## An Introduction to the Operating Systems of the IoT

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#### What is IoT...

The Internet of Things (IoT) is a scenario in which objects, animals or people are provided with unique identifiers and the ability to transfer data over a network without requiring human-to-human or human-to-computer interaction.



## Open Source Operating Systems for the IoT

- ► FreeRTOS
- ► RIOT
- ► Contiki
- ► TinyOS
- ► Embedded Linux
- ► OpenWSN



#### FreeRTOS

- ► FreeRTOS is designed to be small and simple.
- ▶ The kernel itself consists of only three or four C files.
- ▶ It provides methods for multiple threads or tasks, mutexes, semaphores and software timers.
- ► Key features are very small memory footprint, low overhead, and very fast execution.



#### **RIOT**

- ► RIOT is a real-time multi-threading operating system.
- ► RIOT is based on design objectives including:
  - Energy-Efficiency
  - Reliability
  - Real-Time Capabilities
  - Small Memory Footprint
  - Modularity
  - Uniform API Access independent of the underlying hardware (this API offers partial POSIX compliance)



#### Contiki

- ► Contiki is an open source operating system for networked, memory-constrained systems
- ► Contiki provides three network mechanisms:
  - The uIP stack, which provides IPv4 networking,
  - The uIPv6 stack, which provides IPv6 networking,
  - The Rime stack, which is a set of custom lightweight networking protocols designed specifically for low-power wireless networks.



# **TinyOS**

- ► TinyOS is a component-based operating system and platform targeting wireless sensor networks.
- ► TinyOS is an embedded operating system written in the nesC programming language as a set of cooperating tasks and processes.



#### **Embedded Linux**

- ► Embedded Linux is created using OpenEmbedded, the build framework for embedded Linux.
- ► OpenEmbedded offers a best-in-class cross-compile environment.



## **OpenWSN**

The goal of the OpenWSN project is to provide open-source implementations of a complete protocol stack based on Internet of Things standards, on a variety of software and hardware platforms.



# Comparison

OS	Min RAW	Min ROM	C Support	C++ Support
Contiki	< 2kB	< 30 <i>kB</i>	Partial support	No support
Tiny OS	< 1kB	< 4 <i>kB</i>	No support	No support
Linux	$\sim 1 MB$	$\sim 1 MB$	Full support	Full support
RIOT	$\sim 1.5$ kB	$\sim 5kB$	Full support	Full support









# Comparison

OS	Multi-Threading	Modularity	Real-Time
Contiki	Partial support	Partial support	Partial support
Tiny OS	Partial support	No support	No support
Linux	Full support	Partial support	Partial support
RIOT	Full support	Full support	Full support











# Why Not Linux?

#### Real-Time Linux

Controlling a laser with Linux is crazy, but everyone in this room is crazy in his own way. So if you want to use Linux to control an industrial welding laser, I have no problem with your using PREEMPT\_RT.

- Linux Torvalds





## Why Not Linux?

- Linux certainly is a robust, developer-friendly OS
- ▶ Linux has a disadvantage when compared to a real-time operating system:
  - Memory footprint
  - It simply will not run on 8 or 16-bit MCUs



## Requirements for IoT

- Scalability
- Modularity
- Connectivity
- Reliability



### Internet Usage and Protocols for the IoT

► Can you build an IoT system with familiar Web technologies?

### Internet Usage and Protocols for the IoT

- ► Can you build an IoT system with familiar Web technologies?
- ► Yes you can, although the result would not be as efficient as with the newer protocols.

## Internet Usage and Protocols for the IoT



- · Inefficient content encoding
- · Huge overhead, difficult parsing
- · Requires full Internet devices

# Internet of Things Tens of bytes **Web Objects CoAP DTLS UDP 6LoWPAN**

- · Efficient objects
- Efficient Web
- Optimized IP access

# Questions?