Transform-and-Conquer Strategy

CMSC 142: Design and Analysis of Algorithms

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OVERVIEW

Transform-and-Conquer Strategy

Instance Simplification

Representation Change

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Transform-and-Conquer Strategy

The **transform-and-conquer** works as two-stage procedures:

- (i) transformation stage the problem's instance is modified to be more amenable to solution
- (ii) conquering stage transformed problem is solved

Three major variations of transform-and-conquer:

- ▶ instance simplification transformation to a simpler or more convenient instance of the same problem
- representation change transformation to a different representation of same instance
- problem reduction transformation to an instance of a different problem for which an algorithm is already available

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INSTANCE SIMPLIFICATION: PRESORTING

Interest in sorting algorithms is due to the fact that many questions about a list are easier to answer if the list (array) is sorted.

Element Uniqueness Problem

- ▶ *Brute Force*: compare pairs of the array elements until either two equal elements are found or no more pairs were left; $C(n) \in \mathcal{O}(n^2)$
- ► Transform and conquer: sort then check for possibility of consecutive elements that are equal

What is the overall efficiency of this transform-and-conquer algorithm?

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INSTANCE SIMPLIFICATION: PRESORTING

Finding the Mode

- ▶ A **mode** is a value that occurs most often in a list.
- ▶ *Brute Force*: scan list, compute frequencies of all distinct values, then find the value with largest frequency
- ► Transform and conquer: *Sort* then find the longest run of adjacent equal values in sorted array

What is the overall efficiency of this transform-and-conquer algorithm?

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```
ALGORITHM PresortMode(A[0..n-1])
    //Computes the mode of an array by sorting it first
    //Input: An array A[0..n-1] of orderable elements
    //Output: The array's mode
    sort the array A
    i \leftarrow 0
                              //current run begins at position i
    modefrequency \leftarrow 0 //highest frequency seen so far
    while i < n-1 do
        runlength \leftarrow 1; runvalue \leftarrow A[i]
        while i + runlength \le n - 1 and A[i + runlength] = runvalue
             runlength \leftarrow runlength + 1
        if runlength > modefrequency
            modefrequency \leftarrow runlength; modevalue \leftarrow runvalue
        i \leftarrow i + runlength
    return modevalue
```

Figure: Pseudocode of the transform-and-conquer algorithm in finding mode

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Instance Simplification: Gaussian Elimination

Solving a System of Linear Equations

- ▶ standard method: substitution/ elimination of variables
- ► transform and conquer: transform system of *n* linear equations in *n* unknowns to an equivalent system with an upper triangular coefficient matrix using **Gaussian elimination**, then solve sytem by *backward-substitution*
- ► Gaussian elimination is a series of execution of elementary row operations (EROs): (i) exchanging two equations of the system, (ii) replacing an equation with its nonzero multiple, (iii) replacing an equation with a sum or difference of this equation and some multiple of another equation

Remark. Any system that is obtained through a series of EROs will have the same solution as the original one.

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```
ALGORITHM ForwardElimination(A[1..n, 1..n], b[1..n])
    //Applies Gaussian elimination to matrix A of a system's coefficients,
    //augmented with vector b of the system's right-hand side values
    //Input: Matrix A[1..n, 1..n] and column-vector b[1..n]
    //Output: An equivalent upper-triangular matrix in place of A with the
    //corresponding right-hand side values in the (n + 1)st column
    for i \leftarrow 1 to n do A[i, n+1] \leftarrow b[i] //augments the matrix
    for i \leftarrow 1 to n-1 do
        for i \leftarrow i + 1 to n do
             for k \leftarrow i to n+1 do
                  A[i, k] \leftarrow A[i, k] - A[i, k] * A[i, i] / A[i, i]
```

Figure: Pseudocode for the elimination stage of Gaussian elimination

Pseudocode for the Gaussian elimination with partial pivoting

```
BetterForwardElimination(A[1..n, 1..n], b[1..n])
ALGORITHM
    //Implements Gaussian elimination with partial pivoting
    //Input: Matrix A[1..n, 1..n] and column-vector b[1..n]
    //Output: An equivalent upper-triangular matrix in place of A and the
    //corresponding right-hand side values in place of the (n + 1)st column
    for i \leftarrow 1 to n do A[i, n+1] \leftarrow b[i] //appends b to A as the last column
    for i \leftarrow 1 to n-1 do
         pivotrow \leftarrow i
         for i \leftarrow i + 1 to n do
              if |A[i,i]| > |A[pivotrow,i]| pivotrow \leftarrow i
         for k \leftarrow i to n+1 do
              swap(A[i, k], A[pivotrow, k])
         for i \leftarrow i + 1 to n do
              temp \leftarrow A[i, i] / A[i, i]
              for k \leftarrow i to n+1 do
                   A[i, k] \leftarrow A[i, k] - A[i, k] * temp
```

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Representation Change

Horner's Rule (William George Horner, early 19th century)

- efficient algorithm for evaluating a polynomial
- ▶ problem: find $p(x) = a_n x^n + a_{n-1} x^{n-1} + ... + a_1 x + a_0$ at $x = x_0$
- ightharpoonup representation change: represent p(x) as

$$p(x) = (\dots (a_n x + a_{n-1})x + \dots)x + a_0$$

Example

Evaluate $p(x) = 2x^4 - x^3 + 3x^2 + x - 5$ at x = 3.

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```
ALGORITHM Horner(P[0..n], x)

//Evaluates a polynomial at a given point by Horner's rule

//Input: An array P[0..n] of coefficients of a polynomial of degree n,

// stored from the lowest to the highest and a number x

//Output: The value of the polynomial at x

p \leftarrow P[n]

for i \leftarrow n-1 downto 0 do

p \leftarrow x * p + P[i]

return p
```

Figure: Pseudocode for the Horner's algorithm

Take multiplication as basic operation. What is the overall efficiency of Horner's rule?

Representation Change: Binary Exponentiation and

▶ Let $n = b_1 \dots b_i \dots b_0$ be the bit string representing a positive integer n in the binary number system. The value of n is equal to p(x) at x = 2 where

$$p(x) = b_I x^I + \ldots + b_i x^i + \ldots + b_0.$$

representation change: $a^n = a^{p(2)} = a^{b_l x^l + \dots + b_i x^i + \dots + b_0}$

Horner's rule for the binary polynomial $p(2)$	Implications for $a^n = a^{p(2)}$
$p \leftarrow 1$ //the leading digit is always 1 for $n \ge 1$ for $i \leftarrow I - 1$ downto 0 do	$a^p \leftarrow a^1$ for $i \leftarrow I - 1$ downto 0 do
$p \leftarrow 2p + b_i$	$a^p \leftarrow a^{2p+b_i}$

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LEFT-TO-RIGHT BINARY EXPONENTIATION

```
ALGORITHM LeftRightBinaryExponentiation(a, b(n))

//Computes a^n by the left-to-right binary exponentiation algorithm

//Input: A number a and a list b(n) of binary digits b_1, \ldots, b_0

// in the binary expansion of a positive integer n

//Output: The value of a^n

product \leftarrow a

for i \leftarrow I - 1 downto 0 do

product \leftarrow product * product

if b_i = 1 product \leftarrow product * a

return product
```

Figure: Pseudocode for the left-to-right binary exponentiation method

What is the overall efficiency of the transform-and-conquer algorithm?

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RIGHT-TO-LEFT BINARY EXPONENTIATION

Let $n = b_1 \dots b_i \dots b_0$ be the binary representation of $n \in \mathbb{N}$ and p(2) be the binary polynomial associated to n. Then,

$$a^n = a^{b_1 x^1 + \dots + b_i x^i + \dots + b_0}$$

= $a^{b_1 2^1} \cdot \dots \cdot a^{b_i 2^i} \cdot \dots \cdot a^{b_0}$

```
ALGORITHM RightLeftBinaryExponentiation(a, b(n))
//Computes a^n by the right-to-left binary exponentiation algo
//Input: A number a and a list b(n) of binary digits b_1, \ldots, b_0
         in the binary expansion of a nonnegative integer n
//Output: The value of a^n
term \leftarrow a //initializes a^{2^i}
if b_0 = 1 product \leftarrow a
else product \leftarrow 1
for i \leftarrow 1 to I do
    term \leftarrow term * term
    if b_i = 1 product \leftarrow product * term
return product
```

What is the overall efficiency of the transform-and-conquer algorithm?

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PROBLEM REDUCTION

Main idea: "If you need to solve a problem, reduce it to another problem that you know how to solve."



Examples

- 1. Computing the Least Common Multiple
- 2. Counting Paths in a Graph
- 3. Linear Programming
- 4. Reduction of Optimization Problems and Reduction to Graphs

End of Lecture