```
R^{3} - xyz
(p_{x}, p_{y}, p_{z}) \in R^{3}
\mathbf{p}(t) = (p_{x}(t), p_{y}(t), p_{z}(t)) \in R^{3}
\mathbf{p}(t) = R^{3}
\mathbf{p}(t) = R^{3}
\mathbf{p}(t) - \mathbf{q}(t) = \mathbf{p}(t)
\mathbf{x}' = x_x' \mathbf{x} + x_y' \mathbf{z} + x_z' \mathbf{z},
           \mathbf{y}' = y_x' \mathbf{x} + y_y' \mathbf{z} + y_z' \mathbf{z},
               \mathbf{z}' = z_x' \mathbf{x} + z_y' \mathbf{z} + z(\mathbf{z})
           \begin{aligned} & ?? \\ \mathbf{R} = \left[ \left. \mathbf{x}' \mathbf{y}' \mathbf{z}' \right] = \left[ \left. x'_x y'_x z'_x x'_y y'_y z'_y x'_z y'_z z'_z \right] = \left[ \left. \mathbf{x}^{\, \prime T} \mathbf{x} \mathbf{y}^{\prime T} \mathbf{x} \mathbf{z}^{\prime T} \mathbf{y} \mathbf{y}^{\prime T} \mathbf{y} \mathbf{z}^{\prime T} \mathbf{y} \mathbf{z}^{\prime T} \mathbf{z} \mathbf{z}^{\prime T} \mathbf{z} \right] , \end{aligned} 
 (5)

\underbrace{\mathbf{b}}_{-xyz}

          \mathbf{P} \mathbf{O}' - x'y'z'
p = p'_x x' + p'_y y' + p'_z z' = [\mathbf{x}' \mathbf{y}' \mathbf{z}'] [p'_x p'_y p'_z] = Rp'.
(6)
          \mathbf{f}_{3\times3}^{T}\mathbf{R} = \det_{\pm1}^{3}\mathbf{R} =
          \det^{\perp 1} \mathbf{R} = \mathbf{x}'^T (\mathbf{y}' \times \mathbf{z}').
           det \mathbf{R} =
           SO(3) =
           \begin{cases} R \in \\ R^{3 \times 3} : \\ R^T R = \\ I, \ det R = \\ 1 \end{cases} 
          \mathbf{R}_{z}(\alpha) = \left[c\,\alpha - s\alpha 0s\alpha c\alpha 0001\right]; \mathbf{R}_{y}(\beta) = \left[c\,\beta 0s\beta 010 - s\beta 0c\beta\right]; \mathbf{R}_{x}(\gamma) = \left[1\,000c\gamma - s\gamma 0s\gamma c\gamma\right].
(8) \begin{array}{c} cv = \\ cos(v) \\ sv = \\ sin(v) \\ v = \\ \alpha, \beta, \gamma \end{array}
           \begin{array}{l} ?\\O_1-x_1y_1z_1\\O_2-x_2y_2z_2\\T_{12}\\T_{12}=\left[\,R_{12}(p_{12})_10_{1\times 3}1\right]. \end{array}
SE(3) =
```