

Swinburne University of Technology*School of Science, Computing and Engineering Technologies***ASSIGNMENT COVER SHEET**

Subject Code: COS30008
Subject Title: Data Structures and Patterns
Assignment number and title: 4, A Tree-like Priority Queue
Due date: Friday, May 26, 2023, 23:59
Lecturer: Dr. Markus Lumpe

Your name: _____ **Your student id:** _____

Check Tutorial	Tues 08:30	Tues 10:30	Tues 12:30 BA603	Tues 12:30 ATC627	Tues 14:30	Wed 08:30	Wed 10:30	Wed 12:30	Wed 14:30	Thurs 08:30	Thurs 10:30

Marker's comments:

Problem	Marks	Obtained
1	66	
Total	66	

Extension certification:

This assignment has been given an extension and is now due on _____

Signature of Convener: _____

```
// COS30008, Problem Set 4, 2023
```

```
#pragma once
```

```
#include <vector>
#include <optional>
#include <algorithm>
```

```
template<typename T, typename P>
```

```
class PriorityQueue
```

```
{
private:
```

```
    struct Pair
```

```
    {
```

```
        P priority;
```

```
        T payload;
```

```
        Pair( const P& aPriority, const T& aPayload ) :
```

```
            priority(aPriority),
```

```
            payload(aPayload)
```

```
        {}
```

```
    };
```

```
    std::vector<Pair> fHeap;
```

```
    /*
```

```
    In the array representation, if we are starting to count indices from 0,
    the children of the i-th node are stored in the positions  $(2 * i) + 1$  and
 $2 * (i + 1)$ , while the parent of node i is at index  $(i - 1) / 2$  (except
    for the root, which has no parent).
```

```
    */
```

```
void bubbleUp( size_t aIndex ) noexcept
```

```
{
```

```
    if ( aIndex > 0 )
```

```
    {
```

```
        Pair lCurrent = fHeap[aIndex];
```

```
        do
```

```
        {
```

```
            size_t lParentIndex = (aIndex - 1) / 2;
```

```
            if ( fHeap[lParentIndex].priority < lCurrent.priority )
```

```
            {
```

```
                fHeap[aIndex] = fHeap[lParentIndex];
```

```
                aIndex = lParentIndex;
```

```
            }
```

```
            else
```

```
            {
```

```
                break;
```

```
            }
```

```
        } while (aIndex > 0);
```

```
        fHeap[aIndex] = lCurrent;
```

```
    }
```

```
}
```

```
void pushDown( size_t aIndex = 0 ) noexcept
```

```
{
```

```
    if ( fHeap.size() > 1 )
```

```
    {
```

```
        size_t lFirstLeafIndex = ((fHeap.size() - 2) / 2) + 1;
```

```
        if ( aIndex < lFirstLeafIndex )
```

```
        {
```

```
            Pair lCurrent = fHeap[aIndex];
```

```
            do
```

```
            {
```

```
                size_t lChildIndex = (2 * aIndex) + 1;
```

```
                size_t lRight = 2 * (aIndex + 1);
```

```

        if ( lRight < fHeap.size() && fHeap[lChildIndex].priority < fHeap[lRight].priority )
        {
            lChildIndex = lRight;
        }

        if ( fHeap[lChildIndex].priority > lCurrent.priority )
        {
            fHeap[aIndex] = fHeap[lChildIndex];
            aIndex = lChildIndex;
        }
        else
        {
            break;
        }

    } while ( aIndex < lFirstLeafIndex );

    fHeap[aIndex] = lCurrent;
}
}
}

public:

    size_t size() const noexcept{
        return fHeap.size();
    }

    std::optional<T> front() noexcept
    {
        if(size() > 0){
            T lResult = fHeap[0].payload;

            fHeap[0] = fHeap.back();
            fHeap.pop_back();

            if(!fHeap.empty()){
                pushDown();
            }
            return std::optional<T>(lResult);
        }
        else{
            return std::optional<T>();
        }
    }

    void insert( const T& aPayload, const P& aPriority ) noexcept{
        // use emplace back to construct the Pair in place
        fHeap.emplace_back(aPriority, aPayload);
        bubbleUp(size() - 1 );
    }

    void update( const T& aPayload, const P& aNewPriority ) noexcept{
        for(size_t index = 0; index < size() ; index++){
            if(fHeap[index].payload == aPayload){
                P aOldPriority = fHeap[index].priority ;
                fHeap[index].priority = aNewPriority;
                if(aOldPriority < aNewPriority){
                    bubbleUp(index);
                }
                else if(aOldPriority > aNewPriority)
                    pushDown(index);
            }
        }
    }
};

```