

Sensor Integration and Calibration

Simulation

High Performance Computing **Artificial Intelligence**

Data Processing

Sensor Fusion

Planning and

Control

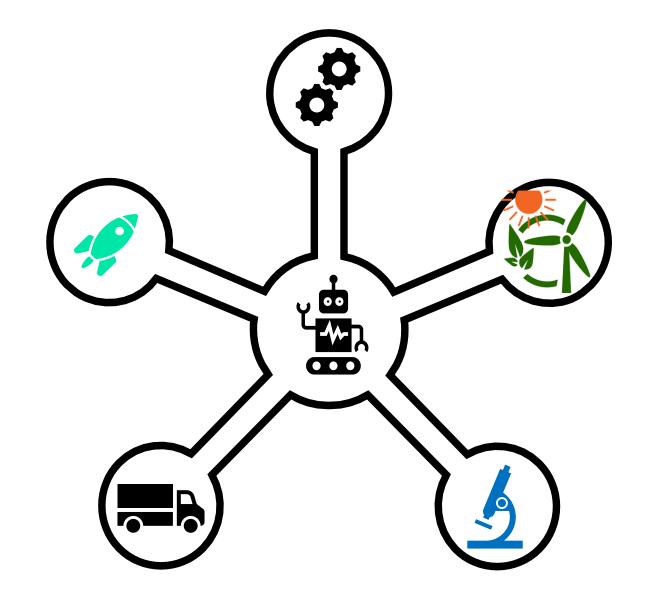
Development Infrastrukture

Regression
Testing and
Continuous
Integration

Product Acceleration



Accelerate in Robotics







Proprietary Technology

Virtually every one of the 1,250+ codebases we audited contained open source. In fact, 70% of the code in those codebases was open source.

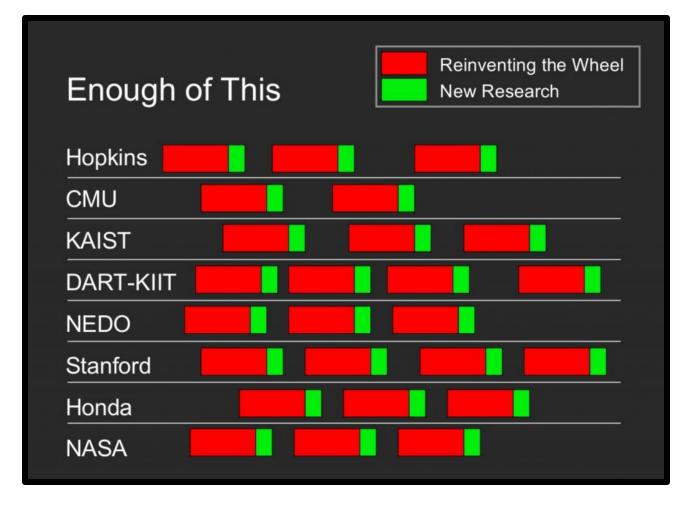
~ 70 %

Synopsys Report on Open Source Usage in Software Product analysed for Security and Risk in 2020

Open Fechnology



On the Shoulders of Giants



Why ROS? (Robot Operating System)
https://www.theconstructsim.com/history-ros/

The reinventing of the wheel is one of the major stumbling blocks for new innovative applications and product development in general.

Up to 70% of the development costs can be saved by standing on the shoulders of giants and stop reinventing the wheel.



Innovation Strategy in Robotics

Prototyping

Quality Analysis
Sensor Integration
Sensor Calibration
DevOps Support
Development Process

Maintenance



Q4 2020



Q1 2021



Q2 2021

Investigation
State-of-the-Art
Concept
Minimum viable product
Sensor Concept
Mock Up Simulation
Requirements
Scenarios

Product Development

Refactoring and Porting
Software Hardening
Embedded Systems
Security and Risk Analysis
Scaling of Infrastructure
Creating Standards
Health Monitoring



Service Roadmap