An Introduction to the Operating Systems of the IoT

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What is IoT...

The Internet of Things (IoT) is a scenario in which objects, animals or people are provided with unique identifiers and the ability to transfer data over a network without requiring human-to-human or human-to-computer interaction.



Open Source Operating Systems for the IoT

- ▶ FreeRTOS
- ► RIOT
- ► Contiki
- ► TinyOS
- ► Embedded Linux
- ► OpenWSN



FreeRTOS

- ► FreeRTOS is designed to be small and simple.
- ▶ The kernel itself consists of only three or four C files.
- ▶ It provides methods for multiple threads or tasks, mutexes, semaphores and software timers.
- ► Key features are very small memory footprint, low overhead, and very fast execution.



RIOT

- ► RIOT is a real-time multi-threading operating system.
- ► RIOT is based on design objectives including:
 - Energy-Efficiency
 - Reliability
 - Real-Time Capabilities
 - Small Memory Footprint
 - Modularity
 - Uniform API Access independent of the underlying hardware (this API offers partial POSIX compliance)



Contiki

- ► Contiki is an open source operating system for networked, memory-constrained systems
- ► Contiki provides three network mechanisms:
 - The uIP stack, which provides IPv4 networking,
 - The uIPv6 stack, which provides IPv6 networking,
 - The Rime stack, which is a set of custom lightweight networking protocols designed specifically for low-power wireless networks.



TinyOS

- ► TinyOS is a component-based operating system and platform targeting wireless sensor networks.
- ► TinyOS is an embedded operating system written in the nesC programming language as a set of cooperating tasks and processes.



Embedded Linux

- ► Embedded Linux is created using OpenEmbedded, the build framework for embedded Linux.
- ► OpenEmbedded offers a best-in-class cross-compile environment.



OpenWSN

The goal of the OpenWSN project is to provide open-source implementations of a complete protocol stack based on Internet of Things standards, on a variety of software and hardware platforms.



Questions?