



$$\alpha = (\vec{z}_0, \vec{z}_1)$$

$$\alpha_1 = (\vec{x}_0, \vec{x}_1)$$

$$\theta_1 = (\vec{z}_0, \vec{z}_4)$$

$$\overrightarrow{OA_1} = -a\vec{x}_0 - b\vec{z}_0$$

$$\overrightarrow{A_1B_1} = \lambda_1\vec{z}_4$$

$$\overrightarrow{OB_1} = L\vec{x}_1$$