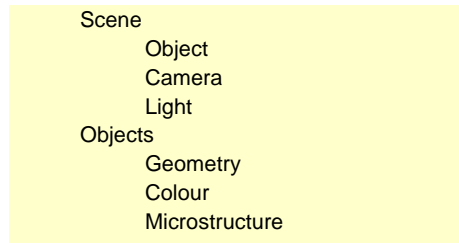
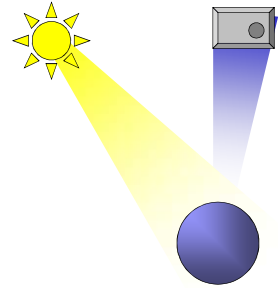


Object rendering Overview



Rendering: setting up the scene

- Given
 - Object surfaces
 - Light sources
 - Camera
- Compute
 - Colour of each pixel on the screen
 - This is colour that bounces off the surface point and goes in the direction of the camera (viewer)



Object

- Geometry
 - Structure ✓
 - Surface orientation (normal vectors)
- Colour
- Microstructure
 - Shiny
 - Matt
 - Textured
- Transparency

Light

- Location
 - w.r.t object
 - w.r.t. camera
- Sources
 - Ambient
 - Directional: diffuse
 - Directional: point source
 - Divergence
- Colour

Camera

- Position w.r.t. object
 - Direction of view
 - Angle of view
 - Tilt (up-vector)
- } Camera viewing
- Magnification (zoom)
 - Projection (parallel / perspective)
- } Projection

Relationships between the entities

Camera			
	Posit ion	View	Proj.
Posit ion	X	X	
Dire ction		X	
Colo ur			

Object			
	Orie nt.	Micr ostr	Colo ur
Posit ion	X		X
Dire ction	X	X	X
Colo ur			X

Camera			
	Posit ion	View	Proj.
Orie nt	X	X	X
Micr ostr			
Colo ur			

Topics for the next lectures

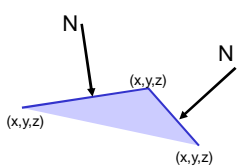
- Surface orientation – normal vectors
- Lighting
- Surface shading algorithms
- Colour and colour representations
- Viewing and projections

Normal vectors

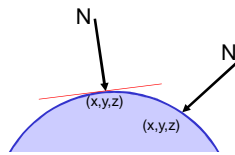
- What they are
- How to compute them

Normal vectors

- Normal vector = vector perpendicular to the face

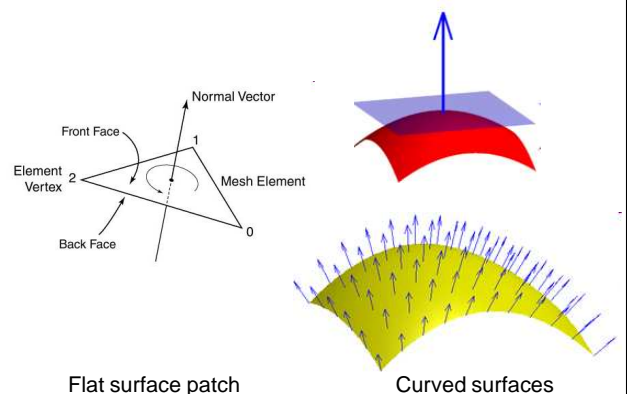


Flat surface patch



Curved surfaces

Normal vectors



Flat surface patch

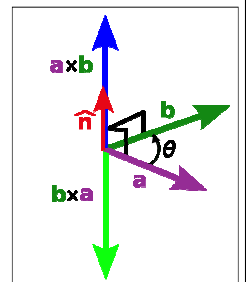
Curved surfaces

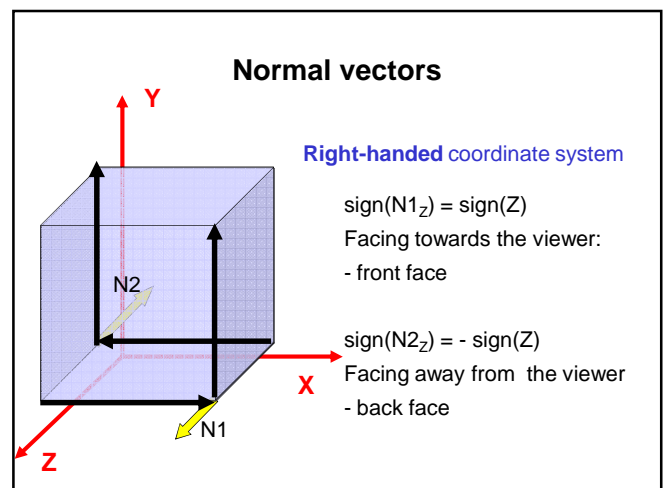
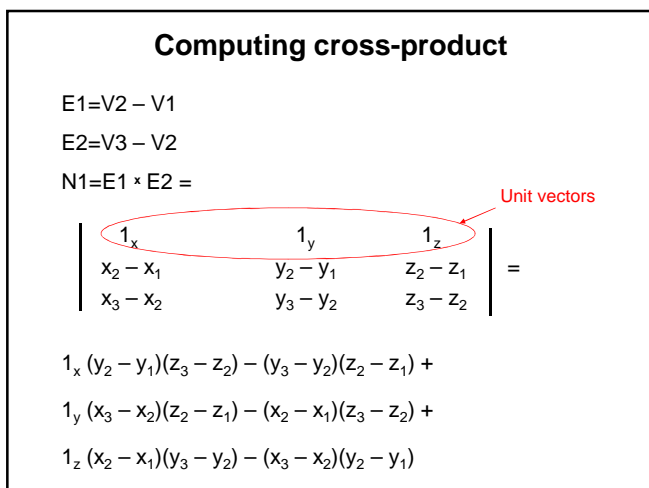
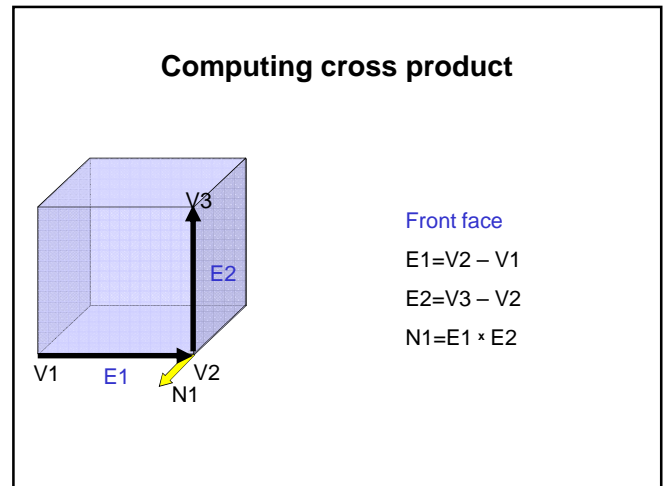
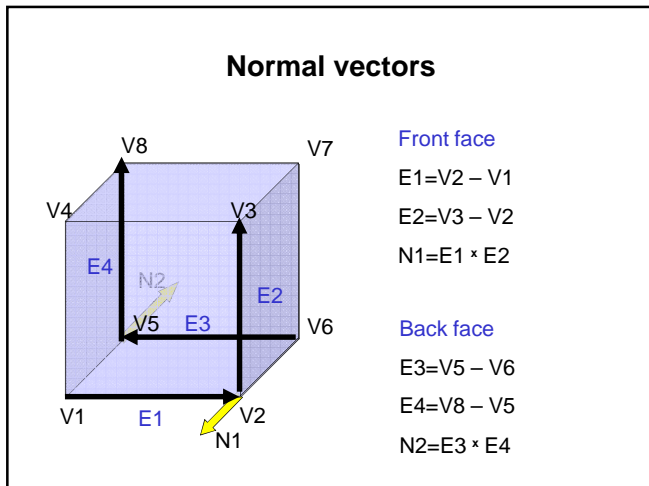
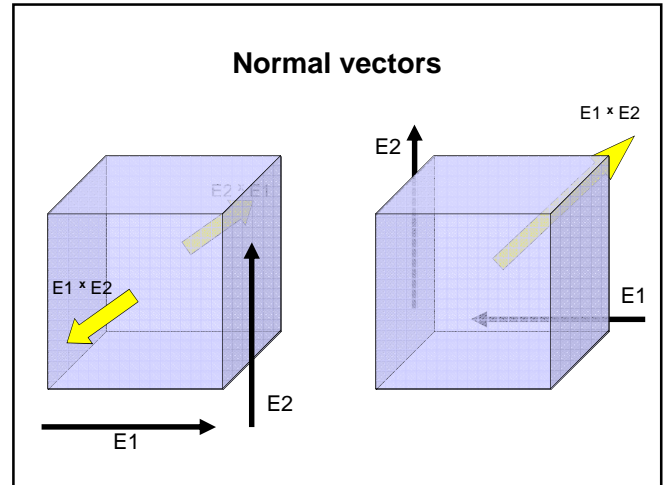
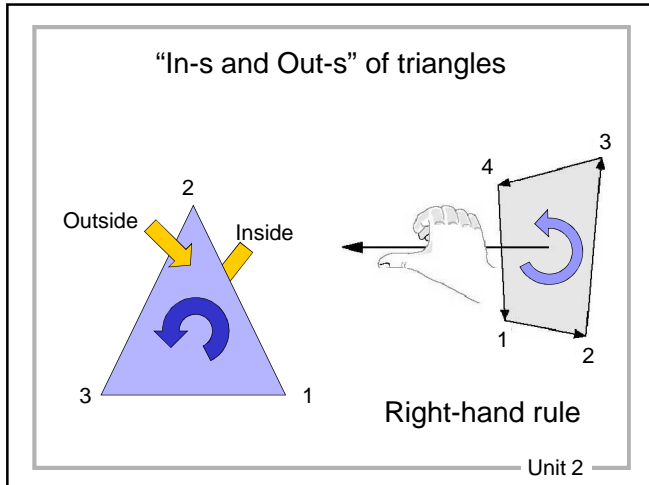
Surface normal vectors - uses

- Surface visibility (\rightarrow hidden surface removal)
- Surface shading
- Surface texture

Normal vectors

- Computing normal vectors
 - A cross-product of two vectors is a vector perpendicular (orthogonal, normal) to both input vectors
if $n = a \times b$, $n \perp a$ and $n \perp b$
- Cross product is NOT commutative:
 - $a \times b \neq b \times a$
 - although both cross-products are orthogonal to a and b





Surface visibility from surface normal

$$E1 = V2 - V1$$

$$E2 = V3 - V2$$

$$N1 = E1 \times E2 =$$

$$\begin{vmatrix} 1_x & 1_y & 1_z \\ x_2 - x_1 & y_2 - y_1 & z_2 - z_1 \\ x_3 - x_2 & y_3 - y_2 & z_3 - z_2 \end{vmatrix} =$$

Unit vectors

$$1_x (y_2 - y_1)(z_3 - z_2) - (y_3 - y_2)(z_2 - z_1) +$$

$$1_y (x_3 - x_2)(z_2 - z_1) - (x_2 - x_1)(z_3 - z_2) +$$

$$1_z (x_2 - x_1)(y_3 - y_2) - (x_3 - x_2)(y_2 - y_1) \leftarrow N_z$$

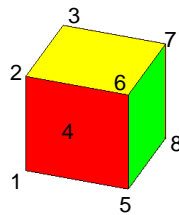
Surface visibility from surface normal

- In right-handed coordinate system an outer (visible) surface will have positive value of z-coordinate of the normal vector: $N_z > 0$
- Render only the visible surfaces facing the viewer

Vertices

V1	0	0	0
V2	0	1	0
V3	0	1	1
V4	0	0	1
V5	1	0	0
V6	1	1	0
V7	1	1	1
V8	1	0	1

Example



Faces

Faces	1	2	3	4	5	sign N_z
F1	1	5	6	2	1	+
F2	2	6	7	3	2	+
F3	3	7	8	4	3	-
F4	4	8	5	1	4	-
F5	1	2	3	4	1	-
F6	8	7	6	5	8	+

Homework



- In the cube defined by vertices and faces in the previous slide, demonstrate that face F2 is visible and face F4 is not visible in the left-handed coordinate system.

Next lecture

Illumination and shading

Credits

http://www.absoluteastronomy.com/topics/Surface_normal

<http://commons.wikimedia.org/wiki/File:Crossproduct.png>