

Zubov's method for interconnected systems

Fabian Wirth

Institute of Mathematics
University of Würzburg

SADCO - Kick off meeting
Paris, March, 1–2 2011.

joint work with:
Fabio Camilli (L'Aquila) and Lars Grüne (Bayreuth)



Zubov's Method

The domain of attraction

Zubov's equation

Robust domains of attraction

Problem statement

A robust version of Zubov's theorem

Examples

Interconnected Systems

ISS and Lyapunov functions

Zubov's Method and Interconnected Systems



The domain of attraction

Consider a nonlinear system

$$\begin{aligned}\dot{x} &= f(x) \\ x(0) &= x_0 \in \mathbb{R}^n,\end{aligned}\tag{1}$$

f Lipschitz continuous, $f(0) = 0$.

Assume $x^* = 0$ is **asymptotically stable**.



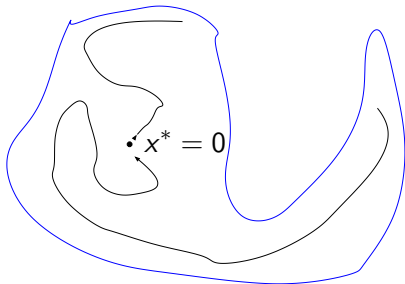
The domain of attraction

Consider a nonlinear system

$$\begin{aligned}\dot{x} &= f(x) \\ x(0) &= x_0 \in \mathbb{R}^n,\end{aligned}\tag{1}$$

f Lipschitz continuous, $f(0) = 0$.

Assume $x^* = 0$ is **asymptotically stable**.



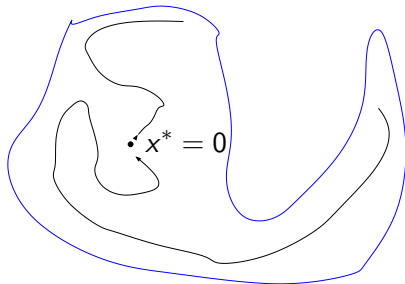
The domain of attraction

Consider a nonlinear system

$$\begin{aligned}\dot{x} &= f(x) \\ x(0) &= x_0 \in \mathbb{R}^n,\end{aligned}\tag{1}$$

f Lipschitz continuous, $f(0) = 0$.

Assume $x^* = 0$ is **asymptotically stable**.



The **domain of attraction** of 0 is defined by

$$\mathcal{A}(0) := \{x \in \mathbb{R}^n \mid \varphi(t; x) \rightarrow 0, \text{ as } t \rightarrow \infty\}.$$

Here $\varphi(\cdot; x)$ denotes the solution of (1).



Zubov's result (1956)

$$\dot{x} = f(x) \quad (1)$$

$$f(0) = 0, \quad x^* = 0 \quad \text{is asymptotically stable.} \quad (2)$$

Theorem

A set A containing 0 in its interior is the domain of attraction of (1) if and only if



Zubov's result (1956)

$$\dot{x} = f(x) \quad (1)$$

$$f(0) = 0, \quad x^* = 0 \quad \text{is asymptotically stable.} \quad (2)$$

Theorem

A set A containing 0 in its interior is the domain of attraction of (1) if and only if there exist continuous functions V, h such that



Zubov's result (1956)

$$\dot{x} = f(x) \quad (1)$$

$$f(0) = 0, \quad x^* = 0 \quad \text{is asymptotically stable.} \quad (2)$$

Theorem

A set A containing 0 in its interior is the domain of attraction of (1) if and only if there exist continuous functions V, h such that

- ▶ $V(0) = h(0) = 0,$
 $0 < V(x) < 1$ for $x \in A \setminus \{0\}, h > 0$ on $\mathbb{R}^n \setminus \{0\}$



Zubov's result (1956)

$$\dot{x} = f(x) \quad (1)$$

$$f(0) = 0, \quad x^* = 0 \quad \text{is asymptotically stable.} \quad (2)$$

Theorem

A set A containing 0 in its interior is the domain of attraction of (1) if and only if there exist continuous functions V, h such that

- ▶ $V(0) = h(0) = 0,$
 $0 < V(x) < 1$ for $x \in A \setminus \{0\}, h > 0$ on $\mathbb{R}^n \setminus \{0\}$
- ▶ $V(x_n) \rightarrow 1$ for $x_n \rightarrow \partial A$ or $\|x_n\| \rightarrow \infty,$



Zubov's result (1956)

$$\dot{x} = f(x) \quad (1)$$

$$f(0) = 0, \quad x^* = 0 \quad \text{is asymptotically stable.} \quad (2)$$

Theorem

A set A containing 0 in its interior is the domain of attraction of (1) if and only if there exist continuous functions V, h such that

- ▶ $V(0) = h(0) = 0,$
 $0 < V(x) < 1$ for $x \in A \setminus \{0\}, h > 0$ on $\mathbb{R}^n \setminus \{0\}$
- ▶ $V(x_n) \rightarrow 1$ for $x_n \rightarrow \partial A$ or $\|x_n\| \rightarrow \infty,$

▶ $DV(x) \cdot f(x) = -h(x)(1 - V(x))\sqrt{1 + \|f(x)\|^2}$



Robust domains of attraction

Consider systems

$$\dot{x}(t) = f(x(t), d(t)), \quad t \in \mathbb{R}$$

with a perturbation term d . We are interested in robust stability properties. In particular, the **robust domain of attraction**.

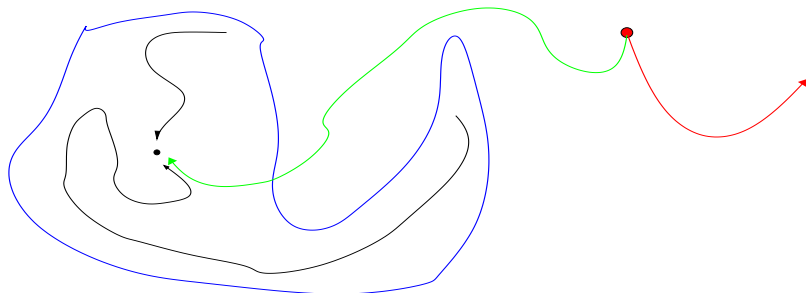


Robust domains of attraction

Consider systems

$$\dot{x}(t) = f(x(t), d(t)), \quad t \in \mathbb{R}$$

with a perturbation term d . We are interested in robust stability properties. In particular, the **robust domain of attraction**.



Robust domains of attraction

$$\dot{x}(t) = f(x(t), d(t)), \quad t \in \mathbb{R}$$

Assumptions:

- $f : \mathbb{R}^n \times D \rightarrow \mathbb{R}^n$ continuous, locally Lipschitz continuous in x , uniformly in d
- $D \subset \mathbb{R}^m$ compact, convex, $d(t) \in D$ a.e.



Robust domains of attraction

$$\dot{x}(t) = f(x(t), d(t)), \quad t \in \mathbb{R}$$

Assumptions:

- $f : \mathbb{R}^n \times D \rightarrow \mathbb{R}^n$ continuous, locally Lipschitz continuous in x , uniformly in d
- $D \subset \mathbb{R}^m$ compact, convex, $d(t) \in D$ a.e.
- $f(0, d) = 0$ for all $d \in D$
- 0 is locally uniformly asymptotically stable

Notation: $\mathcal{D} := \{d : \mathbb{R} \rightarrow D ; d \text{ Lebesgue measurable}\}$



Robust domains of attraction

$$\dot{x}(t) = f(x(t), d(t)), \quad t \in \mathbb{R}$$

Assumptions:

- $f : \mathbb{R}^n \times D \rightarrow \mathbb{R}^n$ continuous, locally Lipschitz continuous in x , uniformly in d
- $D \subset \mathbb{R}^m$ compact, convex, $d(t) \in D$ a.e.
- $f(0, d) = 0$ for all $d \in D$
- 0 is locally uniformly asymptotically stable

Notation: $\mathcal{D} := \{d : \mathbb{R} \rightarrow D ; d \text{ Lebesgue measurable}\}$

$$\mathcal{A}_D(0) := \{x \in \mathbb{R}^n \mid \phi(t; x, d) \rightarrow 0 \forall d \in \mathcal{D}\}$$



A robust version of Zubov's theorem

Theorem:[Zubov's theorem for perturbed systems, SICON 2001]

Under suitable growth conditions on g there is a unique viscosity solution of

$$\begin{cases} \inf_{d \in D} \{-Dv(x)f(x, d) - (1 - v(x))g(x, d)\} = 0 \\ v(0) = 0 \end{cases}$$

The robust domain of attraction satisfies

$$\mathcal{A}_D(0) = v^{-1}([0, 1)).$$



Example

$$\begin{aligned}\dot{x}_1 &= -x_1 + x_2 \\ \dot{x}_2 &= 0.1x_1 - 2x_2 - x_1^2 - 0.1x_1^3\end{aligned}$$

Fixed points:

$[0, 0]$, unstable

$[-2.5505, -2.5505]$, asymptotically stable

$[-7.4495, -7.4495]$, asymptotically stable.

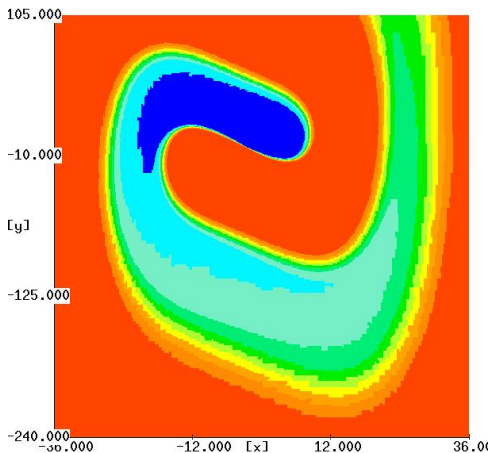


Example

$$\dot{x}_1 = -x_1 + x_2$$

$$\dot{x}_2 = 0.1x_1 - 2x_2 - x_1^2 - (0.1 + d(t))x_1^3$$

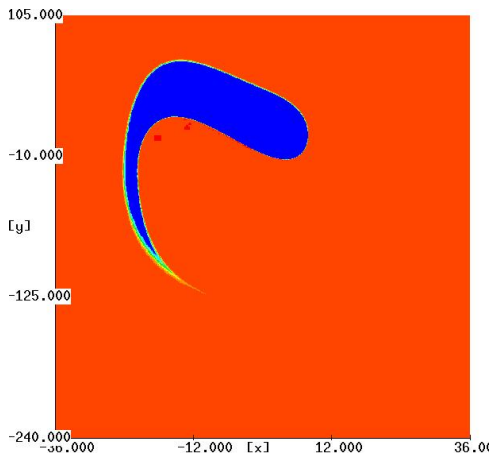
$$D = \{0\}$$



Example

$$\begin{aligned}
 \dot{x}_1 &= -x_1 + x_2 \\
 \dot{x}_2 &= 0.1x_1 - 2x_2 - x_1^2 \\
 &\quad - (0.1 + d(t))x_1^3
 \end{aligned}$$

$$D = [-0.02, 0.02]$$



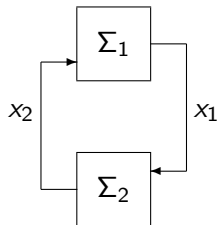
Interconnection of two systems

Consider

$$\Sigma_1 : \dot{x}_1 = f_1(x_1, x_2)$$

$$\Sigma_2 : \dot{x}_2 = f_2(x_1, x_2)$$

$$f_i : \mathbb{R}^{N_1+N_2+N_u} \rightarrow \mathbb{R}^{N_i}$$



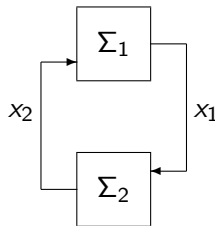
Interconnection of two systems

Consider

$$\Sigma_1 : \dot{x}_1 = f_1(x_1, x_2)$$

$$\Sigma_2 : \dot{x}_2 = f_2(x_1, x_2)$$

$$f_i : \mathbb{R}^{N_1+N_2+N_u} \rightarrow \mathbb{R}^{N_i}$$



with two **Lyapunov functions** such that

$$V_1(x_1) > \gamma_{12}(V_2(x_2)) \Rightarrow \dot{V}_1 < -\alpha_1(\|x_1\|)$$

$$V_2(x_2) > \gamma_{21}(V_1(x_1)) \Rightarrow \dot{V}_2 < -\alpha_2(\|x_2\|)$$



◀ ◻ ▶ ◀ ◻ ▶ ◀ ≡ ▶ ◀ ≡ ▶ ≡ 🔍 ↺

Input-to-state stability (ISS) — Lyapunov version

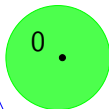
$$V > \gamma(\|u\|) \implies \dot{V} < 0$$



Input-to-state stability (ISS) — Lyapunov version

$\{x : V(x) \leq c\}$

$$V > \gamma(\|u\|) \implies \dot{V} < 0$$



Input-to-state stability (ISS) — Lyapunov version

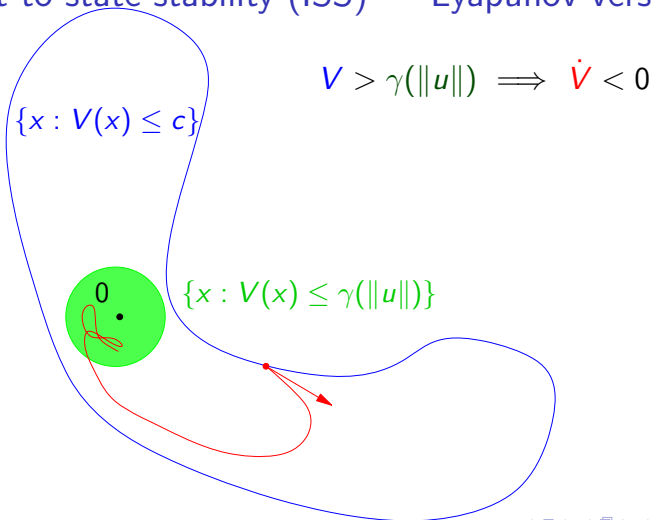
$$\{x : V(x) \leq c\}$$

$$V > \gamma(\|u\|) \implies \dot{V} < 0$$

$$\{x : V(x) \leq \gamma(\|u\|)\}$$

$$\dot{x}(t)$$

Input-to-state stability (ISS) — Lyapunov version



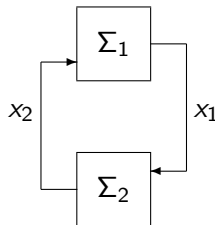
Interconnection of two systems

Consider

$$\Sigma_1 : \dot{x}_1 = f_1(x_1, x_2)$$

$$\Sigma_2 : \dot{x}_2 = f_2(x_1, x_2)$$

$$f_i : \mathbb{R}^{N_1+N_2+N_u} \rightarrow \mathbb{R}^{N_i}$$



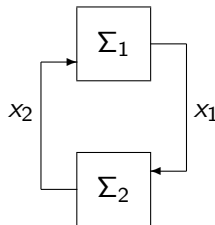
Interconnection of two systems

Consider

$$\Sigma_1 : \dot{x}_1 = f_1(x_1, x_2)$$

$$\Sigma_2 : \dot{x}_2 = f_2(x_1, x_2)$$

$$f_i : \mathbb{R}^{N_1+N_2+N_u} \rightarrow \mathbb{R}^{N_i}$$



with two **Lyapunov functions** such that

$$V_1(x_1) > \gamma_{12}(V_2(x_2)) \Rightarrow \dot{V}_1 < -\alpha_1(\|x_1\|)$$

$$V_2(x_2) > \gamma_{21}(V_1(x_1)) \Rightarrow \dot{V}_2 < -\alpha_2(\|x_2\|)$$



Can we compute ISS Lyapunov functions using a Zubov approach ?



Zubov and ISS Lyapunov functions

Choose a gain $\gamma \in \mathcal{K}_\infty$ and define

$$\begin{aligned}\tilde{f}_\gamma &: \mathbb{R}^n \times B(0, 1) \rightarrow \mathbb{R}^n \\ (x, d) &\mapsto f(x, \gamma(\|x\|)d)\end{aligned}$$

$$\dot{x} = f(x, \gamma(\|x\|)d) := \tilde{f}_\gamma(x, d), \quad (3)$$

Proposition

Let $\gamma \in \mathcal{K}_\infty$ be locally Lipschitz on $(0, \infty)$.

If V is a robust Lyapunov function for (3) it is an ISS Lyapunov function for

$$\dot{x} = f(x, d)$$

with Lyapunov gain γ^{-1} .



Outline of procedure

- (i) For each of the subsystems $i = 1, 2$ choose $\gamma_i \in \mathcal{K}_\infty$ and compute the robust Lyapunov function v_i .



Outline of procedure

- (i) For each of the subsystems $i = 1, 2$ choose $\gamma_i \in \mathcal{K}_\infty$ and compute the robust Lyapunov function v_i .
- (ii) For each $v_{\gamma,i}$ compute bounds

$$\psi_{i,1}(\|x_i\|) \leq v_i(x_i) \leq \psi_{i,2}(\|x_i\|)$$

- (iii) The gain for each of the Lyapunov functions is then given by

$$\tilde{\gamma}_{ij} := \psi_{j,2} \circ \gamma_i^{-1} \circ \psi_{i,1}^{-1}.$$



Outline of procedure

- (i) For each of the subsystems $i = 1, 2$ choose $\gamma_i \in \mathcal{K}_\infty$ and compute the robust Lyapunov function v_i .
- (ii) For each $v_{\gamma,i}$ compute bounds

$$\psi_{i,1}(\|x_i\|) \leq v_i(x_i) \leq \psi_{i,2}(\|x_i\|)$$

- (iii) The gain for each of the Lyapunov functions is then given by

$$\tilde{\gamma}_{ij} := \psi_{j,2} \circ \gamma_i^{-1} \circ \psi_{i,1}^{-1}.$$

- (iv) Do the two gains $\tilde{\gamma}_{12}, \tilde{\gamma}_{21}$ satisfy the small gain condition ?



Outline of procedure

- (i) For each of the subsystems $i = 1, 2$ choose $\gamma_i \in \mathcal{K}_\infty$ and compute the robust Lyapunov function v_i .
- (ii) For each $v_{\gamma,i}$ compute bounds

$$\psi_{i,1}(\|x_i\|) \leq v_i(x_i) \leq \psi_{i,2}(\|x_i\|)$$

- (iii) The gain for each of the Lyapunov functions is then given by

$$\tilde{\gamma}_{ij} := \psi_{j,2} \circ \gamma_i^{-1} \circ \psi_{i,1}^{-1}.$$

- (iv) Do the two gains $\tilde{\gamma}_{12}, \tilde{\gamma}_{21}$ satisfy the small gain condition ?
- (v) If this is the case there is a constructive procedure to get a Lyapunov function for the interconnected system, (see Dashkovskiy, Rüffer, W. 2009).
- (vi) Use this function to estimate the domain of attraction.



