#### Outline

- Static hashing
  - Division
  - –Mid square
  - —Folding
  - Digit analysis
- Overflow handling
  - -Open addressing
  - -Chaining



## Overflow Handling

- An overflow occurs when bucket is full
- We may handle overflows by
  - 1. Open addressing
    - Search the hash table in systematic fashion to exploit available buckets (and slots)
  - 2. Chaining
    - Eliminate overflows by permitting each bucket to keep all pairs in a linked list

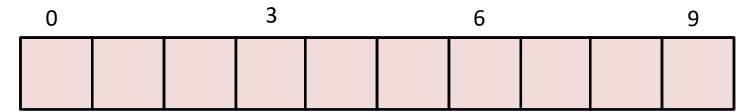


• Find available bucket by examining ht[(h(k)+j)%b] for j=0, 1, 2, ..., b-1

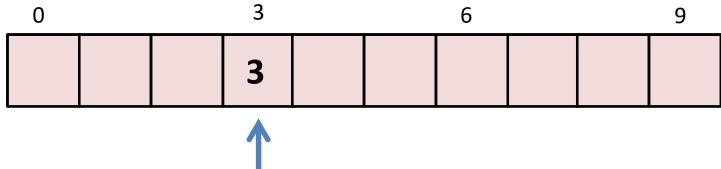
- Hash table operations
  - –Insert: find empty bucket
  - –Search: find matching key; If empty, key is not in the table
  - –Delete: delete matching key



- Divisor = # of buckets = 10
- h(k) = k % 10
- # of slots = 1



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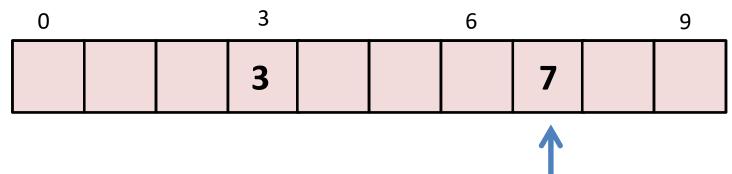




$$-3\%10=3$$



- Divisor = # of buckets = 10
- h(k) = k % 10
- # of slots = 1

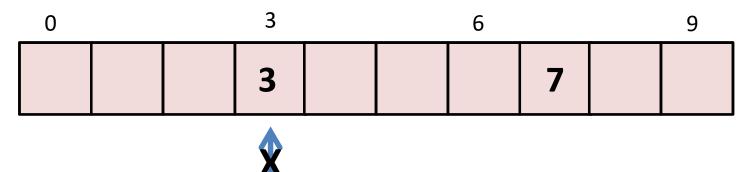




$$-7\%10=7$$



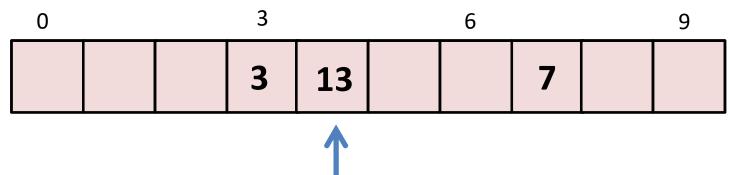
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- Insert 13
  - $-13\%10=3 \rightarrow \text{collision & overflow!}$



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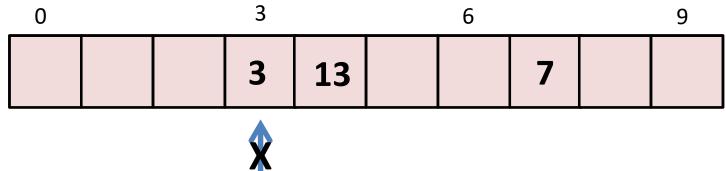


• Insert 13

$$-(13+1)\%10=4$$



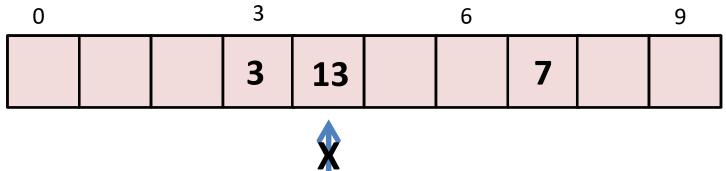
- Divisor = # of buckets = 10
- h(k) = k % 10
- # of slots = 1



- Insert 23
  - $-23\%10=3 \rightarrow \text{collision & overflow!}$



- Divisor = # of buckets = 10
- h(k) = k % 10
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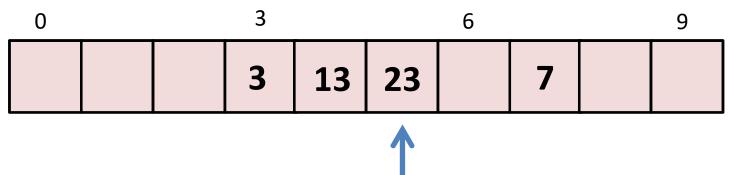


Insert 23

$$-(23+1)\%10=4 \rightarrow \text{collision & overflow!}$$



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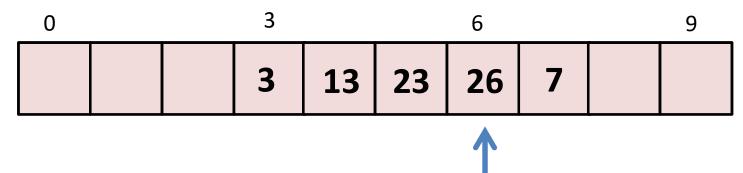




$$-(23+2)\%10=5$$



- Divisor = # of buckets = 10
- h(k) = k % 10
- # of slots = 1





$$-26\%10=6$$



- Divisor = # of buckets = 10
- h(k) = k % 10
- # of slots = 1

0	3			6		_	9
	3	13	23	26	7	36	

- Insert 36
  - $-36\%10=6 \rightarrow collision \& overflow!$
  - -Next available bucket: 8



- Divisor = # of buckets = 10
- h(k) = k % 10
- # of slots = 1



Same color: same hash value group



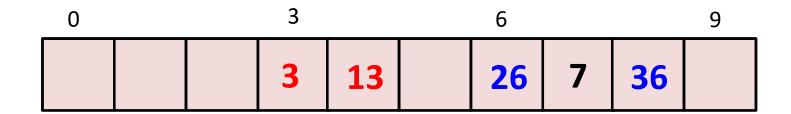
- Divisor = # of buckets = 10
- h(k) = k % 10
- # of slots = 1



- Delete 23
  - —Then, search the right-side cluster if there is a key to shift to left



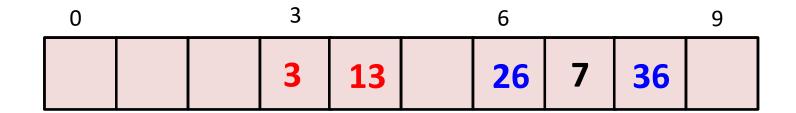
- Divisor = # of buckets = 10
- h(k) = k % 10
- # of slots = 1



• Delete 23

$$-h(26) = 6$$
,  $h(7) = 7$ ,  $h(36) = 8$  (due to collision at 6): no shifting required

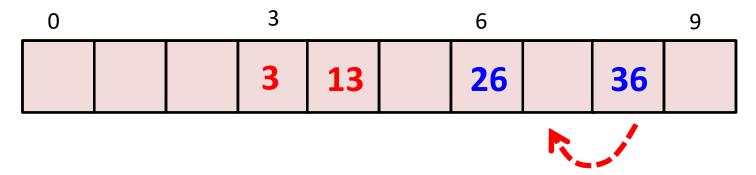
- Divisor = # of buckets = 10
- h(k) = k % 10
- # of slots = 1



- Delete 7
  - -Then, search the right-side cluster (which is 36)



- Divisor = # of buckets = 10
- h(k) = k % 10
- # of slots = 1

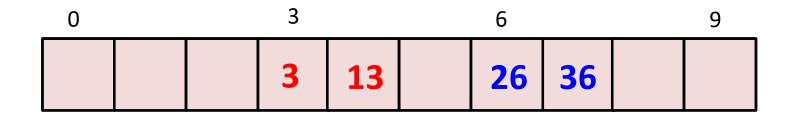


• Delete 7

-h(36) = 7 (since 6 is collision and 7 is empty)



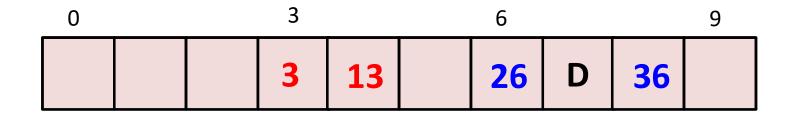
- Divisor = # of buckets = 10
- h(k) = k % 10
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- Delete 7
  - -Shift 36 to left



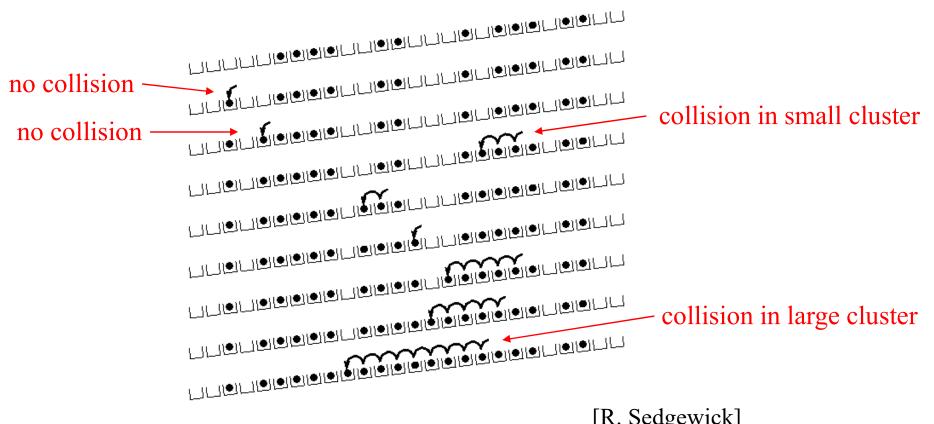
- Divisor = # of buckets = 10
- h(k) = k % 10
- # of slots = 1



- Delete without shifting
  - -Mark as *deleted*, and a new key can be inserted to that location later (retain cluster)



# Linear Probing – Clustering



[R. Sedgewick]



#### Performance of Linear Probing

- Load factor  $\alpha = \frac{n}{sb}$  is important for performance
  - -If  $\alpha$  is small, fewer collisions occur
  - -If  $\alpha$  is large, hash table is filling up, clusters get fewer and larger, and more collisions occur
    - Collision resolution is more costly
- Worst-case search/insert/delete time
  - -O(n), when?



#### Search Performance

Expected # of probed for large tables

-Successful search: 
$$\frac{1}{2} \left[ 1 + \frac{1}{1-\alpha} \right]$$

-Unsucessful search: 
$$\frac{1}{2} \left[ 1 + \frac{1}{(1-\alpha)^2} \right]$$

α	S <sub>n</sub>	U <sub>n</sub>
0.50	1.5	2.5
0.75	2.5	8.5
0.90	5.5	50.5

Performance quickly degrades for  $\alpha > 0.5$ 



#### Discussion about Linear Probing

- Pros
  - –Simple to compute
- Cons
  - -Clustering: increase the average time to locate keys
  - -Worst case O(n) for hash table operations
  - Delete can be more expensive due to shifting
- More random redistribution is desired



#### **Quadratic Probing**

- $ht[(h(k)+j^2)\%b]$  for j=0, 1, 2, ..., b-1
- Search the next available bucket from the original address by the distance 1, 4, 9, 16, ...
- Pros
  - -Simple calculation, reduce clustering
- Cons
  - Not all buckets can be examined



#### Other Open Addressing Methods

#### Rehashing

- –Use a series of different hash functions  $h_1$ ,  $h_2$ , ...,  $h_m$
- $-ht[h_i(k)\%b]$  for j=1, 2, ..., m
- -Minimize clustering

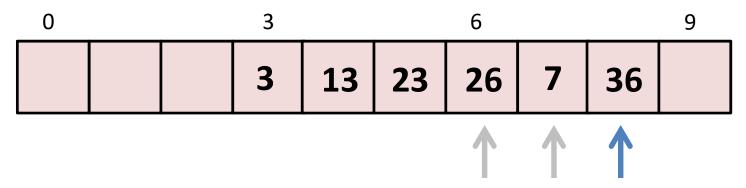
#### Random probing

- -ht[(h(k)+s(i))%b] for i=1, 2, ..., b-1
- -s(i): pseudo random number between 1 to b-1
  - Each number is generated only once



#### Chaining: Motivation

- Problem of open addressing
  - Unnecessarily compare keys that have different hash values → unnecessarily increase costs



- To find 36, comparing to 26 and 7 is required
  - -h(7) != h(36), so this comparison is unnecessary



#### Chaining

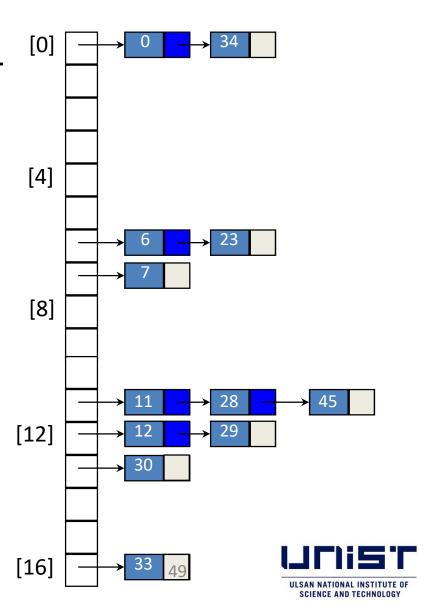
- Linear list per each hash address
  - Chain (singly linked list) is often used
  - -Sorted or unsorted
- ht[0:b-1]: has table with b buckets
- ht[i]: point to the first node of the chain for bucket i



#### **Example: Sorted Chain**

Insert 6, 12, 34, 29, 28, 11, 23, 7, 0, 33, 30, 45

• h[k] = k%17



#### **Expected Performance**

#### Chaining

$$U_n \approx \alpha$$
  
 $S_n \approx 1 + \frac{\alpha}{2}$   
 $\alpha = \frac{n}{b}$ : loading density

α	S <sub>n</sub>	U <sub>n</sub>
0.50	1.25	0.5
0.75	1.375	0.75
0.90	1.45	0.9

- Less calculation than open addressing
- Extra dynamic memory usage (pointers)



### Hash Table Design

- Maximum permissible loading density for given performance requirements
- e.g., linear probing
  - -Max comparison for successful search: 10
    - $S_n \sim \frac{1}{(1 + 1/(1 \alpha))}$
    - α <= 18/19
  - -Max comparison for unsuccessful search: 13
    - $U_n \sim \frac{1}{(1 + 1/(1 \alpha)^2)}$
    - $\alpha <= 4/5$
  - -Therefore,  $\alpha \le \min\{18/19, 4/5\} = 4/5 = 0.8$



#### Hash Table Design

- Dynamic resizing of table
  - -When loading density exceeds threshold
  - Array doubling
  - -Rehash old table into new large table (slow)



## Questions?

