



UNIVERSITÀ  
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Department of  
Information Engineering and Computer Science

# Automated Reasoning and **Formal Verification**

## Laboratory 9

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<https://github.com/masinag/arfv2025>

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May 07, 2025

These slides are derived from those by Stefano Tonetta, Alberto Griggio, Silvia Tomasi, Thi Thieu Hoa Le, Alessandra Giordani, Patrick Trentin, Giuseppe Spallitta for FM lab 2005-2024.



# Outline

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## 1. Planning problem

Blocks Example

## 2. Exercises

## 3. Homeworks

## Planning Problem

Given  $\langle I, G, A \rangle$ , where

$I$  : (representation of) initial states

$G$  : (representation of) goal states

$A$  : (representation of) actions leading from one state to another

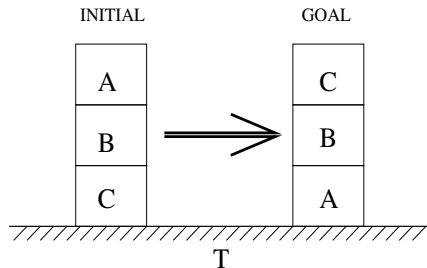
find a **plan** (sequence of actions)  $a_1, \dots, a_n$  leading from an initial state to a goal state.

## Idea: from Planning to Model Checking

Encode a planning problem as a model checking problem:

1. Impose  $I$  as initial state(s)
2. Encode  $A$  as transition relation system
3. Verify the LTL property  $(! F \text{ goal})$ . The plan is a **counter-example for it**.

# Example: Blocks [1/9]



*Init :*  $Above(A, B) \wedge Above(B, C) \wedge Above(C, T) \wedge Clear(A)$

*Goal :*  $Above(C, B) \wedge Above(B, A) \wedge Above(A, T)$

*Move(a, b, c)*

*Precond :*  $Block(a) \wedge Clear(a) \wedge Above(a, b) \wedge (Clear(c) \vee Table(c)) \wedge a \neq b \wedge a \neq c \wedge b \neq c$

*Effect :*  $Clear(b) \wedge \neg Above(a, b) \wedge Above(a, c) \wedge \neg Clear(c)$

## Example: Blocks [2/9]

```
MODULE block(id, ab, bl)
VAR   above : {none, a, b, c}; -- the block above this one
      below : {none, a, b, c}; -- the block below this one
DEFINE clear := (above = none);
INIT   above = ab & below = bl
INVAR  below != id & above != id -- a block cannot be above/below itself

MODULE main
VAR   move : {move_a, move_b, move_c}; -- at each step one block moves
      block_a : block(a, none, b);
      block_b : block(b, a, c);
      block_c : block(c, b, none);
...

```

## Example: Blocks [3/9]

---

- ▶ A block cannot move if it has some other block above itself

INVAR

```
(!block_a.clear -> move != move_a) &  
(!block_b.clear -> move != move_b) &  
(!block_c.clear -> move != move_c);
```

## Example: Blocks [3/9]

- ▶ A block cannot move if it has some other block above itself

INVAR

```
(!block_a.clear -> move != move_a) &  
(!block_b.clear -> move != move_b) &  
(!block_c.clear -> move != move_c);
```

Q: Why INVAR and not TRANS?

## Example: Blocks [3/9]

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**INVAR**

```
(!block_a.clear -> move != move_a) &  
(!block_b.clear -> move != move_b) &  
(!block_c.clear -> move != move_c);
```

**Q:** Why **INVAR** and not **TRANS**?

**A:** **INVAR** p is equivalent to **INIT** p and **TRANS** next(p).

With **TRANS** only, we could have in initial state with move\_b.



## Example: Blocks [3/9]

- ▶ A block cannot move if it has some other block above itself

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```
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**Q:** Why **INVAR** and not **TRANS**?

**A:** **INVAR** p is equivalent to **INIT** p and **TRANS** next(p).

With **TRANS** only, we could have in initial state with move\_b.

**Q:** What's wrong with following formulation?

**INVAR**

```
(block_a.clear -> move = move_a) &  
(block_b.clear -> move = move_b) &  
(block_c.clear -> move = move_c);
```

## Example: Blocks [3/9]

- ▶ A block cannot move if it has some other block above itself

**INVAR**

```
(!block_a.clear -> move != move_a) &  
(!block_b.clear -> move != move_b) &  
(!block_c.clear -> move != move_c);
```

**Q:** Why **INVAR** and not **TRANS**?

**A:** **INVAR** p is equivalent to **INIT** p and **TRANS** next(p).

With **TRANS** only, we could have in initial state with move\_b.

**Q:** What's wrong with following formulation?

**INVAR**

```
(block_a.clear -> move = move_a) &  
(block_b.clear -> move = move_b) &  
(block_c.clear -> move = move_c);
```

**A:** Two clear blocks would cause an **inconsistency** (move can have **one** valid value).  
Moreover, any non-clear block would still be able to move.

## Example: Blocks [4/9]

- ▶ A **moving** block changes location and remains clear

TRANS

```
(move = move_a -> next(block_a.clear) &  
                        next(block_a.below) != block_a.below) &  
(move = move_b -> next(block_b.clear) &  
                        next(block_b.below) != block_b.below) &  
(move = move_c -> next(block_c.clear) &  
                        next(block_c.below) != block_c.below);
```

- ▶ A **non-moving** block does not change its location

TRANS

```
(move != move_a -> next(block_a.below) = block_a.below) &  
(move != move_b -> next(block_b.below) = block_b.below) &  
(move != move_c -> next(block_c.below) = block_c.below);
```

- ▶ A block remains connected to any *non-moving* block

## TRANS

```
(move != move_a & block_b.above = a -> next(block_b.above) = a) &  
(move != move_a & block_c.above = a -> next(block_c.above) = a) &  
(move != move_b & block_a.above = b -> next(block_a.above) = b) &  
(move != move_b & block_c.above = b -> next(block_c.above) = b) &  
(move != move_c & block_a.above = c -> next(block_a.above) = c) &  
(move != move_c & block_b.above = c -> next(block_b.above) = c);
```

- ▶ A block remains connected to any *non-moving* block

## TRANS

```
(move != move_a & block_b.above = a -> next(block_b.above) = a) &  
(move != move_a & block_c.above = a -> next(block_c.above) = a) &  
(move != move_b & block_a.above = b -> next(block_a.above) = b) &  
(move != move_b & block_c.above = b -> next(block_c.above) = b) &  
(move != move_c & block_a.above = c -> next(block_a.above) = c) &  
(move != move_c & block_b.above = c -> next(block_b.above) = c);
```

Q: What about “below” block?

- ▶ A block remains connected to any *non-moving* block

## TRANS

```
(move != move_a & block_b.above = a -> next(block_b.above) = a) &  
(move != move_a & block_c.above = a -> next(block_c.above) = a) &  
(move != move_b & block_a.above = b -> next(block_a.above) = b) &  
(move != move_b & block_c.above = b -> next(block_c.above) = b) &  
(move != move_c & block_a.above = c -> next(block_a.above) = c) &  
(move != move_c & block_b.above = c -> next(block_b.above) = c);
```

**Q:** What about “below” block?

**A:** Covered in previous slide!

- Positioning of blocks: above and below relations must be symmetric.

## INVAR

```
(block_a.above = b <-> block_b.below = a) &  
(block_a.above = c <-> block_c.below = a) &  
(block_b.above = a <-> block_a.below = b) &  
(block_b.above = c <-> block_c.below = b) &  
(block_c.above = a <-> block_a.below = c) &  
(block_c.above = b <-> block_b.below = c);
```

Notice that the above handles also the case of none blocks!

## Remark

A **plan** is a sequence of transitions/actions leading from the initial state to an accepting/goal state.

## Idea

- ▶ Assert property  $p$ : “goal state is not reachable”
- ▶ If a plan **exists**, nuXmv produces a counter-example for  $p$
- ▶ The counterexample for  $p$  is a plan to reach the goal





# Example: Blocks [8/9]

## Examples

- ▶ Get a plan for reaching “goal state”

## Examples

- Get a plan for reaching “goal state”

### LTLSPEC

```
! F(block_a.below = none & block_a.above = b    &  
    block_b.below = a    & block_b.above = c    &  
    block_c.below = b    & block_c.above = none);
```

## Examples

- Get a plan for reaching “goal state”

LTLSPEC

```
! F(block_a.below = none & block_a.above = b    &  
    block_b.below = a    & block_b.above = c    &  
    block_c.below = b    & block_c.above = none);
```

- Get a plan for reaching a configuration in which all blocks are placed on the table

## Examples

- Get a plan for reaching “goal state”

LTLSPEC

```
! F(block_a.below = none & block_a.above = b    &  
    block_b.below = a    & block_b.above = c    &  
    block_c.below = b    & block_c.above = none);
```

- Get a plan for reaching a configuration in which all blocks are placed on the table

LTLSPEC

```
! F(block_a.below = none & block_b.below = none &  
    block_c.below = none);
```



# Example: Blocks [9/9]

---

## Examples

- ▶ At any given time, at least one block is placed on the table



# Example: Blocks [9/9]

## Examples

- ▶ At any given time, at least one block is placed on the table

INVARSPEC

```
block_a.below=none | block_b.below=none | block_c.below=none;
```

## Examples

- ▶ At any given time, at least one block is placed on the table

INVARSPEC

`block_a.below=none | block_b.below=none | block_c.below=none;`

- ▶ At any given time, at least one block has nothing above

## Examples

- ▶ At any given time, at least one block is placed on the table

INVARSPEC

`block_a.below=none | block_b.below=none | block_c.below=none;`

- ▶ At any given time, at least one block has nothing above

INVARSPEC

`block_a.above=none | block_b.above=none | block_c.above=none;`





# Outline

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1. Planning problem

2. Exercises

Tower of Hanoi

Ferryman

Tic-Tac-Toe

3. Homeworks

## Exercise 9.1: Tower of Hanoi

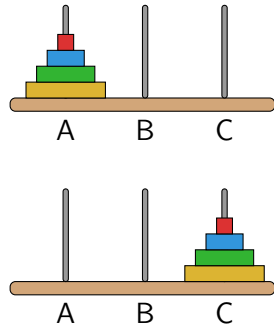
Given 3 poles and  $N$  disks of different sizes:

**Init** A stack of disks with decreasing sizes is placed on pole  $A$

**Goal** Move the stack to pole  $C$

**Rules**

- ▶ Only one disk can be moved per step
- ▶ Only the upper disk can be moved
- ▶ A disk cannot be put above a smaller disk



► Base system model

```
MODULE main
```

```
VAR d1    : {left,middle,right}; -- smallest  
    d2    : {left,middle,right};  
    d3    : {left,middle,right};  
    d4    : {left,middle,right}; -- largest  
    move  : 1..4;                -- possible moves
```

► Base system model

```
MODULE main
VAR d1    : {left,middle,right}; -- smallest
    d2    : {left,middle,right};
    d3    : {left,middle,right};
    d4    : {left,middle,right}; -- largest
    move  : 1..4;                -- possible moves
```

► A disk cannot move if a smaller disk is above it (i.e. they share the same column)

```
DEFINE clear1 := TRUE;
    clear2 := d2 != d1;
    clear3 := d3 != d1 & d3 != d2;
    clear4 := d4 != d1 & d4 != d2 & d4 != d3;
```



# Tower of Hanoi [3/5]

---

► Initial state

`INIT d1 = left & d2 = left & d3 = left & d4 = left;`



► Initial state

```
INIT d1 = left & d2 = left & d3 = left & d4 = left;
```

► Moves descriptions

TRANS

```
(move = 4 ->  
  -- disks location changes  
  next(d1) = d1 & next(d2) = d2 & next(d3) = d3 & next(d4) != d4 &  
  -- d4 can not move on top of smaller disks  
  next(d4) != d1 & next(d4) != d2 & next(d4) != d3) &  
(move = 3 -> ...)  
(move = 2 -> ...)  
(move = 1 -> ...);
```

- ▶ A non-clear disk cannot move

INVAR

```
(!clear1 -> move != 1) & (!clear2 -> move != 2) &  
(!clear3 -> move != 3) & (!clear4 -> move != 4);
```

- ▶ A non-clear disk cannot move

INVAR

```
(!clear1 -> move != 1) & (!clear2 -> move != 2) &  
(!clear3 -> move != 3) & (!clear4 -> move != 4);
```

- ▶ If all columns are being used, don't move the largest disk (or we would reach a deadlock).

INVAR

```
((clear1 & clear2 & clear3) -> move != 3) &  
((clear1 & clear2 & clear4) -> move != 4) &  
((clear1 & clear2 & clear3) -> move != 4) &  
((clear2 & clear3 & clear4) -> move != 4);
```



- Get a plan for a reaching “goal state”:

LTLSPEC

`! F (d1 = right & d2 = right & d3 = right & d4 = right);`

INVARSPEC

`! (d1 = right & d2 = right & d3 = right & d4 = right);`

## Exercise 9.2: Ferryman

A ferryman has to bring a sheep, a cabbage, and a wolf safely across a river:

**Init** all the items are on the right side

**Goal** all the items are on the left side

**Actions**

- ▶ The ferryman can have at most one passenger on his boat
- ▶ The cabbage and the sheep cannot be left unattended on the same side of the river
- ▶ The sheep and the wolf cannot be left unattended on the same side of the river

**Q:** Can the ferryman transport all the items to the other side safely?

► Base system model

```
MODULE main
```

```
VAR
```

```
  cabbage : {right,left};  sheep : {right,left};
```

```
  wolf    : {right,left};  man    : {right,left};
```

```
  move    : {c, s, w, e};  -- possible moves
```

```
DEFINE
```

```
  carry_cabbage := (move = c); carry_sheep := (move = s);
```

```
  carry_wolf    := (move = w); no_carry    := (move = e);
```

► Initial state

```
INIT cabbage = right & sheep = right & wolf = right & man = right;
```

- The ferryman can move to the other side of the river with one item at a time

TRANS

```
next(man) != man &
(carry_cabbage ->
  (next(cabbage) != cabbage & next(sheep) = sheep & next(wolf) = wolf)) &
(carry_sheep ->
  (next(cabbage) = cabbage & next(sheep) != sheep & next(wolf) = wolf)) &
(carry_wolf ->
  (next(cabbage) = cabbage & next(sheep) = sheep & next(wolf) != wolf)) &
(no_carry ->
  (next(cabbage) = cabbage & next(sheep) = sheep & next(wolf) = wolf));
```

- If the man is not in the same side of an item, we cannot choose it for the next movement (otherwise deadlock).

## TRANS

```
(next(man) != next(cabbage) -> !next(carry_cabbage)) &  
(next(man) != next(sheep) -> !next(carry_sheep)) &  
(next(man) != next(wolf) -> !next(carry_wolf));
```

- Get a plan for reaching a “goal state”

## DEFINE

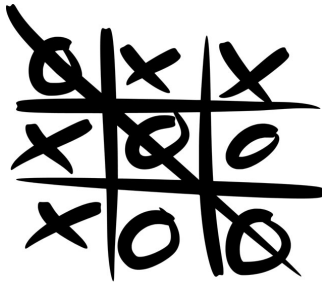
```
safe_state := (sheep = wolf | sheep = cabbage) -> sheep = man;  
goal := cabbage = left & sheep = left & wolf = left;
```

## LTLSPEC

```
! (safe_state U goal);
```

## Exercise 9.3: Tic-Tac-Toe

Tic-tac-toe is a turn-based game for two adversarial players ( $\times$  and  $\circ$ ) marking the squares of a  $3 \times 3$  grid. The player who succeeds in placing three respective marks in a horizontal, vertical or diagonal row wins the game.



Scenario where  $\circ$  wins

- Base system model: we model the grid as an array of size 9:

1		2		3
----- ----- -----				
4		5		6
----- ----- -----				
7		8		9

```
MODULE main
```

```
VAR
```

```
  B : array 1..9 of {0,1,2};
```

```
  player : 1..2;
```

```
  move : 0..9;
```

- Base system model: we model the grid as an array of size 9:

1		2		3
---		---		---
4		5		6
---		---		---
7		8		9

```
MODULE main
```

```
VAR
```

```
  B : array 1..9 of {0,1,2};
```

```
  player : 1..2;
```

```
  move : 0..9;
```

- Initial state

```
INIT
```

```
  B[1] = 0 & B[2] = 0 & B[3] = 0 & B[4] = 0 & B[5] = 0 &
```

```
  B[6] = 0 & B[7] = 0 & B[8] = 0 & B[9] = 0 & move = 0;
```





# Tic-Tac-Toe [3/5]

---

## ► Turns Modeling

### ASSIGN

```
init(player) := 1;
```

```
next(player) := player = 1 ? 2 : 1;
```



## ► Turns Modeling

### ASSIGN

```
init(player) := 1;  
next(player) := player = 1 ? 2 : 1;
```

## ► Moves Modeling

### TRANS

```
B[1] != 0 -> next(move) != 1;
```

### TRANS

```
next(move) = 1 -> next(B[1]) = player &  
  next(B[2])=B[2] & next(B[3])=B[3] & next(B[4])=B[4] &  
  next(B[5])=B[5] & next(B[6])=B[6] & next(B[7])=B[7] &  
  next(B[8])=B[8] & next(B[9])=B[9];
```

...

► “End” state

## DEFINE

```
win1 := (B[1]=1 & B[2]=1 & B[3]=1) | (B[4]=1 & B[5]=1 & B[6]=1) |
        (B[7]=1 & B[8]=1 & B[9]=1) | (B[1]=1 & B[4]=1 & B[7]=1) |
        (B[2]=1 & B[5]=1 & B[8]=1) | (B[3]=1 & B[6]=1 & B[9]=1) |
        (B[1]=1 & B[5]=1 & B[9]=1) | (B[3]=1 & B[5]=1 & B[7]=1);
win2 := (B[1]=2 & B[2]=2 & B[3]=2) | (B[4]=2 & B[5]=2 & B[6]=2) |
        (B[7]=2 & B[8]=2 & B[9]=2) | (B[1]=2 & B[4]=2 & B[7]=2) |
        (B[2]=2 & B[5]=2 & B[8]=2) | (B[3]=2 & B[6]=2 & B[9]=2) |
        (B[1]=2 & B[5]=2 & B[9]=2) | (B[3]=2 & B[5]=2 & B[7]=2);
draw := !win1 & !win2 &
        !(B[1]=0 | B[2]=0 | B[3]=0 | B[4]=0 | B[5]=0 |
          B[6]=0 | B[7]=0 | B[8]=0 | B[9]=0);
```

## INVAR

```
(win1 | win2 | draw) <-> next(move)=0;
```

- We can easily check if there is a way to reach every end state using the typical formulation:

LTLSPEC

! (F draw);

LTLSPEC

! (F win1);

LTLSPEC

! (F win2);

For each property, a trace satisfying the property is returned as a counterexample.



# Outline

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1. Planning problem
2. Exercises
3. Homeworks



## Homework 9.1: Tower of Hanoi

Extend the Tower of Hanoi to handle five disks, and check that the goal state is reachable.

## Homework 9.2: Ferryman

Another ferryman has to bring a fox, a chicken, a caterpillar and a crop of lettuce safely across a river.

**Init** All the items are on the right side

**Goal** All the items are on the left side

**Rules**

- ▶ The ferryman can cross the river with at most **two** passengers on his boat
- ▶ The fox eats the chicken if left unattended on the same side of the river
- ▶ The chicken eats the caterpillar if left unattended on the same side
- ▶ The caterpillar eats the lettuce if left unattended on the same side

Can the ferryman bring every item safely on the other side?