

课程名称： 计算机图形学 指导教师： 王振武

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实验项目名称：

7. 纹理映射

实验目的及要求：

完成纹理映射

实验内容（方法和步骤）：

把某种墙的纹理映射到球面上。

实际上 OpenGL 的纹理映射是在 rasterization 过程中发生的，rasterization 阶段产生的 fragments 被送入 fragment shader 处理，像素的颜色也在此阶段决定。因此和实验 1 ~ 实验 3 一样，这里也只是纹理映射的模拟。

目录结构：

```
texture/  
|-- image.cc  
|-- main.cc  
|-- makefile  
|-- point.cc  
|-- point.hh  
|-- rgb.cc  
|-- rgb.hh  
|-- shader.cc  
|-- shader.hh  
|-- texture.cc  
|-- texture.hh  
|-- trivial.frag  
|-- trivial.vert  
|-- wall.jpg
```

为了获得与每个点关联的颜色，fragment shader 中声明 **in vec3** texColor，颜色直接从 texColor 中取出：

```
1 #version 330 core
2 in vec3 texColor;
3 out vec4 color;
4 void main()
5 {
6     color = vec4(texColor,1.0f);
7 }
```

code 1: trivial.frag

fragment shader 的变量 texColor 由 vertex shader 传入：

```
1 #version 330 core
2 layout (location = 0) in vec3 aPos;
3 layout (location = 1) in vec3 aColor;
4
5 out vec3 texColor;
6
7 uniform mat4 M;
8 uniform mat4 M_cam;
9
10 const int windowHeight = 1920;
11 const int windowHeight = 1028;
12 const float depth = 2000;
13 const float l = - (windowWidth - 1) / 2.0f;
14 const float r = (windowWidth - 1) / 2.0f;
15 const float b = - (windowHeight - 1) / 2.0f;
16 const float t = (windowHeight - 1) / 2.0f;
17 const float n = 0;
18 const float f = -depth;
19 const mat4 M_ortho_proj = mat4(
20     vec4(2.0f/(r - l),0.0f,0.0f,0.0f),
21     vec4(0.0f,2.0f/(t - b),0.0f,0.0f),
22     vec4(0.0f,0.0f,2.0f/(n - f),0.0f),
23     vec4((r + l)/(l - r),(t + b)/(b - t),(n + f)/(f - n),1.0f)
24 );
25
```

```
26 void main()
27 {
28     gl_Position = M_ortho_proj * M_cam * vec4(aPos,1.0f);
29     texColor = aColor;
30 }
```

code 2: trivial.vert

图片 wall.jpg 的读取用 stb 库。该库是 header-only library，其要求存在一个 .cc 文件包含 stb 库相应头文件的实际实现：

```
1 #define STB_IMAGE_IMPLEMENTATION
2 #include <stb/stb_image.h>
```

code 3: image.cc

这个实验使用了 point 和 rgb 类，其中 point 类与之前实验的类似，只是扩展到了三维：

```
1 #ifndef POINT_HH
2 #define POINT_HH
3
4 #include <glbinding/gl/gl.h>
5 #include <glbinding/glbinding.h>
6
7 class point
8 {
9     public:
10         gl::GLfloat x;
11         gl::GLfloat y;
12         gl::GLfloat z;
13         point(float xx, float yy, float zz):x(xx),y(yy),z(zz) {}
14 };
15 bool lessf(const point &p1, const point &p2);
16
17 #endif //POINT_HH
```

code 4: point.hh

```
1  #include "point.hh"
2  bool lessf(const point &p1,const point &p2) {
3      if (p1.x < p2.x) {
4          return true;
5      }
6      else if (p1.x == p2.x) {
7          if (p1.y < p2.y) {
8              return true;
9          }
10         else if (p1.y == p2.y) {
11             return p1.z < p2.z;
12         }
13         return false;
14     }
15     return false;
16 }
```

code 5: point.cc

rgb 类只是颜色分量的集合：

```
1  #ifndef RGB_HH
2  #define RGB_HH
3
4  #include <glbinding/gl/gl.h>
5  #include <glbinding/glbinding.h>
6
7  class rgb
8  {
9      public:
10         gl::GLfloat r;
11         gl::GLfloat g;
12         gl::GLfloat b;
13         rgb(float rr,float gg,float bb) : r(rr),g(gg),b(bb) {}
14         rgb() = default;
15 };
16
17 #endif //RGB_HH
```

code 6: rgb.hh

```
1 #include "rgb.hh"
```

code 7: rgb.cc

`rasterize_with_texture` 将球心坐标 \vec{o} ，半径 300 的球体 rasterize，并根据每个像素的位置 (φ, θ) 映射到纹理图片，取出相应颜色与该像素绑定，返回所有像素点及与其对应的颜色。

`texture.cc` 中用的是粗糙的 rasterization 的方法。对 $\varphi \in [0, 2\pi]$ 及 $\theta \in [0, \pi]$ 分别以某个步长遍历，得到整个球面上采样点的坐标。步长越小，球面就显示得越精细。这个实验中 $\Delta\theta$ 和 $\Delta\varphi$ 都为 0.2° ，效果可以接受。

图片上点的自由度为 2，球面上点的自由度也是 2，可以方便地建立映射。为了方便，使用 $row = A \cdot \theta + C_1, col = B \cdot \varphi + C_2$ 的形式。

令 $C_1 = C_2 = 0, A \cdot \theta_{max} = height, B \cdot \frac{1}{2} \cdot \varphi_{max} = width$ ，其中 $width$ 和 $height$ 分别为纹理图片以像素为单位的宽度和高度。则每半个球面分布一张纹理图片。

```
1 #ifndef TEXTURE_HH
2 #define TEXTURE_HH
3
4 #include "rgb.hh"
5 #include "point.hh"
6
7 #include <cmath>
8 #include <map>
9
10 //glm
11 #include <glm/glm.hpp>
12 #include <glm/gtc/matrix_transform.hpp>
13 #include <glm/gtc/type_ptr.hpp>
14
15 #include <glbinding/gl/gl.h>
16 #include <glbinding/glbinding.h>
17
18 gl::GLfloat *rasterize_with_texture(const unsigned char *image, int width, int
    ↪ height, size_t &cnt);
19 rgb map_to_tex(const unsigned char *image, int width, int height, float
    ↪ theta, float phi);
```

20

21 `#endif //TEXTURE_HH`

code 8: texture.hh

```
1 #include "texture.hh"
2
3 using namespace gl;
4 using namespace std;
5
6 GLfloat *rasterize_with_texture(const unsigned char *image,int width,int
  ↪ height,size_t &cnt)
7 {
8   //rasterize a sphere with radius 300 and center  $\vec{o}$ 
9   const float r(300);
10  //control the grainularities in 2 directions
11  const float delta_phi(glm::radians(0.2f));
12  const float delta_theta(glm::radians(0.2f));
13
14  map<point, rgb, decltype(lessf)*> points(lessf);
15  for (float phi = 0; phi < glm::radians(360.0f); phi += delta_phi) {
16    for (float theta = 0; theta < glm::radians(180.0f); theta +=
  ↪ delta_theta) {
17      const point p(
18        r * sin(theta) * cos(phi),
19        r * sin(theta) * sin(phi),
20        r * cos(theta)
21      );
22      //map to texture coordinate from spherical coord.
23      points[p] = map_to_tex(image,width,height,theta,phi);
24    }
25  }
26
27  cnt = points.size();
28  auto retval = new GLfloat[6 * cnt];
29  size_t i(0);
30
31  #define ADD(M) retval[i++]=M
32  #define ADD_POINT(X,Y,Z,R,G,B) ADD(X);ADD(Y);ADD(Z);ADD(R);ADD(G);ADD(B);
```

```

33
34     for (const auto &p : points) {
35         ADD_POINT(p.first.x, p.first.y, p.first.z, p.second.r, p.second.g,
36                 ↪ p.second.b);
37     }
38     return retval;
39 }
40 rgb map_to_tex(const unsigned char *image,int width,int height,float
41 ↪ theta,float phi)
42 {
43     //  $A \cdot \theta_{max} = height$ 
44     const int A(height / glm::radians(180.0f));
45     //  $B \cdot \frac{\phi_{max}}{2} = width$ 
46     const int B(width / glm::radians(180.0f));
47
48     const int row = static_cast<int>(A * theta) % height;
49     const int col = static_cast<int>(B * phi) % width;
50     const int pos = 3 * (row * width + col);
51     return rgb(image[pos]/255.0,image[pos+1]/255.0,image[pos+2]/255.0);
52 }

```

code 9: texture.cc

camera transformation 与三维图形变换实验中用到的类似，以 \vec{o} 为圆心在 xOz 平面上以半径 400 绕 y 轴旋转。

```

1  #include "shader.hh"
2  #include "point.hh"
3  #include "rgb.hh"
4  #include "texture.hh"
5
6  #include <iostream>
7  //disable inclusion of the development environment header
8  #define GLFW_INCLUDE_NONE
9  #include <GLFW/glfw3.h>
10 //glbinding
11 #include <glbinding/gl/gl.h>
12 #include <glbinding/glbinding.h>

```

```
13 //image loading
14 #include <stb/stb_image.h>
15
16 using namespace std;
17 using namespace gl;
18
19 GLFWwindow *initWindow();
20 glm::mat4 gen_M_cam(const glm::vec3 &center);
21
22 const unsigned windowHeight(1920);
23 const unsigned windowHeight(1028);
24
25 int main()
26 {
27     auto wd = initWindow();
28     glbinding::initialize(glFWGetProcAddress);
29     glEnable(GL_DEPTH_TEST);
30
31     shader prog("trivial.vert", "trivial.frag");
32
33     //load image data
34     int width,height,channel;
35     const auto image = stbi_load("wall.jpg", &width, &height, &channel, 0);
36
37     //rasterize a sphere with texture
38     size_t cnt;
39     const auto vert = rasterize_with_texture(image,width,height,cnt);
40     stbi_image_free(image);
41
42     GLuint vao;
43     glGenVertexArrays(1, &vao);
44     glBindVertexArray(vao);
45
46     GLuint vbo;
47     glGenBuffers(1,&vbo);
48     glBindBuffer(GL_ARRAY_BUFFER, vbo);
49     glBufferData(GL_ARRAY_BUFFER, sizeof(GL_FLOAT)*cnt*6, vert,
50     ↪ GL_STATIC_DRAW);
51     delete [] vert;
```



```
51
52     glVertexAttribPointer(0, 3, GL_FLOAT, GL_FALSE, 6*sizeof(GL_FLOAT), (void
    ↪ *));
53     glEnableVertexAttribArray(0);
54     //every 3D point comes with RGB color
55     glVertexAttribPointer(1, 3, GL_FLOAT, GL_FALSE, 6*sizeof(GL_FLOAT), (void
    ↪ *) (3*sizeof(GL_FLOAT)));
56     glEnableVertexAttribArray(1);
57
58     //unbind
59     glBindBuffer(GL_ARRAY_BUFFER, 0);
60     glBindVertexArray(0);
61
62     glPolygonMode(GL_FRONT_AND_BACK, GL_LINE);
63     while(!glfwWindowShouldClose(wd))
64     {
65         if (glfwGetKey(wd, GLFW_KEY_ESCAPE) == GLFW_PRESS) {
66             glfwSetWindowShouldClose(wd, true);
67         }
68
69         glClearColor(1,1,1,1);
70         glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT);
71
72         //get new camera transformation, center at  $\vec{o}$ 
73         const auto M_cam = gen_M_cam(glm::vec3(0,0,0));
74
75         prog.use();
76         prog.setMat4("M_cam", M_cam);
77
78         glBindVertexArray(vao);
79         //draw as points as to simulate the process of texturing
80         glDrawArrays(GL_POINTS, 0, cnt);
81
82         glfwSwapBuffers(wd);
83         glfwPollEvents();
84     }
85
86     glDeleteVertexArrays(1, &vao);
87     glDeleteBuffers(1, &vbo);
```

```
88
89     glfwTerminate();
90 }
91 glm::mat4 gen_M_cam(const glm::vec3 &center)
92 {
93     //eye position
94     const float radius = 400;
95     const auto time = glfwGetTime();
96     //eye rotates along a circle whose plane is perpendicular to y axis
97     const auto e = glm::vec3(
98         center.x + radius*sin(time),
99         center.y,
100        center.z + radius*cos(time)
101    );
102    //gaze direction
103    const auto target = center;
104    const auto g = target - e;    //always gaze at the center of the cuboid
105    //view-up vector
106    const auto t = glm::vec3(0,1,0);
107    //construct ( $\vec{u}, \vec{v}, \vec{w}$ ) basis
108    const auto w = - glm::normalize(g);
109    const auto u = glm::normalize(glm::cross(t, w));
110    const auto v = glm::cross(w, u);
111    //matrix to align ( $\vec{u}, \vec{v}, \vec{w}$ ) to ( $\vec{x}, \vec{y}, \vec{z}$ )
112    glm::mat4 M_cam_rot(
113        glm::vec4(u,0),    //first col
114        glm::vec4(v,0),    //second col
115        glm::vec4(w,0),    //third col
116        glm::vec4(0,0,0,1) //translation col
117    );
118    M_cam_rot = glm::transpose(M_cam_rot);
119    //matrix to translate  $\vec{e}$  to  $\vec{o}$ 
120    const glm::mat4 M_cam_transl(
121        glm::vec4(1,0,0,0),
122        glm::vec4(0,1,0,0),
123        glm::vec4(0,0,1,0),
124        glm::vec4(-e,1)
125    );
126    //construct M_cam
```

```
127     return M_cam_rot * M_cam_transl;
128 }
129 GLFWwindow *initWindow()
130 {
131     if (!glfwInit()) {
132         std::cerr << "init failed." << std::endl;
133     }
134     glfwWindowHint(GLFW_CONTEXT_VERSION_MAJOR, 3);
135     glfwWindowHint(GLFW_CONTEXT_VERSION_MINOR, 3);
136     glfwWindowHint(GLFW_OPENGL_PROFILE, GLFW_OPENGL_CORE_PROFILE);
137
138     auto w = glfwCreateWindow(windowWidth, windowHeight, "tAsK", nullptr,
139                               ↪ nullptr);
139     if (!w) {
140         std::cerr << "window creation failed" << std::endl;
141         exit(-1);
142     }
143     glfwMakeContextCurrent(w);
144
145     return w;
146 }
```

code 10: main.cc

实验结果与分析：



图 1: 某种墙的纹理



图 2: 效果

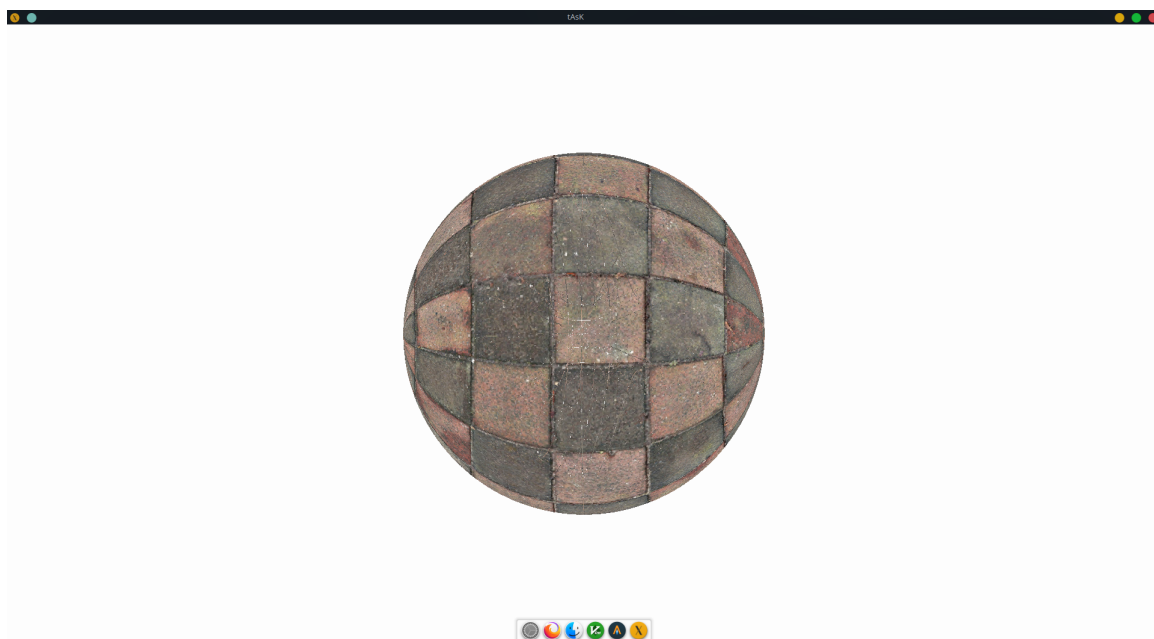


图 3: 另一个角度的效果

成绩:

批阅教师签名:

年 月 日