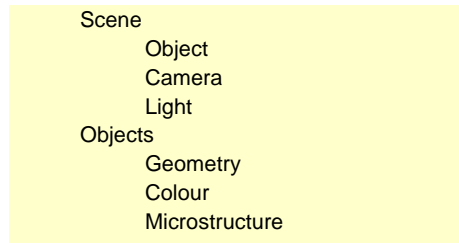
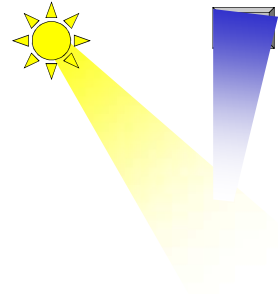


Object rendering Overview



Rendering: setting up the scene

- Given
 - Object surfaces
 - Light sources
 - Camera
- Compute
 - Colour of each pixel on the screen
 - This is colour that bounces off the surface point and goes in the direction of the camera (viewer)



Object

- Geometry
 - Structure ✓
 - Surface orientation (normal vectors)
- Microstructure
 - Shiny
 - Matt
 - Textured
- Colour
- Transparency

Light

- Location
 - w.r.t object
 - w.r.t. camera
- Sources
 - Ambient
 - Directional: diffuse
 - Directional: point source
 - Divergence
- Colour

Camera

- Position w.r.t. object
- Direction of view
 - Angle of view
 - Tilt (up-vector)
 } Camera viewing
- Magnification (zoom)
 - Projection (parallel / perspective)
 } Projection

Relationships between the entities

Camera			
	Position	View	Proj.
Position	X	X	
Direction		X	
Colour			

Object			
	Orient.	Microstr.	Colour.
Position	X		X
Direction	X	X	X
Colour			X

Camera			
	Position	View	Proj.
Orient	X	X	X
Microstr			
Colour			

Topics for the next lectures

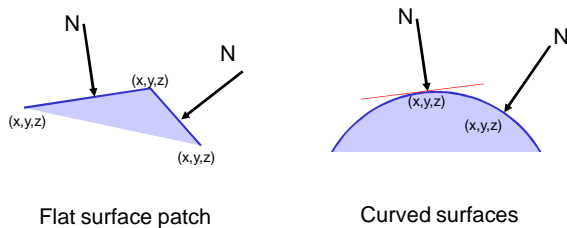
- Surface orientation – normal vectors
- Lighting
- Surface shading algorithms
- Colour and colour representations
- Revision of the above
- Viewing and projections

Normal vectors

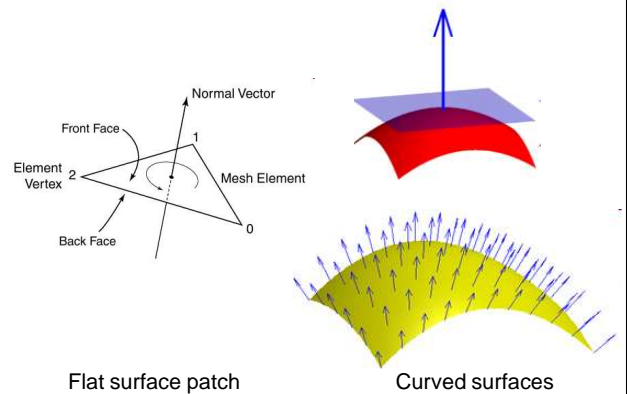
- What they are
- How to compute them

Normal vectors

- Normal vector = vector perpendicular to the face



Normal vectors

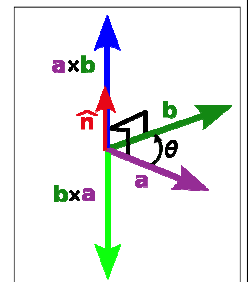


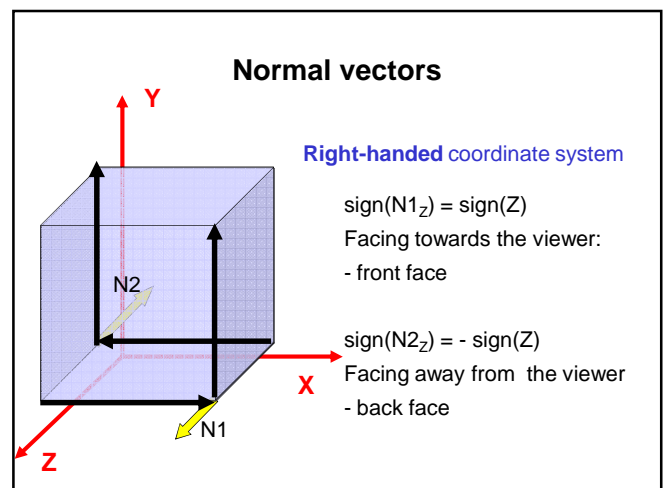
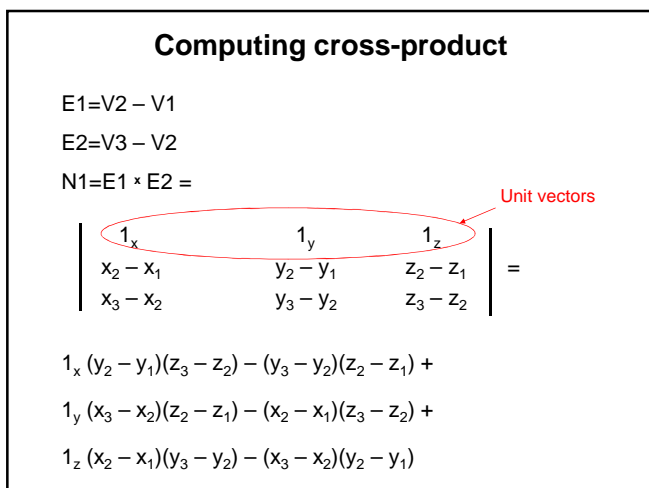
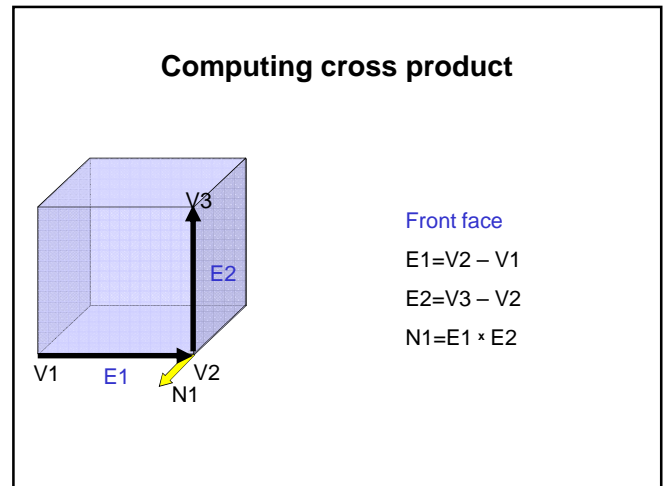
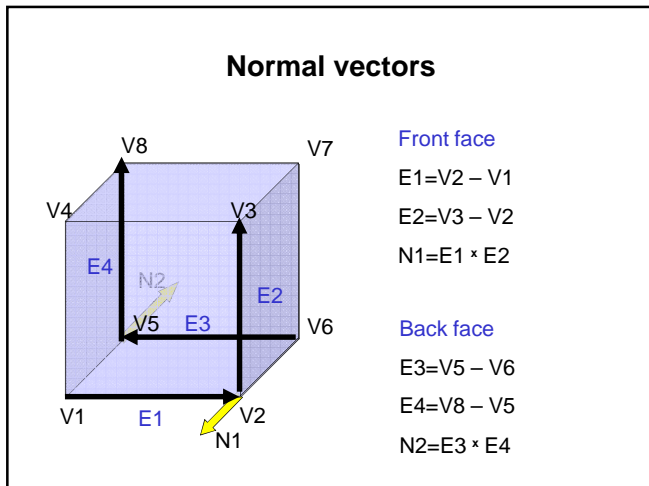
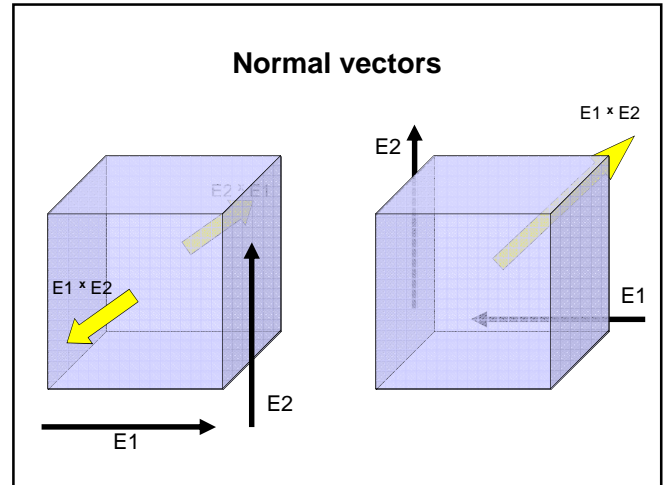
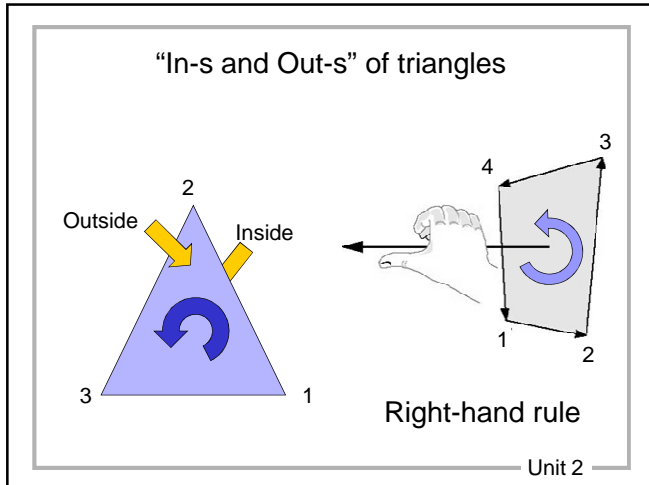
Surface normal vectors - uses

- Surface visibility (\rightarrow hidden surface removal)
- Surface shading
- Surface texture

Normal vectors

- Computing normal vectors
 - A cross-product of two vectors is a vector perpendicular (orthogonal, normal) to both input vectors
if $n = a \times b$, $n \perp a$ and $n \perp b$
- Cross product is NOT commutative:
 $a \times b \neq b \times a$
although both cross-products are orthogonal to a and b





Surface visibility from surface normal

$$E1 = V2 - V1$$

$$E2 = V3 - V2$$

$$N1 = E1 \times E2 =$$

$$\begin{vmatrix} 1_x & 1_y & 1_z \\ x_2 - x_1 & y_2 - y_1 & z_2 - z_1 \\ x_3 - x_2 & y_3 - y_2 & z_3 - z_2 \end{vmatrix} =$$

Unit vectors

$$1_x (y_2 - y_1)(z_3 - z_2) - (y_3 - y_2)(z_2 - z_1) +$$

$$1_y (x_3 - x_2)(z_2 - z_1) - (x_2 - x_1)(z_3 - z_2) +$$

$$1_z (x_2 - x_1)(y_3 - y_2) - (x_3 - x_2)(y_2 - y_1) \leftarrow N_z$$

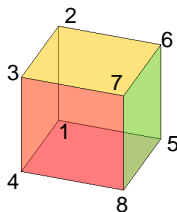
Surface visibility from surface normal

- In a right-handed coordinate system a surface visible to the viewer will have positive value of z-coordinate of the normal vector: $N_z > 0$
- Render only the visible surfaces facing the viewer

Vertices

V1	0	0	0
V2	0	1	0
V3	0	1	1
V4	0	0	1
V5	1	0	0
V6	1	1	0
V7	1	1	1
V8	1	0	1

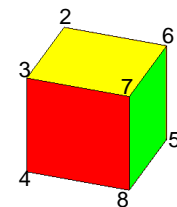
Example



Faces

F1	1	2	6	5	+
F2	5	6	7	8	+
F3	3	4	8	7	-
F4	1	4	3	2	-
F5	1	5	8	4	-
F6	2	3	7	6	+

sign N_z



Homework



- In the cube defined by homogeneous vertices in the vertex table V and faces in the face table F, demonstrate that face F2 is visible and face F4 is not visible in the right-handed coordinate system.
- Given the same vertex table V and the face table F, would it be the case in the left-handed coordinate system?

Vertices

V1	0.00	0.00	0.00	1.00
V2	0.00	1.00	0.00	1.00
V3	-0.26	1.00	0.97	1.00
V4	-0.26	0.00	0.97	1.00
V5	0.97	0.00	0.26	1.00
V6	0.97	1.00	0.26	1.00
V7	0.71	1.00	1.22	1.00
V8	0.71	0.00	1.22	1.00

Faces

F1	1	2	6	5
F2	5	6	7	8
F3	3	4	8	7
F4	1	4	3	2
F5	1	5	8	4
F6	2	3	7	6

Next lecture

Illumination and shading

Credits

http://www.absoluteastronomy.com/topics/Surface_normal

<http://commons.wikimedia.org/wiki/File:Crossproduct.png>