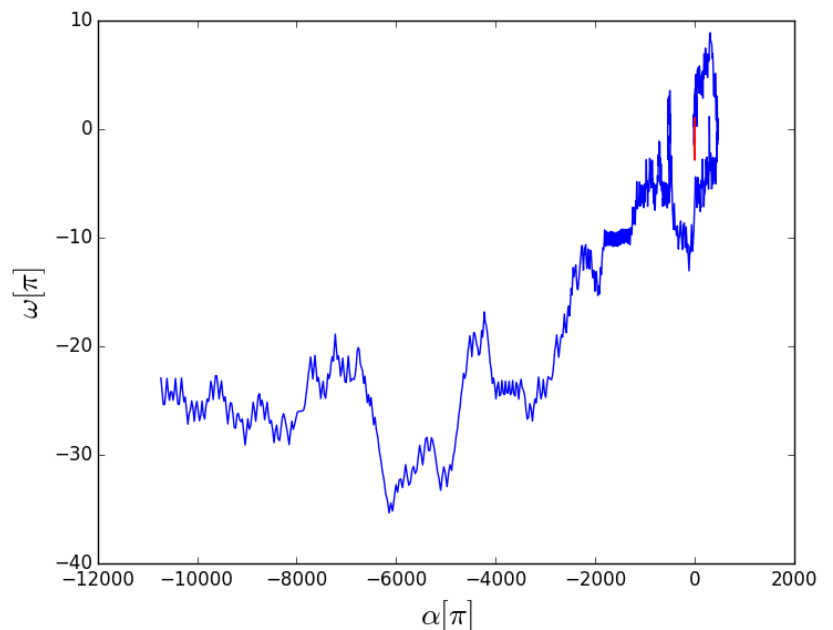
* On the other hand ...

If K is big, then there is a possibility that the number of kicks at the top and bottom are not the same. therefore there is a chance that the rotator get kicked more at the top for a while. The energy is temporarily increases, but the direction of the kick would be against the rotation after a while. ...

So, as a conclusion in the chaotic mode, on average No energy would be added to ^{the} system.

```
w[0] = 0.1      # velocity
a[0] = 0        # location
K = 4
```

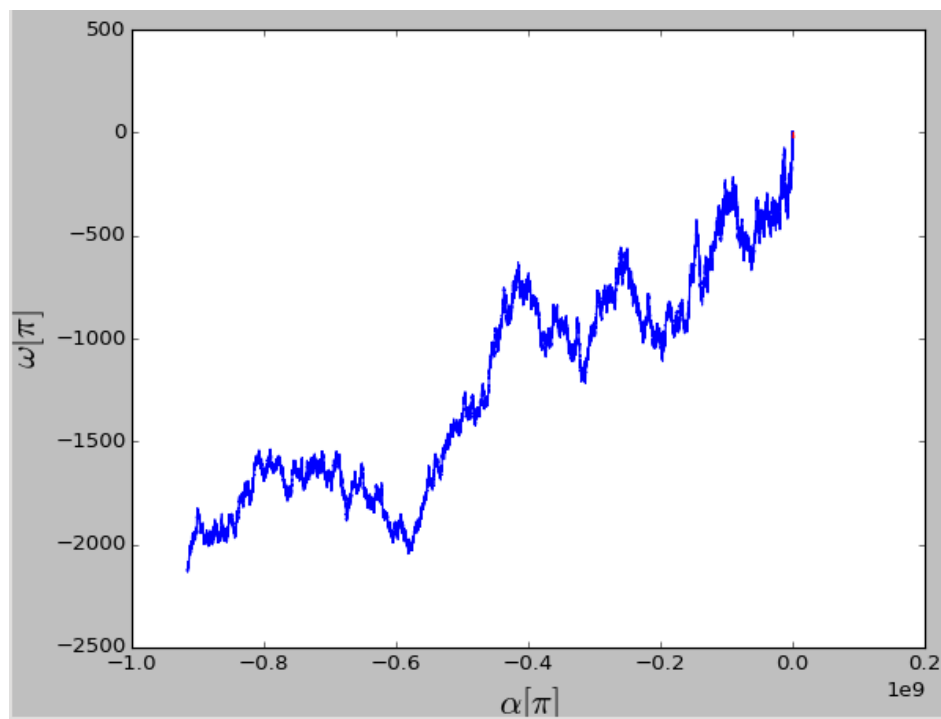
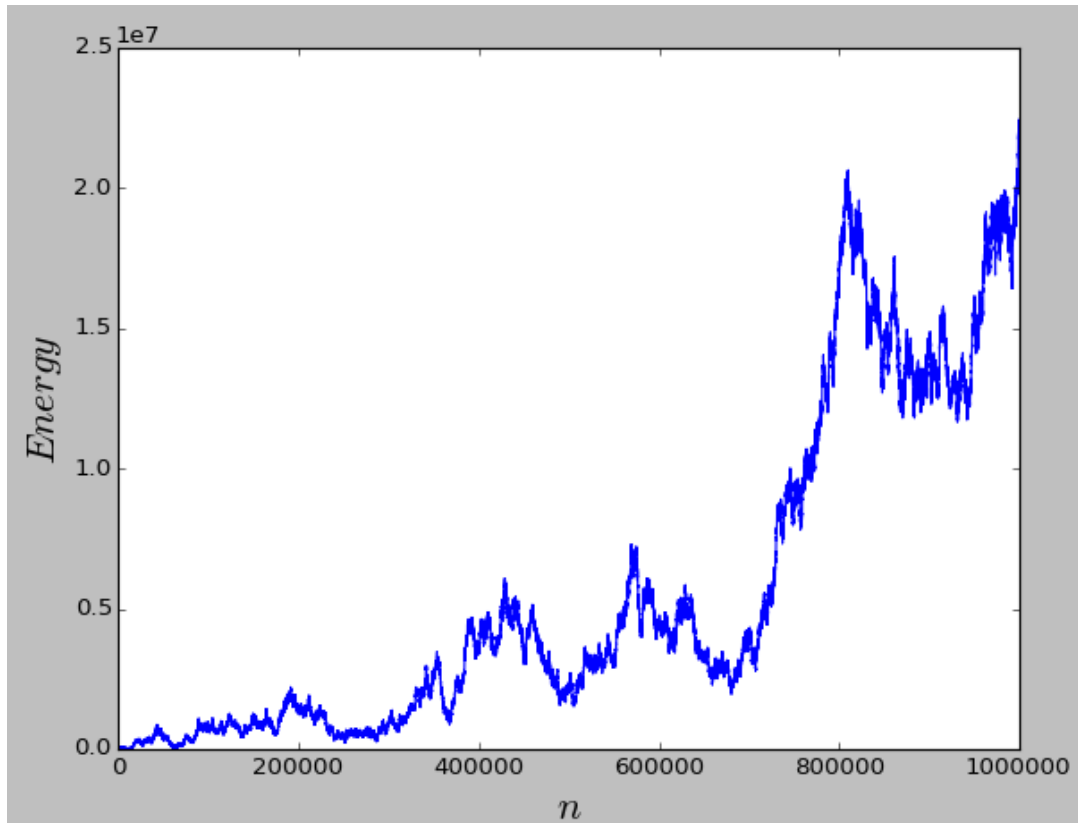
When K is increases, chaos starts.



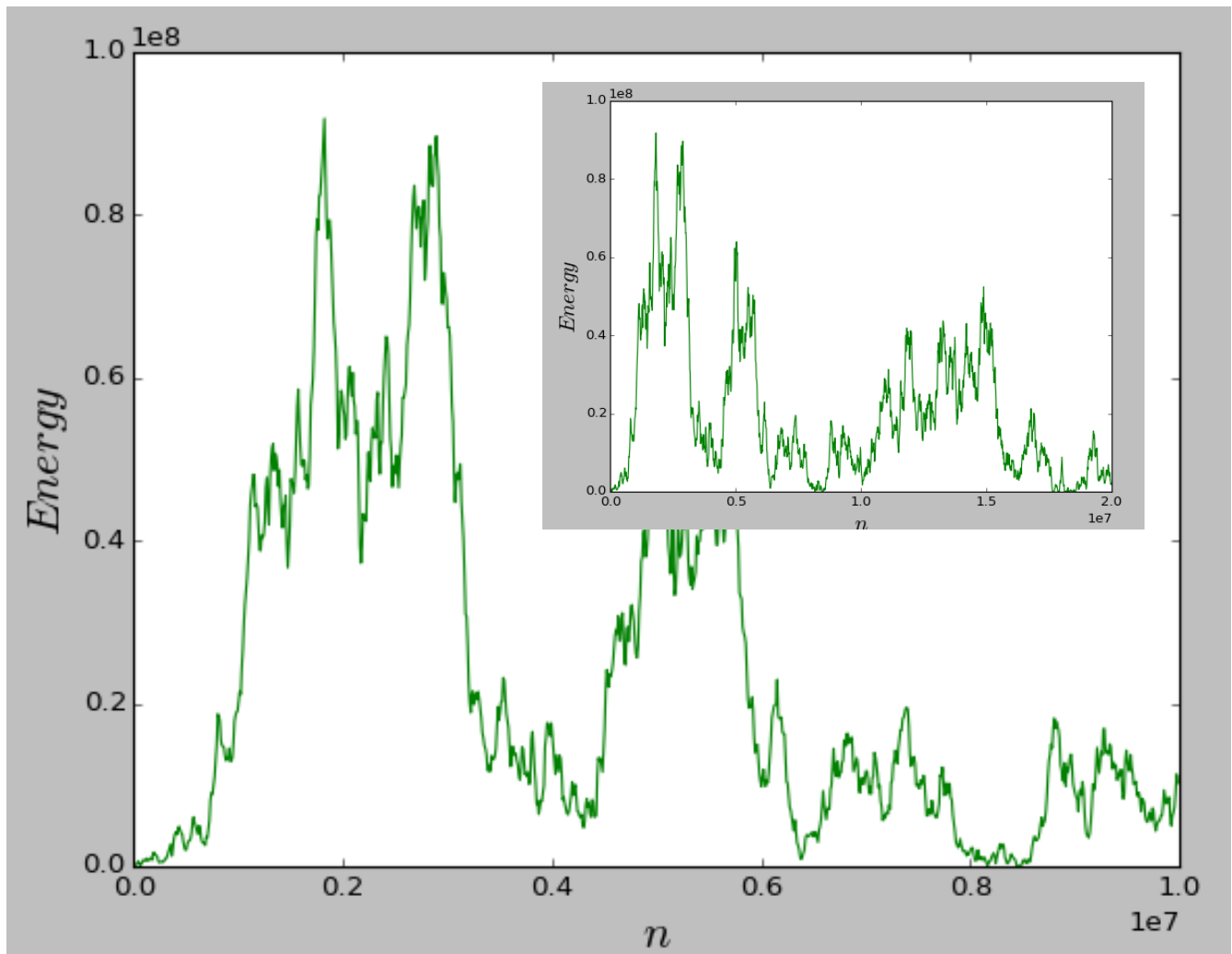
Phase space

Now, I am trying to find how energy is changing:

```
w[0] = 0.1      # velocity  
a[0] = 0        # location  
K = 5
```



Phase diagram: starting from top-right corner



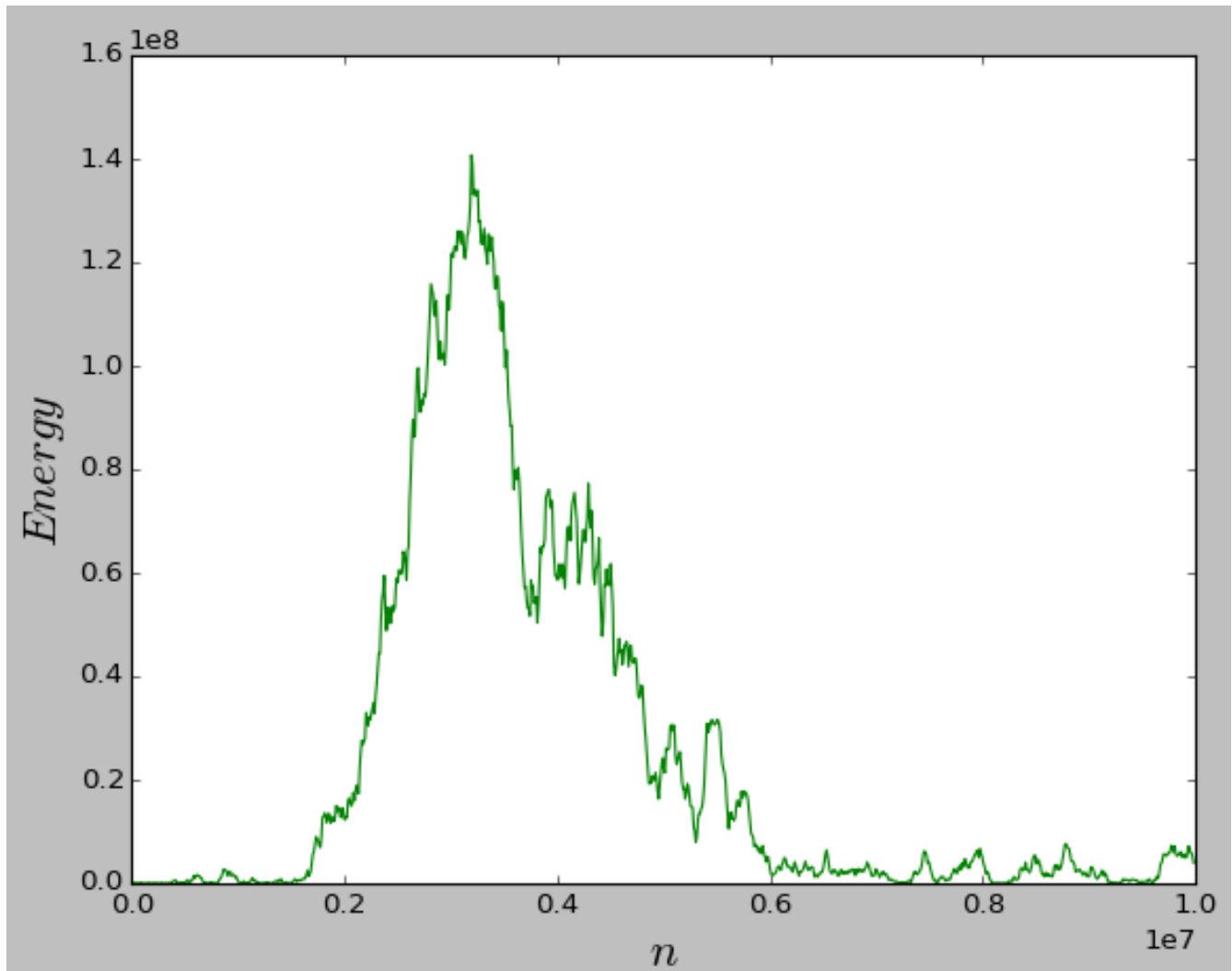
This inset diagram shows my try for twice number of steps (20,000,000 steps), and still everything is chaotic.

And also it's really sensitive to the initial value.

Let's slightly change the initial velocity

```
w[0] = 0.1+1.E-10      # velocity  
a[0] = 0                # location  
K = 5
```

This is the results :



By studying this single state, my conclusion is that, the energy does not reach to infinity. Since K is big, it dramatically changes the velocity of the rotators. The applied change in the velocity is $K * \sin(\alpha)$, since α is rapidly changing at big velocities, $\sin(\alpha)$ is like a random generator, generating random numbers between K and $-K$ Therefore the average effect of this random change in the velocity is almost zero.

How to obtain the ensemble average of the states

Ok, one can linearize these set of equations in order to analyze the system:

let $T = 1$

$$1) d\alpha/dt = \omega$$

$$2) d\omega/dt = K \sin(\alpha + \omega)$$

Then the Jacobin matrix would be:

$$J = \begin{vmatrix} 0 & 1 \\ K \cos(\alpha + \omega) & K \cos(\alpha + \omega) \end{vmatrix}$$

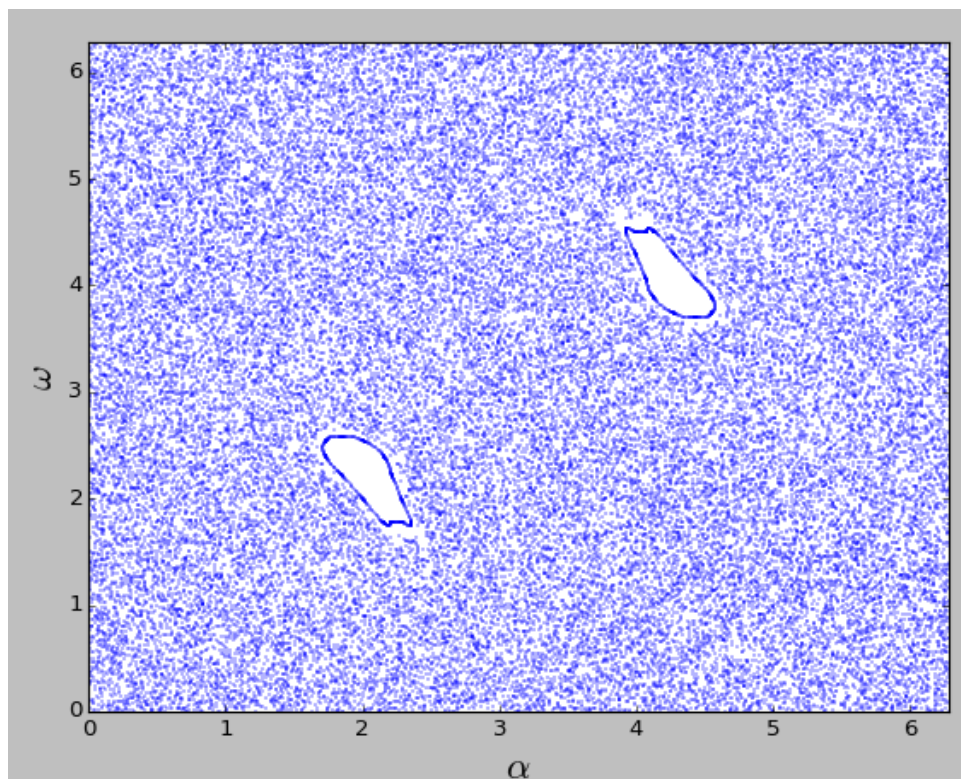
$$f(\alpha, \omega) = \omega$$

$$g(\alpha, \omega) = K \sin(\alpha + \omega)$$

The equilibrium points are $f(\alpha_0, \omega_0) = 0$ and $g(\alpha_0, \omega_0) = 0$

which happens for $(\alpha_0=0, \omega_0=0)$ and $(\alpha_0=\pi, \omega_0=0)$

Since, the Jacobin is symmetric with respect to α and ω , we can treat both variable in the same way, considering they vary between 0 and 2π . The resulting phase space would be like the following diagram.



In this diagram, all point show how randomly the phase space is populated.

$K = 5$

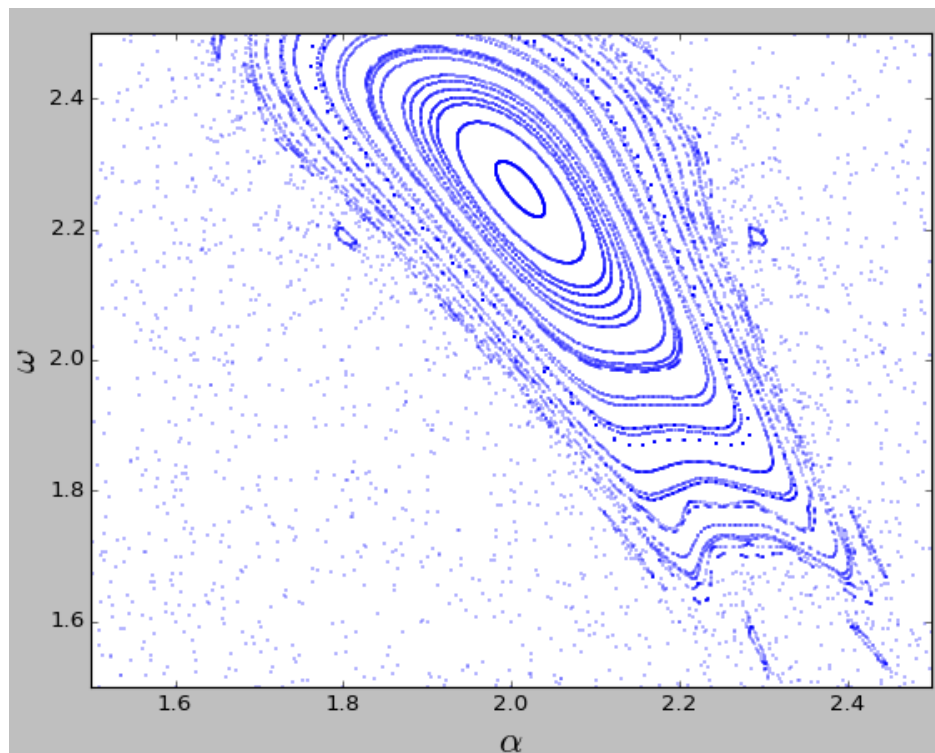
and

$\alpha_0 = 0, 1, 3, \dots, 6$

$\omega_0 = 0, 1, 3, \dots, 6$

The white regions are the regions where we have stable/periodic solution, that we want to avoid for our ensemble average calculations.

The closer look at the bottom left hole is as following:



As seen, the solutions inside this hole are periodic.

For the sake of the ensemble average calculations of the energy, we then choose

α_0 in $[0:1]$

ω_0 in $[0:2\pi]$

This way, we make sure to avoid the hole.

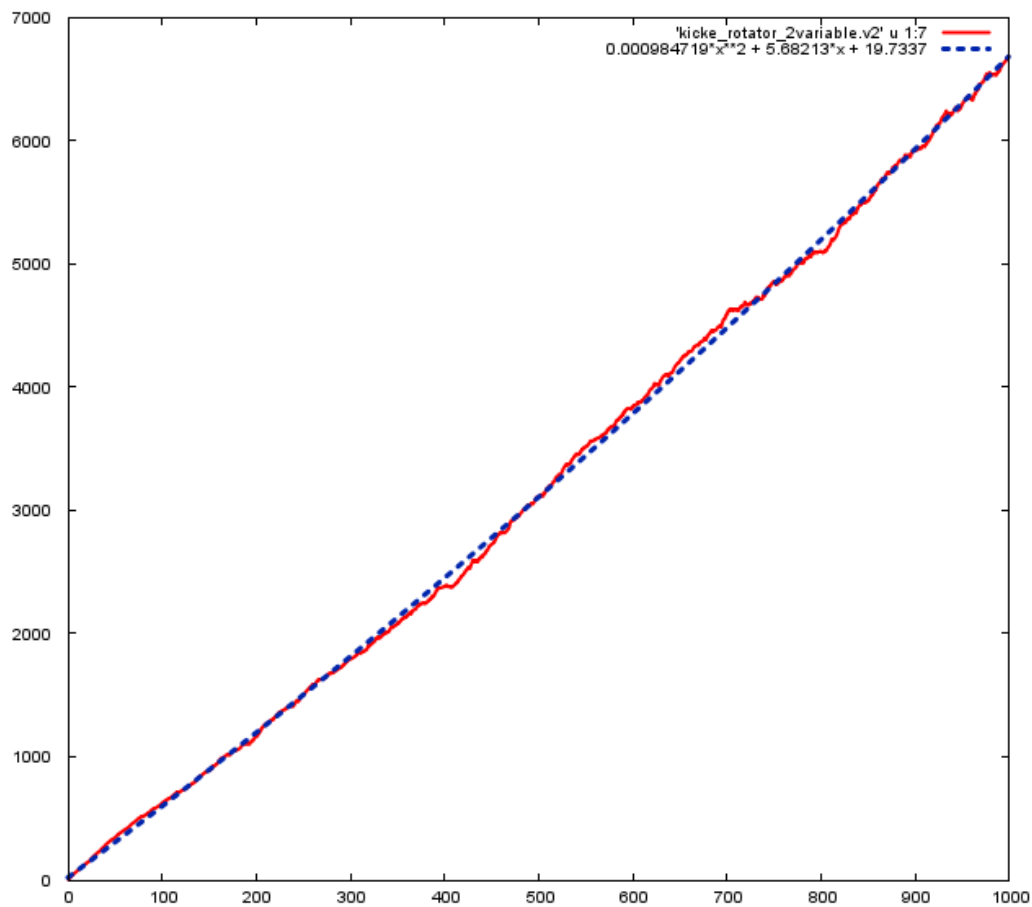
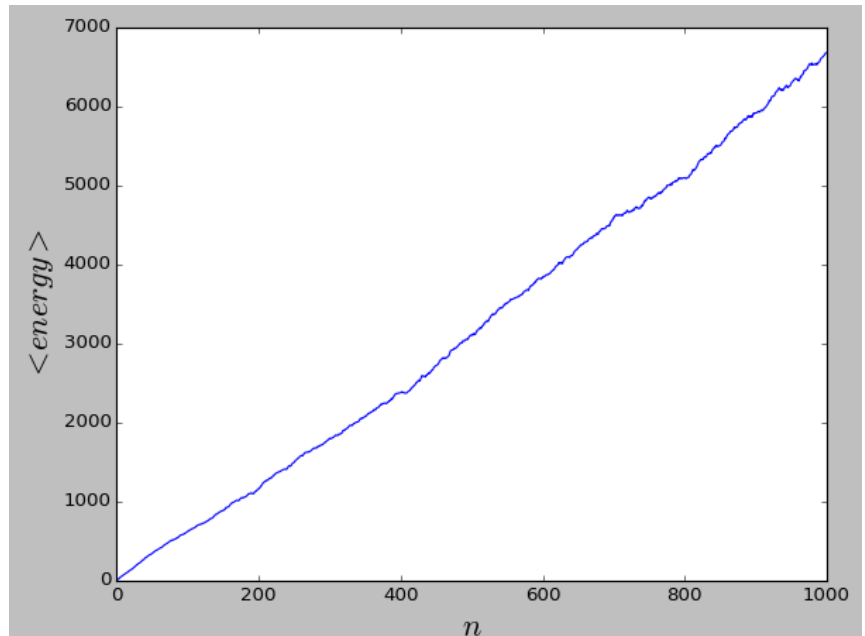
On the right, you see the results of the ensemble average of energy as a function of the kick number.

n : kick number, (or time)

I have used an ensemble of 1,000 set of initial values, taken uniformly

α_0 in $[0:1]$

ω_0 in $[0:2\pi]$



This is the same as the previous plot. The dashed line is the best quadratic fitted line, obtained by gnuplot package.

I used a quadratic function, however it look to have a linear fit. In the above diagram, the red curve is the data, and the dashed-line is the fitted line.

```
gnuplot> f(x) = a*x**2 + b*x + c
gnuplot> fit f(x) 'kicke_rotator_2variable.v2' u 1:7 via a, b, c
```

Iteration 8

```
WSSR          : 2.29483e+06      delta(WSSR)/WSSR   : -1.39784e-11
delta(WSSR)    : -3.2078e-05     limit for stopping : 1e-05
lambda        : 0.00257876
```

resultant parameter values

```
a          = 0.000984719 > it's small, compared to b and c
b          = 5.68213    > therefore, we can ignore it and
c          = 19.7337    > just use a linear function.
```

After 8 iterations the fit converged.

final sum of squares of residuals : 2.29483e+06

rel. change during last iteration : -1.39784e-11

```
degrees of freedom (FIT_NDF)          : 997
rms of residuals   (FIT_STDFIT) = sqrt(WSSR/ndf) : 47.9764
variance of residuals (reduced chisquare) = WSSR/ndf : 2301.74
```

```
Final set of parameters          Asymptotic Standard Error
=====
```

```
a          = 0.000984719      +/- 2.035e-05      (2.067%)
b          = 5.68213          +/- 0.021           (0.3696%)
c          = 19.7337          +/- 4.542           (23.02%)
```

correlation matrix of the fit parameters:

```
      a      b      c
a      1.000
b     -0.968  1.000
c      0.745 -0.866  1.000
```

- the plotting command

```
gnuplot> plot 'kicke_rotator_2variable.v2' u 1:7 w l lw 2,
0.000984719*x**2 + 5.68213*x + 19.7337 lc rgb '#0025ad' lw 3 lt 0.4
```