

2.5 Inverse matrices

If a square matrix A is invertible, the unique inverse of A is denoted by A^{-1} . Then A^{-1} is a square matrix of the same size as A , so that $A^{-1}A = I$ and $AA^{-1} = I$.

Ways of verifying that the inverse of a matrix exists:

(1) If a matrix C can be found such that $AC = I$, or $CA = I$, then A is invertible, and C is the inverse of A .

(2) If A is invertible, $A\vec{x} = \vec{b}$ has the unique solution $\vec{x} = A^{-1}\vec{b}$

(3) If A is invertible, $A \xrightarrow{\text{row operations}} I$ $[A \mid I] \rightarrow [I \mid A^{-1}]$

All the elimination steps can be done with matrices.

and they can be inverted with matrices

$$E_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$E_{21}A = \begin{bmatrix} 2 & 4 & -2 \\ 0 & 1 & 1 \\ -2 & -3 & 7 \end{bmatrix}$$

$$E_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

$$= E_{31}E_{21}A$$

$$E_{31}(E_{21}A) = \begin{bmatrix} 2 & 4 & -2 \\ 0 & 1 & 1 \\ 0 & 1 & 5 \end{bmatrix}$$

$= E_{32}E_{31}E_{21}A$ pivots

$$E_{32} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$$

$$E_{32}(E_{31}E_{21}A) = \begin{bmatrix} 2 & 4 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 4 \end{bmatrix} = U$$

$$U = \underline{\underline{E_{32}E_{31}E_{21}A}} \quad \text{det } L = \underline{\underline{E_{32}E_{31}(E_{21}I)}} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 3 & -1 & 1 \end{bmatrix}$$

$$[A \ I] \rightarrow [U \ L]$$

agrees with the matrix multiplication.

The last step contains 2 elementary row operations.

It agrees with the multiplication

$$\underbrace{\begin{bmatrix} \frac{1}{2} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix}}_D \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{bmatrix} = \begin{bmatrix} \frac{2}{2} & -\frac{11}{2} & \frac{3}{2} \\ 0 & \frac{5}{4} & -\frac{1}{4} \\ 0 & 3 & -1 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \frac{2}{4} & -\frac{11}{4} & \frac{3}{4} \\ -\frac{11}{4} & \frac{5}{4} & -\frac{1}{4} \\ \frac{3}{4} & -\frac{1}{4} & \frac{1}{4} \end{bmatrix}$$

Since A is invertible with 3 pivots,
elimination is equivalent to multiply

$$[A \ I] \text{ by } A^{-1}$$

$$[A \ I] \rightarrow [I \ A^{-1}]$$

$$\text{agrees with } A^{-1}[A \ I] = [I \ A^{-1}]$$

$$(1) [A \ I] = \left[\begin{array}{ccc|ccc} 2 & 4 & -2 & 1 & 0 & 0 \\ 4 & 9 & -3 & 0 & 1 & 0 \\ -2 & -3 & 7 & 0 & 0 & 1 \end{array} \right] \xrightarrow{r_2 - 2r_1} \left[\begin{array}{ccc|ccc} 2 & 4 & -2 & 1 & 0 & 0 \\ 0 & 1 & 1 & -2 & 1 & 0 \\ -2 & -3 & 7 & 0 & 0 & 1 \end{array} \right]$$

$$\xrightarrow{r_3 + r_1} \left[\begin{array}{ccc|ccc} 2 & 4 & -2 & 1 & 0 & 0 \\ 0 & 1 & 1 & -2 & 1 & 0 \\ 0 & 1 & 5 & 1 & 0 & 1 \end{array} \right] \xrightarrow{r_3 - r_2} \left[\begin{array}{ccc|ccc} 2 & 4 & -2 & 1 & 0 & 0 \\ 0 & 1 & 1 & -2 & 1 & 0 \\ 0 & 0 & 4 & 3 & -1 & 1 \end{array} \right].$$

$$(2) \xrightarrow{r_2 - r_3/4} \left[\begin{array}{ccc|ccc} 2 & 4 & -2 & 1 & 0 & 0 \\ 0 & 1 & 0 & -11/4 & 5/4 & -1/4 \\ 0 & 0 & 4 & 3 & -1 & 1 \end{array} \right]$$

$$\xrightarrow{r_1 + r_3/2} \left[\begin{array}{ccc|ccc} 2 & 4 & 0 & 5/2 & -1/2 & 1/2 \\ 0 & 1 & 0 & -11/4 & 5/4 & -1/4 \\ 0 & 0 & 4 & 3 & -1 & 1 \end{array} \right] \xrightarrow{r_1 - 4r_2} \left[\begin{array}{ccc|ccc} 2 & 0 & 0 & 27/2 & -11/2 & 3/2 \\ 0 & 1 & 0 & -11/4 & 5/4 & -1/4 \\ 0 & 0 & 4 & 3 & -1 & 1 \end{array} \right].$$

$$(3) \xrightarrow{r_1/2} \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 27/4 & -11/4 & 3/4 \\ 0 & 1 & 0 & -11/4 & 5/4 & -1/4 \\ 0 & 0 & 1 & 3/4 & -1/4 & 1/4 \end{array} \right].$$

Example 1 (Inverse of an elimination matrix). Let $E = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

For any matrix A with 3 rows, the multiplication EA subtracts 2 times row 1 of A from row 2.

To add it back, we multiply $E^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ times EA such that $E^{-1}(EA) = A$.

We are subtracting and adding the same 2 times row 1

Elimination is really a sequence of multiplication.

(1) elimination matrices E 's, which produces zeros below and above the pivots.

(2) permutation matrices P 's, which exchange rows, if needed

(3) D , which divides the rows by the pivots, to change all the pivots to 1's.

In the row reduction $[A \ I] \rightarrow [I \ \vec{x}_1 \vec{x}_2 \dots \vec{x}_n]$ a right inverse of A

The change from A to I by $\boxed{DE \cdot P \cdot E} A = I$ And $A \boxed{[\vec{x}_1 \vec{x}_2 \dots \vec{x}_n]} = [\vec{0} \ \vec{0}_2 \ \dots \vec{0}_n] = I$ a left inverse of A

So $DE \cdot P \cdot E = [\vec{x}_1 \vec{x}_2 \dots \vec{x}_n]$

By Gauss-Jordan elimination,
a square matrix with a full set of
pivots always has a two-sided inverse

Example For $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} = \begin{bmatrix} ad-bc & 0 \\ 0 & ad-bc \end{bmatrix} = (ad-bc) I$

A 2 by 2 matrix $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is invertible if and only if $ad-bc \neq 0$, and $A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$

A triangular matrix is invertible if and only if no diagonal entries are zero, and the inverse is still triangular.

Example Invert $L = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 3 & -1 & 1 \end{bmatrix}$ by Gauss-Jordan method.

$$= E_{32} E_{21} E_{21} \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 2 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_2+2R_1} \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 2 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} L & I \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ -2 & 1 & 0 & 0 & 1 & 0 \\ 3 & -1 & 1 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_3-3R_1} \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 2 & 1 & 0 \\ 0 & 0 & 1 & -3 & 0 & 1 \end{bmatrix} \xrightarrow{R_3+R_2} \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 2 & 1 & 0 \\ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix} = [I \ L']$$

$$L^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{2} & 1 & 0 \\ -\frac{1}{3} & \frac{1}{2} & 1 \end{bmatrix}$$

$= (E_{32} E_{31} E_{21})^{-1}$. A square matrix is called a diagonal matrix if all the entries off the diagonal are zero.

$$\text{A diagonal matrix } A = \begin{bmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_n \end{bmatrix} \text{ has an inverse provided no diagonal entries are zero, and } A^{-1} = \begin{bmatrix} \frac{1}{d_1} & 0 & \dots & 0 \\ 0 & \frac{1}{d_2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \frac{1}{d_n} \end{bmatrix}$$

1. $ad - bc = 1 \times 2 - 2 \times 1 = 0.$

2. $\begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \xrightarrow{R_2 \leftarrow R_2 - 2R_1} \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}$. A has only 1 pivot.

Whenever A is not invertible,

elimination fails to reduce A to I.

3. $A\vec{x} = \vec{0}$ has a nonzero solution $\vec{x} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$

then A is invertible, and C is the inverse

of A.

$$A^{-1} = \underline{\begin{bmatrix} 1 & 2 \\ 2 & -1 \end{bmatrix}}$$