

REGULAR LANGUAGES AND LEXICAL ANALYSIS

a.y. 2022-2023

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Recognizing languages

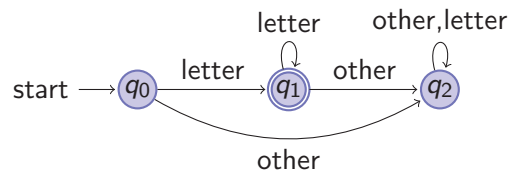
- $\mathcal{L} = \{a^n b^n \mid n > 0\}$ is a free language
- Stack seem ideal to recognize words in \mathcal{L}
- Read the string one symbol at a time: push a s onto stack; pop one symbol for each b and reject further a s; check emptiness
- Do we really need all that “counting” to generate, e.g., arbitrary strings over the English alphabet?

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Recognizing languages

ARBITRARY STRINGS OVER THE ALPHABET

- Do we really need all that “counting” to generate, e.g., arbitrary strings over the alphabet?
- $S \rightarrow a \mid b \mid \dots \mid z \mid aS \mid bS \mid \dots \mid zS$
- A state machine is enough



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Regular languages

- Regular grammars: free grammars with productions of the form
 - $A \rightarrow a$
 - $A \rightarrow aB$
 - $A \rightarrow \epsilon$
- Regular expressions
- Nondeterministic finite state automata
- Deterministic finite state automata
- At the basis of lexical analysis

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Regular expressions

- Fix an alphabet \mathcal{A} , and a number of operators
- Define regular expressions inductively
 - Base:
 - Every $a \in \mathcal{A}$ is a regular expression
 - ϵ is a regular expression
 - Step: If r_1 and r_2 are regular expressions then
 - (Alternation) $r_1 \mid r_2$ is a regular expressions
 - (Concatenation) $r_1 \cdot r_2$ is a regular expressions (written $r_1 r_2$)
 - (Kleene star) r_1^* is a regular expressions
 - (Parentheses) (r_1) is a regular expression

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Regular expressions

DENOTED LANGUAGE

- Given a regular expression r over \mathcal{A} , the **language denoted** by r , written $\mathcal{L}(r)$, is also inductively defined on the structure of r
 - Base:
 - $\mathcal{L}(a) = \{a\}$ for every $a \in \mathcal{A}$
 - $\mathcal{L}(\epsilon) = \{\epsilon\}$
 - Step:
 - If $r = r_1 \mid r_2$ then $\mathcal{L}(r) = \mathcal{L}(r_1) \cup \mathcal{L}(r_2)$
 - If $r = r_1 r_2$ then $\mathcal{L}(r) = \{w_1 w_2 \mid w_1 \in \mathcal{L}(r_1) \text{ and } w_2 \in \mathcal{L}(r_2)\}$
 - If $r = r_1^*$ then

$$\mathcal{L}(r) = \{\epsilon\} \cup \{w_1 w_2 \dots w_k \mid k \geq 1 \text{ and } \forall i : 1 \leq i \leq k. w_i \in \mathcal{L}(r_1)\}$$
 - If $r = (r_1)$ then $\mathcal{L}(r) = \mathcal{L}(r_1)$

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Regular expressions

CONVENTIONS

- Kleene star has highest precedence, is left associative
- Concatenation has second highest precedence, is left associative
- Alternation has lowest precedence, is left associative
- Then $(a \mid bc^*)$ means
 - $(a \mid b(c^*))$
 - $(a \mid (b(c^*)))$

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Regular expressions

EXAMPLES

- $\mathcal{L}(a \mid b) = \{a, b\}$
- $\mathcal{L}((a \mid b)(a \mid b)) = \{aa, ab, ba, bb\}$
- $\mathcal{L}(a^*) = \{a^n \mid n \geq 0\}$
- $\mathcal{L}(a \mid a^*b) = \{a\} \cup \{a^n b \mid n \geq 0\}$

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Regular expressions

EXAMPLES

- $(a \mid b \mid \dots \mid z)(a \mid b \mid \dots \mid z)^*$ denotes the set of words over the alphabet
- $(0 \mid 1)^*0$ denotes all the even binary numbers
- $b^*(abb^*)^*(a \mid \epsilon)$ denotes the set of words over $\{a, b\}$ with no consecutive occurrences of a
- $(a \mid b)^*aa(a \mid b)^*$ denotes the set of words over $\{a, b\}$ with consecutive occurrences of a

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Finite states automata

- Finite state automata are used to decide whether a word belongs to the language denoted by a regular expression
- Nondeterministic Finite state Automata (NFA)
- Deterministic Finite state Automata (DFA)

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Nondeterministic finite state automata

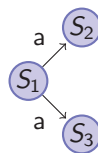
- An NFA is a tuple $(S, \mathcal{A}, \text{move}_n, s_0, F)$
- Where
 - S is a set of states
 - \mathcal{A} is an alphabet with $\epsilon \notin \mathcal{A}$
 - $s_0 \in S$ is the **initial** state
 - $F \subseteq S$ is the set of **final** (or **accepting**) states
 - $\text{move}_n : S \times (\mathcal{A} \cup \{\epsilon\}) \rightarrow 2^S$ is the transition function

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Nondeterministic finite state automata

GRAPHICAL REPRESENTATION

- $(S, \mathcal{A}, \text{move}_n, s_0, F)$ is represented as a directed graph
- Where
 - Nodes represent states
 - The initial state is identified by an incoming arrow
 - Final states are identified by a double circle
 - Edges represent the transition function
 - E.g., suppose $\text{move}_n(S_1, a) = \{S_2, S_3\}$, then

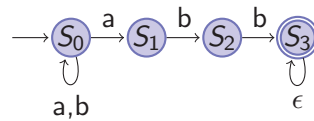


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Nondeterministic finite state automata

EXAMPLE

An NFA



Tabular representation of its transition function

	ϵ	a	b
S_0	\emptyset	$\{S_0, S_1\}$	$\{S_0\}$
S_1	\emptyset	\emptyset	$\{S_2\}$
S_2	\emptyset	\emptyset	$\{S_3\}$
S_3	$\{S_3\}$	\emptyset	\emptyset

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Nondeterministic finite state automata

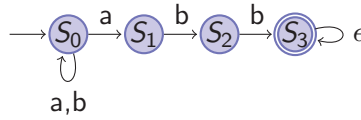
ACCEPTED LANGUAGES

- The NFA \mathcal{N} **accepts** (or **recognizes**) w iff there exists **at least** a path spelling w from its initial state to one of its final states
- Recall
 - $\epsilon\epsilon$ spells ϵ
 - $a\epsilon$ spells a
 - ϵa spells a
- The language **accepted** (or **recognized**) by \mathcal{N} , written $\mathcal{L}(\mathcal{N})$, is the set of all the strings accepted by \mathcal{N}

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Nondeterministic finite state automata

EXAMPLE



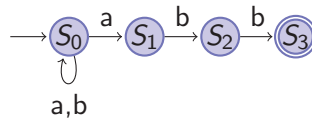
Accepted language

$$\mathcal{L}((a \mid b)^*abb)$$

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Nondeterministic finite state automata

EXAMPLE



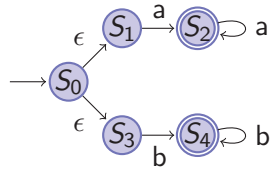
Accepted language

$$\mathcal{L}((a \mid b)^*abb)$$

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Nondeterministic finite state automata

EXAMPLE



Accepted language

$$\mathcal{L}(aa^* \mid bb^*)$$

Thompson's construction

An algorithm to construct an NFA \mathcal{N} from a regular expression r in such a way that

$$\mathcal{L}(\mathcal{N}) = \mathcal{L}(r)$$

Thompson's construction

The construction is based on the inductive definition of regular expressions

- Base: r is either ϵ or a symbol of the alphabet
 - Define an NFA to recognize $\mathcal{L}(\epsilon)$
 - Define an NFA to recognize $\mathcal{L}(a)$
- Step: r is either $r_1 \mid r_2$, or $r_1 r_2$, or r_1^* , or (r_1)
 - Given NFAs \mathcal{N}_1 and \mathcal{N}_2 such that $\mathcal{L}(\mathcal{N}_i) = \mathcal{L}(r_i)$ for $i = 1, 2$
 - Define an NFA to recognize $\mathcal{L}(r_1 \mid r_2)$
 - Define an NFA to recognize $\mathcal{L}(r_1 r_2)$
 - Define an NFA to recognize $\mathcal{L}(r_1^*)$
 - Define an NFA to recognize $\mathcal{L}((r_1))$

Thompson's construction

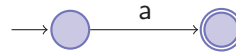
MAIN FEATURES

- Every step of the construction introduces 2 new states at most
 - The generated NFA has $2k$ states at most, where k is the number of symbols and of operators in the regular expression
- In every intermediate NFA there is
 - Exactly one final state
 - No edge incoming in the initial state
 - No edge outgoing from the final state

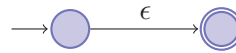
Thompson's construction

BASE

$$r = a$$



$$r = \epsilon$$

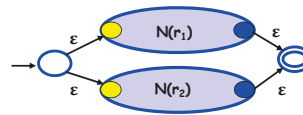


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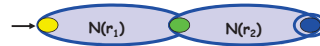
Thompson's construction

STEP

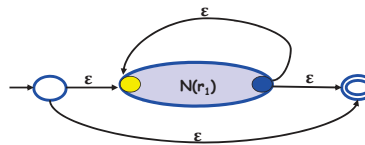
$$r = r_1 \mid r_2$$



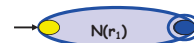
$$r = r_1 r_2$$



$$r = r_1^*$$



$$r = (r_1)$$



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Thompson's construction

COMPLEXITY

- Constructs an NFA with n nodes and m edges
- Every step adds at most 2 states and 4 edges
- Every step has constant time
- There are $|r|$ steps
- Then:
 - **Space:** $n + m$ is $\mathcal{O}(|r|)$
 - **Time:** $\mathcal{O}(|r|)$

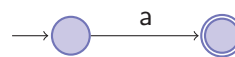
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Thompson's construction

EXAMPLE OF APPLICATION

Take $r = (a \mid b)^*abb$

$a = r_1$



$b = r_2$



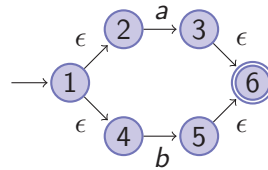
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Thompson's construction

EXAMPLE OF APPLICATION

$$a \mid b = r_1 \mid r_2 = r_3$$

Apply Thompson's construction for alternation to the automata for r_1 and r_2 , and get the automaton for r_3



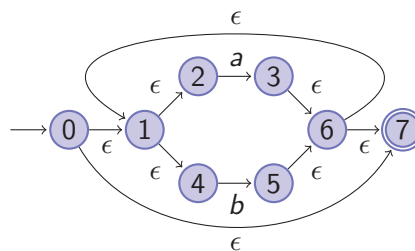
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Thompson's construction

EXAMPLE OF APPLICATION

$$(a \mid b) = (r_3) = r_4 \qquad (a \mid b)^* = r_4^* = r_5$$

Apply Thompson's construction for parentheses and for Kleene star to the automaton for r_3 , and get the automaton for r_5



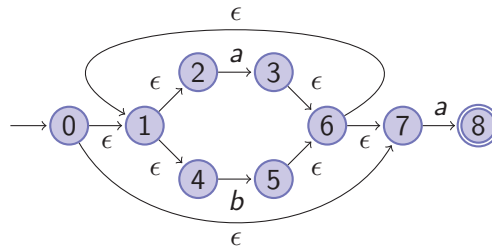
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Thompson's construction

EXAMPLE OF APPLICATION

$$(a \mid b)^* a = r_5 r_1 = r_6$$

Apply Thompson's construction for concatenation to the automata for r_5 and for r_1 , and get the automaton for r_6



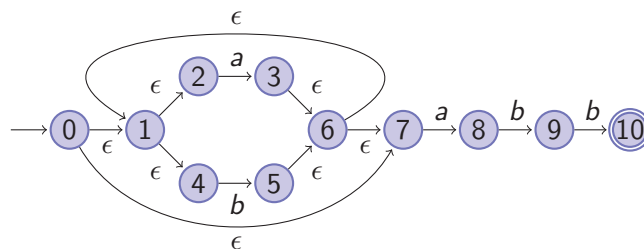
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Thompson's construction

EXAMPLE OF APPLICATION

$$r = (a \mid b)^* abb$$

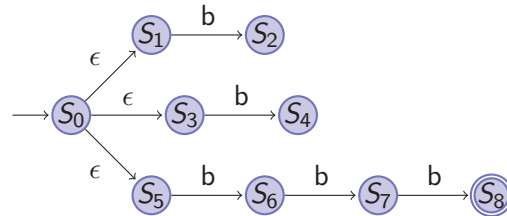
In two more steps



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Simulation of NFAs

- Given a word w and an NFA \mathcal{N} decide whether $w \in \mathcal{L}(\mathcal{N})$
- Let $w = bbb$



- Reading bbb from S_0 is the same as reading it from any of the states in $\{S_0, S_1, S_3, S_5\}$

Simulation of NFAs

ϵ -CLOSURE

- Let $(S, \mathcal{A}, \text{move}_n, s_0, F)$ be an NFA, t be a state in S , and T be a subset of states
- $\epsilon\text{-closure}(\{t\})$ is the set of states in S which are reachable from t by zero or more ϵ -transitions
- $\epsilon\text{-closure}(T) = \bigcup_{t \in T} \epsilon\text{-closure}(\{t\})$

Simulation of NFAs

COMPUTATION OF ϵ -CLOSURE

Data structures:

- Stack
- Boolean array “alreadyOn” of size $|S|$ to check in constant time whether a state t is on the stack
- Bidimensional array to record move_n . Every entry (t, x) is a linked list containing all the states in $\text{move}_n(t, x)$

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Simulation of NFAs

COMPUTATION OF ϵ -CLOSURE

```

foreach  $i=1, \dots, |S|$  do alreadyOn[i] = false ;
function closure( $t, \text{stack}$ )
    push  $t$  onto stack ;
    alreadyOn[t] = true ;
    foreach  $u \in \text{move}_n(t, \epsilon)$  do
        if not alreadyOn[u] then
            closure ( $u, \text{stack}$ ) ;

```

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Simulation of NFAs

COMPLEXITY OF ϵ -CLOSURE

```
1 push t onto stack;  
2 set alreadyOn[t] bit;  
3 find next  $u \in \text{move}_n(t, \epsilon)$ ;  
4 test alreadyOn[u] bit;
```

- Each of them takes constant time
- How many times are they repeated?

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Simulation of NFAs

COMPLEXITY OF ϵ -CLOSURE

```
1 push t onto stack;  
2 set alreadyOn[t] bit;  
3 find next  $u \in \text{move}_n(t, \epsilon)$ ;  
4 test alreadyOn[u] bit;
```

- Line1 & Line2: Executed at each invocation of closure (either initial or recursive)
 - Every state goes onto stack at most once (alreadyOn bit initially false, then set to true, never changed again)
- In aggregate, assuming that the NFA has n states and m edges, $\mathcal{O}(n)$

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Simulation of NFAs

COMPLEXITY OF ϵ -CLOSURE

```

1 push t onto stack;
2 set alreadyOn[t] bit;
3 find next  $u \in \text{move}_n(t, \epsilon)$ ;
4 test alreadyOn[u] bit;

```

- Line3 & Line4: Executed at each invocation of closure for all $u \in \text{move}_n(t, \epsilon)$
 - In the worst case every state goes onto the stack, and every state has at least an ϵ -transition
- In aggregate, assuming that the NFA has n states and m edges, $\mathcal{O}(m)$

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Simulation of NFAs

COMPLEXITY OF ϵ -CLOSURE

```

function closure( $t, \text{stack}$ )
    push t onto stack ;
    alreadyOn[t] = true ;
    foreach  $u \in \text{move}_n(t, \epsilon)$  do
        if not alreadyOn[u] then
            closure (u, stack) ;

```

$$\mathcal{O}(n + m)$$

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Simulation of NFAs

ALGORITHM

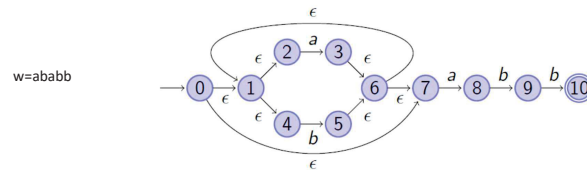
```

input           : NFA  $\mathcal{N} = (S, \mathcal{A}, \text{move}_n, s_0, F)$ , w$
output          : "yes" if  $w \in \mathcal{L}(\mathcal{N})$ , "no" otherwise
states =  $\epsilon$ -closure( $\{s_0\}$ ) ;
symbol = nextchar() ;
while symbol  $\neq$  $ do
    states =  $\epsilon$ -closure( $\bigcup_{t \in \text{states}} \text{move}_n(t, \text{symbol})$ ) ;
    symbol = nextchar() ;
if states  $\cap F \neq \emptyset$  then
    | return "yes" ;
else
    | return "no" ;
  
```

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Simulation of NFAs

EXAMPLE



states	symbol	$\bigcup_{t \in \text{move}(t, \text{symbol})}$	ϵ -closure
T0 = {0,1,2,4,7}	a	{3,8}	{1,2,3,4,6,7,8}
T1 = {1,2,3,4,6,7,8}	b	{5,9}	{1,2,4,5,6,7,9}
T2 = {1,2,4,5,6,7,9}	a	{3,8}	T1
T1	b		T2
T2	b	{5,10}	{1,2,4,5,6,7,10}
T3 = {1,2,4,5,6,7,10}	\$		

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Simulation of NFAs

COMPLEXITY

Dominant

```
while symbol  $\neq$  $ do
L1  |   states =  $\epsilon$ -closure( $\bigcup_{t \in \text{states}}$  moven(t, symbol)) ;
    |   symbol = nextchar() ;
```

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Simulation of NFAs

COMPLEXITY

Data structures:

- Two stacks for states:
 - currentStack for the current states ("states" on the right-side of the assignment at Line L1)
 - nextStack for the next states ("states" on the left-side of the assignment at Line L1)
- Boolean array "alreadyOn" of size $|S|$ to check in constant time whether a state in onto the stack
- Bidimensional array to record move_{*n*}. Every entry (*t*, *x*) is a linked list containing all the states in move_{*n*}(*t*, *x*)

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Simulation of NFAs

COMPLEXITY, LINE L1

```

foreach t on currentStack do
  foreach  $u \in \text{move}_n(t, \text{symbol})$  do
    if not alreadyOn[u] then
      closure(u, nextStack);
  pop t from currentStack;
foreach s on nextStack do
  pop s from nextStack ;
  push s on currentStack ;
  alreadyOn[s] = false ;

```

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Simulation of NFAs

COMPLEXITY, LINE L1

```

foreach t on currentStack do
  :
  ;
/* populate nextStack */
foreach s on nextStack do
  :
  ;
/* swap nextStack with currentStack */

```

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Simulation of NFAs

COMPLEXITY

- Assume that the NFA has n states and m edges
- For each while-cycle
 - Populating nextStack is $\mathcal{O}(n + m)$
 - Swapping the stacks is $\mathcal{O}(n)$
- One while-cycle costs $\mathcal{O}(n + m)$
- The simulation of w costs $\mathcal{O}(|w|(n + m))$
- If the NFA results from Thompson's construction, $(n + m)$ is $\mathcal{O}(|r|)$, then simulating w is $\mathcal{O}(|w||r|)$

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Wrap-up: Accepting regular languages by NFAs

- Take a regular expression r
- Apply Thomson's construction, get NFA $\leftarrow \mathcal{O}(|r|)$
- Simulate NFA $\leftarrow \mathcal{O}(|w||r|)$
- Overall: $\mathcal{O}(|w||r|)$

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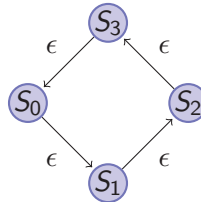
On ϵ -closure, again

Let $(S, \mathcal{A}, \text{move}_n, s_0, F)$ be an NFA, and let $M \subseteq S$.

Then $\epsilon\text{-closure}(M)$ is **the least** set $X \subseteq S$ that is a solution to the set equation

$$X = M \cup \{N' \mid N \in X \text{ and } N' \in \text{move}_n(N, \epsilon)\}$$

- For example



- $\epsilon\text{-closure}(\{S_0\}) = \{S_0, S_1, S_2, S_3\}$
- Start with S_0 in the set
- Take S_1 because $S_1 \in \text{move}_n(S_0, \epsilon)$
- ...

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Fixed Point

- The set equation

$$X = M \cup \{N' \mid N \in X \text{ and } N' \in \text{move}_n(N, \epsilon)\}$$

- Is an instance of the general form of set equation

$$X = f(X)$$

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Fixed Point

- If
 - $f : 2^D \rightarrow 2^D$ for some finite set D , and
 - f is monotonic, i.e. $X \subseteq Y$ implies $f(X) \subseteq f(Y)$
- Then there is a precise technique to solve the equation $X = f(X)$

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Fixed Point

THEOREM

Let S be a finite set, and let $f : 2^S \rightarrow 2^S$ be monotonic.

Then $\exists m \in \mathbb{N}$ such that the unique minimal solution to the set equation $X = f(X)$ is $f^m(\emptyset)$

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Fixed Point

PROOF

- Show that $m \in \mathbb{N}$ exists such that $f^m(\emptyset)$ is a solution to $X = f(X)$
- Show that $f^m(\emptyset)$ is the unique minimal solution

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Fixed Point

PROOF

$m \in \mathbb{N}$ exists such that $f^m(\emptyset)$ is a solution to $X = f(X)$

- $\emptyset \subseteq f(\emptyset)$
- Then, by f monotonic, $f(\emptyset) \subseteq f^2(\emptyset)$
- Then, by induction, $f^i(\emptyset) \subseteq f^{i+1}(\emptyset)$ for all $i \in \mathbb{N}$
- Then we have a chain $\emptyset \subseteq f^1(\emptyset) \subseteq f^2(\emptyset) \subseteq f^3(\emptyset) \dots$
- Then, by 2^S finite, the sets in the chain cannot be all different
- Then for some m it must be $f^m(\emptyset) = f^{m+1}(\emptyset) = f(f^m(\emptyset))$
- Then $f^m(\emptyset)$ is a solution to $X = f(X)$

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Fixed Point

PROOF

$f^m(\emptyset)$ is the unique minimal solution

- Suppose another solution to $X = f(X)$ exists, say A .
- Then, by hypothesis, $A = f(A)$
- Then, $A = f(A)$, $A = f(A) = f^2(A) = \dots = f^m(A)$
- Then, by $\emptyset \subseteq A$ and f monotonic, $f^m(\emptyset) \subseteq f^m(A)$
- Then, by $f^m(A) = A$, $f^m(\emptyset) \subseteq A$
- Then $f^m(\emptyset)$ is the unique minimal solution to $X = f(X)$

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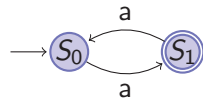
Deterministic finite state automata

- NFA: $(S, \mathcal{A}, \text{move}_n, s_0, F)$
where $\text{move}_n : S \times (\mathcal{A} \cup \{\epsilon\}) \rightarrow 2^S$
- DFA: $(S, \mathcal{A}, \text{move}_d, s_0, F)$
where $\text{move}_d : S \times \mathcal{A} \rightarrow S$
- In any DFA
 - There is no ϵ -transition
 - If move_d is **total**, then from every state there is **exactly one** a -transition for every $a \in \mathcal{A}$
 - If move_d is **partial**, then from every state there is **at most one** a -transition for every $a \in \mathcal{A}$

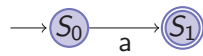
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Deterministic finite state automata

- Take the alphabet $\{a\}$
- An example of DFA with total transition function is



- An example of DFA with partial transition function is



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Simulation of DFAs

ACCEPTED LANGUAGES

The language recognized by a DFA \mathcal{D} , denoted by $\mathcal{L}(\mathcal{D})$, is the set of words w such that

- Either there is a path spelling $w = a_1 \cdots a_k$ with $k \geq 1$ from the initial state of \mathcal{D} to some of its final states
- Or the initial state is also final and $w = \epsilon$

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Simulation of DFAs

TOTAL TRANSITION FUNCTION

- Answer the question “ $w \in \mathcal{L}(\mathcal{D})$?”
- Starting from the initial state, follow the path spelling w
- If the reached state is final, then return “yes”
- Otherwise return “no”

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Simulation of DFAs

PARTIAL TRANSITION FUNCTION

- Answer the question “ $w \in \mathcal{L}(\mathcal{D})$?”
- Starting from the initial state, begin following the path spelling
 $w = a_1 \cdots a_k$
- If for some a_i there is no target state, then return “no”
- If w is over and the reached state is final, then return “yes”
- Otherwise return “no”

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Deterministic finite state automata

PARTIAL VS TOTAL TRANSITION FUNCTION

- Let \mathcal{D} be a DFA with partial transition function
- Can you define a DFA \mathcal{D}' with total transition function such that $\mathcal{L}(\mathcal{D}') = \mathcal{L}(\mathcal{D})$?
- Use a **sink**
 - Add a sink to the states of \mathcal{D}
 - Let the sink be the target of all the undefined transitions
 - For every symbol in the alphabet, add the sink with a self-loop



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Subset construction

Given the NFA \mathcal{N} construct a DFA \mathcal{D} such that $\mathcal{L}(\mathcal{D}) = \mathcal{L}(\mathcal{N})$

Idea: Use ϵ -closure to map subsets of states of the NFA into one single state of the DFA

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Subset Construction

- This is the first instance of a construction we will see again later in the course
- Define the initial state of the DFA
- Populate the collection of all its states while defining the transition function

```

foreach state  $T$  already collected do
  foreach symbol  $a$  in the alphabet do
    compute the plausible target of the  $a$ -transition from  $T$  ;
    call it  $T'$  ;
    if  $T'$  is already in the collection then
      nothing else to do ;
    else
      add  $T'$  to the collection ;

```

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Subset Construction

```

input      : NFA  $\mathcal{N} = (S, \mathcal{A}, \text{move}_n, S_0, F)$ 
output     : DFA  $\mathcal{D} = (R, \mathcal{A}, \text{move}_d, T_0, E)$  such that  $\mathcal{L}(\mathcal{D}) = \mathcal{L}(\mathcal{N})$ 
 $T_0 = \epsilon\text{-closure}(\{S_0\})$ ;
 $R = \{T_0\}$  ;
set  $T_0$  as unmarked ;
while some  $T \in R$  is unmarked do
  mark  $T$  ;
  foreach  $a \in \mathcal{A}$  do
     $T' = \epsilon\text{-closure}(\bigcup_{t \in T} \text{move}_n(t, a))$  ;
    if  $T' \neq \emptyset$  then
       $\text{move}_d(T, a) = T'$  ;
      if  $T' \notin R$  then
        add  $T'$  to  $R$  ;
        set  $T'$  as unmarked ;
  foreach  $T \in R$  do
    if  $(T \cap F) \neq \emptyset$  then set  $T \in E$  ;

```

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Subset Construction

COMPLEXITY

Dominant

```

while some  $T \in R$  is unmarked do
  ...;
  foreach  $a \in \mathcal{A}$  do
     $T' = \epsilon\text{-closure}(\bigcup_{t \in T} \text{move}_n(t, a))$  ;
    :

```

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Subset Construction

COMPLEXITY

```

while some  $T \in R$  is unmarked do
  ...;
  foreach  $a \in \mathcal{A}$  do
     $T' = \epsilon\text{-closure}(\bigcup_{t \in T} \text{move}_n(t, a))$  ;
    :

```

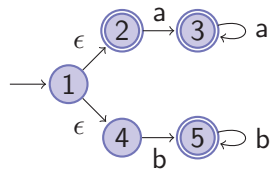
- Suppose the NFA has n states and m edges, and the DFA has n_d states
- **while** is repeated n_d times
- **foreach** is repeated $|\mathcal{A}|$ times
- $\epsilon\text{-closure}(\bigcup_{t \in T} \text{move}_n(t, a))$ costs $\mathcal{O}(n + m)$
- Then the subset construction is $\mathcal{O}(n_d \cdot |\mathcal{A}| \cdot (n + m))$
- The question is: how big can n_d be?

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Subset construction

EXAMPLE OF APPLICATION

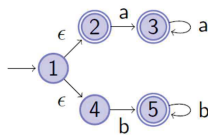
From the NFA



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Subset construction

EXAMPLE OF APPLICATION



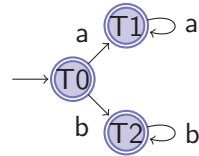
	a	b
$T0 = \epsilon\text{-closure}(\{1\}) = \{1,2,4\}$ % initial, final	$\epsilon\text{-closure}(\{3\}) = T1$	$\epsilon\text{-closure}(\{5\}) = T2$
$T1 = \{3\}$ % final	$\epsilon\text{-closure}(\{3\}) = T1$	---
$T2 = \{5\}$ % final	---	$\epsilon\text{-closure}(\{5\}) = T2$

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Subset construction

EXAMPLE OF APPLICATION

Get the DFA

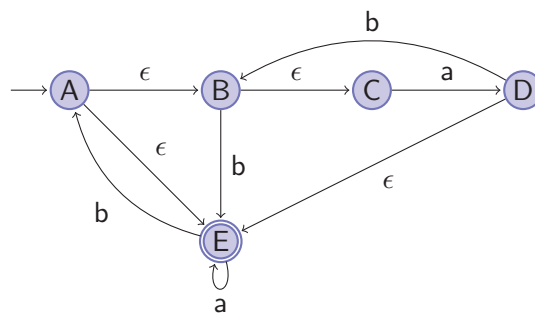


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Subset construction

EXAMPLE OF APPLICATION

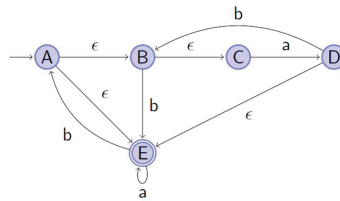
From the NFA



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Subset construction

EXAMPLE OF APPLICATION



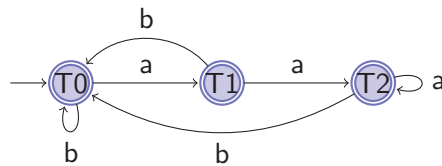
	a	b
$T0 = \epsilon\text{-closure}(\{A\}) = \{A, B, C, E\}$ % initial, final	$\epsilon\text{-closure}(\{D, E\}) = T1$	$\epsilon\text{-closure}(\{A, E\}) = \{A, B, C, E\} = T0$
$T1 = \{D, E\}$ % final	$\epsilon\text{-closure}(\{E\}) = T2$	$\epsilon\text{-closure}(\{A, B\}) = \{A, B, C, E\} = T0$
$T2 = \{E\}$ % final	$\epsilon\text{-closure}(\{E\}) = T2$	$\epsilon\text{-closure}(\{A\}) = T0$

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Subset construction

EXAMPLE OF APPLICATION

Get the DFA

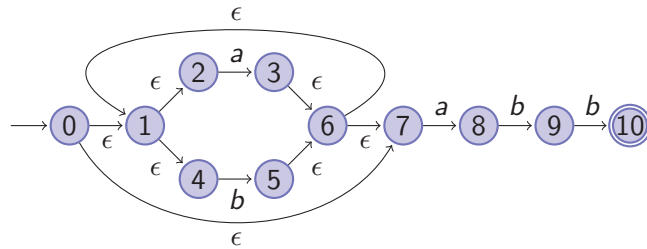


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Subset construction

EXAMPLE OF APPLICATION

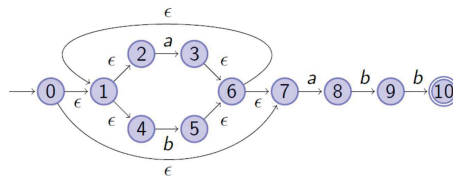
From the NFA



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Subset construction

EXAMPLE OF APPLICATION



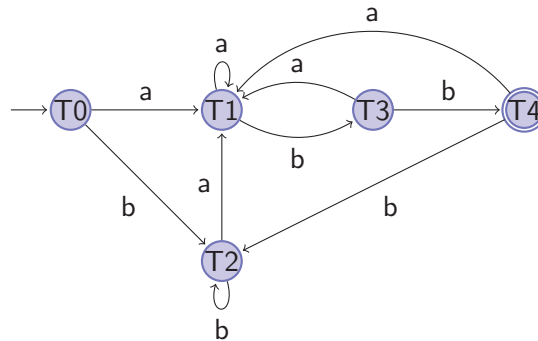
	a	b
T0 = ϵ -closure({0}) = {0,1,2,4,7} % initial	ϵ -closure({3,8}) = T1	ϵ -closure({5}) = T2
T1 = {1,2,3,4,6,7,8}	ϵ -closure({3,8}) = T1	ϵ -closure({5,9}) = T3
T2 = {1,2,4,5,6,7}	ϵ -closure({3,8}) = T1	ϵ -closure({5}) = T2
T3 = {1,2,4,5,6,7,9}	ϵ -closure({3,8}) = T1	ϵ -closure({5,10}) = T4
T4 = {1,2,4,5,6,7,10} % final	ϵ -closure({3,8}) = T1	ϵ -closure({5}) = T2

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Subset construction

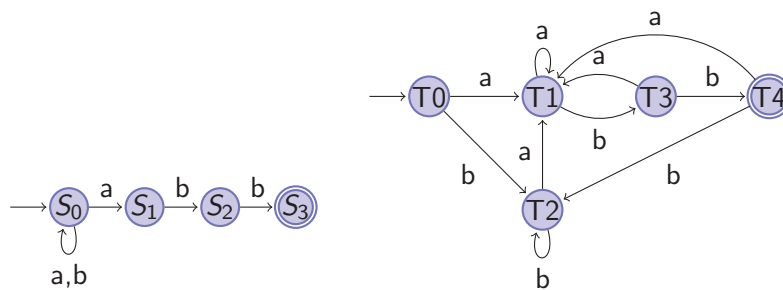
EXAMPLE OF APPLICATION

Get the DFA



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Subset construction



Both automata recognize $\mathcal{L}((a \mid b)^*abb)$

Can we get a smaller deterministic structure accepting the same language?

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DFA minimization

Given the DFA \mathcal{D} construct a minimal DFA \mathcal{D}' such that $\mathcal{L}(\mathcal{D}') = \mathcal{L}(\mathcal{D})$

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DFA minimization

INTUITION

Partition the states of the DFA into equivalent classes

Two states s and t are equivalent iff
for every x
the simulation of x from s is successful iff
the simulation of x from t is successful

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DFA minimization

STATE EQUIVALENCE

Let $\mathcal{D} = (S, \mathcal{A}, \text{move}_d, s_0, F)$ be a DFA with **total** transition function

Then $s, t \in S$ are **equivalent** iff the following holds

$\text{move}_d^*(s, x) \in F$ iff $\text{move}_d^*(t, x) \in F$ for every $x \in \mathcal{A}^*$

where the multi-step transition function move_d^* is defined by induction on the length of strings

- $\text{move}_d^*(s, \epsilon) = s$
- $\text{move}_d^*(s, wa) = \text{move}_d(\text{move}_d^*(s, w), a)$

DFA minimization

PARTITION REFINEMENT

- Partition the states into blocks (subsets of states)
- Start with the two blocks
 - $B_1 = F$
 - $B_2 = S \setminus F$
 - Why this choice for the initial partition?
 - $s \in B_1$ and $t \in B_2$ are not equivalent because $\text{move}_d^*(s, \epsilon) \in F$ and $\text{move}_d^*(t, \epsilon) \notin F$

DFA minimization

PARTITION REFINEMENT

- Check whether the blocks contain equivalent states
- If not so, refine the blocks by splitting them further
- Repeat the checking-refining steps up to the point that the partition cannot be further refined

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DFA minimization

PARTITION REFINEMENT: SPLITTING BLOCKS

- If all the states in $B_i = \{s_1, \dots, s_k\}$ are equivalent, then for every $a \in \mathcal{A}$ the target states of the a -transition from s_1, \dots, s_k should belong to the same block
- The block B_i can be split wrt (a, B_j) if for some $s, t \in B_i$
 $\text{move}_d(s, a) \in B_j$ and $\text{move}_d(t, a) \notin B_j$
- Splitting the block B_i wrt (a, B_j) amounts to replacing B_i by the two blocks
 - $\{s \in B_i \mid \text{move}_d(s, a) \in B_j\}$
 - $\{s \in B_i \mid \text{move}_d(s, a) \notin B_j\}$

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DFA minimization

PARTITION REFINEMENT

```

 $B_1 = F$  ;
 $B_2 = S \setminus F$  ;
 $P = \{B_1, B_2\}$  ;
while Some  $B_i \in P$  can be split wrt some  $(a, B_j)$  do
    Update  $P$  by removing  $B_i$  and adding the two blocks
     $\{s \in B_i \mid \text{move}_d(s, a) \in B_j\}$  and
     $\{s \in B_i \mid \text{move}_d(s, a) \notin B_j\}$ 

```

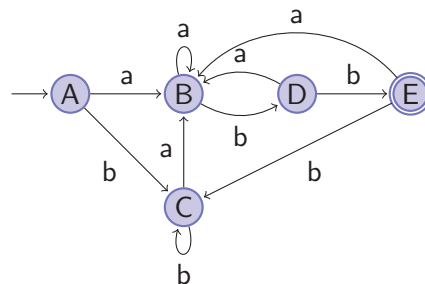
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DFA minimization

PARTITION REFINEMENT

Block B_i can be split wrt (a, B_j) if for some $s, t \in B_i$

- $\text{move}_d(s, a) \in B_j$ and $\text{move}_d(t, a) \notin B_j$



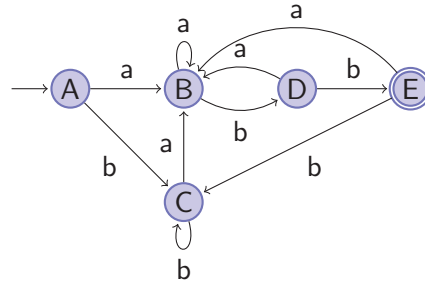
Initial Partition: $B_1 = \{E\}$ $B_2 = \{A, B, C, D\}$

- $\text{move}_d(D, b) = E \in B_1$ and $\text{move}_d(A, b) = C \notin B_1$
- Then we can split B_2 wrt (b, B_1)

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DFA minimization

PARTITION REFINEMENT



Init $B_1 = \{E\}; B_2 = \{A, B, C, D\}$

split B_2 $B_1 = \{E\}; B_{21} = \{D\}; B_{22} = \{A, B, C\}$

split B_{22} $B_1 = \{E\}; B_{21} = \{D\}; B_{221} = \{B\}; B_{222} = \{A, C\}$

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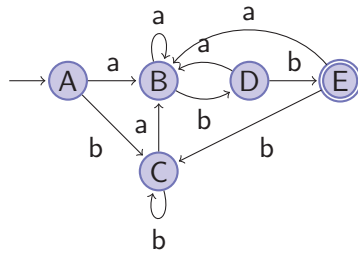
DFA Minimization

- Run partition refinement over a DFA with **total** transition function
- Each block is *temporarily* considered a state of the min-DFA
- The initial state of the min-DFA is the one represented by the block containing s_0
- The final states of the min-DFA are those represented by blocks containing final states of the original DFA
- The transition function of the min-DFA is derived from the original move_d as follows:
If $s \in B_i$ and $\text{move}_d(s, a) \in B_j$, then there is an a -transition in the min-DFA from the state represented by B_i to the state represented by B_j
- If any of the temporary state is dead, remove it, and remove all the transitions to/from it
- **Observe:** The min-DFA can have **partial** transition function

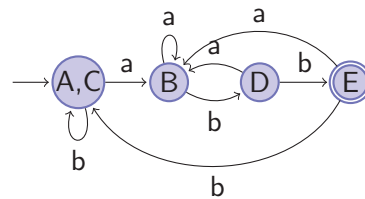
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DFA minimization

PARTITION REFINEMENT



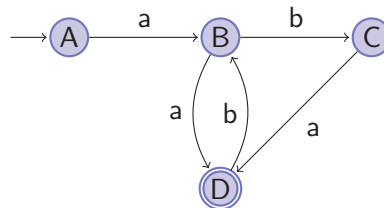
$\{E\}; \{D\}; \{B\}; \{A, C\}$



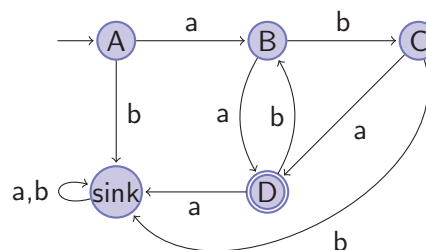
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Training

- Minimize the DFA

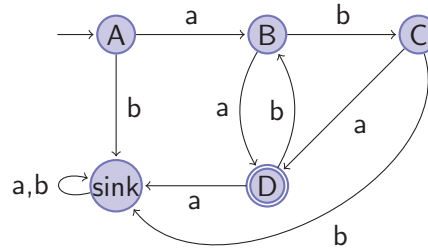


- The DFA has partial transition function, then take



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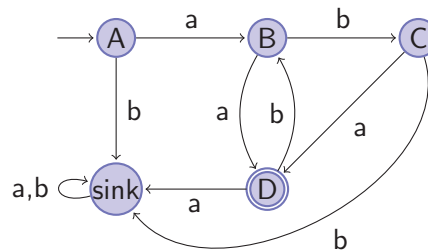
Training



- Initial partition:
 $B_1 = \{D\}; B_2 = \{A, B, C, \text{sink}\}$
- Split B_2 by $\text{move}_d(A, a) \in B_2$ and $\text{move}_d(B, a) \notin B_2$
- First refinement:
 $B_1 = \{D\}; B_{21} = \{A, \text{sink}\}; B_{22} = \{B, C\}$

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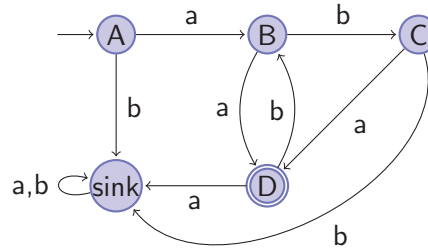
Training



- First refinement:
 $B_1 = \{D\}; B_{21} = \{A, \text{sink}\}; B_{22} = \{B, C\}$
- Split B_{22} by $\text{move}_d(B, b) \in B_{22}$ and $\text{move}_d(C, b) \notin B_{22}$
- Second refinement:
 $B_1 = \{D\}; B_{21} = \{A, \text{sink}\}; B_{221} = \{B\}; B_{222} = \{C\}$

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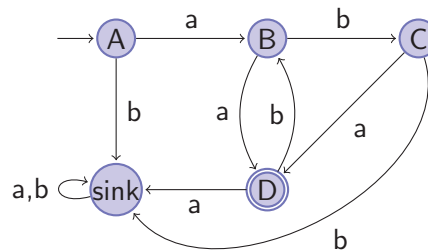
Training



- Second refinement:
 $B_1 = \{D\}$; $B_{21} = \{A, \text{sink}\}$; $B_{221} = \{B\}$ $B_{222} = \{C\}$
- Split B_{21} by $\text{move}_d(A, a) \in B_{221}$ and $\text{move}_d(\text{sink}, a) \notin B_{221}$
- Last refinement:
 $B_1 = \{D\}$; $B_{211} = \{A\}$; $B_{212} = \{\text{sink}\}$; $B_{221} = \{B\}$ $B_{222} = \{C\}$

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Training

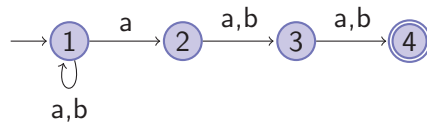


- Last refinement:
 $B_1 = \{D\}$; $B_{211} = \{A\}$; $B_{212} = \{\text{sink}\}$; $B_{221} = \{B\}$ $B_{222} = \{C\}$
- Remove the sink and all the transitions to/from it, get the original DFA
- The original DFA was already minimal

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Training

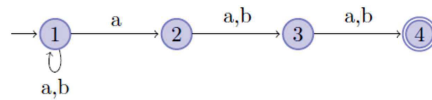
- Find the minimal equivalent DFA



- First find the equivalent DFA
- Then minimize the DFA

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Training

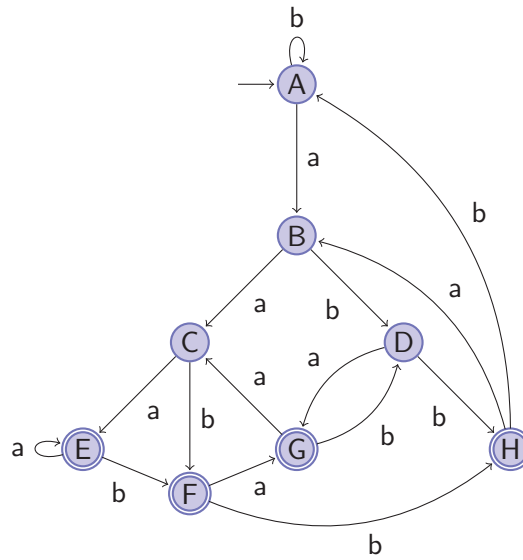


		a	b
A={1}	initial	B	A
B={1,2}		C	D
C={1,2,3}		E	F
D={1,3}		G	H
E={1,2,3,4}	final	E	F
F={1,3,4}	final	G	H
G={1,2,4}	final	C	D
H={1,4}	final	B	A

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Training

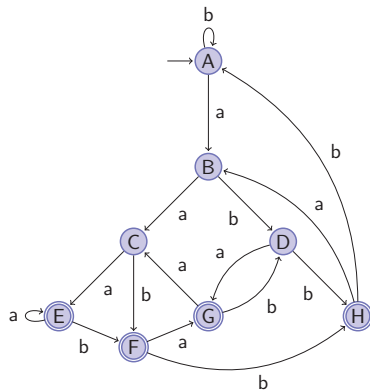
DFA resulting from the subset construction



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Training

MINIMIZATION

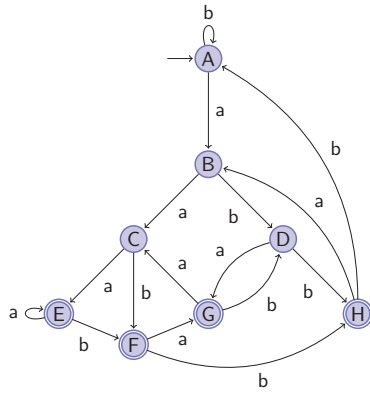


- Partition: $\{A, B, C, D\}; \{E, F, G, H\}$
- Split: $\text{move}_d(A, a), \text{move}_d(C, a)$
- Partition: $\{A, B\}; \{C, D\}; \{E, F, G, H\}$
- Split: $\text{move}_d(A, a), \text{move}_d(B, a)$
- Partition: $\{A\}; \{B\}; \{C, D\}; \{E, F, G, H\}$
- Split: $\text{move}_d(G, b), \text{move}_d(H, b)$
- Partition: $\{A\}; \{B\}; \{C, D\}; \{E, F, H\}; \{G\}$

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Training

MINIMIZATION



- Partition: $\{A\}; \{B\}; \{C, D\}; \{E, F, H\}; \{G\}$
- Split: by $\text{move}_d(C, a)$, $\text{move}_d(D, a)$
- Partition: $\{A\}; \{B\}; \{C\}; \{D\}; \{E, F, H\}; \{G\}$
- Split: $\text{move}_d(E, a)$, $\text{move}_d(H, a)$
- Partition: $\{A\}; \{B\}; \{C\}; \{D\}; \{E, F\}; \{H\}; \{G\}$
- Split: $\text{move}_d(E, a)$, $\text{move}_d(F, a)$
- Partition: $\{A\}; \{B\}; \{C\}; \{D\}; \{E\}; \{F\}; \{G\}; \{H\}$
- Already minimal

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Number of states of DFAs: worst case

LEMMA

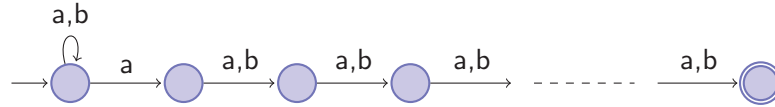
For each $n \in \mathbb{N}^+$ there is an NFA with $(n + 1)$ states whose minimal equivalent DFA has at least 2^n states and total transition function

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Number of states of DFAs: worst case

PROOF

- Take $\mathcal{L} = \mathcal{L}((a \mid b)^* a (a \mid b)^{n-1})$
- There is an NFA accepting \mathcal{L} which has exactly $n + 1$ states



- Suppose, by contradiction, that a minimal DFA \mathcal{D} exists which accepts \mathcal{L} and has $k < 2^n$ states
- There are exactly 2^n distinct words over $\{a, b\}$ whose length is n
- Then there are two paths in \mathcal{D}
 - Whose length is n
 - Spell, respectively, w_1 and w_2 with $w_1 \neq w_2$
 - Share at least one node

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Number of states of DFAs: worst case

PROOF

- Then, for some x_1, x_2, x , either
 - $w_1 = x_1 a x$ and $w_2 = x_2 b x$ or
 - $w_1 = x_1 b x$ and $w_2 = x_2 a x$
- Wlog suppose that $w_1 = x_1 a x$ and $w_2 = x_2 b x$
- Then $w'_1 = x_1 a b^{n-1} \in \mathcal{L}(\mathcal{D})$
- Then the state reached by w'_1 in \mathcal{D} is final
- Contradiction: that state cannot be final because it is also reached by $x_2 b b^{n-1} \notin \mathcal{L}(\mathcal{D})$

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Pumping Lemma for regular languages

LEMMA

Let \mathcal{L} be a regular language. Then

- $\exists p \in \mathbb{N}^+$ such that
- $\forall z \in \mathcal{L}$ such that $|z| > p$
- $\exists u, v, w$ such that
 - $z = uvw$ and
 - $|uv| \leq p$ and
 - $|v| > 0$ and
 - $\forall i \in \mathbb{N}. uv^i w \in \mathcal{L}$

Pumping Lemma for regular languages

PROOF

- Let \mathcal{L} be a regular language
- Then there exists a DFA $\mathcal{D} = (S, \mathcal{A}, \text{move}_d, s_0, F)$ such that $\mathcal{L} = \mathcal{L}(\mathcal{D})$
- Let $p = |S| - 1$
- Then all the paths from s_0 to some final state that traverse every state at most once have their lengths bounded by p
- Then, by $|z| > p$, for some a_1, \dots, a_p and for some z' , $z = a_1 \cdots a_p z'$ and at least one state, say s^* , is traversed more than once along the path $a_1 \cdots a_p$

Pumping Lemma for regular languages

PROOF

- Then there is a cycle in \mathcal{D} that goes from s^* to s^* and that spells $a_{i+1} \cdots a_j$ for some i and j such that $i < j \leq p$
- Then let
 - $u = a_1 \cdots a_i$
 - $v = a_{i+1} \cdots a_j$
 - $w = \begin{cases} z' & \text{if } j = p \\ a_{j+1} \cdots a_p z' & \text{if } j < p \end{cases}$
- Then
 - $|uv| \leq p$
 - The length of v is at least 1
 - $uv^i w$ is accepted by \mathcal{D} for every $i \in \mathbb{N}$

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Pumping Lemma for regular languages

WHAT FOR

- Show by contradiction that a language is not regular
 - Assume the language be regular
 - Show that not(thesis) is true
- Thesis:

$\exists p \in \mathbb{N}^+. \forall z \in \mathcal{L}: |z| > p. \exists u, v, w. P$

where

$P \equiv (z = uvw \text{ and } |uv| \leq p \text{ and } |v| > 0 \text{ and } \forall i \in \mathbb{N}. uv^i w \in \mathcal{L})$
- not(thesis):

$\forall p \in \mathbb{N}^+. \exists z \in \mathcal{L}: |z| > p. \forall u, v, w. Q$

where

$Q \equiv (z = uvw \text{ and } |uv| \leq p \text{ and } |v| > 0) \text{ implies } (\exists i \in \mathbb{N}. uv^i w \notin \mathcal{L})$

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Pumping Lemma at work

LEMMA

$\mathcal{L} = \{a^n b^n \mid n > 0\}$ is not regular

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Pumping Lemma at work

PROOF

- Suppose \mathcal{L} is regular, and let p be an arbitrary positive integer
- Take $z = a^p b^p$
- Observe that $\forall u, v, w$ if $(z = uvw$ and $|uv| \leq p$ and $|v| > 0)$
 - Then v contains only a s, by $|uv| \leq p$
 - And v contains at least one a , by $|v| > 0$
- Then, for some $j > 0$, $uv^2w = a^p a^j b^p$
- Then $uv^2w \notin \mathcal{L}$ which contradicts the Pumping Lemma for regular languages

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Training

- Let \mathcal{L}_1 be the language of words over $\{a, b\}$ with an odd number of occurrences of bs . Is \mathcal{L}_1 regular?
- Let \mathcal{L}_2 be the language of words over $\{a, b\}$ with an even number of occurrences of as . Is \mathcal{L}_2 regular?
- Let \mathcal{L}_3 be the language of words over $\{a, b\}$ with an even number of occurrences of as and an odd number of occurrences of bs . Is \mathcal{L}_3 regular?

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Closure properties of regular languages

LEMMA

Regular languages are closed wrt

- union
- concatenation
- complementation
- intersection

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Lexical analysis

Provide input to syntax analysis

Example grammar: c99_grammar.y

Typical choice of tokens:

- One token for each keyword
- Tokens for operators (or for classes of operators)
- One token for identifiers
- Tokens for punctuation symbols

Task:

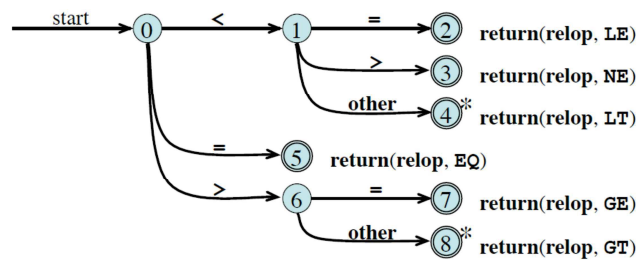
- Recognize lexemes
- Return tokens (pairs of token-name and token-value)

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Lexical analysis

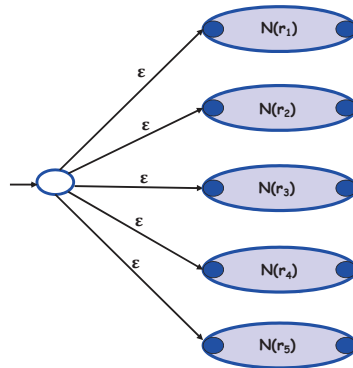
Lexemes

- Described by regular expressions
- Recognized by a state machine that can take appropriate actions when recognizing words



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Pattern matching based on NFAs



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Pattern matching based on NFAs

- Simulate the NFA
- Actions are associated with final states
- Find the longest match: continue simulating until no further move is possible
- If the reached set of states has associated actions, execute the “first” action
- Otherwise
 - Look backwards to the sequence of states
 - Pick up the first set of states containing at least a final one
 - Execute the “first” action
 - Update the pointer to the input buffer accordingly

Pattern matching based on DFAs obtained by subset construction is analogous

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Lexical analysis generators

FLEX

- flex is normally distributed with C, and available from <http://flex.sourceforge.net/>
- Write a file `file.l` for flex
- Compile `file.l` with flex and get `lex.yy.c`
- Compile `lex.yy.c` with gcc and get the lexer

```
$> flex file.l
$> gcc lex.yy.c -lfl
$> ./a
```

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Lexical analysis generators

FILES FOR FLEX

```
.....
%%
.....
%%
.....

%{ code
}%
shorthands for patterns
%%
pattern-1 {action-1};
pattern-2 {action-2};
....
%%
user routines, copied into lex.yy.c
```

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Lexical analysis generators

DISAMBIGUATION

```

.....
%%
pattern-1 {action-1};
pattern-2 {action-2};
....
%%
.....

```

- Always take the longest match
- If there are more longest matches, take the first in the list

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Lexical analysis generators

PATTERNS FOR FLEX

- Metacharacters
`\ / - * + > ' ' { } . $ () | % [] ^`
- Metacharacter matches

<code>.</code>	any character except newline
<code>\n</code>	newline
<code>*</code>	zero or more copies of
<code>+</code>	one or more copies of
<code>?</code>	zero or one copy of
<code>[]</code>	character class
<code>^</code>	beginning of line, negation if used in <code>[]</code>
<code>\$</code>	end of line
<code>a b</code>	a or b
<code>()</code>	grouping
<code>"+"</code>	literal <code>"+"</code>
<code>{ }</code>	regexp defined in the preamble

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