# TZE HO ELDEN TSE

https://eldentse.github.io

Intelligent Robotics Laboratory, School of Computer Science, University of Birmingham  $(+44)7865\ 630076 \Leftrightarrow \boxtimes \text{txt994@student.bham.com}$ 

#### **EDUCATION**

# University of Birmingham, United Kingdom

Feb. 2020 - present

Ph.D. student in Computer Science

Supervised by Dr. Hyung Jin Chang, Dr. Kwang In Kim and Prof. Aleš Leonardis

Research area: Graph Neural Networks in Computer Vision

# Cranfield University, United Kingdom

Sept. 2018 - Jun. 2020

PGDip in Engineering Competence Part of BAE Systems graduate scheme

## University of Oxford, United Kingdom

Oct. 2014 - Jul. 2018

M. Eng in Engineering Science (First Class Honours, 78%)

Specialised in Information Engineering

#### WORK EXPERIENCE

## University of Birmingham, United Kingdom

Mar. 2022 - present

Research Assistant

- · Collaboration with Dongguk University Machine Learning Lab.
- · Project title: "Graph Neural Network for Visual Recognition and Representation" In this research, we are developing a deep semantic graph neural network based knowledge representation and learning framework for high-level vision tasks, such as hand-object pose estimation and representation.

### BAE Systems, United Kingdom

Sept. 2018 - Jul. 2021

PLD Engineer

- · Hardware sensor design for Eurofighter Typhoon (6 months)
- · PLD verification for F-16 head-up-display (6months)
- · AI R&D with Innovation and Growth Team (6 months)
- · PLD verification for flight control computer (16 months)

#### **PUBLICATIONS**

S<sup>2</sup>Contact: Graph-based Network for 3D Hand-Object Contact Estimation with Semi-Supervised Learning

**Tze Ho Elden Tse\***, Zhongqun Zhang\*, Kwang In Kim, Aleš Leonardis, Feng Zheng, Hyung Jin Chang European Conference on Computer Vision (ECCV 2022)

Collaborative Learning for Hand and Object Reconstruction with Attention-guided Graph Convolution

**Tze Ho Elden Tse**, Kwang In Kim, Aleš Leonardis, Hyung Jin Chang *IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR 2022)* 

# TP-AE: Temporally Primed 6D Object Pose Tracking with Auto-Encoders

Linfang Zheng, Aleš Leonardis, **Tze Ho Elden Tse**, Nora Horanyi, Wei Zhang, Hua Chen, Hyung Jin Chang The 39th IEEE Conference on Robotics and Automation (ICRA 2022)

No Need to Scream: Robust Sound-based Speaker Localisation in Challenging Scenarios Tze Ho Elden Tse. D. De Martini and L. Marchegiani

The 11th International Conference on Social Robotics (ICSR 2019)

# **TEACHING**

Teaching Assistant [06/2022-09/2022] MSc projects

[02/2022-07/2022] Computer Vision and Imaging [09/2021-07/2022] MSc Computer Science project

[09/2021-01/2022] Programming for Data Science and AI

# ACADEMIC SERVICES

Reviewer ECCV 2022; ICML 2022; CVPR 2022, 2021; ICCV 2021; BMVC 2021; NeurIPS 2020

**AWARDS** 

2014-2018 College Scholarship for Outstanding Performance in Engineering Exams

# TECHNICAL STRENGTHS

Programming Languages Python, SystemVerilog, VHDL, MATLAB

Libraries PyTorch, PyTorch Geometric, OpenCV