

2.5 Inverse matrices

If a square matrix A is invertible, the unique inverse of A is denoted by A^{-1} .
Then A^{-1} is a square matrix of the same size as A , so that $A^{-1}A = I$ and $AA^{-1} = I$.

Ways of verifying that the inverse of a matrix exists:

- 1) If a matrix C can be found such that $AC = I$, or $CA = I$, then A is invertible, and C is the inverse of A .
- 2) If A is invertible, $A\vec{x} = \vec{b}$ has the unique solution $\vec{x} = A^{-1}\vec{b}$.
- 3) If A is invertible, $A \xrightarrow{\text{row operations}} I$ $[A \ I] \rightarrow [I \ A^{-1}]$

All the elimination steps can be done with matrices.
and they can be inverted with matrices

$$E_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$E_{21}A = \begin{bmatrix} 2 & 4 & -2 \\ 0 & 1 & 1 \\ -2 & -3 & 7 \end{bmatrix}$$

$$= E_{31}E_{21}A$$

$$E_{31}(E_{21}A) = \begin{bmatrix} 2 & 4 & -2 \\ 0 & 1 & 1 \\ 0 & 1 & 5 \end{bmatrix}$$

$$= E_{32}E_{31}E_{21}A$$

$$E_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

$$E_{32} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$$

$$E_{32}(E_{31}E_{21}A) = \begin{bmatrix} \textcircled{2} & 4 & -2 \\ 0 & \textcircled{1} & 1 \\ 0 & 0 & \textcircled{4} \end{bmatrix} = U$$

$$U = \underbrace{E_{32}E_{31}E_{21}}_L A \quad \text{Let } L = E_{32}E_{31}(E_{21}I) = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 3 & -1 & 1 \end{bmatrix}$$

$$[A \ I] \longrightarrow \begin{bmatrix} U & L \\ I & A \end{bmatrix} \text{ agrees with the matrix multiplication.}$$

The last step contains 2 elementary row operations.
It agrees with the multiplication

$$\begin{bmatrix} \frac{1}{2} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 & \frac{27}{2} & -\frac{11}{2} & \frac{3}{2} \\ 0 & 1 & 0 & -\frac{11}{4} & \frac{5}{4} & -\frac{1}{4} \\ 0 & 0 & 4 & 3 & -1 & 1 \end{bmatrix}$$

\Rightarrow

$$\begin{bmatrix} \textcircled{1} & 0 & 0 & \frac{27}{4} & -\frac{11}{4} & \frac{3}{4} \\ 0 & \textcircled{1} & 0 & -\frac{11}{4} & \frac{5}{4} & -\frac{1}{4} \\ 0 & 0 & \textcircled{1} & \frac{3}{4} & -\frac{1}{4} & \frac{1}{4} \end{bmatrix}$$

Since A is invertible with 3 pivots,
elimination is equivalent to multiply
[A I] by A^{-1}

$$[A \ I] \longrightarrow [I \ A^{-1}]$$

$$\text{agrees with } A^{-1}[A \ I] = [I \ A^{-1}]$$

$$\begin{aligned}
 (1) \quad [A \ I] &= \left[\begin{array}{ccc|ccc} 2 & 4 & -2 & 1 & 0 & 0 \\ 4 & 9 & -3 & 0 & 1 & 0 \\ -2 & -3 & 7 & 0 & 0 & 1 \end{array} \right] \xrightarrow{r_2-2r_1} \left[\begin{array}{ccc|ccc} 2 & 4 & -2 & 1 & 0 & 0 \\ 0 & 1 & 1 & -2 & 1 & 0 \\ -2 & -3 & 7 & 0 & 0 & 1 \end{array} \right] \\
 &\xrightarrow{r_3+r_1} \left[\begin{array}{ccc|ccc} 2 & 4 & -2 & 1 & 0 & 0 \\ 0 & 1 & 1 & -2 & 1 & 0 \\ 0 & 1 & 5 & 1 & 0 & 1 \end{array} \right] \xrightarrow{r_3-r_2} \left[\begin{array}{ccc|ccc} 2 & 4 & -2 & 1 & 0 & 0 \\ 0 & 1 & 1 & -2 & 1 & 0 \\ 0 & 0 & 4 & 3 & -1 & 1 \end{array} \right].
 \end{aligned}$$

$$(2) \quad \xrightarrow{r_2-r_3/4} \left[\begin{array}{ccc|ccc} 2 & 4 & -2 & 1 & 0 & 0 \\ 0 & 1 & 0 & -11/4 & 5/4 & -1/4 \\ 0 & 0 & 4 & 3 & -1 & 1 \end{array} \right]$$

$$\xrightarrow{r_1+r_3/2} \left[\begin{array}{ccc|ccc} 2 & 4 & 0 & 5/2 & -1/2 & 1/2 \\ 0 & 1 & 0 & -11/4 & 5/4 & -1/4 \\ 0 & 0 & 4 & 3 & -1 & 1 \end{array} \right] \xrightarrow{r_1-4r_2} \left[\begin{array}{ccc|ccc} 2 & 0 & 0 & 27/2 & -11/2 & 3/2 \\ 0 & 1 & 0 & -11/4 & 5/4 & -1/4 \\ 0 & 0 & 4 & 3 & -1 & 1 \end{array} \right].$$

$$(3) \quad \xrightarrow[r_3/4]{r_1/2} \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 27/4 & -11/4 & 3/4 \\ 0 & 1 & 0 & -11/4 & 5/4 & -1/4 \\ 0 & 0 & 1 & 3/4 & -1/4 & 1/4 \end{array} \right].$$

Example 1 Inverse of an elimination matrix. Let $E = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

For any matrix A with 3 rows, the multiplication EA subtracts 2 times row 1 of A from row 2.

To add it back, we multiply $E^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ times EA such that $E^{-1}(EA) = A$.

We are subtracting and adding the same 2 times row 1

Elimination is really a sequence of multiplication.

- (1) elimination matrices E 's, which produces zeros below and above the pivots.
- (2) permutation matrices P 's, which exchange rows, if needed
- (3) D , which divides the rows by the pivots, to change all the pivots to 1's.

By Gauss-Jordan elimination, a square matrix with a full set of pivots always has a two-sided inverse.

In the row reduction $[A \ I] \rightarrow [I \ \begin{pmatrix} \vec{x}_1 \\ \vec{x}_2 \\ \vdots \\ \vec{x}_n \end{pmatrix}]$ a right inverse of A

The change from A to I by $(D \cdot E \cdot P \cdot E)A = I$ a left inverse of A And $A \begin{pmatrix} \vec{x}_1 & \vec{x}_2 & \dots & \vec{x}_n \end{pmatrix} = [\vec{e}_1 \ \vec{e}_2 \ \dots \ \vec{e}_n] = I$

So $D \cdot E \cdot P \cdot E = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \dots & \vec{x}_n \end{bmatrix}$

Example For $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} = \begin{bmatrix} ad-bc & 0 \\ 0 & ad-bc \end{bmatrix} = (ad-bc)I$

A 2 by 2 matrix $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is invertible if and only if $ad-bc \neq 0$, and $A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$

A triangular matrix is invertible if and only if no diagonal entries are zero, and the inverse is still triangular.

Example Invert $L = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 3 & -1 & 1 \end{bmatrix}$ by Gauss-Jordan method.

$$[L \ I] = \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ -2 & 1 & 0 & 0 & 1 & 0 \\ 3 & -1 & 1 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_2 + 2R_1} \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 2 & 1 & 0 \\ 3 & -1 & 1 & 0 & 0 & 1 \end{bmatrix}$$

$$\text{So } L^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -1 & -1 & 1 \end{bmatrix} \xrightarrow{R_3 - 3R_1} \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 2 & 1 & 0 \\ 0 & -1 & 1 & -3 & 0 & 1 \end{bmatrix} \xrightarrow{R_3 + R_2} \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 2 & 1 & 0 \\ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix} = [I \ L^{-1}]$$

$$= (E_{32} E_{31} E_{21})^{-1}$$

A square matrix is called a diagonal matrix if all the entries off the diagonal are zero.

$$\text{A diagonal matrix } A = \begin{bmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_n \end{bmatrix}$$

has an inverse provided no diagonal entries are zero, and $A^{-1} = \begin{bmatrix} \frac{1}{d_1} & 0 & \dots & 0 \\ 0 & \frac{1}{d_2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \frac{1}{d_n} \end{bmatrix}$

$$1 \quad ad - bc = 1 \times 2 - 2 \times 1 = 0.$$

$$2 \quad \begin{bmatrix} 1 & 2 \\ 1 & 2 \end{bmatrix} \xrightarrow{r_2 - r_1} \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix}. A \text{ has only 1 pivot.}$$

Whenever A is not invertible,

elimination fails to reduce A to I .

$$3. A\vec{x} = \vec{0} \text{ has a nonzero solution } \vec{x} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

then A is invertible, and C is the inverse of A .

$$A\vec{x} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$