

Estimating β and θ

$$e^{\ell(\beta, \theta)} \propto |\mathbf{D}|^{-\frac{1}{2}} \int e^{\{\sum_{i=1}^n \ell_i(Y_i | \mathbf{b}; \beta) - \frac{1}{2} \mathbf{b}^T \mathbf{D}^{-1} \mathbf{b}\}} d\mathbf{b}$$

So far, to estimate β and θ :

1. Conditional inference (condition on sufficient statistic)
2. Full MLE using numerical integration (Gaussian Quadrature)

Other strategies:

1. Approximate Inference
2. Expectation Maximization algorithm
3. Gibbs Sampling

Approximate Inference

Idea: To approximate the integrated log-likelihood $\ell(\beta, \theta)$ using various lower-order approximations and maximize the approximate log-likelihood wrt $\mathbf{s}(\beta, \mathbf{s}\theta)$.

- Laplace approximation
- Solomon-Cox approximation
- Penalized Quasilikelihood (PQL)
- Corrected PQL

Note: These approximation procedures do not always give consistent estimation of β and θ except for normal data.

Laplace Approximation

Idea: To expand the integrand about the mode $\mathbf{b} = \hat{\mathbf{b}}$ in a lower-order Taylor series before integration.

Then we have

$$\ell(\beta, \mathbf{b}) \approx \ell(\beta, \hat{\mathbf{b}}) - \frac{1}{2}(\mathbf{b} - \hat{\mathbf{b}})^T \left[-\ell''_{\mathbf{bb}}(\beta, \theta, \mathbf{b})|_{\mathbf{b}=\hat{\mathbf{b}}} \right] (\mathbf{b} - \hat{\mathbf{b}})$$

and using this approximation we can calculate

$$\begin{aligned} e^{\ell(\beta, \theta)} &\propto |\mathbf{D}|^{-\frac{1}{2}} \int e^{\{\sum_{i=1}^n \ell_i(Y_i|\mathbf{b};\beta) - \frac{1}{2}\mathbf{b}^T \mathbf{D}^{-1} \mathbf{b}\}} d\mathbf{b} \\ &\approx \int e^{\ell(\beta, \hat{\mathbf{b}}) - \frac{1}{2}(\mathbf{b} - \hat{\mathbf{b}})^T \left[-\ell''_{\mathbf{bb}}(\beta, \theta, \mathbf{b})|_{\mathbf{b}=\hat{\mathbf{b}}} \right] (\mathbf{b} - \hat{\mathbf{b}})} d\mathbf{b} \\ &= L(\beta, \hat{\mathbf{b}}) \int e^{-\frac{1}{2}(\mathbf{b} - \hat{\mathbf{b}})^T \left[-\ell''_{\mathbf{bb}}(\beta, \theta, \mathbf{b})|_{\mathbf{b}=\hat{\mathbf{b}}} \right] (\mathbf{b} - \hat{\mathbf{b}})} d\mathbf{b} \\ &= L(\beta, \hat{\mathbf{b}}) \sqrt{\frac{(2\pi)^q}{\left| -\ell''_{\mathbf{bb}}(\beta, \theta, \mathbf{b})|_{\mathbf{b}=\hat{\mathbf{b}}} \right|}} \end{aligned}$$

Laplace Approximation (2)

$$\ell(\boldsymbol{\beta}, \boldsymbol{\theta}) \approx \ell(\boldsymbol{\beta}, \hat{\mathbf{b}}) - \frac{1}{2} \log \left\{ \left| -\ell''_{\mathbf{b}\mathbf{b}}(\boldsymbol{\beta}, \boldsymbol{\theta}, \mathbf{b}) \right|_{\mathbf{b}=\hat{\mathbf{b}}} \right\} + \frac{q}{2} \log(2\pi)$$

- Laplace likelihood only approximates: some amount of error in the resulting estimates
- Usually “accurate enough”

References

Tierney and Kadane (1986, JASA, 82-86)

Breslow and Clayton (1993, JASA);

Breslow and Lin (1995, Biometrika, 81-91)

Soloman-Cox Approximation

Idea: To expand the integrand about the mode $\mathbf{b} = 0$ before integration.

Similar idea to Laplace approximation: simpler than Laplace, but also less accurate

References

Barndorff-Nielsen and Cox, 1989, 3.3

Solomon and Cox, 1992, Biometrika

Breslow and Lin, 1995, Biometrika, 81-91

Penalized Quasilielihood (PQL)

Idea: Modified Laplace in which we replace the GLM aspect with a nonlinear least-squares model

Main feature is that it iteratively fits linear mixed models using GLM-type working weights and working vectors

Usual PQL does not work well for sparse (e.g. binary) data since Laplace doesn't work so well → corrected PQL

References

Schall, 1991, Biometrika

Breslow and Clayton, 1993, JASA

Breslow and Lin, 1995, Biometrika

Lin and Breslow, 1996, JASA

Expectation-Maximization (EM) Algorithm

Complete data: \mathbf{Y}, \mathbf{Z} Observed data: \mathbf{Y}

We want to estimate β which has likelihood $L(\beta; \mathbf{Y}, \mathbf{Z})$ by maximizing the marginal likelihood

$$L(\beta; \mathbf{Y}) = \int L(\beta; \mathbf{Y}, \mathbf{Z}) d\mathbf{Z}.$$

Expectation (E) Step: Define $Q(\beta|\beta^{(k)})$ as expected log likelihood wrt current distribution of $\mathbf{Z}|\mathbf{Y}$ and current parameters $(\beta^{(k)})$

$$Q(\beta|\beta^{(k)}) = E_{\mathbf{Z}|\mathbf{Y}, \beta^{(k)}}[\ell(\beta; \mathbf{Y}\mathbf{Z})]$$

Maximization (M) Step: Find parameters that maximize

$$\beta^{(k+1)} = \underset{\beta}{\operatorname{argmax}} Q(\beta|\beta^{(k)})$$

EM for G/LMM

Complete data: \mathbf{Y}, \mathbf{b}

Observed data: \mathbf{Y}

E-step:

$$Q(\beta, \theta | \beta^{[k]}, \theta^{[k]}) = E\{\ell(\mathbf{Y} | \mathbf{b}; \beta) + \ell(\mathbf{b}; \theta) | \mathbf{Y}; \beta^{[k]}, \theta^{[k]}\}$$

Involves the same dimension of integration as the likelihood but the terms are relatively easier to calculate.

- Gaussian approximation (Stiratelli, et al, 1982, Biometrika)
- 2nd order Laplace approximation (Steele, 1996, Biometrics)
- Monte-Carlo simulation (Metropolis) (McCulloch, 1994, 1997, JASA; Waller, et al, 1997, JASA)

M-step: Maximize $Q(\beta, \theta | \beta^{[k]}, \theta^{[k]})$ wrt β and θ .

Remarks

- Implementation of EM in practice is done backward, as it is harder to deal with maximization but easier to deal with equation solving.
- One starts from the M-step by calculating using the complete data loglikelihood the score equations for the model parameters, i.e., β and θ , and identify terms that involve the missing data, i.e., the terms involving \mathbf{b}_i .
- At the E-step, calculate the expectations of the identified terms that involve the missing data \mathbf{b}_i and evaluate the expectations at $\hat{\beta}^{[k]}$ and $\hat{\theta}^{[k]}$.
- Iterate between the M-step and the E-step until convergence.

Example: EM for LMM

Model:

$$\mathbf{Y}_i = \mathbf{X}_i\boldsymbol{\beta} + \mathbf{Z}_i\mathbf{b}_i + \mathbf{e}_i$$

where $\mathbf{e}_i \sim N(0, \sigma^2\mathbf{I})$, $\mathbf{b}_i \sim N_q(0, \mathbf{D})$.

Observed data: \mathbf{Y}

Complete data: \mathbf{Y}, \mathbf{b}

Parameters: $\boldsymbol{\beta}, \sigma^2, \mathbf{D}$

Complete Data Loglikelihood

$$\begin{aligned} & \sum_{i=1}^m \ell(\mathbf{Y}_i | \mathbf{b}_i; \boldsymbol{\beta}, \sigma^2) + \ell(\mathbf{b}_i; \mathbf{D}) \\ &= \sum_{i=1}^m \left\{ -\frac{n_i}{2} \ln \sigma^2 - \frac{1}{2\sigma^2} (\mathbf{Y}_i - \mathbf{X}_i\boldsymbol{\beta} - \mathbf{Z}_i\mathbf{b}_i)^T (\mathbf{Y}_i - \mathbf{X}_i\boldsymbol{\beta} - \mathbf{Z}_i\mathbf{b}_i) \right. \\ & \quad \left. - \frac{1}{2} \ln |\mathbf{D}| - \frac{1}{2} \mathbf{b}_i^T \mathbf{D}^{-1} \mathbf{b}_i \right\} \end{aligned}$$

Example: EM for LMM (2)

Score equations for complete data:

$$\sum_{i=1}^m \mathbf{x}_i^T (\mathbf{Y}_i - \mathbf{x}_i \beta - \mathbf{Z}_i \mathbf{b}_i) = 0$$

\Rightarrow

$$\hat{\beta} = \left(\sum_{i=1}^m \mathbf{x}_i^T \mathbf{x}_i \right)^{-1} \sum_{i=1}^m (\mathbf{Y}_i - \mathbf{Z}_i \mathbf{b}_i)$$

$$\hat{\mathbf{D}} = \frac{1}{m} \sum_{i=1}^m \mathbf{b}_i \mathbf{b}_i^T$$

$$\hat{\sigma}^2 = \frac{1}{\sum n_i} \sum_{i=1}^m (\mathbf{Y}_i - \mathbf{x}_i \beta - \mathbf{Z}_i \mathbf{b}_i)^T (\mathbf{Y}_i - \mathbf{x}_i \beta - \mathbf{Z}_i \mathbf{b}_i)$$

Example: EM for LMM - E-step

Need to calculate

$$E[\mathbf{b}_i | \mathbf{Y}_i, \hat{\boldsymbol{\beta}}^{[k]}, \hat{\mathbf{D}}^{[k]}, \hat{\sigma}^2^{[k]}]$$

$$E[\mathbf{b}_i \mathbf{b}_i^T | \mathbf{Y}_i, \hat{\boldsymbol{\beta}}^{[k]}, \hat{\mathbf{D}}^{[k]}, \hat{\sigma}^2^{[k]}]$$

$$E[\mathbf{e}_i^T \mathbf{e}_i | \mathbf{Y}_i, \hat{\boldsymbol{\beta}}^{[k]}, \hat{\mathbf{D}}^{[k]}, \hat{\sigma}^2^{[k]}],$$

where $\mathbf{e}_i = \mathbf{Y}_i - \mathbf{X}_i \boldsymbol{\beta} - \mathbf{Z}_i \mathbf{b}_i$.

Example: EM for LMM - E-step (2)

Recall LMMs:

$$\mathbf{Y}_i = \mathbf{X}_i\beta + \mathbf{Z}_i\mathbf{b}_i + \mathbf{e}_i, \quad \mathbf{b}_i \sim N(0, \mathbf{D})$$

Fact 1:

$$\begin{pmatrix} \mathbf{Y}_i \\ \mathbf{b}_i \end{pmatrix} \sim N \left[\begin{pmatrix} \mathbf{X}_i\beta \\ 0 \end{pmatrix}, \begin{pmatrix} \mathbf{V}_i & \mathbf{Z}_i\mathbf{D} \\ \mathbf{DZ}_i^T & \mathbf{D} \end{pmatrix} \right]$$

where $\mathbf{V}_i = \mathbf{Z}_i\mathbf{DZ}_i^T + \sigma^2\mathbf{I}$. Then

$$\begin{aligned} \hat{\mathbf{b}}_i &= E(\mathbf{b}_i|\mathbf{Y}_i) &= \mathbf{DZ}_i^T\mathbf{V}_i^{-1}(\mathbf{Y}_i - \mathbf{X}_i\beta) \\ \hat{\mathbf{V}}_{b_i} &= \text{cov}(\mathbf{b}_i|\mathbf{Y}_i) &= \mathbf{D} - \mathbf{DZ}_i^T\mathbf{V}_i^{-1}\mathbf{Z}_i\mathbf{D} \end{aligned}$$

Fact 2:

If a random variable $\mathbf{c} \sim N(\boldsymbol{\mu}, \boldsymbol{\Sigma})$, then

$$E(\mathbf{c}^T \mathbf{A} \mathbf{c}) = \text{tr}(\mathbf{A}\boldsymbol{\Sigma}) + \boldsymbol{\mu}^T \mathbf{A} \boldsymbol{\mu}$$

Example: EM for LMM - E-step (3)

$$\begin{aligned}\hat{\mathbf{b}}_i^{[k]} &= E[\mathbf{b}_i | \mathbf{Y}_i; \hat{\beta}^{[k]}, \hat{\mathbf{D}}^{[k]}, \hat{\sigma}^2^{[k]}] &= \mathbf{D}^{[k]} \mathbf{Z}_i^T \mathbf{V}_i^{-1} (\mathbf{Y}_i - \mathbf{X}_i \beta^{[k]}) \\ \hat{\mathbf{V}}_{b_i}^{[k]} &= cov[\mathbf{b}_i | \mathbf{Y}_i; \hat{\beta}^{[k]}, \hat{\mathbf{D}}^{[k]}, \hat{\sigma}^2^{[k]}] &= \mathbf{D}^{[k]} - \mathbf{D}^{[k]} \mathbf{Z}_i^T \mathbf{V}_i^{-1} \mathbf{Z}_i \mathbf{D}^{[k]} \\ &E[\mathbf{b}_i \mathbf{b}_i^T | \mathbf{Y}_i; \hat{\beta}^{[k]}, \hat{\mathbf{D}}^{[k]}, \hat{\sigma}^2^{[k]}] &= \hat{\mathbf{V}}_{b_i}^{[k]} + \hat{\mathbf{b}}_i^{[k]} \hat{\mathbf{b}}_i^{[k]T} \\ &E[\mathbf{e}_i^T \mathbf{e}_i | \mathbf{Y}_i; \hat{\beta}^{[k]}, \hat{\mathbf{D}}^{[k]}, \hat{\sigma}^2^{[k]}] &= tr(\mathbf{Z}_i^T \hat{\mathbf{V}}_{b_i}^{[k]} \mathbf{Z}_i) + \hat{\mathbf{e}}_i^{[k]T} \hat{\mathbf{e}}_i^{[k]},\end{aligned}$$

where $\hat{\mathbf{e}}_i^{[k]} = \mathbf{Y}_i - \mathbf{X}_i \beta^{[k]} - \mathbf{Z}_i \mathbf{b}_i^{[k]}$.

Example: EM for LMM - M-step

$$\hat{\beta}^{[k+1]} = \left(\sum_{i=1}^m \mathbf{x}_i^T \mathbf{x}_i \right)^{-1} \sum_{i=1}^m (\mathbf{y}_i - \mathbf{z}_i \hat{\mathbf{b}}_i^{[k]})$$

$$\begin{aligned} \hat{\mathbf{D}}^{[k+1]} &= \frac{1}{m} \sum_{i=1}^m E(\mathbf{b}_i \mathbf{b}_i^T | \mathbf{y}_i; \beta, \hat{\mathbf{D}}^{[k]}, \hat{\sigma}^2^{[k]}) \\ &= \frac{1}{m} \sum_{i=1}^m (\hat{\mathbf{V}}_{b_i}^{[k]} + \hat{\mathbf{b}}_i^{[k]} \hat{\mathbf{b}}_i^{[k]T}) \end{aligned}$$

$$\begin{aligned} \hat{\sigma}^2^{[k+1]} &= \frac{1}{\sum n_i} \sum_i E(\mathbf{e}_i^T \mathbf{e}_i | \mathbf{y}_i; \hat{\beta}^{[k]}, \hat{\mathbf{D}}^{[k]}, \hat{\sigma}^2^{[k]}) \\ &= \frac{1}{\sum n_i} \sum_{i=1}^m \{ \text{tr}(\mathbf{z}_i^T \hat{\mathbf{V}}_{b_i}^{[k]} \mathbf{z}_i) + \hat{\mathbf{e}}_i^{[k]T} \hat{\mathbf{e}}_i^{[k]} \}. \end{aligned}$$

Gibbs Sampling

A popular Bayesian inference procedure in hierarchical models.

Prior for β : nearly non-informative prior, i.e., $\beta \sim (0, 1000\mathbf{I})$.

Prior for $\mathbf{D}(\theta)$: Gamma/Wishart (Jeffery prior does not work, since the posterior is not proper).

Objective: Generate the joint distribution of $[\beta, \theta, \mathbf{b} \mid \mathbf{Y}]$

How: Generate a series of conditional distributions $[\beta \mid \theta, \mathbf{b}, \mathbf{Y}]$, $[\mathbf{b} \mid \beta, \theta, \mathbf{Y}]$, $[\theta \mid \beta, \mathbf{b}, \mathbf{Y}]$

References: Zeger and Karim (1991, JASA); McCulloch (1994, JASA)