

Linear Algebra Support Lecture



Alexandru Ion

StudCee

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Vectors & Systems of linear equations

Most important concepts for
vectors:

- Inner product
- Angle between two vectors
- Linear combinations

Most important concepts for
Systems of linear equations:

- Parametric form

Inner Product

Let \vec{a} and \vec{b} be two vectors: $\vec{a} = \begin{bmatrix} a_1 \\ a_2 \\ \dots \\ a_n \end{bmatrix}$ $\vec{b} = \begin{bmatrix} b_1 \\ b_2 \\ \dots \\ b_n \end{bmatrix}$

Then the inner product is defined by:

$$\vec{a} \cdot \vec{b} = a_1 \cdot b_1 + a_2 \cdot b_2 + \dots + a_n \cdot b_n$$

Example

$$\vec{a} = \begin{bmatrix} 0 \\ 3 \\ 5 \end{bmatrix} \quad \vec{b} = \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} \quad \Rightarrow \quad \vec{a} \cdot \vec{b} = 0 \cdot 1 + 3 \cdot 2 + 5 \cdot 4 = 26$$

Angle between two vectors

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Compute the angle between \vec{a} and \vec{b} .

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$$\vec{a} \cdot \vec{b} = 3 \cdot 0 + 3 \cdot 4 + 0 \cdot 4 = 12$$

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$$\left. \begin{array}{l} 12 = 3\sqrt{2} \cdot 4\sqrt{2} \cdot \cos \alpha \\ 12 = 24 \cdot \cos \alpha \\ \cos \alpha = \frac{1}{2} \Rightarrow \alpha = 60^\circ \end{array} \right\} \Rightarrow$$

Linear combinations

Given vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ and scalars c_1, c_2, \dots, c_n

$$\vec{y} = c_1 \cdot \vec{v}_1 + c_2 \cdot \vec{v}_2 + \dots + c_n \cdot \vec{v}_n$$

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Example

Is $\vec{a} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ a linear combination of $\vec{b} = \begin{bmatrix} 1 \\ 5 \\ 9 \end{bmatrix}$ and $\vec{c} = \begin{bmatrix} 0 \\ 3 \\ 6 \end{bmatrix}$?

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$$\begin{pmatrix} 1 & 0 & 1 \\ 5 & 3 & 3 \\ 9 & 6 & 3 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 & 1 \\ 0 & 3 & -3 \\ 0 & 6 & -6 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 & 1 \\ 0 & 3 & -3 \\ 0 & 0 & 0 \end{pmatrix} \Rightarrow x_1 = 1, x_2 = -1;$$

R2 - 5R1

R3 - 2R2

R3 - 9R1

So, $\vec{a} = 1 \cdot \vec{b} + (-1) \cdot \vec{c}$.

Parametric form

$$\text{Let } A = \begin{pmatrix} 1 & 0 & 3 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Determine the corresponding solution set in parametric form.

We can take x_3 as a free variable since x_1 and x_2 can be expressed in terms of x_3 .

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$$\Rightarrow x_2 = -x_3$$

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Linear Transformations

- When is a transformation linear?
- Rotations
- Reflections / Shears / Projections
- One-to-one & Onto

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- $T(cu) = c T(u)$, for all scalars c and all u

Rotations

Let $T : R^2 \rightarrow R^2$ be the transformation that rotates each point in R^2 about the origin through an angle ϕ , with counterclockwise rotation for a positive angle.

Then the standard matrix A for this transformation is:

$$\begin{pmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{pmatrix}$$

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Reflections / Shears / Projections

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Projection onto the x_2 axis $\Rightarrow \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$

Reflections / Shears / Projections

Example

$T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ first rotates a vector by $\frac{\pi}{4}$ and then mirrors the resulting vectors horizontally along the x_1 axis. Find the standard matrix of T .

Reflections / Shears / Projections

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$$\begin{pmatrix} \cos \frac{\pi}{4} & -\sin \frac{\pi}{4} \\ \sin \frac{\pi}{4} & \cos \frac{\pi}{4} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix}$$

T mirrors the resulting vectors horizontally along the x_1 axis.

$$\Rightarrow \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \times \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \\ -\frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} \end{pmatrix}$$

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- T maps R^n onto R^m if and only if the columns of A span R^m .
- T is one-to-one if and only if the columns of A are linearly independent.

Matrices & Determinants

Another useful method to compute the determinant:

$$A = \begin{pmatrix} 1 & 4 & 0 \\ 3 & 2 & 2 \\ 0 & 0 & 2 \end{pmatrix} \text{ Choose the row or column which has the most 0.}$$

$$\det(A) = (-1)^{3+1} 0 \cdot \begin{vmatrix} 4 & 0 \\ 2 & 2 \end{vmatrix} + (-1)^{3+2} 0 \cdot \begin{vmatrix} 1 & 0 \\ 3 & 2 \end{vmatrix} + (-1)^{3+3} 2 \cdot$$

$$\begin{vmatrix} 1 & 4 \\ 3 & 2 \end{vmatrix} = 2 \cdot (2 - 12) = -20$$

Matrices & Determinants

The inverse of a matrix A is denoted by A^{-1} , so that:

$$A^{-1}A = I \text{ and } AA^{-1} = I$$

- A^{-1} exists if $\det(A) \neq 0$
- The equation $Ax = b$ has the unique solution $x = A^{-1}b$
- The columns of A form a linearly independent set.

Matrices & Determinants

Example

$$A = \begin{pmatrix} 1 & 4 & 0 \\ 0 & 2 & 2 \\ 0 & 0 & 1 \end{pmatrix} \text{ Compute } A^{-1}.$$

$$\det(A) = 1 \cdot 2 \cdot 1 = 2 \neq 0$$

$$\begin{pmatrix} 1 & 4 & 0 & 1 & 0 & 0 \\ 0 & 2 & 2 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R2 - 2R3} \begin{pmatrix} 1 & 4 & 0 & 1 & 0 & 0 \\ 0 & 2 & 0 & 0 & 1 & -2 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{pmatrix}$$

$$\xrightarrow{R1 - 2R2} \begin{pmatrix} 1 & 0 & 0 & 1 & -2 & 4 \\ 0 & 2 & 0 & 0 & 1 & -2 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 1 & 0 & 0 & 1 & -2 & 4 \\ 0 & 1 & 0 & 0 & 1/2 & -1 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{pmatrix}$$

$$\xrightarrow{R2 \cdot 1/2} \begin{pmatrix} 1 & 0 & 0 & 1 & -2 & 4 \\ 0 & 1 & 0 & 0 & 1/2 & -1 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{pmatrix}$$

$$\Rightarrow A^{-1} = \begin{pmatrix} 1 & -2 & 4 \\ 0 & 1/2 & -1 \\ 0 & 0 & 1 \end{pmatrix}$$

Eigenvalues & Eigenvectors

An eigenvector of a matrix A is a nonzero vector x such that $Ax = \lambda x$ for some scalar λ . A scalar λ is called an eigenvalue of A if there is a nontrivial solution x of $Ax = \lambda x$.

A scalar λ is an eigenvalue of a matrix A if and only if λ satisfies the characteristic equation:

$$\det(A - \lambda I) = 0$$

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Since A is a triangular matrix $\Rightarrow \lambda_1 = 1, \lambda_2 = 1/5$ and $\lambda_3 = 3/5$.

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Eigenvalues & Eigenvectors

Example

Let $x = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$, for $\lambda_1 = 1 \Rightarrow$

$$(A - \lambda I)x = \begin{pmatrix} 0 & 0 & 1 \\ 0 & -6/5 & -1/5 \\ 0 & 0 & -2/5 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} c \\ -(6/5)b + (1/5)c \\ -(2/5)c \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Leftrightarrow \begin{matrix} c = 0 \\ -(6/5)b + (1/5)c = 0 \\ -(2/5)c = 0 \end{matrix} \Rightarrow b = 0, c = 0 \text{ and } a \in \mathbb{R}$$

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$$\text{So, } x_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

Diagonalization

A matrix A is diagonalizable if and only if A has n linearly independent eigenvectors. The eigenvector-eigenvalue information of A can be displayed in the form of $A = PDP^{-1}$, where D is a diagonal matrix.

Diagonalization

Example

$$A = \begin{pmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \\ 3 & 3 & 1 \end{pmatrix} \text{ Diagonalize the matrix } A, \text{ if possible.}$$

- Find the eigenvalues of A .

$$\lambda_1 = 1, \lambda_2 = -2.$$

- Find three linearly independent eigenvectors.

$$v_1 = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \quad v_2 = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \quad v_3 = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

- Construct P from the eigenvectors in step 2.

$$P = \begin{pmatrix} 1 & -1 & -1 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

Diagonalization

Example

- Construct D from the corresponding eigenvalues.

$$D = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -2 \end{pmatrix}$$

- Check if $AP = PD$.

$$AP = \begin{pmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \\ 3 & 3 & 1 \end{pmatrix} \begin{pmatrix} 1 & -1 & -1 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 2 \\ -1 & -2 & 0 \\ 1 & 0 & -2 \end{pmatrix}$$

$$PD = \begin{pmatrix} 1 & -1 & -1 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -2 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 2 \\ -1 & -2 & 0 \\ 1 & 0 & -2 \end{pmatrix}$$

Exercise 1

Let $a = \begin{pmatrix} 3 \\ 3 \\ 0 \end{pmatrix}$ and $b = \begin{pmatrix} 0 \\ 4 \\ 4 \end{pmatrix}$ Determine all vectors perpendicular to both a and b .

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If c is perpendicular to a and $b \Rightarrow a \cdot c = 0$ and $b \cdot c = 0$.

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Let $c = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$

If c is perpendicular to a and $b \Rightarrow a \cdot c = 0$ and $b \cdot c = 0$.

$$a \cdot c = 3x + 3y + 0 = 3x + 3y = x + y = 0$$

Exercise 1

Let $a = \begin{pmatrix} 3 \\ 3 \\ 0 \end{pmatrix}$ and $b = \begin{pmatrix} 0 \\ 4 \\ 4 \end{pmatrix}$ Determine all vectors perpendicular to both a and b .

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$$y + z = 0 \Rightarrow y = -z. \Rightarrow \text{So } c = \begin{pmatrix} z \\ -z \\ z \end{pmatrix}$$

Exercise 2

Let $u = \begin{pmatrix} 6 - \alpha \\ \alpha \\ 0 \end{pmatrix}$, $v = \begin{pmatrix} 2 \\ 0 \\ 2 \end{pmatrix}$ and $w = \begin{pmatrix} 2\alpha \\ 1 \\ -2\alpha \end{pmatrix}$

Find all values of α that make u , v and w linearly dependent.

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$$\det(A) = \begin{vmatrix} 6 - \alpha & 2 & 2\alpha \\ \alpha & 0 & 1 \\ 0 & 2 & -2\alpha \end{vmatrix}$$

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$$= (-1)^{1+2} 0 \cdot \begin{vmatrix} \alpha & 1 \\ 0 & -2\alpha \end{vmatrix}$$

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Exercise 3

Determine whether the following matrix is invertible or not.

$$\begin{pmatrix} 0.41 & 0.3 & -3 & 0.23 & -2.4 \\ 2 & -2 & 4 & 1.3 & 16 \\ -0.54 & 0.55 & 4 & -13 & -4.4 \\ 23 & -10 & -4.5 & -4 & 80 \\ 1 & 0 & 4 & 8.93 & 0 \end{pmatrix}$$

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The columns of A are not linearly independent (The fifth column is (-8) times the second column).

Multivariable Calculus (CS+AI)

Aron Hardeman

June 14, 2023

- Partial derivatives

- The gradient & directional derivative
- Tangent planes
- Critical points

- In Cartesian coordinates (x, y)

- In polar coordinates (r, θ)

3 Triple integrals

Derivatives

We already know how to compute the derivative of a function of one variable, e.g., for $f(x) = \sin(x^2)$ we get:

$$\frac{df}{dx} = 2x \cos(x^2) \quad \frac{d^2f}{dx^2} = 2 \cos(x^2) - 4x^2 \sin(x^2)$$

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Notice that we use a “curly d” (∂) for partial derivatives.

Computing partial derivatives

To compute partial derivatives, we use this rule: **in order to compute the partial derivative with respect to one variable (say x), we use the regular derivative rules that we already know, while regarding the other variables (y and z) as constants.**

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Take $g(x, y, z) = x^5y + 3e^z$:

$$g_x = 5x^4y \quad g_y = x^5 \quad g_z = 3e^z$$

For example, when we compute g_x , we see that the $3e^z$ term vanishes (since we regard z as a constant, $3e^z$ is also constant, and the derivative of a constant is 0). And the derivative of the term x^5y is just $5x^4y$, since y is regarded as constant.

Higher order partial derivatives

Of course, we can also take the derivative of the derivative, and compute higher order partial derivatives in that way. Take for example

$$f(x, y, z) = xe^y \sin(z^2),$$

$$f_x = e^y \sin(z^2) \quad f_y = xe^y \sin(z^2) \quad f_z = 2xe^y z \cos(z^2)$$

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There are nine second order partial derivatives ($f_{xy} = (f_x)_y$):

$$\begin{array}{lll} f_{xx} = 0 & f_{yx} = e^y \sin(z^2) & f_{zx} = 2e^y z \cos(z^2) \\ f_{xy} = e^y \sin(z^2) & f_{yy} = xe^y \sin(z^2) & f_{zy} = 2xe^y z \cos(z^2) \\ f_{xz} = 2e^y z \cos(z^2) & f_{yz} = 2xe^y z \cos(z^2) & f_{zz} = 2xe^y [\cos(z^2) - 2z^2 \sin(z^2)] \end{array}$$

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We observe that in the end, the order of differentiation did not matter: $f_{xy} = f_{yx}$, and $f_{xz} = f_{zx}$, and $f_{yz} = f_{zy}$. In fact, this is always the case for any function¹. (*Clairaut's theorem*).

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2 Double integrals

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The gradient vector

The gradient is the vector of first-order partial derivatives of a function. For functions of two or three variables, the gradient is

$$\vec{\nabla} f(x, y) = \begin{bmatrix} \frac{\partial}{\partial x} f(x, y) \\ \frac{\partial}{\partial y} f(x, y) \end{bmatrix} \quad \vec{\nabla} g(x, y, z) = \begin{bmatrix} \frac{\partial}{\partial x} g(x, y, z) \\ \frac{\partial}{\partial y} g(x, y, z) \\ \frac{\partial}{\partial z} g(x, y, z) \end{bmatrix}$$

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The gradient of f can also be written as $\text{grad } f$ or ∇f , but in these slides we use $\vec{\nabla} f$ in order to accentuate the vectorial nature of the gradient. The gradient is important, because the directional derivative of a function at a point is maximal when you go in the direction of the gradient. **So, the gradient gives the direction of steepest increase of a function.**

The directional derivative

When you have a function f of more than one input variable, say $f(x, y)$, you might wonder what the rate of change *in a particular direction* is. This is the **directional derivative**.

Directional derivative

The directional derivative of $f(x, y)$ in the direction of a **UNIT** vector

$$\hat{u} = \begin{bmatrix} a \\ b \end{bmatrix} \text{ is}$$

$$D_{\hat{u}}f(x, y) = f_x(x, y)a + f_y(x, y)b = \vec{\nabla}f(x, y) \cdot \hat{u}$$

Similarly, in three dimensions, the directional derivative of $f(x, y, z)$ in the direction of a **UNIT** vector $\hat{u} = [a \ b \ c]^T$ is given by

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Directional derivative: example

- **Question:** calculate the directional derivative of

$f(x, y) = 4x^2 + xe^{x+2y} - ye^{2x+y} + 42$ in the direction of the vector $\vec{v} = \begin{bmatrix} -4 \\ 3 \end{bmatrix}$ at the point $(5, 6)$.

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- **Step 2:** calculate the partial derivatives:

$$f_x(x, y) = 8x + (1 + x)e^{x+2y} - 2ye^{2x+y}$$

$$f_y(x, y) = 2xe^{x+2y} - (1 + y)e^{2x+y}$$

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- **Step 3:** the directional derivative is: (do not forget to use the *unit* vector!)

$$D_{\hat{v}}f(5, 6) = -\frac{4}{5}f_x(5, 6) + \frac{3}{5}f_y(5, 6)$$

$$= -\frac{4}{5}(40 + 6e^{17} - 12e^{16}) + \frac{3}{5}(10e^{17} - 7e^{16}) = \boxed{-32 + \frac{27}{5}e^{16} + \frac{6}{5}e^{17}}$$

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Tangent planes

Tangent planes

Case 1: When you have a function $f(x, y)$ and consider the surface given by all points $(x, y, f(x, y))$, then the tangent plane to the surface at $(a, b, f(a, b))$ is given by

$$z = f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b)$$

Tangent planes

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Case 2: When you have a function $f(x, y, z)$ and consider the surface given by all points for which $f(x, y, z) = K$ (for some K), then the tangent plane to the surface at (a, b, c) is given by

$$f_x(a, b, c)(x - a) + f_y(a, b, c)(y - b) + f_z(a, b, c)(z - c) = 0$$

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- **Question:** Given the function $z = f(x, y) = 3xy + e^{xy^2+3}$, find the tangent plane to this surface at the point $(-3, 1)$.

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- Step 3: rewrite nicely:

$$4x - 15y - z = -19$$

Tangent planes: another example

- **Question:** find the tangent plane to the surface given by $x^2y^3 + 3x^3 + x^2y + xyz^2 + yz^2 = xy$ at the point $(1, -1, 1)$.

Tangent planes: another example

- **Question:** find the tangent plane to the surface given by $x^2y^3 + 3x^3 + x^2y + xyz^2 + yz^2 = xy$ at the point $(1, -1, 1)$.
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- **Step 2:** calculate the partial derivatives:

$$\begin{aligned} f_x(x, y, z) &= 2xy^3 + 9x^2 + 2xy + yz^2 - y & f_x(1, -1, 1) &= 5 \\ f_y(x, y, z) &= 3x^2y^2 + x^2 + xz^2 + z^2 - x & f_y(1, -1, 1) &= 5 \\ f_z(x, y, z) &= 2xyz + 2yz & f_z(1, -1, 1) &= -4 \end{aligned}$$

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$$f_x(x, y, z) = 2xy^3 + 9x^2 + 2xy + yz^2 - y \qquad f_x(1, -1, 1) = 5$$

$$f_y(x, y, z) = 3x^2y^2 + x^2 + xz^2 + z^2 - x \qquad f_y(1, -1, 1) = 5$$

$$f_z(x, y, z) = 2xyz + 2yz \qquad f_z(1, -1, 1) = -4$$

- **Step 3:** The tangent plane is thus (see "case 2"):

$$5(x - 1) + 5(y + 1) - 4(z - 1) = 0$$

1 Derivatives and applications

- Partial derivatives
- The gradient & directional derivative
- Tangent planes
- Critical points

2 Double integrals

- In Cartesian coordinates (x, y)
- In polar coordinates (r, θ)

3 Triple integrals

Critical points

A function $f(x, y)$ can have *local maxima*, *local minima* and/or *saddle points*. These are also called **critical points**.

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Solution: we calculate both partial derivatives and set them equal to zero:

$f_x(x, y) = 4x + 2y$ and $f_y(x, y) = 2x + 6y - 4$; so we get the system of equations $\begin{cases} 4x + 2y = 0 \\ 2x + 6y = 4 \end{cases}$, which has the (only) solution $x = -\frac{2}{5}$, $y = \frac{4}{5}$.

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So the (only) critical point of $f(x, y)$ is $\boxed{\left(-\frac{2}{5}, \frac{4}{5}\right)}$.

The second derivative test

Second derivative test

Suppose a function $f(x, y)$ has a critical point at (a, b) . Then we can calculate $D = D(a, b) = f_{xx}(a, b)f_{yy}(a, b) - [f_{xy}(a, b)]^2$

Then:

- If $D > 0$ and $f_{xx}(a, b) > 0$, then (a, b) is a **local minimum**
- If $D > 0$ and $f_{xx}(a, b) < 0$, then (a, b) is a **local maximum**
- If $D < 0$, then (a, b) is a **saddle point**
- If $D = 0$, then the test is inconclusive

The second derivative test (example)

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- **Step 2:** the second partial derivatives are $f_{xx}(x, y) = 4$, $f_{yy}(x, y) = 6$, $f_{xy}(x, y) = 2$. (Also $f_{yx}(x, y) = 2$, as it should be).

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$$D\left(-\frac{2}{5}, \frac{4}{5}\right) = f_{xx}\left(-\frac{2}{5}, \frac{4}{5}\right) f_{yy}\left(-\frac{2}{5}, \frac{4}{5}\right) - \left[f_{xy}\left(-\frac{2}{5}, \frac{4}{5}\right)\right]^2 = 4 \cdot 6 - 2^2 = 20$$

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- **Step 4:** we see that $D(-\frac{2}{5}, \frac{4}{5}) = 20 > 0$ and $f_{xx}(-\frac{2}{5}, \frac{4}{5}) = 4 > 0$, thus **the point $(-\frac{2}{5}, \frac{4}{5})$ is a local minimum.**

Find the closest point in plane (1/3) (Q4 exam 2021)

- **Question:** find the coordinates of the point (x, y, z) in the plane $z = ax + by + c$ which is closest to the point $(1, 2, -1)$ outside that plane. (Express the result in terms of a , b and c)

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- **Step 1:** The distance between a point (x, y, z) and the point $(1, 2, -1)$ is $\sqrt{(x-1)^2 + (y-2)^2 + (z+1)^2}$. Using the equation of the plane, this distance can be written as $\sqrt{(x-1)^2 + (y-2)^2 + (ax+by+c+1)^2}$, and we must find the x and y that minimize this distance. (From x and y , we can then calculate z using $z = ax + by + c$). But instead of minimizing the square root, we can make our task easier by finding the x and y that minimize $f(x, y) = (x-1)^2 + (y-2)^2 + (ax+by+c+1)^2$.

Find the closest point in plane (2/3) (Q4 exam 2021)

- **Step 2:** We wanted to minimize

$f(x, y) = (x - 1)^2 + (y - 2)^2 + (ax + by + c + 1)^2$, so we set
 $f_x(x, y) = 0$ and $f_y(x, y) = 0$:

$$f_x(x, y) = 2(x - 1) + 2a(ax + by + c + 1) = 0$$

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This results in the linear system of equations

$$(2 + 2a^2)x + (2ab)y = 2 - 2ac - 2a$$

$$(2ab)x + (2 + 2b^2)y = 4 - 2bc - 2b$$

which we must solve for x and y .

Find the closest point in plane (3/3) (Q4 exam 2021)

We can write the system of equations as a matrix:

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By subtracting $\frac{1+b^2}{ab}$ times the first row from the second row, we can find (after a long series of calculations) that $x = \frac{b^2 - 2ab - ac - a + 1}{a^2 + b^2 + 1}$.

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$$z = a \frac{b^2 - 2ab - ac - a + 1}{a^2 + b^2 + 1} + b \frac{2a^2 - ab - bc - b + 2}{a^2 + b^2 + 1} + c = \frac{-a^2 - b^2 + a + 2b + c}{a^2 + b^2 + 1}$$

Find the closest point in plane (3/3) (Q4 exam 2021)

We can write the system of equations as a matrix:

$$\left[\begin{array}{cc|c} (2+2a^2)x & (2ab)y & 2-2ac-2a \\ (2ab)x & (2+2b^2)y & 4-2bc-2b \end{array} \right]$$

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So the point we searched is

$$\left(\frac{b^2-2ab-ac-a+1}{a^2+b^2+1}, \frac{2a^2-ab-bc-b+2}{a^2+b^2+1}, \frac{-a^2-b^2+a+2b+c}{a^2+b^2+1} \right)$$

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Computing normal double integrals (1/2)

- **Question:** calculate the volume of the 3D body between $z = f(x, y) = (2x + 3)e^y$ and the xy -plane, when the bounds of x and y are the rectangle $-1 \leq x \leq 1$ and $0 \leq y \leq 2$.

²The reverse order would also work: $V_{\text{tot}} = \int_{-1}^1 \int_0^2 (2x + 3)e^y dy dx$

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- **Plan of attack:** work from the inside-out. So, we start solving the inner integral: $\int_{-1}^1 (2x + 3)e^y dx$. **Important:** this is an integral in the “ x -world”, because of the dx . It means that x changes, whereas we can treat y as a constant when computing the integral. So:

$$\int_{-1}^1 (2x + 3)e^y dx = e^y \int_{-1}^1 (2x + 3) dx = e^y \left[x^2 + 3x \right]_{-1}^1 = 6e^y$$

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- **Conclusion:** the volume of the 3D body is $V_{\text{tot}} = 6e^2 - 6$.

Another straightforward double integral

- **Question:** calculate the volume of the 3D body between $z = f(x, y) = \frac{x^3}{y}$ and the xy -plane, when the bounds of x and y are the rectangle $3 \leq x \leq 5$ and $2 \leq y \leq 4$.

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- We want to solve the integral

$$\int_2^4 \int_3^5 \frac{x^3}{y} dx dy$$

We start with solving the inner integral, where x changes and y is constant:

$$\int_3^5 \frac{x^3}{y} dx = \frac{1}{y} \int_3^5 x^3 dx = \frac{1}{4y} [x^4]_3^5 = \frac{136}{y}$$

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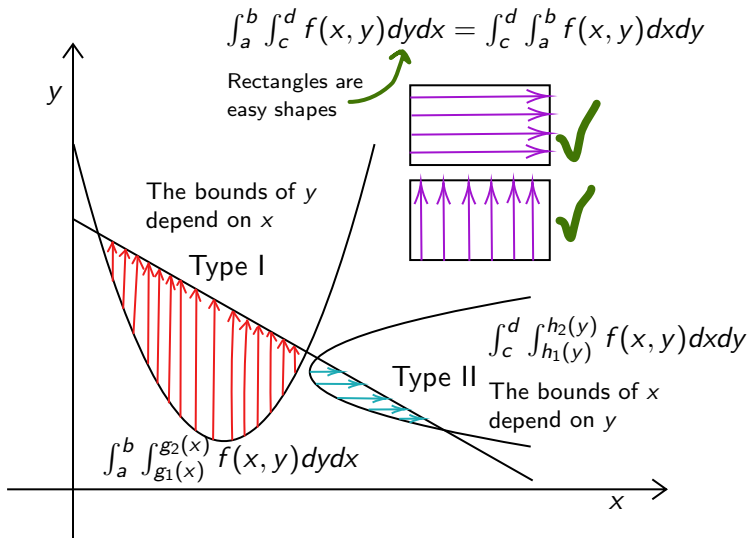
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Now we calculate the full double integral: the volume is

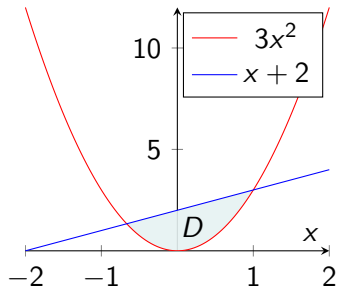
$$\int_2^4 \int_3^5 \frac{x^3}{y} dx dy = \int_2^4 \frac{136}{y} dy = 136 [\ln y]_2^4 = \boxed{136 \ln 2}$$

General regions: Intuition



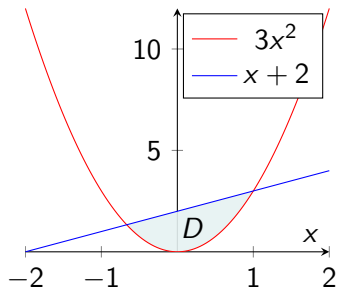
General regions: more intuition

Double integrals are like a for-loop. Suppose we have this question: calculate the volume of the 3D body between the function $z = f(x, y)$ and the xy -plane, above the region D enclosed by the parabola $y = 3x^2$ and the line $y = x + 2$. Given that the intersection points are $(-\frac{2}{3}, \frac{4}{3})$ and $(1, 3)$, what would you do?



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Our intuition would be to say:

Volume = 0; $\Delta x = 0.001$; $\Delta y = 0.001$;

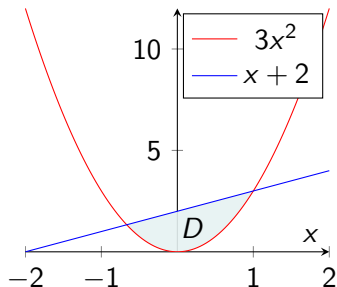
for($x = -2/3$; $x < 1$; $x += \Delta x$)

for($y = 3x^2$; $y < x + 2$; $y += \Delta y$)

Volume += $f(x, y) * \Delta y * \Delta x$;

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Volume += $f(x, y) * \Delta y * \Delta x$;

This program corresponds to
$$V = \int_{-2/3}^1 \int_{3x^2}^{x+2} f(x, y) dy dx$$

Thinking this way can help you determine if you need a type I or II integral.

General regions

Double integrals over general regions

A type I region goes like this:

$$D = \{(x, y) \mid a \leq x \leq b, g_1(x) \leq y \leq g_2(x)\}$$

$$\iint_D f(x, y) dA = \int_a^b \int_{g_1(x)}^{g_2(x)} f(x, y) dy dx$$

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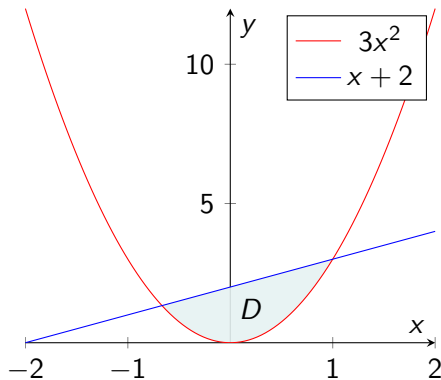
A type II region goes like this:

$$D = \{(x, y) \mid c \leq y \leq d, h_1(y) \leq x \leq h_2(y)\}$$

$$\iint_D f(x, y) dA = \int_c^d \int_{h_1(y)}^{h_2(y)} f(x, y) dx dy$$

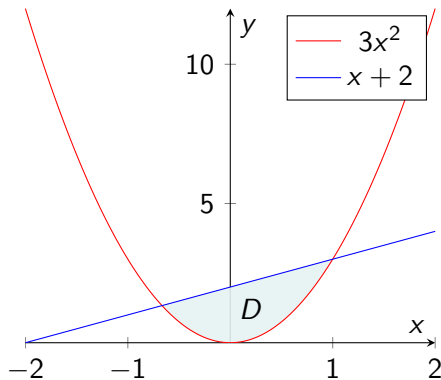
Double integrals over general regions (1/2)

Question: calculate the volume of the 3D body between the paraboloid $z = x^2 + y^2$ and the xy -plane, above the region D enclosed by the parabola $y = 3x^2$ and the line $y = x + 2$.



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Solving the equation $3x^2 = x + 2$ gives the endpoints $x = -\frac{2}{3}$ and $x = 1$, so we get a type I^a

$$V = \iint_D (x^2 + y^2) dA$$

$$V = \int_{-2/3}^1 \int_{3x^2}^{x+2} (x^2 + y^2) dy dx$$

To be computed in the next slide.

^aThe region of integration $D = \{(x, y) \mid -\frac{2}{3} \leq x \leq 1, 3x^2 \leq y \leq x + 2\}$

Double integrals over general regions (2/2)

We calculate the integral from the previous slide to find the volume:

$$V = \int_{-2/3}^1 \int_{3x^2}^{x+2} (x^2 + y^2) dy dx = \int_{-2/3}^1 \left[x^2 y + \frac{y^3}{3} \right]_{y=3x^2}^{y=x+2} dx$$

Double integrals over general regions (2/2)

We calculate the integral from the previous slide to find the volume:

$$\begin{aligned} V &= \int_{-2/3}^1 \int_{3x^2}^{x+2} (x^2 + y^2) dy dx = \int_{-2/3}^1 \left[x^2 y + \frac{y^3}{3} \right]_{y=3x^2}^{y=x+2} dx \\ &= \int_{-2/3}^1 \left[x^2(x+2) + \frac{1}{3}(x+2)^3 - x^2 \cdot 3x^2 - \frac{1}{3}(3x^2)^3 \right] dx \end{aligned}$$

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Double integrals over general regions (2/2)

We calculate the integral from the previous slide to find the volume:

$$\begin{aligned} V &= \int_{-2/3}^1 \int_{3x^2}^{x+2} (x^2 + y^2) dy dx = \int_{-2/3}^1 \left[x^2 y + \frac{y^3}{3} \right]_{y=3x^2}^{y=x+2} dx \\ &= \int_{-2/3}^1 \left[x^2(x+2) + \frac{1}{3}(x+2)^3 - x^2 \cdot 3x^2 - \frac{1}{3}(3x^2)^3 \right] dx \\ &= \int_{-2/3}^1 \left[x^3 + 2x^2 + \frac{1}{3}(x^3 + 6x^2 + 12x + 8) - 3x^4 - 9x^6 \right] dx \\ &= \int_{-2/3}^1 \left(-9x^6 - 3x^4 + \frac{4}{3}x^3 + 4x^2 + 4x + \frac{8}{3} \right) dx \end{aligned}$$

Double integrals over general regions (2/2)

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$$\begin{aligned} V &= \int_{-2/3}^1 \int_{3x^2}^{x+2} (x^2 + y^2) dy dx = \int_{-2/3}^1 \left[x^2 y + \frac{y^3}{3} \right]_{y=3x^2}^{y=x+2} dx \\ &= \int_{-2/3}^1 \left[x^2(x+2) + \frac{1}{3}(x+2)^3 - x^2 \cdot 3x^2 - \frac{1}{3}(3x^2)^3 \right] dx \\ &= \int_{-2/3}^1 \left[x^3 + 2x^2 + \frac{1}{3}(x^3 + 6x^2 + 12x + 8) - 3x^4 - 9x^6 \right] dx \\ &= \int_{-2/3}^1 \left(-9x^6 - 3x^4 + \frac{4}{3}x^3 + 4x^2 + 4x + \frac{8}{3} \right) dx \\ &= \left[-\frac{9}{7}x^7 - \frac{3}{5}x^5 + \frac{1}{3}x^4 + \frac{4}{3}x^3 + 2x^2 + \frac{8}{3}x \right]_{-2/3}^1 = \boxed{\frac{3125}{567}} \end{aligned}$$

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So the volume is $\frac{3125}{567}$. **Note:** in this case, the order of integration matters. We have to first integrate w.r.t. y and then x . (Try the other way, it's very hard.)

Order of integration can matter

- **Question:** evaluate $\iint_D e^{y^2} dA$, where the region of integration is $D = \{(x, y) \mid 0 \leq x \leq 1, 5x \leq y \leq 5\}$
- **Step** $-\infty$: write a Type I integral:

$$\iint_D e^{y^2} dA = \int_0^1 \int_{5x}^5 e^{y^2} dy dx$$

³To see this, draw out the (triangular) region on paper

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- **Step 1:** rewrite the region as³ $D = \{(x, y) \mid 0 \leq y \leq 5, 0 \leq x \leq \frac{y}{5}\}$
- **Step 2:** write a Type II integral and solve it:

$$\begin{aligned} \iint_D e^{y^2} dA &= \int_0^5 \int_0^{y/5} e^{y^2} dx dy = \int_0^5 \left[x e^{y^2} \right]_{x=0}^{x=y/5} dy = \frac{1}{5} \int_0^5 y e^{y^2} dy \\ &= \frac{1}{5} \left[\frac{1}{2} e^{y^2} \right]_0^5 = \boxed{\frac{1}{10} (e^{25} - 1)} \end{aligned}$$

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1 Derivatives and applications

- Partial derivatives
- The gradient & directional derivative
- Tangent planes
- Critical points

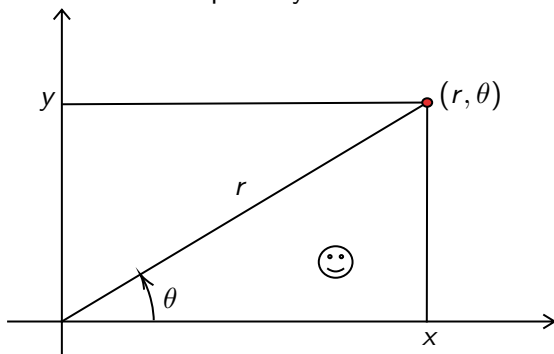
2 Double integrals

- In Cartesian coordinates (x, y)
- In polar coordinates (r, θ)

3 Triple integrals

Polar coordinates (1/2)

Sometimes we need to do integrals using **polar coordinates**. The polar coordinate system uses r for radial distance and θ is the angular coordinate. The polar system looks like this:



We see the important equations for polar coordinates, which we use a lot:

$$x^2 + y^2 = r^2$$

$$x = r \cos \theta$$

$$y = r \sin \theta$$

Polar coordinates (2/2)

Back in normal coordinates, we could just say $dA = dx \, dy$ (or $dA = dy \, dx$). For example:

$$D = \{(x, y) \mid y \leq x \leq y + 2 \wedge 1 \leq y \leq 3\}$$

$$\iint_D f(x, y) \, dA = \int_1^3 \int_y^{y+2} f(x, y) \, dx \, dy$$

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$$D = \{(x, y) \mid y \leq x \leq y + 2 \wedge 1 \leq y \leq 3\}$$

$$\iint_D f(x, y) dA = \int_1^3 \int_y^{y+2} f(x, y) dx \, dy$$

For polar regions, we replace dA with $r \cdot dr \, d\theta$ (or $r \cdot d\theta \, dr$). For example:

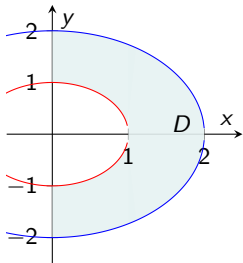
$$D = \{(r, \theta) \mid 1 \leq r \leq 2 \wedge 0 \leq \theta \leq 2\pi\}$$

$$\iint_D f(r, \theta) dA = \int_0^{2\pi} \int_1^2 f(r, \theta) r \, dr \, d\theta$$

IMPORTANT: it is $dA = r \cdot dr \, d\theta$, NOT $dA = dr \, d\theta$. (This factor r is the “Jacobian”, do not forget to write it when doing polar coordinates!)

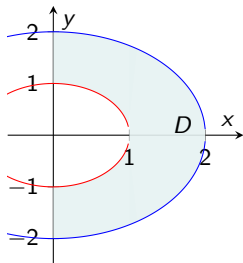
A “polar” integral

- **Question:** calculate the volume of the solid body bounded by the function $z = f(x, y) = x^4 + 2x^2y^2 + y^4$ and the xy -plane above the circular region in the xy -plane given in the plot:



A “polar” integral

- **Question:** calculate the volume of the solid body bounded by the function $z = f(x, y) = x^4 + 2x^2y^2 + y^4$ and the xy -plane above the circular region in the xy -plane given in the plot:

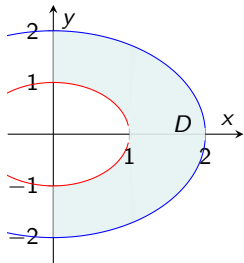


- **Step 1:** we can write the region of the plot as

$$D = \{(r, \theta) \mid 1 \leq r \leq 2 \wedge -\pi/2 \leq \theta \leq \pi/2\}$$

A “polar” integral

- **Question:** calculate the volume of the solid body bounded by the function $z = f(x, y) = x^4 + 2x^2y^2 + y^4$ and the xy -plane above the circular region in the xy -plane given in the plot:



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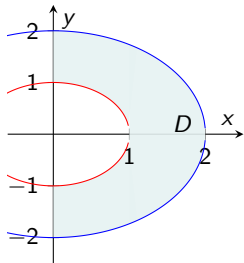
- **Step 2:** we have

$$f(x, y) = x^4 + 2x^2y^2 + y^4 = (x^2 + y^2)^2$$

Using the identity $x^2 + y^2 = r^2$, we see that this is equal to $(r^2)^2 = r^4$.

A “polar” integral

- **Question:** calculate the volume of the solid body bounded by the function $z = f(x, y) = x^4 + 2x^2y^2 + y^4$ and the xy -plane above the circular region in the xy -plane given in the plot:



- **Step 1:** we can write the region of the plot as

$$D = \{(r, \theta) \mid 1 \leq r \leq 2 \wedge -\pi/2 \leq \theta \leq \pi/2\}$$

- **Step 2:** we have

$$f(x, y) = x^4 + 2x^2y^2 + y^4 = (x^2 + y^2)^2$$

Using the identity $x^2 + y^2 = r^2$, we see that this is equal to $(r^2)^2 = r^4$.

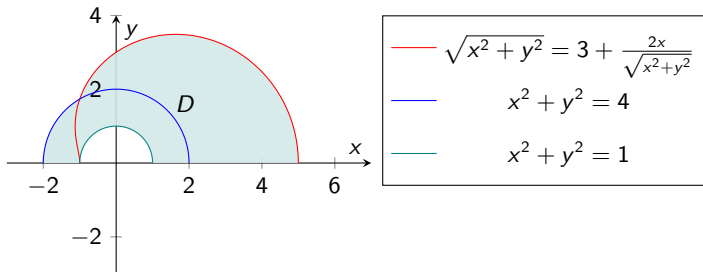
- **Step 3:** set up the integral and solve it (don't forget the extra factor r due to polar coordinates):

$$V = \int_{-\pi/2}^{\pi/2} \int_1^2 r^4 r \, dr \, d\theta = \int_{-\pi/2}^{\pi/2} d\theta \int_1^2 r^5 \, dr = \pi \left[\frac{1}{6} r^6 \right]_1^2 = \boxed{\frac{21}{2} \pi}$$

So the volume is $\frac{21}{2} \pi$.

A harder polar integral (1/4)

- **Question:** calculate the volume of the solid body bounded by the function $z = f(x, y) = y\sqrt{x^2 + y^2}$ and the xy -plane above the shaded region in the xy -plane given in the plot (note: only consider $y \geq 0$):



- **Solution:** next slide

A harder polar integral (2/4)

- Let's first rewrite the equation of the red boundary into polar coordinates (use $x^2 + y^2 = r^2$ and $x = r \cos \theta$):

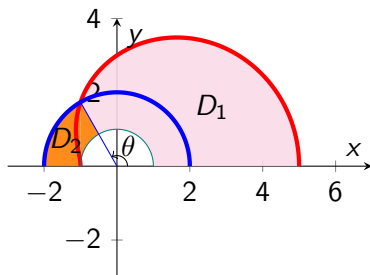
$$\sqrt{x^2 + y^2} = 3 + \frac{2x}{\sqrt{x^2 + y^2}} \rightsquigarrow r = 3 + 2 \cos \theta$$

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$$\sqrt{x^2 + y^2} = 3 + \frac{2x}{\sqrt{x^2 + y^2}} \rightsquigarrow r = 3 + 2 \cos \theta$$

- The other boundaries are just half-circles with radii $r = 1$ and $r = 2$.

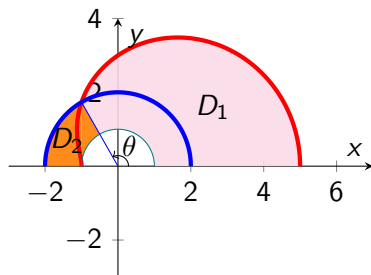


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We need to split the region; see the picture.^a The angle θ as in the picture occurs when $r_{\text{blue}} = r_{\text{red}}$

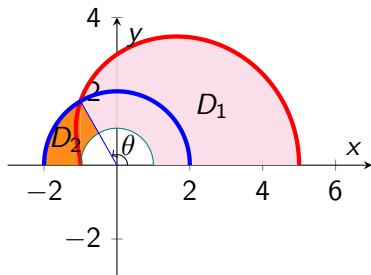
$$2 = 3 + 2 \cos \theta \Rightarrow \cos \theta = -\frac{1}{2}$$

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We need to split the region; see the picture.^a The angle θ as in the picture occurs when $r_{\text{blue}} = r_{\text{red}}$

$$2 = 3 + 2 \cos \theta \Rightarrow \cos \theta = -\frac{1}{2}$$

So we split the integral at $\theta = \frac{2}{3}\pi$.

^aThere are also other ways to split

A harder polar integral (3/4)

In the previous slide, we calculated that the “split angle” is $\theta = \frac{2\pi}{3}$.

A harder polar integral (3/4)

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We can write the region of integration as $D = D_1 \cup D_2$ (with $D_{1,2}$ as in the picture on previous slide, note that these regions do not overlap except at the boundary):

$$D = \{(r, \theta) \mid 0 \leq \theta \leq \frac{2\pi}{3} \wedge 1 \leq r \leq 3 + 2\cos\theta\} \\ \cup \{(r, \theta) \mid \frac{2\pi}{3} \leq \theta \leq \pi \wedge 1 \leq r \leq 2\}$$

A harder polar integral (3/4)

In the previous slide, we calculated that the “split angle” is $\theta = \frac{2\pi}{3}$.

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We obtain (since $z = f(x, y) = y\sqrt{x^2 + y^2} = (r \sin \theta)r = r^2 \sin \theta$)

$$V = \iint_D f(x, y) dA = \iint_{D_1} f(x, y) dA + \iint_{D_2} f(x, y) dA \\ = \int_0^{2\pi/3} \int_1^{3+2 \cos \theta} (r^2 \sin \theta) r dr d\theta + \int_{2\pi/3}^{\pi} \int_1^2 (r^2 \sin \theta) r dr d\theta$$

To be computed in the next slide.

A harder polar integral (4/4)

$$V = \int_0^{2\pi/3} \int_1^{3+2\cos\theta} (r^2 \sin\theta) r \, dr \, d\theta + \int_{2\pi/3}^{\pi} \int_1^2 (r^2 \sin\theta) r \, dr \, d\theta$$

A harder polar integral (4/4)

$$\begin{aligned} V &= \int_0^{2\pi/3} \int_1^{3+2\cos\theta} (r^2 \sin\theta) r \, dr \, d\theta + \int_{2\pi/3}^{\pi} \int_1^2 (r^2 \sin\theta) r \, dr \, d\theta \\ &\quad (* \text{ Rewrite integral, see next slide for detailed explanation } *) \\ &= \int_0^{2\pi/3} \sin\theta \int_1^{3+2\cos\theta} r^3 \, dr \, d\theta + \int_{2\pi/3}^{\pi} \sin\theta \, d\theta \int_1^2 r^3 \, dr \end{aligned}$$

A harder polar integral (4/4)

$$V = \int_0^{2\pi/3} \int_1^{3+2\cos\theta} (r^2 \sin\theta) r \, dr \, d\theta + \int_{2\pi/3}^{\pi} \int_1^2 (r^2 \sin\theta) r \, dr \, d\theta$$

(* Rewrite integral, see next slide for detailed explanation *)

$$= \int_0^{2\pi/3} \sin\theta \int_1^{3+2\cos\theta} r^3 \, dr \, d\theta + \int_{2\pi/3}^{\pi} \sin\theta \, d\theta \int_1^2 r^3 \, dr$$

$$= \int_0^{2\pi/3} \sin\theta \left[\frac{r^4}{4} \right]_1^{3+2\cos\theta} d\theta + \left([-\cos\theta]_{2\pi/3}^{\pi} \left[\frac{r^4}{4} \right]_1^2 \right)$$

A harder polar integral (4/4)

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(* Rewrite integral, see next slide for detailed explanation *)

$$\begin{aligned} &= \int_0^{2\pi/3} \sin\theta \int_1^{3+2\cos\theta} r^3 \, dr \, d\theta + \int_{2\pi/3}^{\pi} \sin\theta \, d\theta \int_1^2 r^3 \, dr \\ &= \int_0^{2\pi/3} \sin\theta \left[\frac{r^4}{4} \right]_1^{3+2\cos\theta} d\theta + \left([-\cos\theta]_{2\pi/3}^{\pi} \left[\frac{r^4}{4} \right]_1^2 \right) \\ &= \frac{1}{4} \int_0^{2\pi/3} \sin\theta \left((3+2\cos\theta)^4 - 1 \right) d\theta + \left([-\cos\theta]_{2\pi/3}^{\pi} \left[\frac{r^4}{4} \right]_1^2 \right) \end{aligned}$$

A harder polar integral (4/4)

$$V = \int_0^{2\pi/3} \int_1^{3+2\cos\theta} (r^2 \sin\theta) r \, dr \, d\theta + \int_{2\pi/3}^{\pi} \int_1^2 (r^2 \sin\theta) r \, dr \, d\theta$$

(* Rewrite integral, see next slide for detailed explanation *)

$$= \int_0^{2\pi/3} \sin\theta \int_1^{3+2\cos\theta} r^3 \, dr \, d\theta + \int_{2\pi/3}^{\pi} \sin\theta \, d\theta \int_1^2 r^3 \, dr$$

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(* Antiderivative of $(\sin\theta)(3+2\cos\theta)^4$ can be found by subbing $u = 3+2\cos\theta$ *)

$$= \frac{1}{4} \left[-\frac{1}{10} (3+2\cos\theta)^5 + \cos\theta \right]_0^{2\pi/3} + \frac{15}{8} = \frac{1}{4} \left(-\frac{37}{10} + \frac{3115}{10} \right) + \frac{15}{8} = \boxed{\frac{3153}{40}}$$

A harder polar integral (4/4)

$$V = \int_0^{2\pi/3} \int_1^{3+2\cos\theta} (r^2 \sin\theta) r \, dr \, d\theta + \int_{2\pi/3}^{\pi} \int_1^2 (r^2 \sin\theta) r \, dr \, d\theta$$

(* Rewrite integral, see next slide for detailed explanation *)

$$= \int_0^{2\pi/3} \sin\theta \int_1^{3+2\cos\theta} r^3 \, dr \, d\theta + \int_{2\pi/3}^{\pi} \sin\theta \, d\theta \int_1^2 r^3 \, dr$$

$$= \int_0^{2\pi/3} \sin\theta \left[\frac{r^4}{4} \right]_1^{3+2\cos\theta} d\theta + \left([-\cos\theta]_{2\pi/3}^{\pi} \left[\frac{r^4}{4} \right]_1^2 \right)$$

$$= \frac{1}{4} \int_0^{2\pi/3} \sin\theta \left((3+2\cos\theta)^4 - 1 \right) d\theta + \left([-\cos\theta]_{2\pi/3}^{\pi} \left[\frac{r^4}{4} \right]_1^2 \right)$$

(* Antiderivative of $(\sin\theta)(3+2\cos\theta)^4$ can be found by subbing $u = 3+2\cos\theta$ *)

$$= \frac{1}{4} \left[-\frac{1}{10} (3+2\cos\theta)^5 + \cos\theta \right]_0^{2\pi/3} + \frac{15}{8} = \frac{1}{4} \left(-\frac{37}{10} + \frac{3115}{10} \right) + \frac{15}{8} = \boxed{\frac{3153}{40}}$$

So the volume is $\frac{3153}{40}$.

“Factoring” integrals

In the last slide, we got the integral

$$\int_{2\pi/3}^{\pi} \int_1^2 (r^2 \sin \theta) r dr d\theta$$

This looks like a hard integral, but in fact it is easy when realized that it can be split into a separate r -integral and θ -integral.

This is because we can take constant factors out of an integral. The nice thing is that e.g. $\sin \theta$ is **also** a constant factor when integrating over r .

Similarly, $\int_1^2 r^3 dr$ itself is a perfectly valid constant factor. We then see:

$$\int_{2\pi/3}^{\pi} \int_1^2 \overbrace{(r^2 \sin \theta)}^{\text{const}} r dr d\theta = \int_{2\pi/3}^{\pi} \sin \theta \overbrace{\int_1^2 r^3 dr}^{\text{const}} d\theta = \left(\int_{2\pi/3}^{\pi} \sin \theta d\theta \right) \left(\int_1^2 r^3 dr \right)$$

Which is the product of two straightforward integrals.

1 Derivatives and applications

- Partial derivatives
- The gradient & directional derivative
- Tangent planes
- Critical points

2 Double integrals

- In Cartesian coordinates (x, y)
- In polar coordinates (r, θ)

3 Triple integrals

Triple integrals

Observation:

Triple integrals have appeared in the homework, but not in past exams (at least not in the ones found on Cover).

The coming slides discuss triple integrals.

(I'm not saying you won't get a triple integral on your exam...)

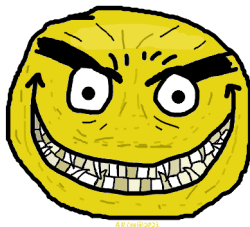
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When the region of integration is a box $E = [a, b] \times [c, d] \times [r, s]$, then:

$$\iiint_E f(x, y, z) dV = \int_a^b \int_c^d \int_r^s f(x, y, z) dz dy dx$$

(all 6 orders of integration are possible, in case of a box, since the bounds of the variables do not depend on each other)

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We can also take triple integrals over general regions. For example:

$$E = \{(x, y, z) \mid 0 \leq y \leq 3, 0 \leq x \leq y^2, 0 \leq z \leq xy + 1\}$$

$$\Rightarrow \iiint_E f(x, y, z) dV = \int_0^3 \int_0^{y^2} \int_0^{xy+1} f(x, y, z) dz dx dy$$

Example triple integral

Question: evaluate $\int_0^3 \int_0^{z^2} \int_0^{y-z} (3x - 2y) dx dy dz$.

Solution:

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$$\int_0^3 \int_0^{z^2} \int_0^{y-z} (3x - 2y) dx dy dz = \int_0^3 \int_0^{z^2} \left[\frac{3}{2}x^2 - 2xy \right]_{x=0}^{x=y-z} dy dz$$

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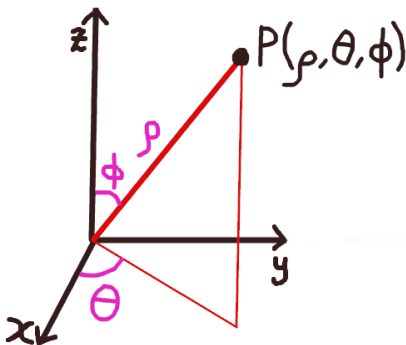
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Spherical coordinates

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In the 2D world, we have polar coordinates. In 3D, we have **spherical coordinates** (ρ, θ, ϕ) . They look like this:



ρ (rho) is the radial distance, θ (theta) is the *azimuthal angle*, and ϕ (phi) is the *polar angle*.

Integration in spherical coordinates

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For spherical coordinates, we have:

$$x = \rho \sin \phi \cos \theta \quad y = \rho \sin \phi \sin \theta \quad z = \rho \cos \phi$$

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Note: the slides use the convention of the book, where ρ is the radial distance, θ is the azimuthal angle and ϕ is the polar angle. However, some sources swap the meanings of θ and ϕ and/or write r instead of ρ , so be aware of that.

Example integral in spherical coordinates (1/2)

Question: evaluate $\iiint_E x e^{x^2+y^2+z^2} dV$, where E is the region with $x^2 + y^2 + z^2 \leq 4$ and $0 \leq y \leq x$.

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Step 1: do geometry; write E in spherical coordinates:

$$E = \left\{ (\rho, \theta, \phi) \mid 0 \leq \rho \leq 2, 0 \leq \theta \leq \frac{\pi}{4}, -\frac{\pi}{2} \leq \phi \leq \frac{\pi}{2} \right\}$$

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Step 2: since $x = \rho \sin \phi \cos \theta$ and $x^2 + y^2 + z^2 = \rho^2$ in spherical coordinates, we can rewrite the integrand as $\rho \sin \phi \cos \theta e^{\rho^2}$.

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Step 3: set up the integral. Do not forget the Jacobian $\rho^2 \sin \phi$ for spherical coordinates!

$$\begin{aligned} \iiint_E x e^{x^2+y^2+z^2} dV &= \int_{-\pi/2}^{\pi/2} \int_0^{\pi/4} \int_0^2 \rho \sin \phi \cos \theta e^{\rho^2} \rho^2 \sin \phi d\rho d\theta d\phi \\ &= \left(\int_{-\pi/2}^{\pi/2} \sin^2 \phi d\phi \right) \left(\int_0^{\pi/4} \cos \theta d\theta \right) \left(\int_0^2 \rho^3 e^{\rho^2} d\rho \right) \end{aligned}$$

We were able to write the long integral as a product of three single-variable integrals by using the idea from slide 33.

Example integral in spherical coordinates (2/2)

Step 4: solve the integral.

$$\iiint_E x e^{x^2+y^2+z^2} dV = \left(\int_{-\pi/2}^{\pi/2} \sin^2 \phi d\phi \right) \left(\int_0^{\pi/4} \cos \theta d\theta \right) \left(\int_0^2 \rho^3 e^{\rho^2} d\rho \right)$$

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The red one can be solved by subbing $u = \rho^2$ (such that $du = 2\rho d\rho$), followed by integration by parts:

$$\int_0^2 \rho^3 e^{\rho^2} d\rho = \frac{1}{2} \int_0^2 u e^u du = \frac{1}{2} \left([u e^u]_0^4 - \int_0^4 e^u du \right) = \frac{1}{2} (4e^4 - (e^4 - 1)) = \frac{3e^4 + 1}{2}$$

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The green one can be solved by using $\sin^2 \phi = \frac{1}{2} (1 - \cos 2\phi)$:

$$\int_{-\pi/2}^{\pi/2} \sin^2 \phi d\phi = \frac{1}{2} \int_{-\pi/2}^{\pi/2} (1 - \cos 2\phi) d\phi = \frac{\pi}{2} - \frac{1}{2} \left[\frac{1}{2} \sin 2\phi \right]_{-\pi/2}^{\pi/2} = \frac{\pi}{2}$$

Example integral in spherical coordinates (2/2)

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The orange one is relatively straightforward, so the answer is:

$$\iiint_E x e^{x^2+y^2+z^2} dV = \left(\frac{\pi}{2} \right) \left(\frac{1}{2} \sqrt{2} \right) \left(\frac{3e^2 + 1}{2} \right) = \boxed{\frac{\pi\sqrt{2}}{8} (3e^2 + 1)}$$

P.S. The need to use substitution, integration by parts and a trigonometric identity makes this question harder than exam-level (no warranty).