

Computer Vision

Lecture 01: Computer vision overview



Course overview

CSE 54501 Computer Vision

Instructor:

- Prof. Seungryul Baek (AIGS, Dept. of CSE)

Goal

- Understand what is computer vision/deep learning algorithms.
- Understand how to implement image/video processing algorithms in Python using OpenCV.
- Understand how to implement/train/test convolutional neural networks (CNNs) and Transformer in PyTorch.

Syllabus

Before mid-term

- Understand basic machine learning & deep learning.
- Understand how to Implement CV algorithms with OpenCV and PyTorch libraries.

After mid-term

- Operate lectures for the challenge (Final term project)
- Recent paper review session.



Grading

- Programming assignments: 50%
 - Python implementation of algorithms.
- **Quizzes**: 20%
 - 2-3 quizzes during the course.
 - Notice 1 week before.
- Final-term Exam: 30%
 - Object recognition challenge (Tentative) conducted with 4-5 team members.



Grading

Late policy:

- 1 free late days
- 25% off per day late



Why should you take this class?

Become a vision researcher in academia

- CVPR/ECCV/ICCV conference
- NeurIPS/ICLR/ICML conference

Become a vision engineer in industry

- Naver, Kakao, Samsung, ...
- Google, Facebook, Amazon, Microsoft, Apple,...

General interest



Pre-requisite

Proficiency in Python

All class assignments will be in Python

We will further learn:

- Computer vision library: OpenCV.
- Deep learning library: PyTorch.
 (We do not allow to use Tensorflow for assignments.)

Pre-requisite

Mathematical Background

- Basic Linear Algebra (Matrix multiplication, ...)
- Basic Probabilistic theory (Random variables, ...)
 - Applied Linear Algebra
 - Probability and Intro. To Random Process

We will further learn:

Machine learning/Deep learning algorithms.

Optional textbook resources

Deep Learning

- Goodfellow, Bengio and Courville
- We have a web access to this material (https://www.deeplearningbook.org/).

Dive into deep learning

We have a web access to this material (https://d2l.ai/).

Assignments

- Programming assignments will be given in this course.
- Two ways of completing assignments
 - On your own local machines w/ GPUs.
 - On Google Colab
 - https://colab.research.google.com/
 - Provides 12 hours of consecutive access to GPUs.
 - After 12 hours, you have to re-connect it.



Final Term Project

- Accuracy will account for 30% of overall score.
 - You may need to secure your own GPU.
- Remaining 70% will be reserved for:
 - Novelty of the work.
 - Result analysis.
 - Team collaboration.
 - Etc.

- Rule 1: You must not look at solutions that are not your own.
 - It is an act of plagiarism to submit work that is copied or derived from the work of others and submitted as your own. Specifically, you should not use nor look at a solution in part or in whole from the Internet, another student (past or present), or some other sources. Many Honor Code infractions we see make use of solution found online. The best way to steer clear of this possibility is not to search for online solutions. Moreover, looking at someone else's solution in order to determine how to solve the problem yourself is also an infraction of the Honor Code. In essence, you should not be looking at someone else's solution in order to solve the problems in class. This is not an appropriate way to "check your work," "get direction," or "see alternative approaches."

- Rule 2: You must not share your solution with other students (even unintentionally).
 - In particular:
 - You should not ask anyone to give you their solution.
 - You should not give your solution to another student who asks you for it, even for friends and family.
 - You should not discuss your algorithmic strategies to such an extent that you and your collaborators end up turning in the same solution.
 - You are expected to take reasonable measures to maintain the privacy of your solutions. For example, you should not leave copies of your work on public computers. Make sure your code does not remain in recycling bins or undeleted trash folders on public computers.
 - You should not post your solution on a public website even after the due date. Posting the solutions from past years is not allowed. Even though you are not taking a particular class, you should not post the solution that can be accessed by the students of that particular class.

UNIST ECE Policy on Cheating and Plagiarism

- Rule 3: You must indicate on your submission any assistance you received. If you make use of such assistance without giving proper credit, you may be guilty of plagiarism.
 - If you received aid while producing your solution, you should indicate from whom you got help (if that person is not a section leader, TA, or instructor for this class) and what help you received. A proper citation should specifically identify the source (e.g., person's name, book title, website URL, etc.) and a clear indication of how this assistance influenced your work (be as specific as possible). For example, you might write "I discussed the approach used for sorting numbers in the sortNumbers method with David." If you make use of such assistance without giving proper credit, you may be guilty of plagiarism.

- Rule 4: You should not use your previous work (self-plagiarism).
 - It is not allowed to use the solutions you submitted in other classes even though it is your own work. This is classified as "self-plagiarism". It is also not allowed to use specific programming or algorithmic templates you used from your previous training/study because this makes the solution similar if others took the same training.

Collaboration Guidelines

- You are encouraged to collaborate amongst yourselves.
 However, the discussion must be "high level" and "general", and actual solutions/source code should not be shared in any case. More specifically, the following are permitted:
 - Discussion of material covered during lecture, problem sessions, or in handouts
 - Discussion of the requirements of an assignment
 - Discussion of the use of tools or development environments
 - Discussion of general approaches to solving problems
 - Discussion of general techniques of coding or debugging (but debugging code for someone else is not allowed)
 - Discussion between a student and a TA or instructor for the course

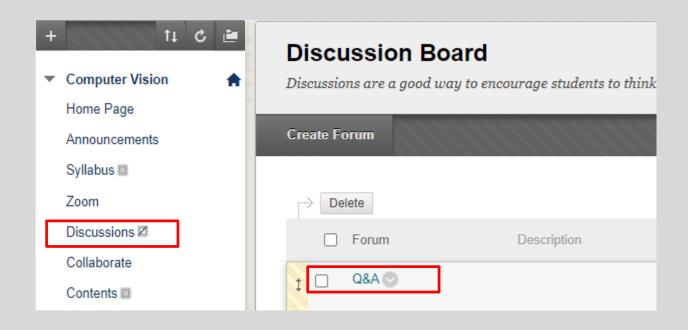
Cheating cases

- Case 1: Looking at someone else's homework.
- Case 2: Copying the solution in preparing homework.
- Case 3: Copying someone else's programming code
- Case 4: Copying code found from the Internet.
- Case 5: Helping others in preparing their homework or projects, without authorization.

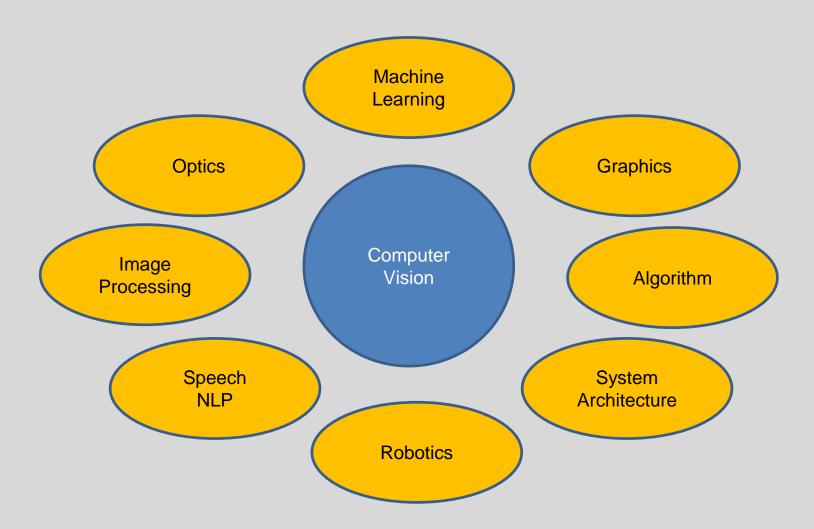




- Over 50 students are taking this class.
- I highly recommend you to use the Q&A board in the BB for Q&A. (Answers will be made within 48 hours.)



What is computer vision?



What is deep learning?



Sensational Go Match between AlphaGO and Lee Sedol (2016)

AlphaGO won Lee Sedol by 4 vs. 1

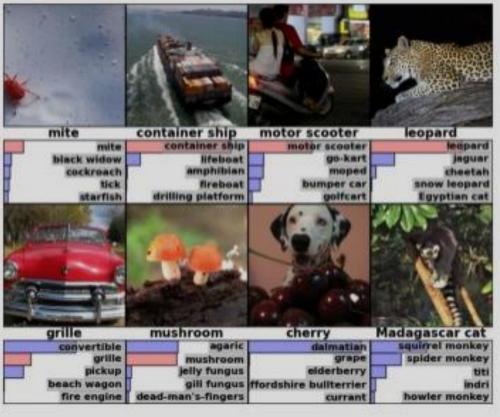
AlphaGo is using a deep learning when training their parameters.

What is deep learning?

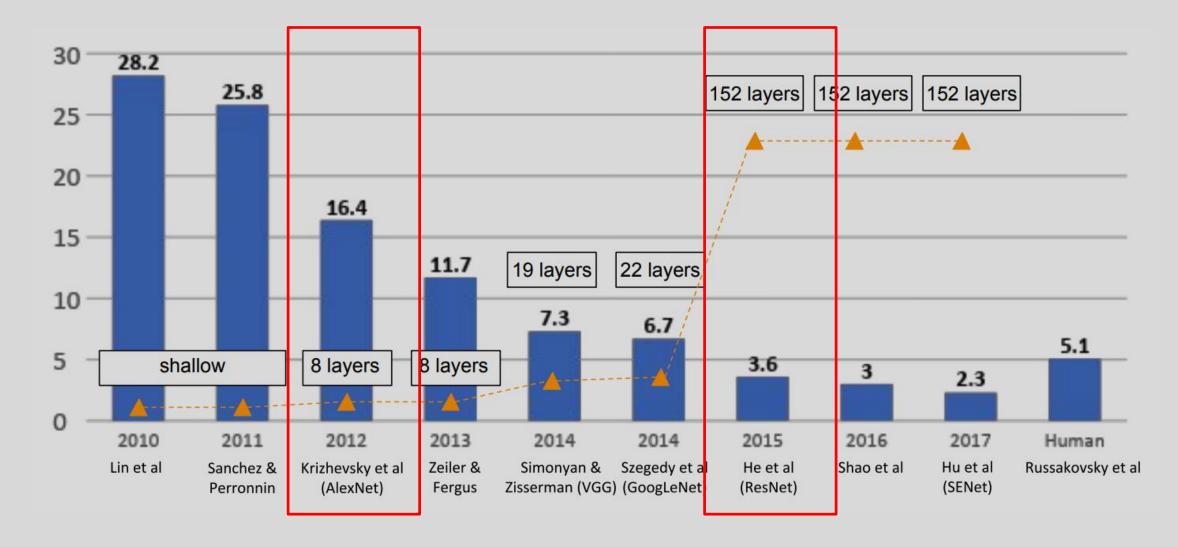
ImageNet Challenge



- 1,000 object classes (categories).
- Images:
 - o 1.2 M train
 - 100k test.



ImageNet winners (getting deeper)



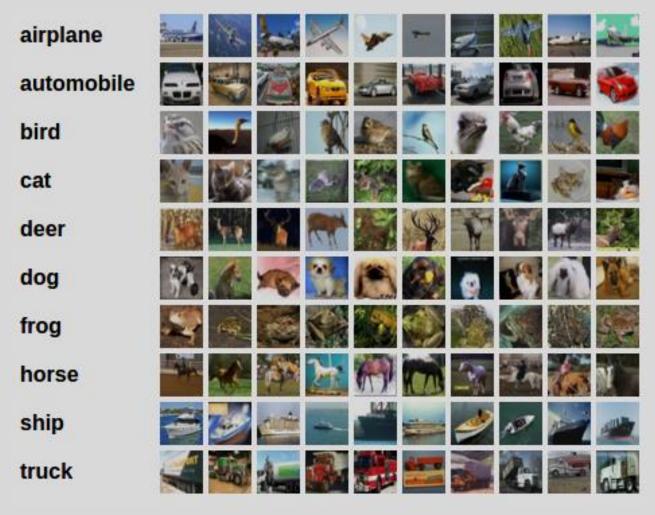
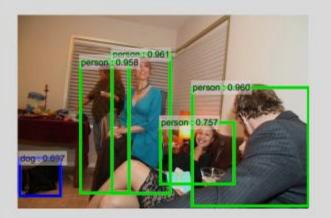
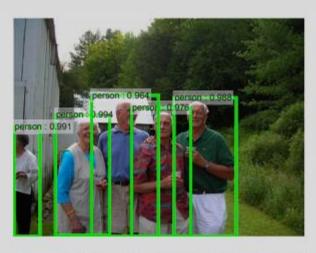
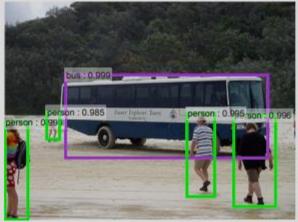


Image classification for Cifar-10 dataset.

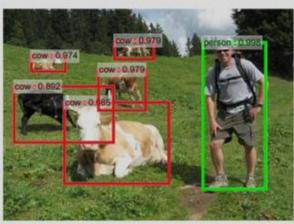










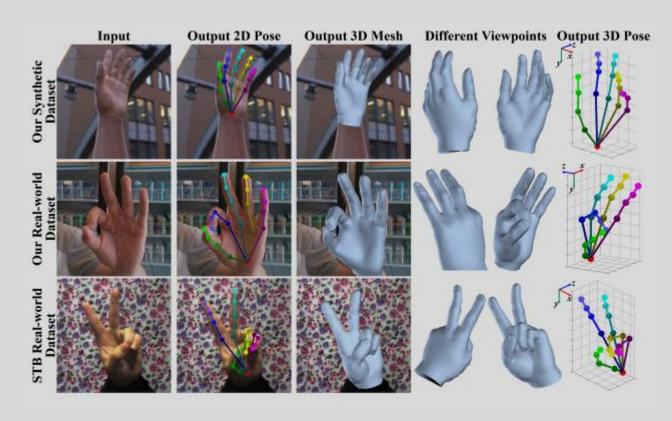


Detecting object locations. [Faster-RCNN NIPS'15]



Detecting object locations and segmentation. [Mask RCNN ICCV'17]





3D hand mesh reconstruction (Ge et al. CVPR'19)



3D human mesh reconstruction (Kanazawa et al. CVPR'18)



Image attribute translation (Binod et al. ICASSP'20)



Google colab

- Free cloud service with GPU for AI developers who have gmail address.
- It is provided by Google.
- We can use python and its libraries (OpenCV, PyTorch, Tensorflow,...)
- http://colab.research.google.com



Google colab

- 1) make a new notebook.
- 2) Type python code and it simply works!

```
print('hello world')

print('hello world')

hello world
```



Open CV Library

- Open source computer vision library.
- Provides easy interface to code image processing.
- Compatible with C/C++, JAVA, Python and etc.
- In python, do import &v2
- Files required are uploaded in this link:

https://drive.google.com/drive/folders/1Gq30m_MtY6N7-hO8dSo3vYD6FEE2aNf3?usp=sharing

OpenCV - Image read

```
from google.colab.patches import cv2_imshow
import cv2
img = cv2.imread('/content/example.jpg', cv2.IMREAD_UNCHANGED)
cv2 imshow(img)
```



OpenCV - Image read

```
from google.colab.patches import cv2_imshow
import cv2
img = cv2.imread('/content/example.jpg', cv2.IMREAD_GRAYSCALE)
cv2 imshow(img)
```





OpenCV - Image shape

```
img.shape

(454, 680, 3) Width of image, height of image, channel # of image.

img[0, 0]

array([182, 115, 0], dtype=uint8) RGB values for x=1, y=1 pixels.

img[0, 0, 0]

182
```



OpenCV - Image channel

from google.colab.patches import cv2_imshow import cv2 img = cv2.imread('/content/example.jpg', cv2.IMREAD_UNCHANGED)

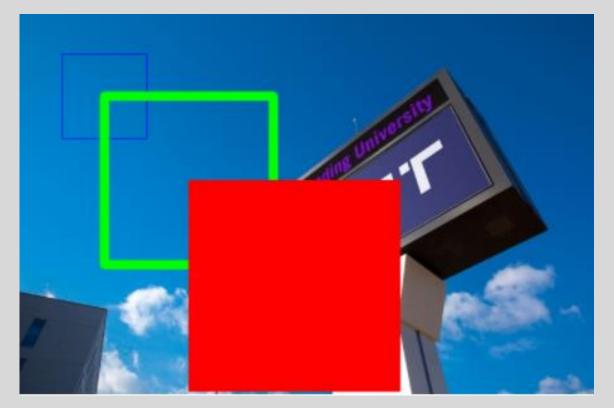
cv2_imshow(img[:, :, 0]) # showing blue channels only.





OpenCV – Draw rectangles

```
from google.colab.patches import cv2_imshow import cv2 img = cv2.imread('/content/example.jpg', cv2.IMREAD_UNCHANGED) cv2.rectangle(img, (50, 50), (150,150), (255, 0, 0)) cv2.rectangle(img, (300, 300), (100,100), (0, 255, 0), 10) cv2.rectangle(img, (450, 200), (200,450), (0, 0, 255), -1) cv2_imshow(img)
```





OpenCV - Draw polylines

from google.colab.patches import cv2_imshow import cv2 img = cv2.imread('/content/example.jpg', cv2.IMREAD_UNCHANGED)

import numpy as np pts1 = np.array([[50,50], [150,150], [100,140], [200,240]], dtype=np.int32) cv2.polylines(img, [pts1], False, (255,0,0))

cv2_imshow(img)





OpenCV – Draw circles

from google.colab.patches import cv2_imshow import cv2 img = cv2.imread('/content/example.jpg', cv2.IMREAD_UNCHANGED) cv2.circle(img, (150,150), 100, (255,0,0)) cv2.ellipse(img, ((325,300), (150,100), 0), (0, 255,0), 5)



cv2_imshow(img)



OpenCV – Put texts

from google.colab.patches import cv2_imshow import cv2 img = cv2.imread('/content/example.jpg', cv2.IMREAD_UNCHANGED)

cv2.putText(img, 'UNIST CSE48001 Computer Vision!', (20,50), cv2.FON T_HERSHEY_PLAIN, 2, (0,255,0))

cv2_imshow(img)



cv2_imshow(dst2)



OpenCV – Image resize

from google.colab.patches import cv2_imshow import cv2 img = cv2.imread('/content/example.jpg', cv2.IMREAD_UNCHANGED)

height, width = img.shape[:2]
dst1 = cv2.resize(img, None, None, 0.5, 0.5, cv2.INTER_CUBIC) #decrease image size by ½.
dst2 = cv2.resize(img, None, None, 2, 2, cv2.INTER_CUBIC) #increase image size by 2.

cv2_imshow(dst1)
cv2_imshow(img)





OpenCV – Image blurring

from google.colab.patches import cv2_imshow import cv2

img = cv2.imread('/content/example.jpg', cv2.IMREAD_UNCHANGED)

blur1 = cv2.blur(img, (10,10))

cv2_imshow(blur1)





OpenCV – Edge detection

from google.colab.patches import cv2_imshow import cv2 img = cv2.imread('/content/example.jpg', cv2.IMREAD_UNCHANGED)

edges = cv2.Canny(img, 100, 200)

cv2_imshow(edges)





OpenCV – Corner detection

```
from google.colab.patches import cv2_imshow import cv2 img = cv2.imread('/content/example.jpg', cv2.IMREAD_UNCHANGED) gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY) corner = cv2.cornerHarris(gray, 2, 3, 0.04) coord = np.where(corner > 0.1*corner.max()) coord = np.stack((coord[1], coord[0]), axis=-1) for x, y in coord: cv2.circle(img, (x,y), 5, (0,0,255), 1, cv2.LINE_AA) cv2_imshow(img)
```



OpenCV – Image matching

```
from google.colab.patches import cv2_imshow import cv2

img1 = cv2.imread('/content/example.jpg', cv2.IMREAD_UNCHANGED)
img2 = cv2.imread('/content/example4.jpg', cv2.IMREAD_UNCHANGED)
gray1 = cv2.cvtColor(img1, cv2.COLOR_BGR2GRAY)
gray2 = cv2.cvtColor(img2, cv2.COLOR_BGR2GRAY)

detector = cv2.ORB_create()
kp1, desc1 = detector.detectAndCompute(gray1, None)
kp2, desc2 = detector.detectAndCompute(gray2, None)

matcher = cv2.BFMatcher(cv2.NORM_L1, crossCheck=True)
matches = matcher.match(desc1, desc2)

res = cv2.drawMatches(img1, kp1, img2, kp2, matches, None, flags=cv2.DRAW_MATCHES_FLAGS_NOT_D
RAW_SINGLE_POINTS)
```



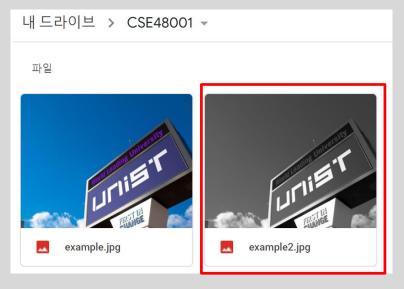
cv2 imshow(res)



OpenCV – Image save

from google.colab.patches import cv2_imshow import cv2 img = cv2.imread('/content/example.jpg', cv2.IMREAD_GRAYSCALE) cv2_imshow(img)

save_file = '/content/example2.jpg'
cv2.imwrite(save_file, img)



New image is saved.



OpenCV - Video read

```
from google.colab.patches import cv2_imshow import cv2

cap = cv2.VideoCapture('/content/example.avi') while True:
 ret, img = cap.read()
 if ret:
 cv2_imshow(img)
```

