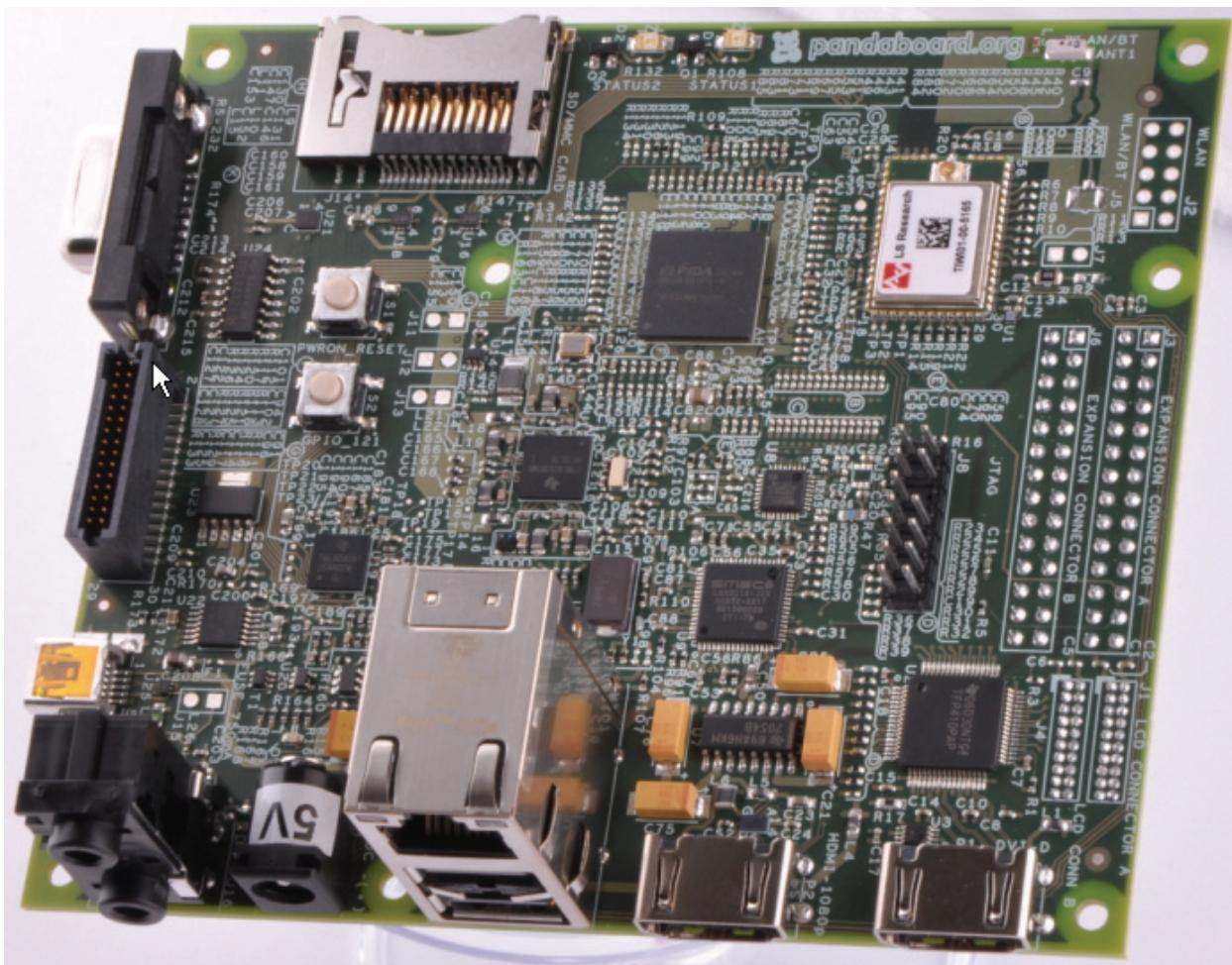




# pandaboard.org

# ***OMAP™ 4 PandaBoard System Reference Manual***





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## Preface

# Read This First

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### About This Manual

This manual should be used by software and hardware developers of applications based on the OMAP4430 chipset. This document describes the OMAP4430 PandaBoard hardware. This document also gives the user information about the different interfaces on the OMAP4430 PandaBoard.

### Related Documentation

- OMAP4430 Technical Reference Manual
- PandaBoard Schematic (750-2152-001-SCH) – Early Adopter Board
- PandaBoard Gerber Files (720-2152-001) – Early Adopter Board
- PandaBoard Bill-of-Materials (750-2152-001-EBOM) – Early Adopter Board
- PandaBoard Schematic (750-2152-002-SCH) – Production Board
- PandaBoard Gerber Files (720-2152-002) – Production Board
- PandaBoard Bill-of-Materials (750-2152-010-EBOM) – Production Board





## Revision History

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### Revision History

Rev	Changes	Date
0.1	Preliminary Release	24 Aug. 2010
0.2	Re-release after initial feedback	2 Sept. 2010
0.3	Document Board ID bits	8 Sept. 2010
0.4	Add information for schematics, PCB information	22 Sept. 2010





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**pandaboard.org**

## **OMAP™ 4 PandaBoard System Reference Manual**

*Revision 0.4  
September 22, 2010  
DOC-21010*

# **1 Introduction**

---

This document is the System Reference Manual for the PandaBoard, a low cost OMAP4430 based board supported through <http://pandaboard.org>. This includes system setup and debugging. This document provides detailed information on the overall design and usage of the PandaBoard from the System perspective.



**pandaboard.org**



## 1.1 OMAP4430 PandaBoard Overview

PandaBoard is an OMAP4430 platform designed to provide access to as many of the powerful features of the OMAP4430 Multimedia Processor as possible, while maintaining a low cost. This will allow the user to develop software to utilize the features of the powerful OMAP4430 processor. In addition, by providing expandability via onboard connectors, the PandaBoard supports development of additional capabilities/functionality. See Table 1 for a listing of the PandaBoard features.

Feature		
<b>Processor</b>		OMAP4430
<b>POP Memory</b>		Micron 8Gb LPDDR2 (EDB8064B1PB-8D-F)
<b>PMIC</b>		TI (TWL6030 Power Management Companion IC)
<b>Debug Support</b>	14-pin JTAG	GPIO Pins
	UART via DB-9 connector	LEDs
<b>PCB</b>	4.5" x 4.0" (114.3 x 101.6 mm)	8 layers
<b>Indicators</b>	3 LEDs (two user-controlled, one overvoltage indicator)	
<b>HS USB 2.0 OTG Port</b>	Mini-AB USB connector, sourced from OMAP USB Transceiver	
<b>HS USB Host Port</b>	Four USB HS Ports, up to 500mA current out on each, two to onboard connectors, two to expansion connectors	
<b>Audio Connectors</b>	3.5mm, L+R out	3.5mm, Stereo In
<b>SD/MMC Connector</b>	6 in 1 SD/MMC/SDIO	4/8 bit support, Dual voltage
<b>User Interface</b>	1-User defined button	Reset Button
<b>Video</b>	DVI-D or HDMI,	Optional user provided plug-in display
	Optional Composite Video out to two-pin header	
<b>Power Connector</b>	USB Power	DC Power
<b>Camera</b>	Not included, but supported via camera expansion connector	
<b>Expansion Connectors (not populated)</b>	See Paragraph 2.16, on page 42	
<b>LCD Expansion Connectors (not populated)</b>	See Paragraph 2.12.2, on page 32	

Table 1: PandaBoard Features





## 1.2 Overview of the OMAP4430 PandaBoard Kit Contents

The OMAP4430 PandaBoard kit contains the following items:

- 1 PandaBoard
- Board packing material
- 1 Shipping Box

The following items can be used with the PandaBoard, but are NOT included in the kit.

- USB Cable (mini-AB to Type A)
- HDMI Cable (Type A)
- DB-9 Male-to-female cable (null-modem)
- HDMI-A Male to DVI-D Cable
- DC wall supply (+5Vdc) – an example of an acceptable supply is Digikey P/N T951-P5P-ND. Information for this part may be found at:  
[http://search.digikey.com/scripts/DkSearch/dksus.dll?lang=en&site=US&WT.z\\_homepage\\_link=hp\\_go\\_button&KeyWords=T951-P5P-ND](http://search.digikey.com/scripts/DkSearch/dksus.dll?lang=en&site=US&WT.z_homepage_link=hp_go_button&KeyWords=T951-P5P-ND)





## 2 OMAP4430 PandaBoard Architecture

---

This chapter explains the architecture of the OMAP4430 PandaBoard.

### 2.1 Overview of the PandaBoard Architecture

Shown in Figure 1 is the Architectural Block Diagram of the OMAP4430 PandaBoard.

Listed below are the major components used on the PandaBoard.

- OMAP4430 Processor
- TWL6030 (Phoenix) Power Management Companion Device
- TWL6040 (Phoenix) Audio Companion Device
- POP Mobile LPDDR2 SDRAM Memory
- HDMI Connector (Type A) – for OMAP4430 HDMI Transmitter output
- HDMI Connector (Type A) – for DVI-D output sourced via OMAP4 parallel display output
- Audio Input & Output Connectors (3.5mm)
- SD/SDIO/MMC Media Card Cage
- UART via RS-232 interface via 9-pin D-Sub Connector
- LS Research Module – 802.11b/g/n, Bluetooth, FM

The Platform also includes connectors that can be used for additional functionality and/or expansion purposes. These connectors are not populated on the platform, but can be installed by the user. They are indicated by the blue blocks in Figure 1, and include:

- Camera Connector (J17)
- LCD Expansion Connectors (J1 and J4)
- Generic Expansion Connectors (J3 and J6)
- Composite Video Header (J12)

See Figure 2 on page 16 for a top side view of the Panda Platform.

The core components of the PandaBoard will be discussed in this section of the document. This would include the OMAP4430 Processor and its POP LPDDR2 memory, the input clock circuitry, the TWL6030 Power Companion IC, and the TWL6040 Audio Companion IC. The functional interfaces will be discussed in later sections of the document.



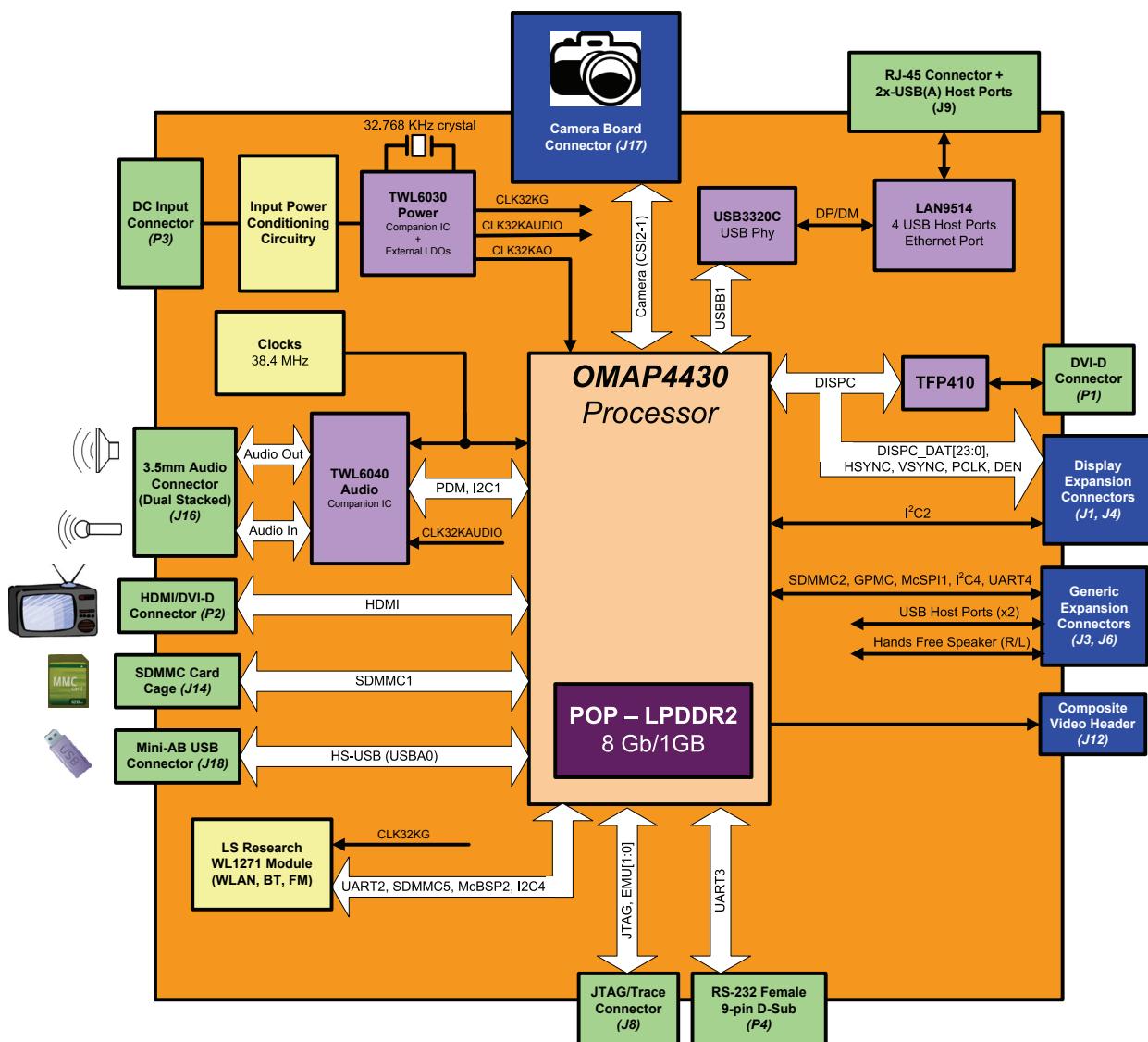


Figure 1 – OMAP4430 PandaBoard Architectural Block Diagram



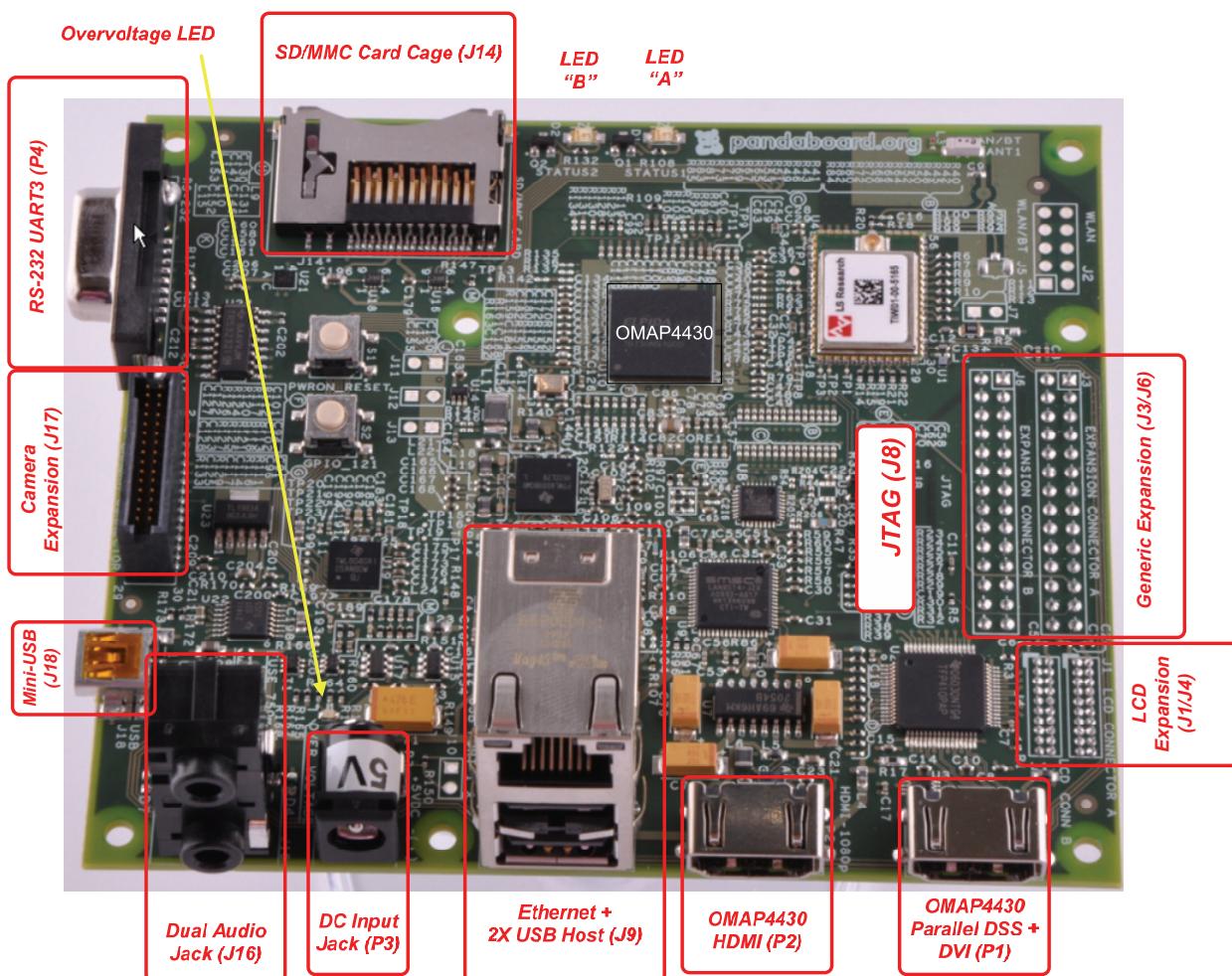


Figure 2 – OMAP4430 PandaBoard (Top View)





## 2.2 System Clock Distribution

The OMAP4430 PandaBoard implements a 38.4 MHz 1.8V CMOS square-wave oscillator that directly drives the FREF\_SLICER\_IN input (ball AG8) of the OMAP4430 processor and the MCLK input to the TWL6040 Audio Companion IC. This clock is used as an input to the PLLs within the OMAP4430 processor so that it can generate all the internal clock frequencies required for system operation.

## 2.3 OMAP4430 Processor

The heart of PandaBoard is the OMAP4430 processor. The OMAP4430 high-performance multimedia application device is based on enhanced OMAP™ architecture and uses 45-nm technology. For more information, refer to the OMAP4430 Technical Reference Manual (TRM). The architecture is designed to provide best-in-class video, image, and graphics processing sufficient to various applications. The device supports the following functions:

- Streaming video up to full high definition (HD) ( $1920 \times 1080$  p, 30 fps)
- 2-dimensional (2D)/3-dimensional (3D) mobile gaming
- Video conferencing
- High-resolution still image (up to 16 Mp)

The device supports high-level operating systems (OSs) such as:

- Windows™ CE, WinMobile™
- Symbian OS™
- Linux®
- Palm OS™

The device is composed of the following subsystems:

- Cortex™-A9 microprocessor unit (MPU) subsystem, including two ARM® Cortex-A9 cores
- Digital signal processor (DSP) subsystem
- Image and video accelerator high-definition (IVA-HD) subsystem
- Cortex™-M3 MPU subsystem, including two ARM Cortex-M3 microprocessors
- Display subsystem
- Audio back-end (ABE) subsystem
- Imaging subsystem (ISS), consisting of image signal processor (ISP) and still image coprocessor (SIMCOP) block
- 2D/3D graphic accelerator (SGX) subsystem
- Emulation (EMU) subsystem

The device includes state-of-art power-management techniques required for high-performance mobile products. Comprehensive power management is integrated into the device. The device also integrates:

- On-chip memory
- External memory interfaces
- Memory management
- Level 3 (L3) and level 4 (L4) interconnects
- System and connecting peripherals





## 2.4 TWL6030 Power Companion IC

The TWL6030 device is a small (7 x 7 mm, 0.4mm pitch) 256 ball FBGA that provides many functions used on the Platform. Shown below is a feature list of the major functions/interfaces provided by the TWL6030 device that are utilized on the Panda platform. This list below doesn't include all device functionality, just that which is used on the PandaBoard.

- A power management system (FSM)
- 1 HS-I2C interface ( $\leq$  2.4Mbits/s) for all Phoenix Power IC GP control commands (CTL-I2C)
- 1 HS-I2C interface ( $\leq$  2.4Mbits/s) for all Smart-Reflex Class 3 control commands (SR-I2C)
- MMC card detection mechanism
- A 24MHz RC oscillator
- A 32kHz RC oscillator for a fast device start-up
- A high-performance crystal oscillator, for 32.768kHz external crystal
- A Real Time Clock (RTC) resource
- Power supply resources:
  - 11 Low Drop Out (LDO) regulators
    - 1 for internal purposes only (VRTC)
    - 1 for internal and platform needs (VANA)
    - 9 for platform needs (VAUX1, VAUX2, VAUX3, VCXIO, VDAC, VMMC, VPP, VUSB, VUSIM)
  - 7 buck SMPS with:
    - DVS capability Smart-Reflex Class 3 compatible (VCORE1, VCORE2, VCORE3)
    - 1 for I/O supply (V1V8), with specific PWMFORCE input control
    - 1 for LDOs pre-regulation (V2V1) and Phoenix Audio features
    - 1 for memory supply (VMEM)
    - 1 for external modem, RF transceiver or I/Os (V1V29)
  - 3 general-purpose enables for possible platform upgrades (REGEN1, REGEN2, SYSEN)

### 2.4.1 TWL6030 Core SMPS Outputs

The TWL6030 implements three Switch Mode Power Supplies (SMPS) that source the three main core voltage rails for the OMAP4430 processor. The default voltage of all of these supplies is 0.95V, and each should be adjusted as required by S/W for the desired processor OPP.

VCORE1 is a 1200mA SMPS that is used to power the VDD\_MPU balls on the OMAP4430 processor (net name VDD\_VCORE1, 9 balls total). VCORE2 is a 600mA SMPS that is used to power the VDD\_IVA\_AUDIO balls on the processor (net name VDD\_VCORE2, 10 balls total). VCORE3 is a 600mA SMPS that is used to power the VDD\_CORE balls on the processor (net name VDD\_VCORE3, 34 balls total) and the VDDA\_DLLn\_LPDDR21 and VDDA\_DLLn\_LPDDR22, where n=0 and 1 (4 balls total).





#### 2.4.2 TWL6030 V1V8 SMPS Output

The TWL6030 V1V8 SMPS provides the I/O voltage for the PandaBoard (net name VIO\_1v8). This is a 1200mA SMPS that provides a 1.8V output that is used to power many balls on the OMAP4430 processor that set the I/O voltage for the device. It also sources onboard peripherals that require an operating voltage referenced to processor I/Os.

#### 2.4.3 TWL6030 V2V1 SMPS Output

The TWL6030 V2V1 SMPS output is used by the TWL6040 Audio Companion IC as an input for some of its internal power supplies (specifically the high side and low side LDOs and the negative charge pump). It is also connected to the TWL6030 as the input voltage to the VCXIO and VDAC LDOs (net name VDD\_2V1). It is a 600mA SMPS with a default output value of 2.10V.

#### 2.4.4 TWL6030 VMEM SMPS Output

The TWL6030 VMEM output is a 600mA SMPS used to provide the operating voltage for the VDD2 LPDDR2 balls on the OMAP4430 processor (net name VDD\_VMEM). These OMAP balls are feed-throughs to the top POP footprint on the OMAP package, where they directly connect to the LPDDR2 VDD2 balls. This SMPS is a 600mA max capacity rail. The Micron LPDDR2 device used is an S4B type device, so VDD2 is required to be 1.2V. This is set in the TWL6030 companion chip by connecting the BOOT1 input to VRTC.

#### 2.4.5 TWL6030 V1V29 SMPS Output

The TWL6030 V1V29 output is a 600mA SMPS used to provide the operating voltage for the VDD2 LPDDR2 balls on the OMAP4430 processor (net name VDD\_VMEM). These OMAP balls are feed-throughs to the top POP footprint on the OMAP package, where they directly connect to the LPDDR2 VDD2 balls. This SMPS is a 600mA max capacity rail. The Micron LPDDR2 device used is an S4B type device, so VDD2 is required to be 1.2V. This is set in the TWL6030 companion chip by connecting the BOOT1 input to VRTC, which causes V1V29 to be set to a default of 1.225V.

#### 2.4.6 TWL6030 LDO Power Resources

The VAUX2 LDO is a programmable LDO that is only connected to pin 1 of the LCD Expansion Connector J4. Its possible output voltage settings include 1.2V, 1.8V, 2.5V, 2.75V, and 2.8V, and its maximum output current is 200mA. The voltage to be programmed will be dependent on the board plugged into the LCD Expansion connectors, but will most likely be 2.8V.

The VAUX3 LDO is a programmable LDO that is only connected to pin 30 of the Camera Expansion Connector, J17. Its possible output voltage settings include 1.0V, 1.2V, 1.3V, 1.8V, 2.5V, 2.8V, 3.0V, and its maximum output current is 200mA. The output voltage to be utilized would depend on the implementation of the camera module.

The VCXIO LDO is a fixed 1.8V, 200mA LDO that provides a 1.8V input to certain noise sensitive OMAP4430 balls. The balls powered by this LDO include the VDDA\_CSI2 balls (V28 and W28), the





VDDA\_DPLL balls (G13, P9 and Y16), and on this revision of the PandaBoard, the VDDS\_DV\_BANK7 ball (M28). This LDO also provides power for the onboard 38.4 MHz oscillator.

The VDAC LDO is a fixed 1.8V, 50mA LDO that provides a 1.8V input to certain noise sensitive OMAP4430 balls. The balls powered by this LDO include the VDDA\_HDMI\_VDAC balls (A11 and G12).

The VMMC LDO is a programmable LDO that provides the voltage to the VDDS\_MMC1 balls on the OMAP processor (pins G7 and H7) as well as the SDMMC cardcage. This LDO is off when the board is powered on, but is turned on and set to 1.8V or 3.0V depending on card capabilities detected.

The VRTC LDO is an adjustable LDO that provides internal voltages to the TWL6030 device. Its possible output voltage settings are 1.8V and 2.5V and its maximum output current is 25mA. In normal operation, it should always be set to 1.8V.

The VUSB LDO is a fixed 3.3V, 35mA LDO that provides voltage to the OMAP4430 that it uses for its internal USB transceiver. The only ball powered by this LDO is the VDDA\_USBA0OTG\_3P3V ball (ball A5).

The VPP LDO is adjustable LDO that powers the VPP\_CUST and VPP\_STD balls on OMAP (balls J8 and Y22). This LDO is only needed for eFuse operations and can be left disabled for normal PandaBoard operation.

#### 2.4.7 TWL6030 Clock Circuitry

The TWL6030 has an 32.768 KHz crystal connected across its OSC32KIN and OSC32KOUT balls. This crystal is used by the TWL6030 to generate three output 32.768 KHz, 1.8V square wave clock outputs. These outputs are:

- CLK32KAO: always on clock connected to the SYS32K input of the OMAP4430 processor.
- CLK32KAUDIO: clock connected to the CLK32K input of the TWL6040 Audio Companion IC.
- CLK32KG: a gated 32.768 clock connected to the SLOW\_CLK input of the LS Research module. This clock will be off by default at reset, and must be enabled by software.

### 2.5 TWL6040 Audio Companion IC

The TWL6040 device is a small (6 x 6 mm, 0.5mm pitch) 120 ball PBGA that provides many functions, primarily audio, used on the Platform. Shown below is a feature list of the major functions/interfaces provided by the TWL6040 device.

- A audio management system
  - PDM Interface for Audio and control
  - Analog Microphone Interface
  - Headset – speaker (32 ohm) and microphone





- Earpiece Output
- FM Input
- Aux Output
- Hands-free 8 ohm driver
- Dual Vibrator
- Misc Control
  - GPO
  - I2C (high speed)
  - Power on/off
- Power
  - Internal LDOs
  - Internal negative charge pump

## 2.6 SYSBOOT Configuration

The OMAP4430 Processor has eight SYSBOOT inputs. These inputs are sampled after a board reset, and determine the booting and operating mode of the OMAP4430 Processor. The upper two inputs (SYSBOOT[7:6]) control the clocking modes of the part (i.e. enabling/disabling the internal oscillator to allow using a crystal input or oscillator). They are currently set to “11” and should not be changed.

The lower six inputs, SYSBOOT[5:0] determine the type and order of memory or peripheral booting. SYSBOOT[5] determines whether memory or peripheral booting is preferred. The SYSBOOT definitions may be found in the OMAP4430 TRM, but are included here for convenience. See Table 2 on page 22 for the SYSBOOT definitions for peripheral preferred booting, and Table 3 on page 23 for memory preferred booting SYSBOOT definitions. The shaded row in Table 2 is the default configuration of the PandaBoard.

If it is desired to change the SYSBOOT configuration, resistors may be added or removed from the SYSBOOT[5:0] lines. The SYSBOOT[5:0] lines have weak internal pull-down resistors, so removing the resistor will result in the line being sampled as a ‘0’ at reset, and installing a 3.3K or lower value resistor will result in the line being sampled as a ‘1’ at reset. See Figure 3 on page 24 for the location of the resistors on SYSBOOT[5:0]. These resistors are connected to OMAP4430 as follows:

- R123: SYSBOOT0
- R136: SYSBOOT1
- R128: SYSBOOT2
- R119: SYSBOOT3
- R135: SYSBOOT4
- R137: SYSBOOT5

*NOTE: Do not use pull-up resistance values higher than 3.3Kohm on the SYSBOOT lines. This would create a voltage divider with the internal OMAP pulldown, potentially causing an invalid value to be internally latched for SYSBOOT.*





SYSBOOT[5:0]	Booting Devices Order			
	1 <sup>st</sup>	2 <sup>nd</sup>	3 <sup>rd</sup>	4 <sup>th</sup>
000000	USB	MMC2(1)		
000001	USB	XIP		
000010	USB	XIPWAIT		
000011	USB	NAND		
000100	USB	EMIF		
000101	USB	MMC1		
000110	USB	OneNAND		
000111	USB	OneNAND	MMC2(1)	
001000	UART	MMC2(1)		
001001	UART	XIP		
001010	UART	XIPWAIT		
001011	UART	NAND		
001100	UART	EMIF		
001101	UART	MMC1		
001110	UART	OneNAND		
001111	USB-ULPI	MMC2(1)		
010000	USB-ULPI	XIP		
010001	USB-ULPI	XIPWAIT		
010010	USB-ULPI	NAND		
010011	USB-ULPI	EMIF		
010100	USB-ULPI	MMC1		
010101	USB-ULPI	OneNAND		
010110	USB	UART	MMC1	MMC2(1)
010111	USB	UART	MMC1	XIP
011000	USB-ULPI	UART	MMC2(2)	
011001	USB	UART	MMC1	NAND
011010	UART	MMC2(2)		
011011	USB	UART	MMC1	
011100	USB	MMC2(2)		
011101	Reserved			
011110	Reserved			
011111 <sup>(1)</sup>	Fast XIP booting. Wait monitoring off		USB	UART

<sup>(1)</sup> Only on GP devices

Table 2: SYSBOOT[5:0] Definitions – Peripheral Preferred Booting





SYSBOOT[5:0]	Boot Device Order			
	1 <sup>st</sup>	2 <sup>nd</sup>	3 <sup>rd</sup>	4 <sup>th</sup>
100000	MMC2(1)	USB		
100001	XIP	USB		
100010	XIPWAIT	USB		
100011	NAND	USB		
100100	EMIF	USB		
100101	MMC1	USB		
100110	OneNAND	USB		
100111	OneNAND	MMC2(1)	USB	
101000	MMC2(1)	UART		
101001	XIP	UART		
101010	XIPWAIT	UART		
101011	NAND	UART		
101100	EMIF	UART		
101101	MMC1	UART		
101110	OneNAND	UART		
101111	MMC2(1)	USB-ULPI		
110000	XIP	USB-ULPI		
110001	XIPWAIT	USB-ULPI		
110010	NAND	USB-ULPI		
110011	EMIF	USB-ULPI		
110100	MMC1	USB-ULPI		
110101	OneNAND	USB-ULPI		
110110	MMC2(1)	USB	UART	MMC1
110111	XIP	USB	UART	MMC1
111000	MMC2(2)	USB-ULPI	UART	
111001	NAND	USB	UART	MMC1
111010	MMC2(2)	UART		
111011	MMC1	USB	UART	
111100	MMC2(2)	USB		
111101	Reserved			
111110	Reserved			
111111 <sup>(1)</sup>	Fast XIP booting. Wait monitoring off		USB	UART

<sup>(1)</sup> Only on GP devices

Table 3: SYSBOOT[5:0] Definitions – Memory Preferred Booting



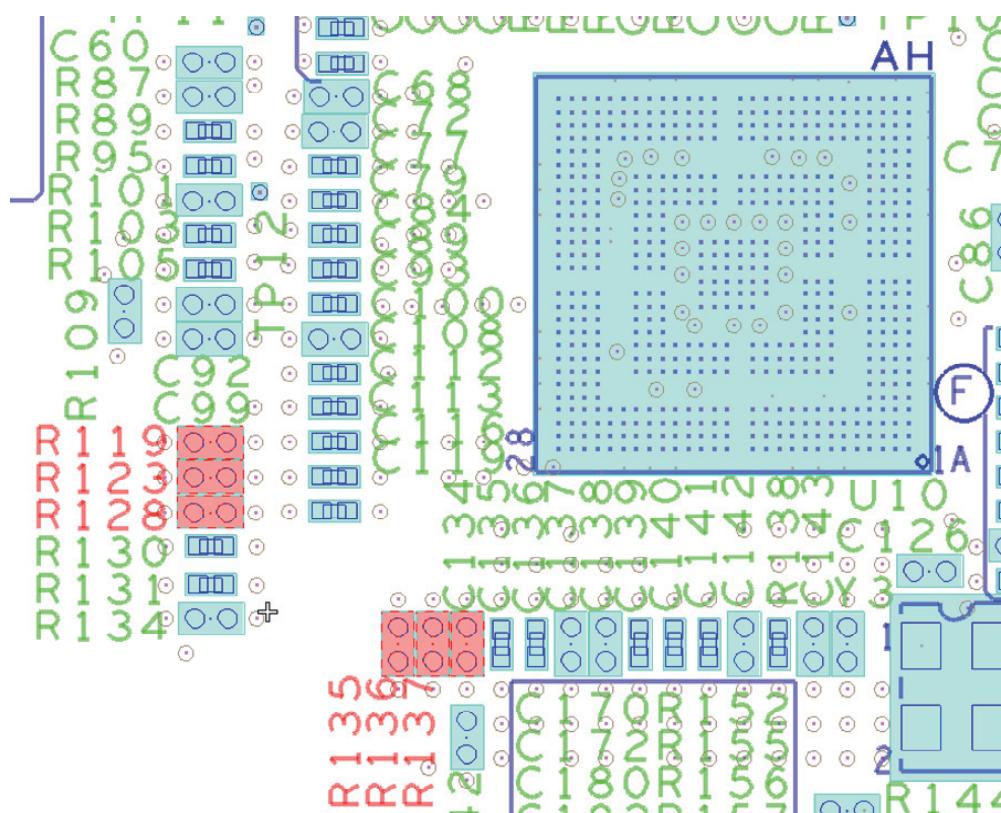


Figure 3 – SYSBOOT[5:0] Resistor Locations

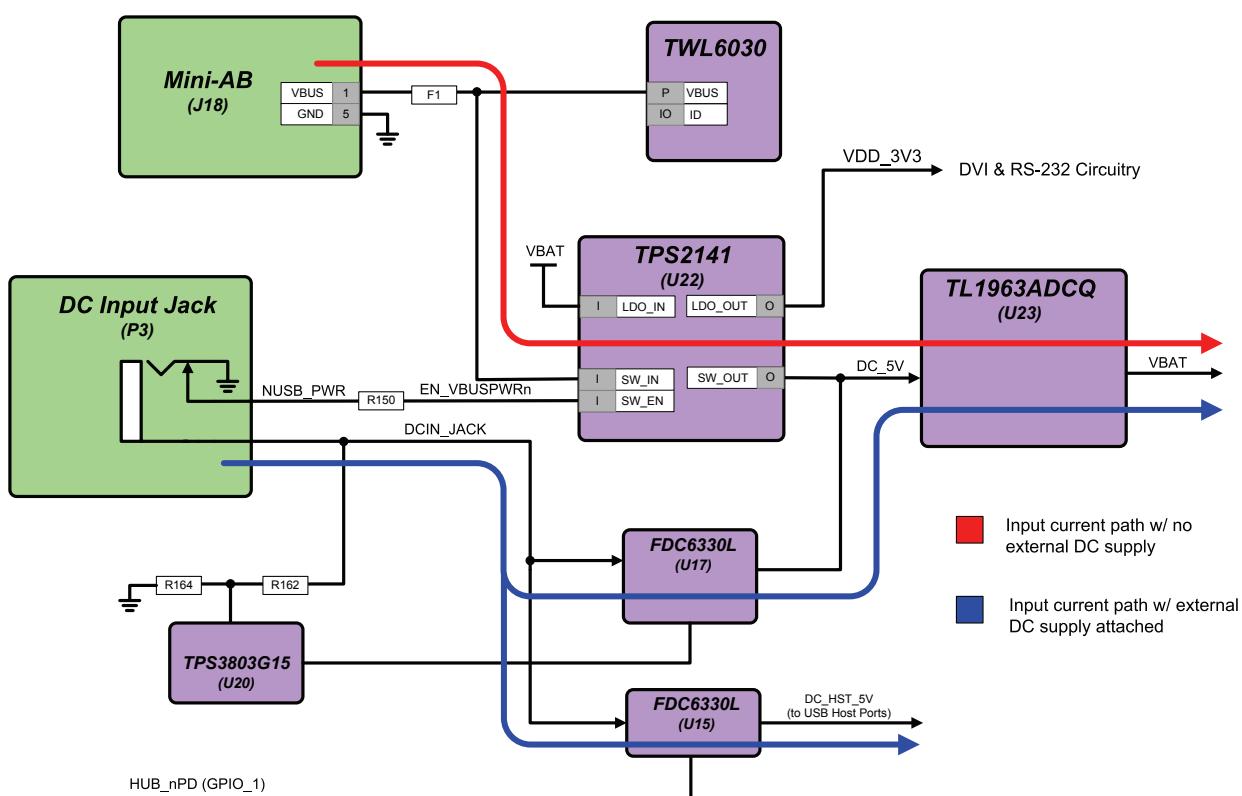
## 2.7 Miscellaneous Power Circuitry

### 2.7.1 Input Power Circuitry

The input power circuitry may be found on sheet 2 of the board schematic. A block diagram of this circuitry is shown in Figure 4 below. The PandaBoard may be run either with or without a DC wall supply plugged into the input power jack at P3.

Without an external power supply plugged in, the 5Vdc input power is supplied from the mini-AB USBOTG connector at J18. This supply is only capable of providing 500mA of output current, so board operations will be limited in this mode (e.g. USB host port operation will not be possible, and other operations could be limited, depending on current requirements). The path of current flow in this mode is designated below by the red arrow. The 5V from VBUS will be routed through the switch at U22, to the LDO at U23, which provides a 4.2V “battery” voltage for the TWL6030 and TWL6040 Companion ICs.





**Figure 4 – PandaBoard Input Power Circuitry Block Diagram**

With an external power supply plugged in, the 5Vdc input power is supplied from the input DC jack at P3. The current capability in this mode is only limited by the particular DC supply being used. The path of current flow in this mode is designated below by the blue arrows. The switch at U22 will be disabled by the insertion of the DC input jack in this mode, and the regulated 5Vdc from the wall supply will be connected to the input of the LDO at U23, which provides a 4.2V “battery” voltage for the TWL6030 and TWL6040 Companion ICs.

An acceptable DC supply that may be used with the PandaBoard is one manufactured by CUI, Incorporated (P/N ETS050400UTC-P5P-SZ). A datasheet for this supply may be found at <http://products.cui.com/getPDF.aspx?filename=20+W+desktop.pdf>. This supply has a 5.5mm outside jack diameter, and a 2.1mm inside diameter. It is currently in stock, and may be ordered from Digikey (Digikey P/N T951-P5P-ND).

**CAUTION: only use a 5Vdc regulated power supply to power the PandaBoard. Connecting a supply with an output higher than +5Vdc could cause possible board damage.**





The supervisor IC at U20 has the DC input power tied to its VDD pin through a voltage divider. When the voltage at the VDD input of this IC exceeds 1.40V (i.e. DCIN\_JACK  $\geq$  5.64V), the reset output of the supervisor is negated. This will enable the two FETs at T1A and T1B, which will illuminate the red overvoltage indicator, and disable the load switch at U17, which removes input power to the onboard circuitry. The load switch at U15 that provides 5V USB Host power is enabled and disabled manually by writing GPIO\_1 to a ‘1’, or a ‘0’, respectively. The load switch at U15 powers up disabled.

### 2.7.2 USB/Ethernet Power Circuitry

There is a fixed 3.3V LDO (U11) that provides power for the LAN9514 Ethernet/USB Hub device. This device is a Texas Instruments TPS73633DBVR device which can provide up to 400mA of output current. This device may be controlled via S/W by writing OMAP4430 GPIO\_1. Writing this GPIO high will enable this LDO, while writing it low will disable it (see Table 9 on page 41). This device is shown on sheet 11 of the schematic.

### 2.8 Standard Volatile Memory

The OMAP4430 processor supports two LPDDR2 channels, accessible only via a POP memory device soldered on the 216-ball, 12x12 mm footprint on top of the OMAP4430 processor. Each channel supports up to two chip-selects, so up to four LPDDR2 memory dies are supported. The two stacked memory packages are directly connected to the two LPDDR2 EMIF4D interfaces of the OMAP4430 die. The base address for the LPDDR2 is 0x8000 0000.

An 8Gb/1GB POP LPDDR2 DRAM device (Elpida P/N EDB8064B1PB-8D-F) is provided on the PandaBoard. The memory device has four dies, with each die being a separate 2Gb LPDDR2.

### 2.9 Debug UART Interface

A single RS-232 port is provided on the PandaBoard via 9-pin D-sub female connector at location P4. It provides access to the UART3 interface of the OMAP4430. See Figure 5 for the implementation of the RS232 port.

The TXS0104EZXUR device at U21 is a voltage translator that translates between the 1.8V logic levels required by the OMAP4430 processor to the 3.3V logic levels required by the SN75C3232EDR. The SN75C3232EDR @ U24 is an RS-232 transceiver that converts the 3.3V logic signals to/from the voltage translator (TXS0104EZXUR) to the RS-232 signal levels required (-5V to +5V).

The UART port at P4 can be accessed by using Teraterm or other terminal emulation program. To use this UART interface, the serial port settings should be applied as follows:

- BAUD RATE: 115200
- DATA: 8 bit





- PARITY: none
- STOP: 1bit
- FLOW CONTROL: none

This port requires the use of a 9-pin D-sub Male to Female null-modem cable.

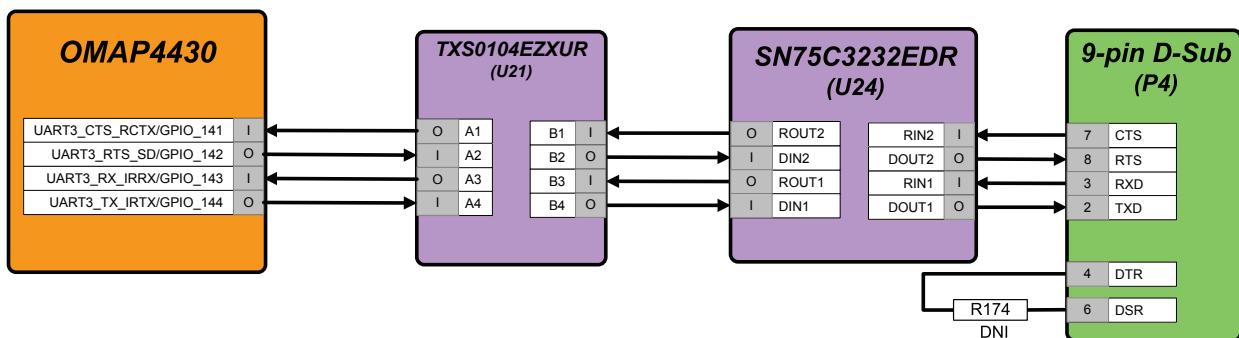


Figure 5 – Panda UART3/RS-232 Block Diagram

## 2.10 SD/MMC Connector

The OMAP4430 PandaBoard supports removable memory storage via onboard SD/MMC card cage. It is an eight-bit card cage that supports 1.8V or 3.0V cards. Card detect functionality is supported via the TWL6030 power companion IC. See Figure 6 for a block diagram of the interface signaling to the card cage. The resistors shown in Figure 6 below are 33 ohm series termination resistors.



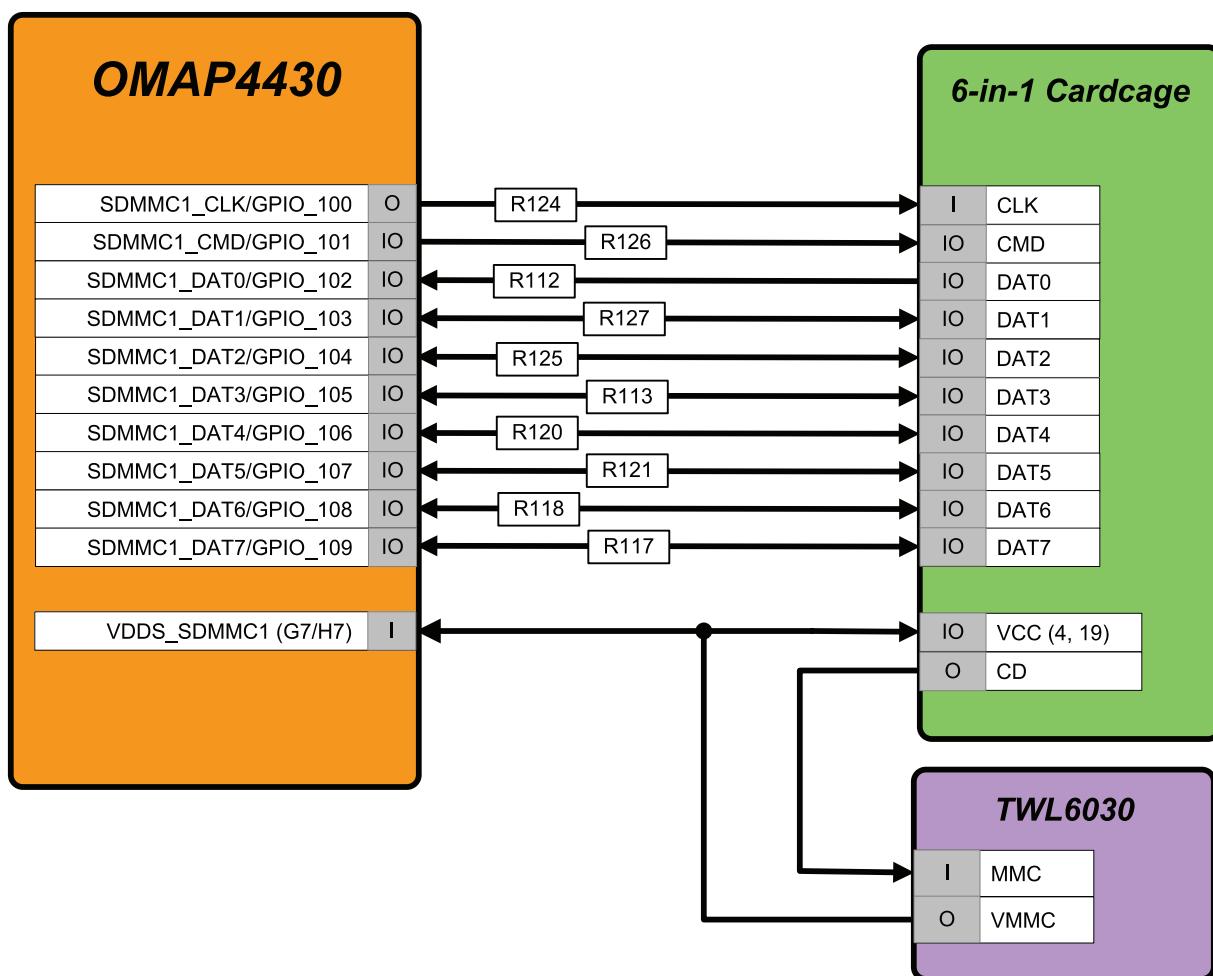


Figure 6 – Panda SDMMC1 Card Cage Block Diagram

## 2.11 HDMI Interface

The OMAP4430 PandaBoard provides a High-Definition Multimedia Interface (HDMI) via an industry-standard Type A connector at location P2. The interface is provided using the internal HDMI module provided by the OMAP4430. See Figure 7 for a block diagram of the PandaBoard HDMI circuitry. This interface includes a Texas Instruments TPD12S015 HDMI Port Protection/Interface device. A datasheet for the TPD12S015 may be found at <http://focus.ti.com/docs/prod/folders/print/tpd12s015.html>. The high-speed differential clock and data lines are connected straight from OMAP to the ESD protection device, to the connector, so that any ESD event experienced at the connector will be absorbed before damaging the OMAP4430 device I/Os.



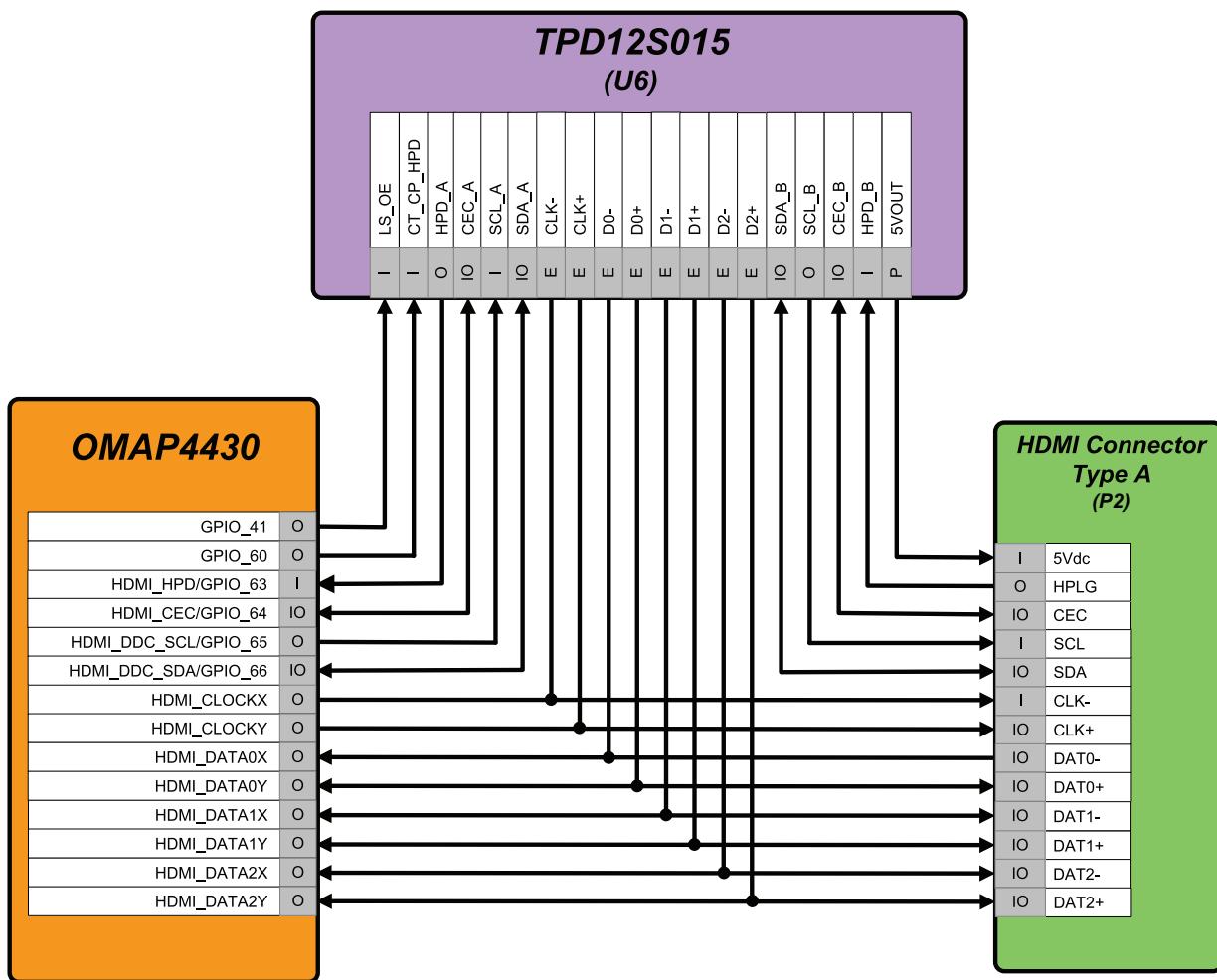


Figure 7 – Panda HDMI Interface Block Diagram

In addition to providing ESD protection on the signals coming from the connector, this device performs voltage translation on the control signals in the HDMI interface (SCL, SDA, CEC, and HPD) from the 1.8V levels of the OMAP4430 to the 5V levels required by a TV set. It also implements a DC/DC boost converter that operates from the “battery” voltage, VBAT, and outputs a 5Vdc output that is capable of sourcing up to 55mA of current. See Table 4 for the GPIOs used on the HDMI interface and a description of their function. The direction column in this table indicates whether this device is an output from OMAP (O) or an input to OMAP (I).





GPIO	Dir	Signal Name	Description
GPIO_41	O	HDMI_LS_OE	TPD12S015 Level Shifter and internal LDO Enable 1 = Enabled, 0 = Disabled
GPIO_60	O	HDMI_CT_CP_HPD	TPD12S015 DC/DC Converter and Hot-Plug Detect Enable 1 = Enabled, 0 = Disabled

Table 4: HDMI GPIO Definitions

## 2.12 Display Interface

The PandaBoard provides two possible options for the usage of the OMAP4430 parallel display signals. The first option (the as-shipped default configuration) routes them to a TFP410 DVI transmitter, whose output feeds an onboard DVI-D connector. The second option routes them to a pair of 20-pin LCD expansion connectors (J1 and J4). Both of these possible options are discussed in the following paragraphs. See Figure 8 for a diagram of the PandaBoard Display Interface. The path shown in red in Figure 8 is the as-shipped default configuration.

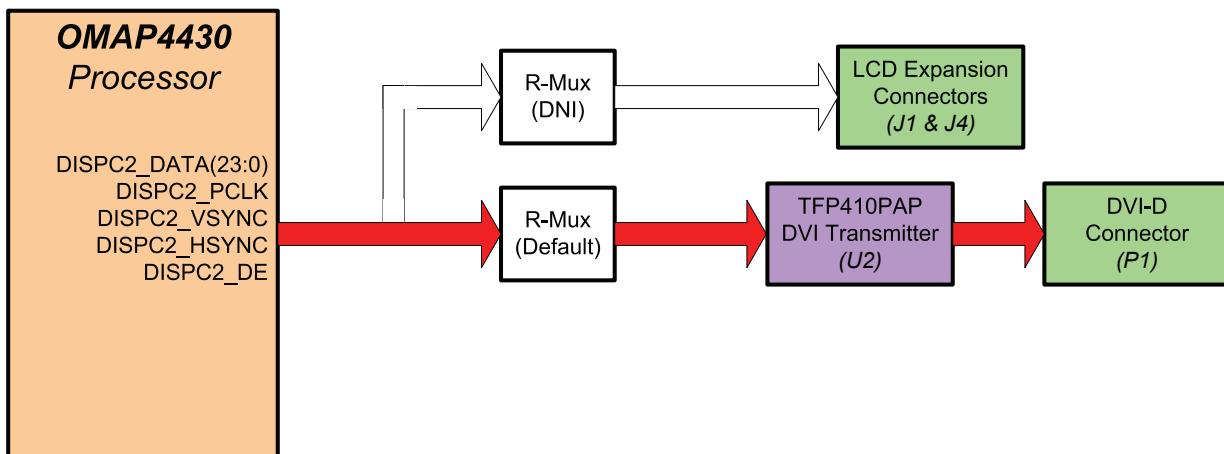


Figure 8 – Panda Display Interface Block Diagram

### 2.12.1 Parallel Display DVI-D connector

As mentioned previously, the as-shipped parallel display interface configuration for the PandaBoard is with the parallel display interface signals from OMAP driven to a TFP410 DVI transmitter, whose output feeds an onboard DVI-D connector. See Figure 9 for a block diagram of this interface.



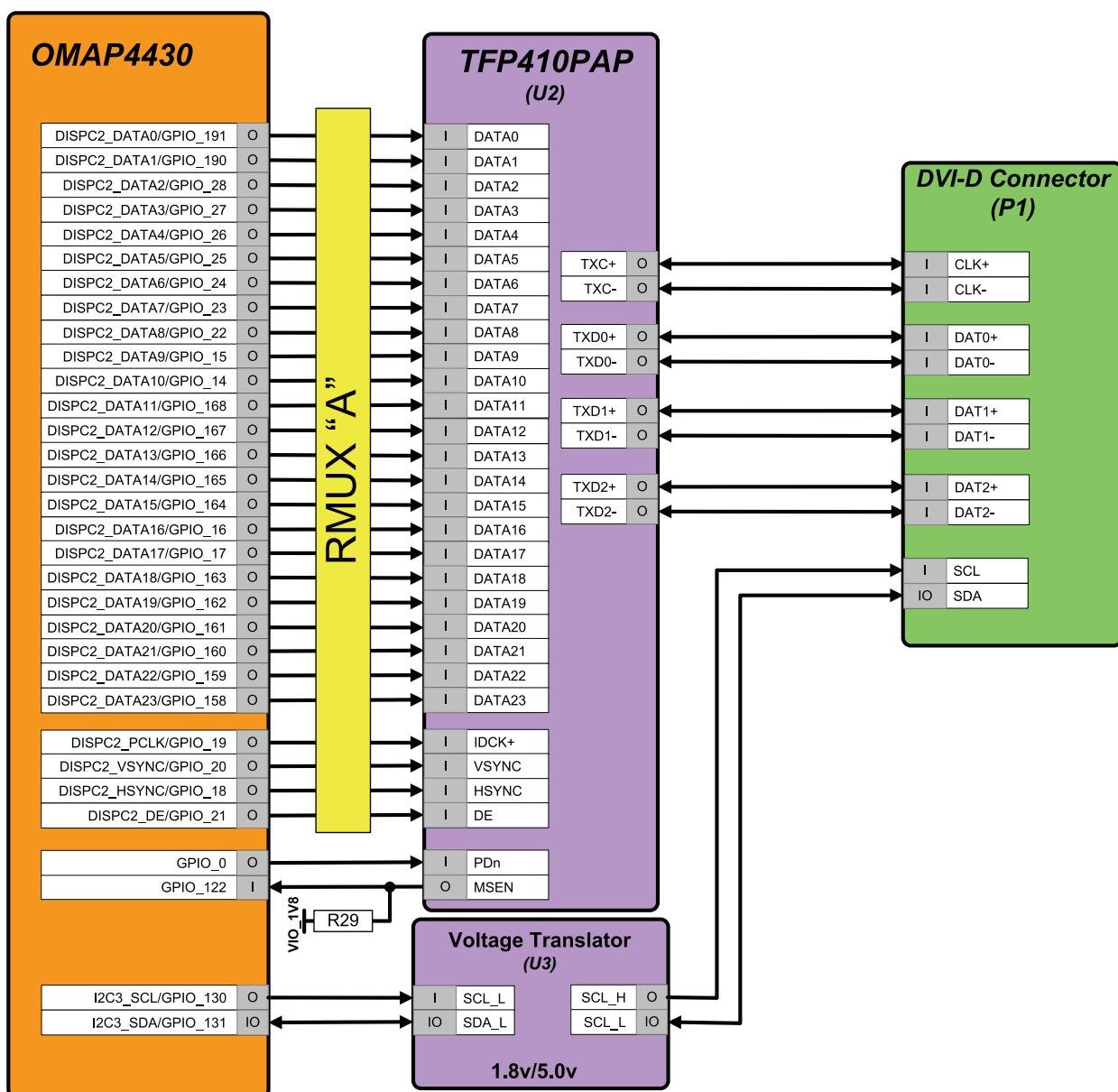


Figure 9 – Panda DVI-D Output Block Diagram

See Table 5 for the GPIOs used on the Parallel display interface and a description of their function. This table does not include the 28 parallel display signals (DATA[23:0], PCLK, VSYNC, HSYNC, and DE). The direction column in this table indicates whether this device is an output from OMAP (O) or an input to OMAP (I).





GPIO	Signal Name	Description
GPIO_0	H_GPIO_0/ TFP410_NPD	TFP410 Device Power down ( <i>note: this GPIO goes through a voltage translator to meet the 3.3V I/O requirement of the TFP410 on this pin</i> ) 1 = Normal Operation, 0 = Power Down
GPIO_122	DVI_MSEN	TFP410 Monitor Sense 0 = Powered on receiver sensed at the differential outputs 1 = No powered on receiver detected. ( <i>note: this output from the TFP410 is open-drain and has a pull-up to 1.8V, so it is connected directly to OMAP</i> )

**Table 5: DVI-D Display GPIO Definitions**

### 2.12.2 Parallel Display Expansion Connector Interface

The second parallel display option for the PandaBoard is to plug an external display module into parallel display expansion connectors J1 and J4. See Figure 10 on page 33 for a diagram of this configuration. To enable this configuration, rework would have to be done to the board. The rework would consist of removing 28 resistors (RMUX “A” shown in Figure 9 on page 31) and adding 28 different resistors (RMUX “B” shown in Figure 10 on page 33). To do this, perform the following two steps:

- 1) Remove the following 28 resistors on the top side of the board as highlighted in red in Figure 11 on page 35 in the following locations: R40-R43, R45, R46, R48-R53, R64-R73, and R80-R85. These 28 resistors comprise the “RMUXA” block shown in Figure 9.
- 2) Add 0201, 33 ohm resistors on the back side of the board as highlighted in red in Figure 12 on page 36 in the following locations: R176-R203. These 28 resistors comprise the “RMUXB” block shown in Figure 10. *Note: if 33 ohm resistors are not available, then zero ohm resistors may be used, or you may simply solder across the individual resistor pads.*

NOTE: the two expansion connectors are through-hole, 1.27mm pitch connectors that are placed identically and are pin-compatible with the display expansion connectors on the OMAP3530 Beagleboard. Display modules that were developed for the Beagleboard may be reused on the PandaBoard.



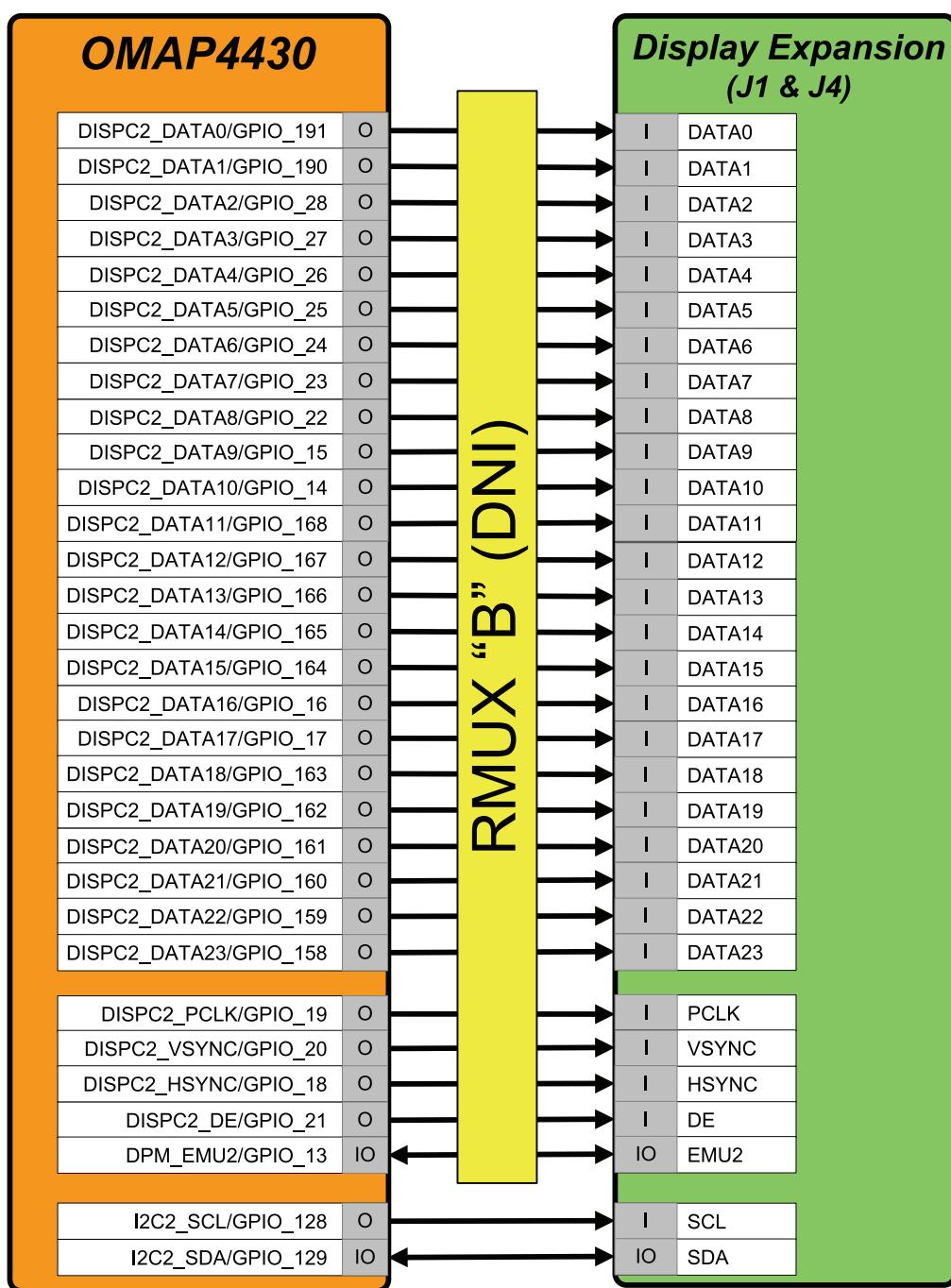


Figure 10 – Panda Display Expansion Block Diagram





Pin#	Signal	I/O	Description
1	DC_5V	PWR	DC rail from the Main DC supply
2	DC_5V	PWR	DC rail from the Main DC supply
3	EXP_DSS_DAT1	I	LCD Pixel Data bit 1
4	EXP_DSS_DAT0	I	LCD Pixel Data bit 0
5	EXP_DSS_DAT3	I	LCD Pixel Data bit 3
6	EXP_DSS_DAT2	I	LCD Pixel Data bit 2
7	EXP_DSS_DAT5	I	LCD Pixel Data bit 5
8	EXP_DSS_DAT4	I	LCD Pixel Data bit 4
9	EXP_DSS_DAT12	I	LCD Pixel Data bit 12
10	EXP_DSS_DAT10	I	LCD Pixel Data bit 10
11	EXP_DSS_DAT23	I	LCD Pixel Data bit 23
12	EXP_DSS_DAT14	I	LCD Pixel Data bit 14
13	EXP_DSS_DAT19	I	LCD Pixel Data bit 19
14	EXP_DSS_DAT22	I	LCD Pixel Data bit 22
15	H_I2C2_SDA	I/O	I2C2 Serial Data
16	EXP_DSS_DAT11	I	LCD Pixel Data bit 11
17	EXP_DSS_VSYNC	I	LCD Vertical Sync Signal
18	H_DPM_EMU2	I	DPM_EMU2/GPIO_13
19	GND	PWR	Ground bus
20	GND	PWR	Ground bus

Table 6: LCD Expansion Connector “A” Pin Definitions (J1)

Pin#	Signal	I/O	Description
1	VDD_VAUX2	PWR	Power rail (adjustable from 1.2V to 2.8V)
2	VIO_1V8	PWR	1.8V system I/O voltage
3	DVI_DATA20	I	LCD Pixel Data bit 20
4	DVI_DATA21	I	LCD Pixel Data bit 21
5	DVI_DATA17	I	LCD Pixel Data bit 17
6	DVI_DATA18	I	LCD Pixel Data bit 18
7	DVI_DATA15	I	LCD Pixel Data bit 15
8	DVI_DATA16	I	LCD Pixel Data bit 16
9	DVI_DATA7	I	LCD Pixel Data bit 7
10	DVI_DATA13	I	LCD Pixel Data bit 13
11	DVI_DATA8	I	LCD Pixel Data bit 8
12	NUSB_PWR	O	No connect
13	DVI_DATA9	I	LCD Pixel Data bit 9
14	I2C2_SCL	I	I2C2 Serial Clock





Pin#	Signal	I/O	Description
15	DVI DATA6	I	LCD Pixel Data bit 6
16	DVI CLK+	I	DVI Clock
17	DVI DEN	I	Data Enable
18	DVI HSYNC	I	Horizontal Sync
19	GND	PWR	Ground bus
20	GND	PWR	Ground bus

Table 7: LCD Expansion Connector “B” Pin Definitions (J4)

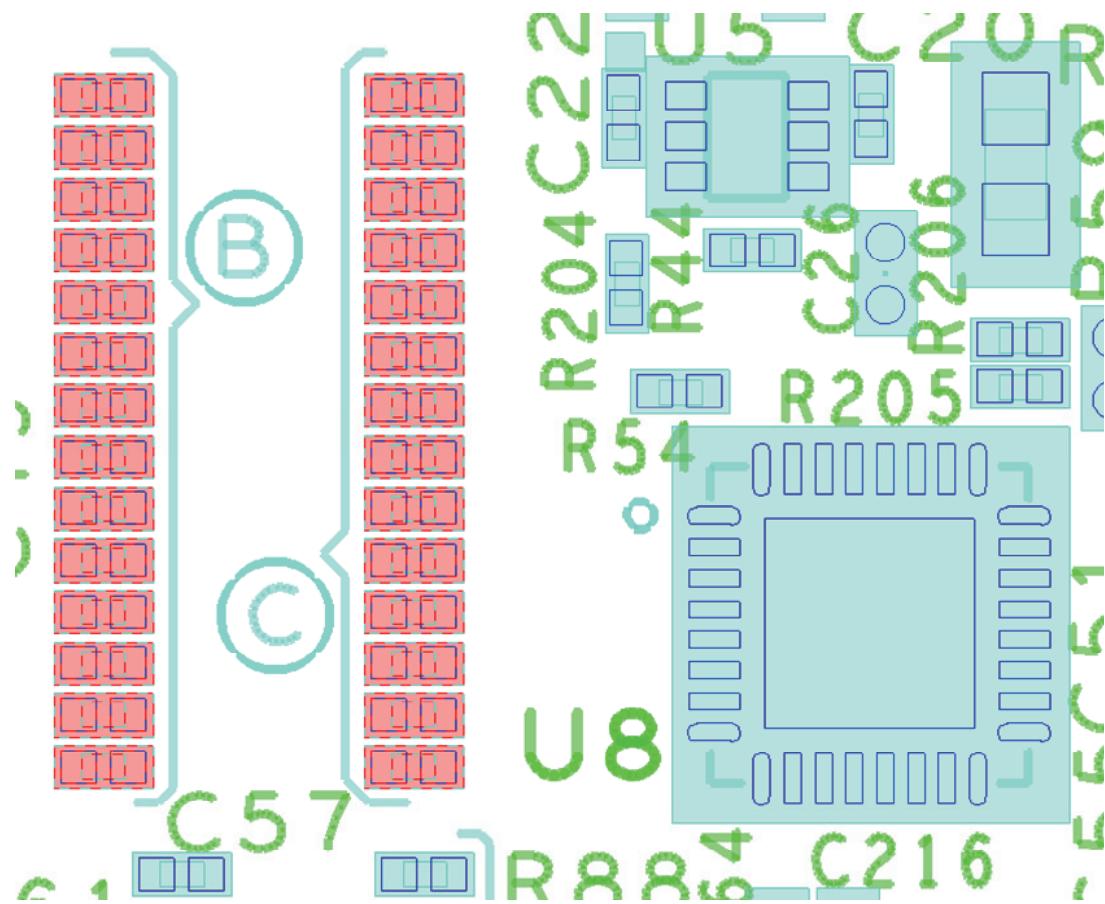


Figure 11 – Panda Display RMUX “A” Resistor Locations (Top Side of PCB)



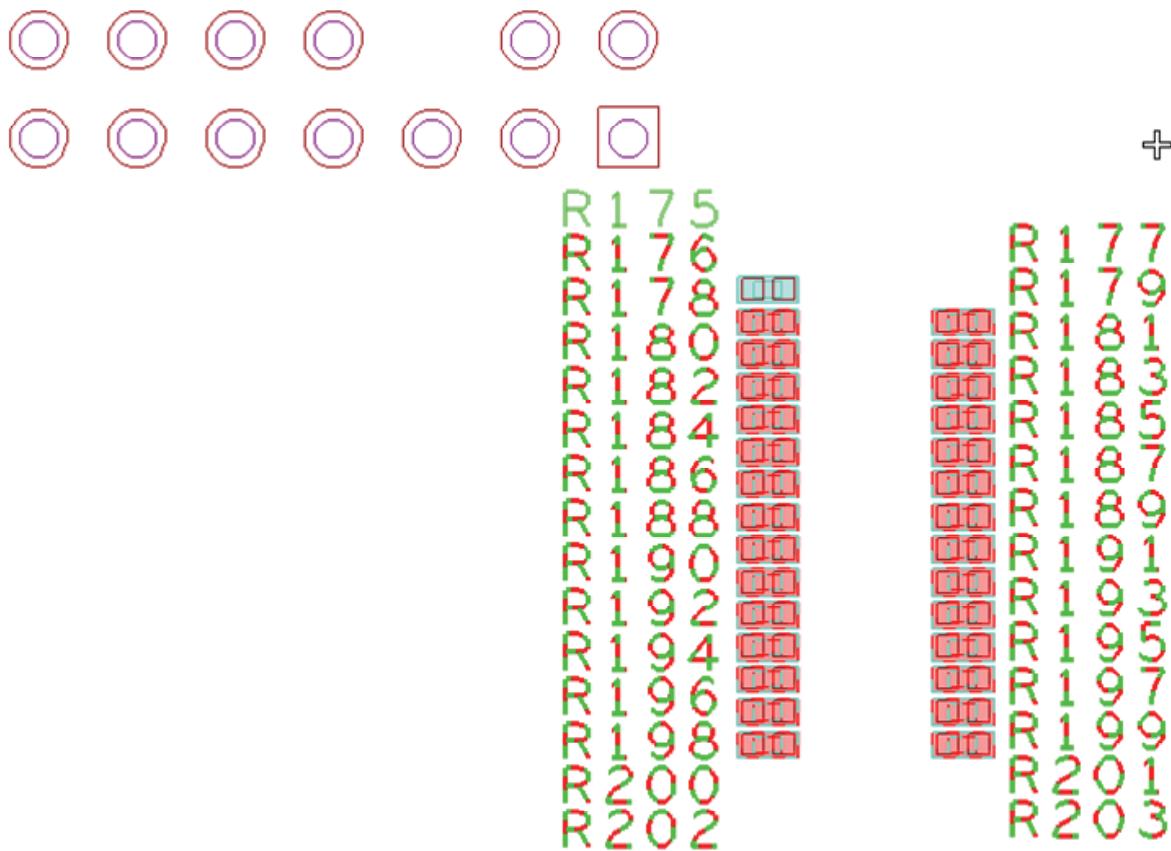


Figure 12 – Panda Display RMUX “B” Resistor Locations (Bottom Side of PCB)

### 2.13 Bluetooth/WLAN Interfaces

The PandaBoard provides a module (LS Research Inc. P/N LS240-WI-01-A20) that provides a Bluetooth interface, a 2.4 GHz 802.11b/g/n interface, and an FM interface. This module may be found on sheet 14 of the schematics (reference designator U4). It uses Texas Instruments' WiLink™ 6.0 solution.

Information for this module may be found at:

[http://www.lsr.com/products/radio\\_modules/802.11\\_BGN\\_BT/tiwi.shtml](http://www.lsr.com/products/radio_modules/802.11_BGN_BT/tiwi.shtml).

See Figure 13 for a diagram of the PandaBoard connectivity to this module. The resistor (R61) that is shaded in Figure 13 and has an asterisk by its reference designator is not installed on the current PCB. See Table 8 on page 38 for a description of the GPIOs used to interface to the module and their function.

The OMAP4430 interfaces are connected to the LS Research WiLink™ module as follows:

- SDMMC5: WLAN SDIO interface





- UART2: Bluetooth Host Control Interface
- McBSP1: Audio Digital PCM Path
- McBSP2: FM I2S Data Path
- I2C4: FM Interface Control

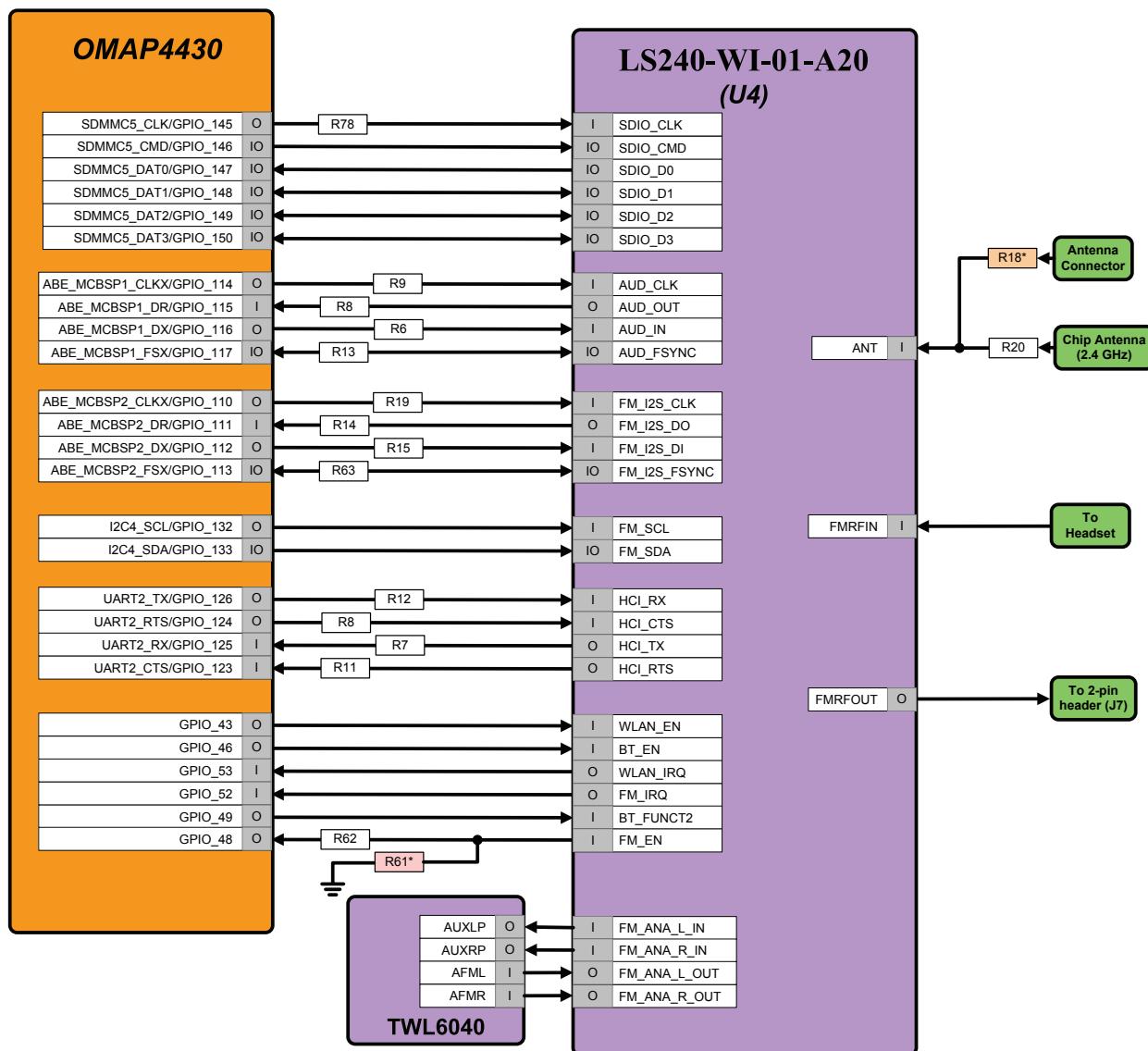


Figure 13 – PandaBoard WLAN/Bluetooth Interface Block Diagram





GPIO	Dir.	Signal Name	Description
GPIO_43	O	WLAN_EN	802.11b/g Enable 1 = Enabled, 0 = Disabled
GPIO_46	O	BT_EN	Bluetooth Enable 1 = Enabled, 0 = Disabled
GPIO_48	O	FM_EN	FM Enable 1 = Enabled, 0 = Disabled
GPIO_49	I	BT_WAKEUP	Bluetooth Wakeup
GPIO_52	I	FM_nIRQ	FM Interrupt Input
GPIO_53	I	WLAN_nIRQ	WLAN Interrupt Input

**Table 8: WLAN/Bluetooth Module GPIO Definitions**

## 2.14 Audio Interfaces

See Figure 14 for a block diagram of the audio connectivity on the PandaBoard. In this block diagram, the signals with a red background in the box specifying their direction are analog I/Os while all others are 1.8V digital I/Os.

The OMAP4430 PandaBoard provides a stacked audio connector, which provides two 3.5mm audio jack connections. The upper jack on this stacked connector (J16A in Figure 14 below), is connected to the Headset Microphone Plus and Minus inputs of the TWL6040 Audio Companion IC. The lower jack on this stacked connector (J16B in Figure 14 below) is connected to the Headset Left and Right outputs of the TWL6040. The digital path for this audio back to the OMAP4430 processor is through the PDM interface. For expansion purposes, the left and right Hands-Free speaker outputs of the TWL6040 are connected to the Expansion Connector J6 (see Paragraph 2.16 on page 42 for further details).

The PandaBoard also provisions an FM analog input and output path from the TWL6040 Audio Companion IC to the LS240-WI-01-A20 module. In addition, there is a digital PCM path for Bluetooth audio from the module to OMAP4430 via McBSP1, and the digital FM I2S path through the OMAP4430 McBSP2 interface.



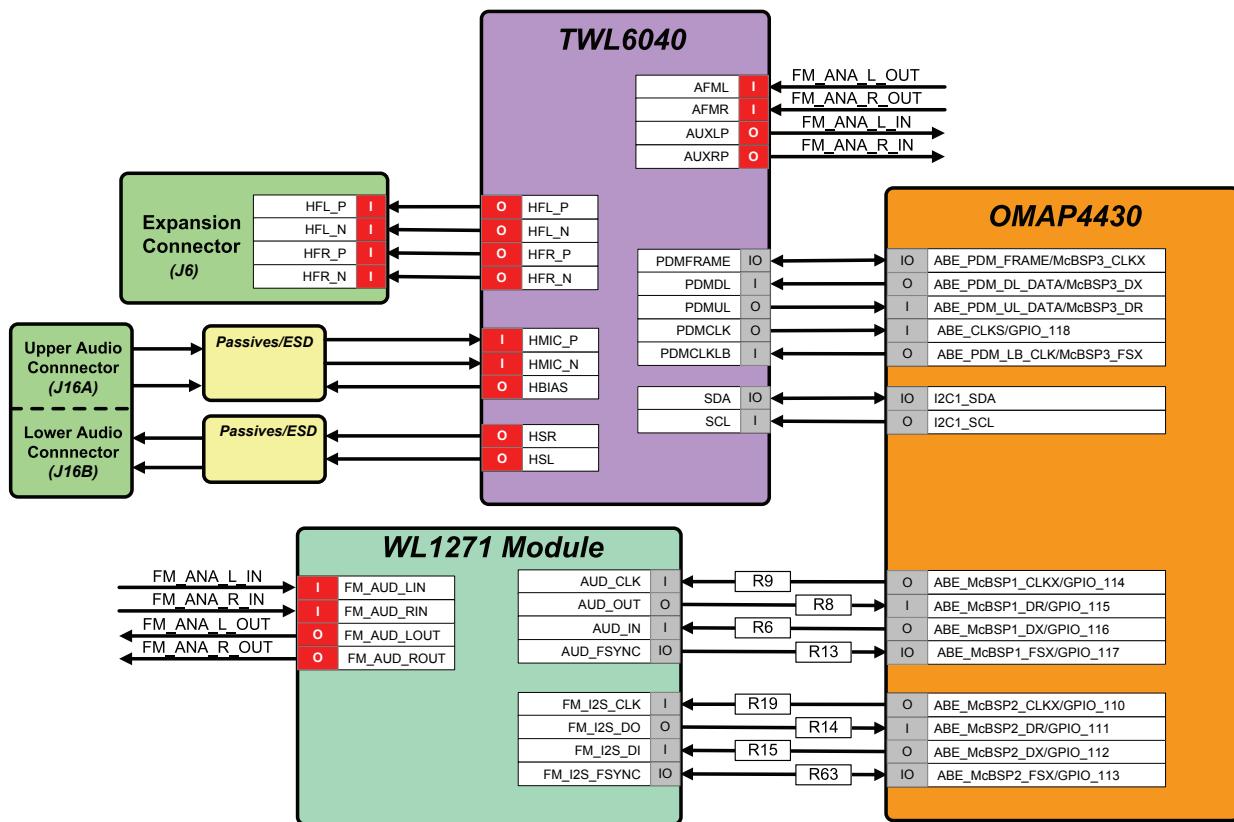


Figure 14 – Panda Audio Interface Block Diagram

## 2.15 USB Interfaces

The PandaBoard utilizes two USB interfaces. The first is a DP/DM interface from the internal transceiver within OMAP to the mini-AB connector J18. The second interface utilizes the 12-wire ULPI interface (USBB1) to an onboard USB phy, whose DP/DM I/Os are interfaced to a Hub IC which provides four downstream USB Host ports, and an Ethernet interface. Each of these interfaces will be discussed in more detail in the following paragraphs.

### 2.15.1 USBOTG Interface

The PandaBoard uses the USB OTG transceiver within the OMAP4430 that is connected to an industry-standard mini-AB connector (J18) as shown in Figure 15. The VBUS from the connector is connected to the TWL6030 companion Power IC, which can provide up to 100mA in host mode. The PandaBoard may only be used in host mode if a +5Vdc power supply is installed in power jack P2.



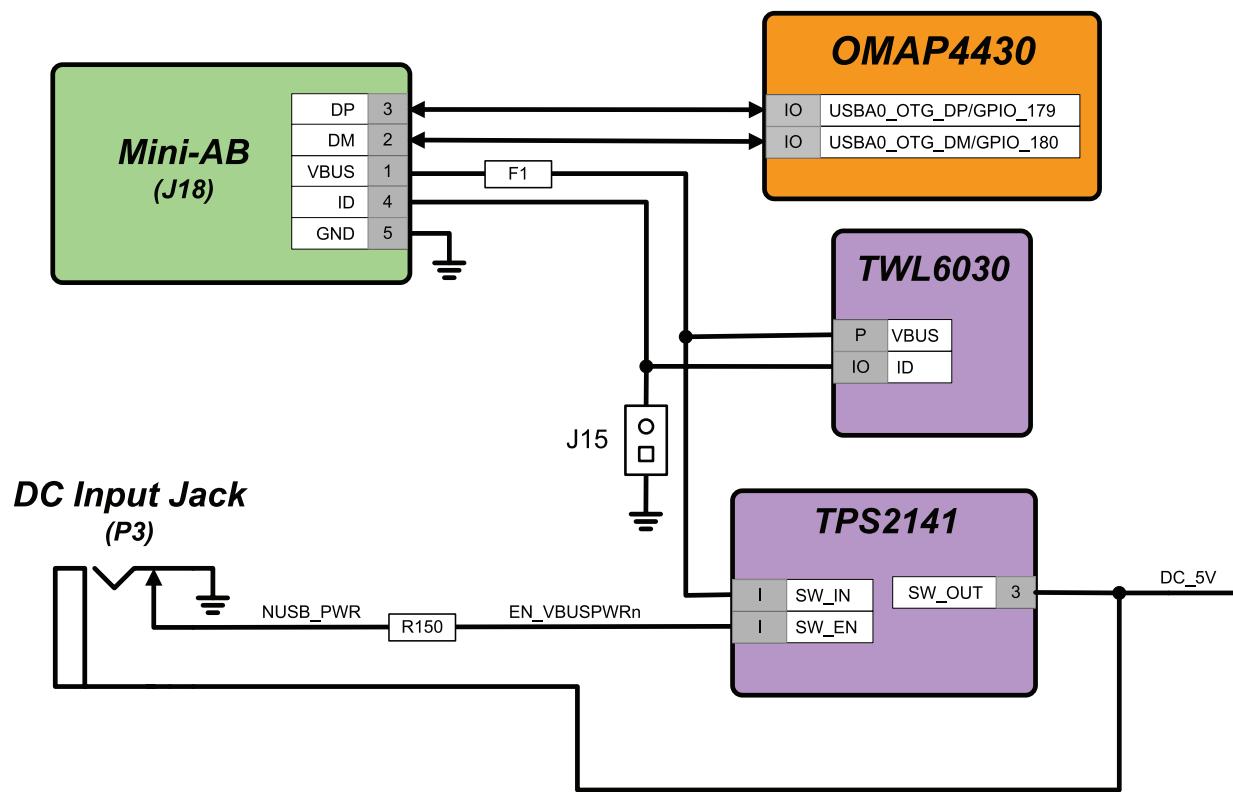


Figure 15 – Panda USBOTG Interface Block Diagram

### 2.15.2 USBB1 Phy Interface

The PandaBoard uses the 12-wire OMAP4430 USBB1 ULPI interface connected to an SMSC USB3320C-EZK phy. This Phy converts the 12-wire ULPI interface to a DP/DM pair that is used as the upstream USB interface to the LAN9514 USB/Ethernet Hub IC. The Hub IC provides four downstream Host USB ports, and an Ethernet interface. Two of the USB Host Ports are available via the combo connector J9, while the other two ports are available via Expansion Connector J6. The Ethernet interface is available via a tab-up RJ-45 connector at J9. See Figure 16 for a block diagram of the PandaBoard USBB1 interface connectivity.

- Note that the reference clock to the USB3320C is sourced from the FREF\_CLK3\_OUT output of OMAP4430, and this OMAP output must be programmed for a clock frequency of 19.2 MHz for proper operation



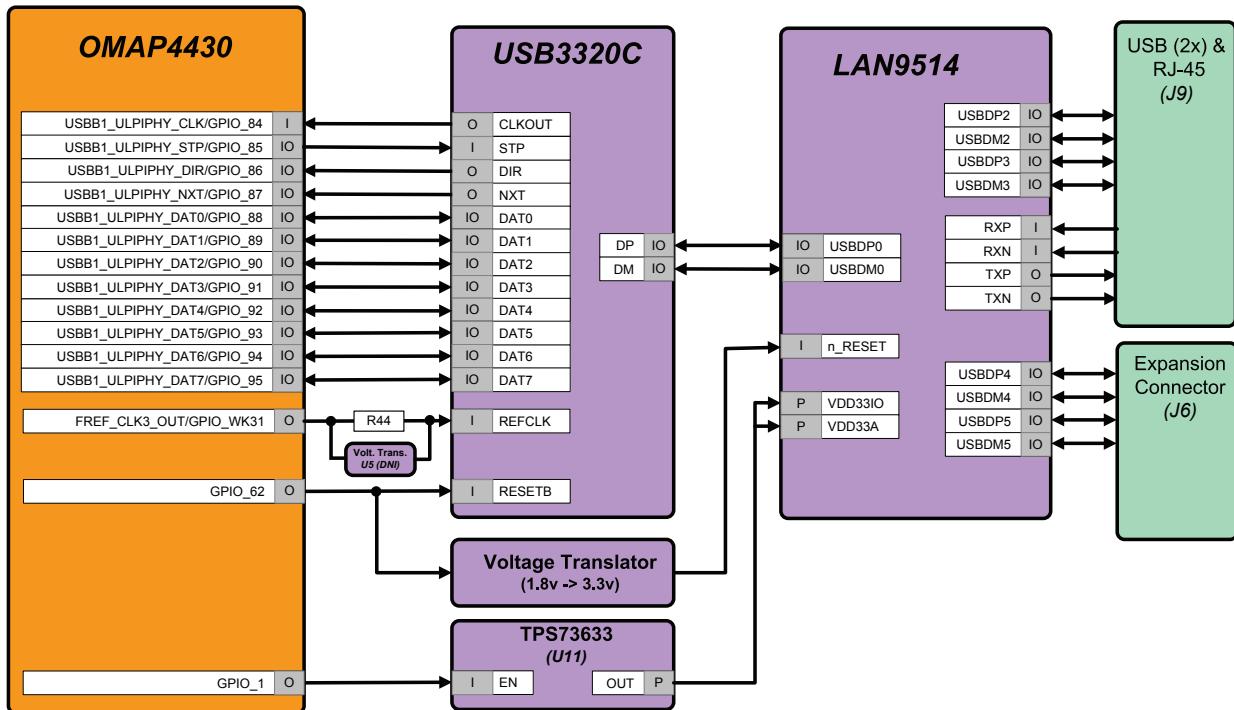


Figure 16 – Panda USBB1 Interface Block Diagram

See Table 9 for the definition of the GPIOs used to provide USB Host Port/Ethernet functions.

GPIO	Dir.	Signal Name	Description
GPIO_1	O	HUB_NPD/ HUB_LDO_EN	Enable to the Hub 3.3V LDO @ U11 (note: this GPIO goes through a voltage translator to provide adequate $V_{ih}$ margin on the LDO enable input). 1 = Enable Hub LDO 0 = Power Down Hub LDO
GPIO_62	O	HUB_NRESET/ HUB_NRESET_3V3	USB/Ethernet Hub Reset 0 = Hub & Phy held in reset 1 = Normal operation.
GPIO_WK31	O	USBB1_PHY_REFCLK	This pin needs to be used as FREF_CLK3_OUT, and programmed to output 19.2 MHz

Table 9: USB Host Port/Ethernet GPIO Definitions

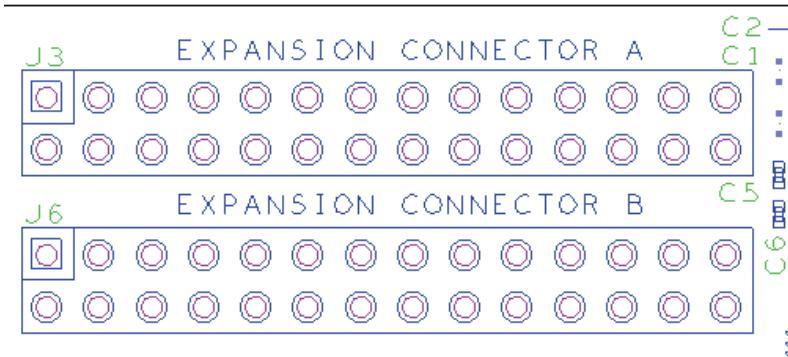




## 2.16 Expansion Connectors (J3 & J6)

The PandaBoard provides locations for two 28-pin, 0.1" through-hole expansion connectors, J3 and J6, to support platform expansion (these connectors are not mounted on the current PandaBoard). The placement of these connectors on the Panda PCB is shown below. On both connectors, the top left pin is pin 1 and odd numbered pins are on the top row of the connector, and even numbered pins are on the bottom row. See Figure 17 for the placement and orientation of these two connectors on the PandaBoard. The distance between pin 1 of the two connectors is 300 mils or 7.62mm. Note that since these are through-hole connectors, boards can be designed to plug into the PandaBoard from either top or bottom, depending on user preference.

See Table 10 for the pinout of expansion connector "A" and Table 11 for the pinout of expansion connector "B". These tables show the primary function that is available on the connector pin, along with the alternate function that can be selected by changing the OMAP4430 pin multiplexing. Some of the OMAP I/Os have more than two possible functions, see Table 21 on page 58 for a complete list of the functions available.





J3 Pin #	OMAP Ball #	Primary Function	Secondary Function	Description of PandaBoard Usage
1	---	VIO_1V8	---	1.8V I/O Power
2	---	DC_5V	---	5Vdc Input Power
3	B16	GPMC_AD7	SDMMC2_DAT7	GPMC Address/Data Bit 7
4	AH23	MCSPI1_CS3	GPIO_140	SPI1 Chip Select 3 (also UART1 RTS)
5	A16	GPMC_AD6	SDMMC2_DAT6	GPMC Address/Data Bit 6
6	AH19	UART4_TX	GPIO_156	UART4 Transmit Data
7	D15	GPMC_AD5	SDMMC2_DAT5	GPMC Address/Data Bit 5
8	AG20	UART4_RX	GPIO_155	UART4 Receive Data
9	C15	GPMC_AD4	SDMMC2_DAT4	GPMC Address/Data Bit 4
10	AF23	MCSPI1_CS1	GPIO_138	SPI1 Chip Select 1 (also UART1 RX)
11	D13	GPMC_AD3	SDMMC2_DAT3	GPMC Address/Data Bit 3
12	AG22	MCSPI1_SIMO	GPIO_136	SPI1 Slave In Master Out
13	C13	GPMC_AD2	SDMMC2_DAT2	GPMC Address/Data Bit 2
14	AG23	MCSPI1_CS2	GPIO_139	SPI1 Chip Select 2 (also UART1 CTS)
15	D12	GPMC_AD1	SDMMC2_DAT1	GPMC Address/Data Bit 1
16	AE23	MCSPI1_CS0	GPIO_137	SPI1 Chip Select 0
17	C12	GPMC_AD0	SDMMC2_DAT0	GPMC Address/Data Bit 0
18	AE22	MCSPI1_SOMI	GPIO_135	SPI1 Slave Out Master In
19	B12	GPMC_NWE	SDMMC2_CMD	GPMC Write Enable
20	AF22	MCSPI1_CLK	GPIO_134	SPI1 Clock Out
21	B11	GPMC_NOE	SDMMC2_CLK	GPMC Output Enable
22	D19	GPMC_AD15	GPIO_39	GPMC Address/Data Bit 15
23	AH22	I2C4_SDA	GPIO_133	I2C4 Serial Data
24	AG21	I2C4_SCL	GPIO_132	I2C4 Serial Clock
25	---	REGEN1	---	TWL6030 REGEN1
26	E7	SYS_NRESPWRON	---	Power On Reset
27	---	DGND	---	Digital Ground
28	---	DGND	---	Digital Ground

Table 10: Expansion Connector “A” Pin Definitions (J3)





J6 Pin #	OMAP Ball #	Primary Function	Secondary Function	Description of PandaBoard Usage
1	---	VBUS 3	---	VBUS out from USB Host Port #3
2	---	VBUS 4	---	VBUS out from USB Host Port #4
3	---	USBH3 DM	---	USB Host Port #3 Data Minus
4	---	USBH4 DM	---	USB Host Port #4 Data Minus
5	---	USBH3 DP	---	USB Host Port #3 Data Plus
6	---	USBH4 DP	---	USB Host Port #4 Data Plus
7	---	DGND	---	Digital Ground
8	---	DGND	---	Digital Ground
9	C19	GPMC AD14	GPIO 38	GPMC Address/Data Bit 14
10	D18	GPMC AD13	GPIO 37	GPMC Address/Data Bit 13
11	AF7	SYS NRESWARM	---	Warm Reset
12	---	PB POWER ON	---	Power on input to TWL6030 (ref. to VBAT)
13	---	HFL P	---	Hands Free Left Speaker Out (+)
14	---	HFR P	---	Hands Free Right Speaker Out (+)
15	---	HFL N	---	Hands Free Left Speaker Out (-)
16	---	HFR N	---	Hands Free Right Speaker Out (-)
17	C18	GPMC AD12	GPIO 36	GPMC Address/Data Bit 13
18	C16	GPMC AD8	GPIO 32	GPMC Address/Data Bit 8
19	B26	GPMC WAIT0	GPIO 61	GPMC Wait input 0
20	D16	GPMC AD9	GPIO 33	GPMC Address/Data Bit 9
21	C25	GPMC NWP	GPIO 54	GPMC Write Protect
22	C17	GPMC AD10	GPIO 34	GPMC Address/Data Bit 10
23	B22	GPMC CLK	GPIO 55	GPMC Clock Out
24	D17	GPMC AD11	GPIO 35	GPMC Address/Data Bit 11
25	B25	GPMC NCS0	GPIO 50	GPMC Chip Select 0
26	D25	GPMC NADV ALE	GPIO 56	GPMC Address Valid/Address Latch Enable
27	C21	GPMC NCS1	GPIO 51	GPMC Chip Select 1
28	C23	GPMC NBE0 CLE	GPIO 59	GPMC Byte Enable 0/Command Latch Enable

Table 11: Expansion Connector “B” Pin Definitions (J6)

### 2.17 Camera Expansion Connector (J17)

The PandaBoard does not provide an onboard camera sensor, but does provision for a 30-pin camera connector. This camera connector receives the five CSI-2 lanes of the OMAP4430 CSI21 camera interface as well as GPIOs for use on a plug-in camera module.

See Table 12 below for the pinout of the camera expansion connector.

**NOTE:** the GPIOs listed below don't have specific functions defined yet, as there has been no camera module designed. These GPIOs will be user-definable per the camera module implementation.





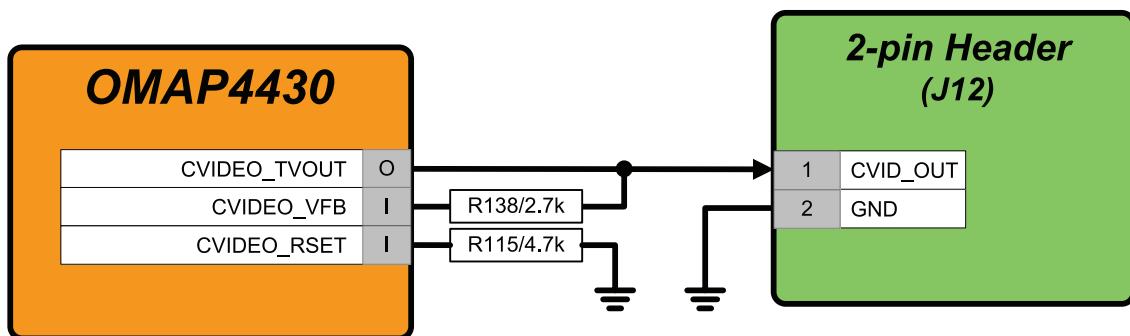
J17 Pin #	OMAP Ball #	Signal Name	Signal Description
1	---	DGND	Signal Ground
2	---	DGND	Signal Ground
3	R26	CSI21_DX0	CSI Signal Lane 0 Data X
4	V26	CSI21_DX3	CSI Signal Lane 3 Data X
5	R25	CSI21_DY0	CSI Signal Lane 0 Data Y
6	V25	CSI21_DY3	CSI Signal Lane 3 Data Y
7	---	DGND	Signal Ground
8	---	DGND	Signal Ground
9	T26	CSI21_DX1	CSI Signal Lane 1 Data X
10	W26	CSI21_DX4	CSI Signal Lane 4 Data X
11	T25	CSI21_DY1	CSI Signal Lane 1 Data Y
12	W25	CSI21_DY4	CSI Signal Lane 4 Data Y
13	---	DGND	Signal Ground
14	---	DGND	Signal Ground
15	U26	CSI21_DX2	CSI Signal Lane 2 Data X
16	B17	H GPIO 40	OMAP GPIO 40
17	U25	CSI21_DY2	CSI Signal Lane 2 Data Y
18	B20	H GPIO 45	OMAP GPIO 45
19	---	DGND	Signal Ground
20	V27	H CAM_GLB_RESET	Camera Global Reset or GPIO 83
21	W27	H I2C3_SCL	I2C3 Serial Clock
22	T27	H CAM_SHUTTER	Camera Shutter or GPIO 81
23	Y27	H I2C3_SDA	I2C3 Serial Data
24	U27	H CAM_STROBE	Camera Strobe or GPIO 82
25	B21	H GPIO 47	OMAP GPIO 47
26	B19	H GPIO 44	OMAP GPIO 44
27	AA28	H FREF_CLK1_OUT	OMAP Camera Clock In
28	B18	H GPIO 42	OMAP GPIO 42
29	---	VBAT	Battery Voltage In
30	---	VDD_VAUX3	TWL6030 VAUX3 LDO (adjustable from 1.0V to 3.0V)

Table 12: Camera Expansion Connector Pin Definitions (J17)

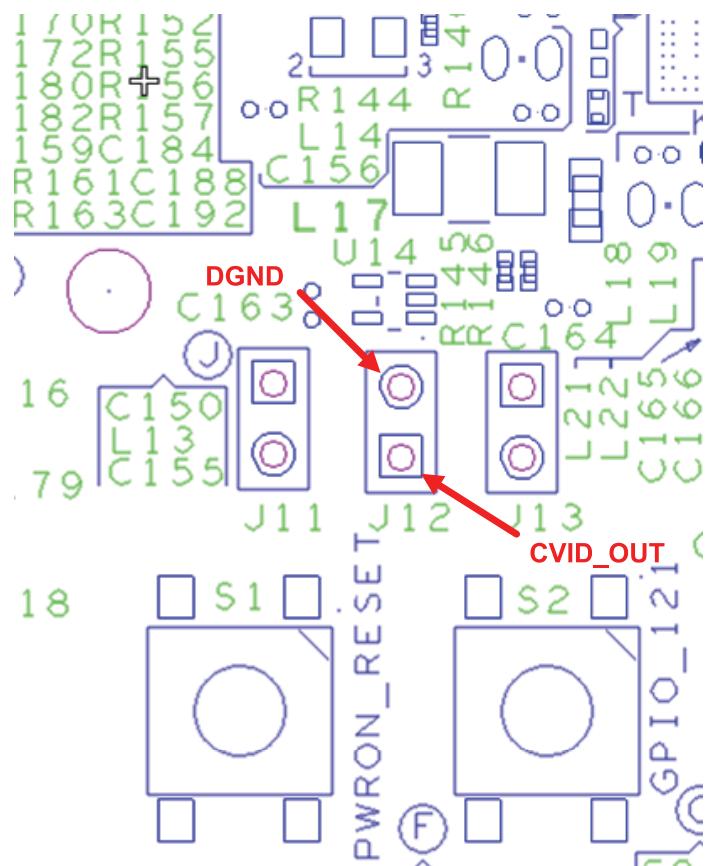
## 2.18 Composite Video (J12)

The PandaBoard provides the possibility of user access to the composite video output of OMAP. It is connected to two-pin header at J12, however, this connector is not installed on the current PCBs. See Figure 18 for a diagram of the composite video connectivity, and see Figure 19 for the orientation of the signals on the two pin header at J12.





**Figure 18 – Composite Video Connectivity**



**Figure 19 – Composite Video Connector J12 PCB Orientation**



## 2.19 JTAG Connector (J8)

The PandaBoard provides a 14-pin 0.1" (2.54mm) pitch through-hole connector at J8 as shown in Figure 20 below. In the figure below, pin 1 is the lower left pin and pin 2 is directly above it. Odd number pins are on the bottom side of the connector, and even numbered pins are along the top. Pin 6 is removed to comply with the keying on the JTAG pods.

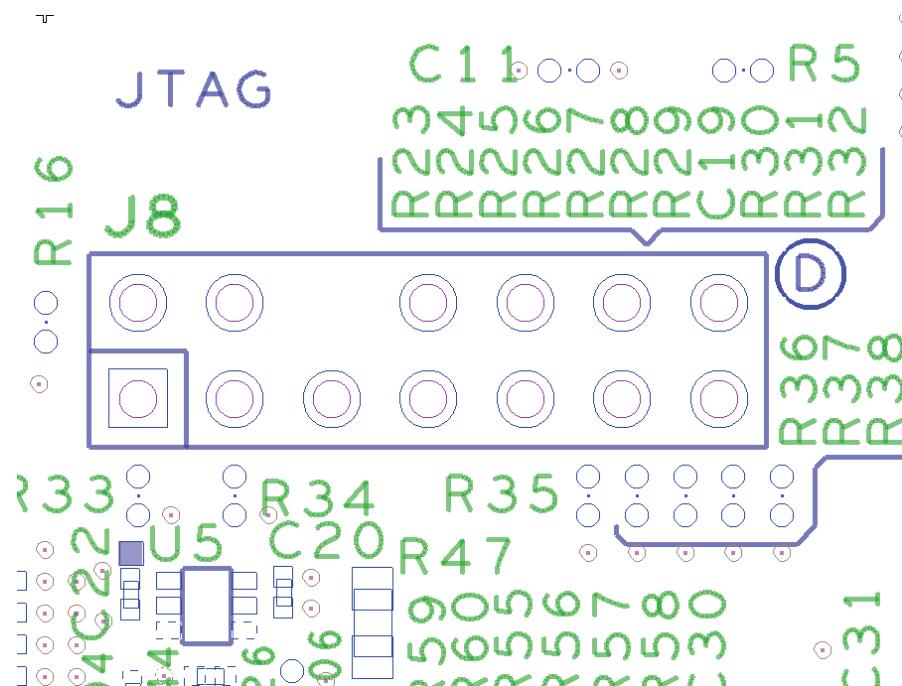


Figure 20 – 14-pin JTAG Connector (J8)

See Table 13 for a description of the pins their connectivity to OMAP4430, and their function on this connector.





J8 Pin #	OMAP Ball #	Signal Name	Signal Description
1	AH1	H_JTAG_TMS	JTAG Test Mode Select
2	AH2	H_JTAG_NTRST	JTAG Test Reset (Active low)
3	AE1	H_JTAG_TDI	JTAG Test Data In
4,8,10,12	----	DGND	Signal Ground
5	---	VIO_1V8	1.8V JTAG Power
6	---	---	N/A
7	AE2	H_JTAG_TDO	JTAG Test Data Out
9	AE3	H_JTAG_RTCK	JTAG Return Clock Out
11	AG1	H_JTAG_TCK	JTAG Clock In
13	M2	H_DPM_EMU0	Emulator I/O 0
14	N2	H_DPM_EMU1	Emulator I/O 1

**Table 13: JTAG Connector Pinout (J8)**

## 2.20 LED Indicators

The PandaBoard provides three LED indicators. See Figure 21 for the location of these three LEDs on the Panda PCB.

LED D1 is a green LED that is controlled via OMAP4430 GPIO\_WK7 (ball AC2). Writing this GPIO high will turn on the LED, while writing it low will turn off the LED.

LED D2 is a green LED that is controlled via OMAP4430 GPIO\_WK8 (ball AC3). Writing this GPIO high will turn on the LED, while writing it low will turn off the LED.

LED D3 is a red LED that is controlled automatically via onboard circuitry. This LED being illuminated indicates an overvoltage condition on the input DC supply (i.e. a supply of greater than 5V has been plugged into P3). The supervisor IC at U20 on sheet 2 of the schematics monitors the voltage from the DC input jack (through a voltage divider to set the appropriate threshold). If a DC supply of more than 5V is plugged into the PandaBoard, the U20 output reset will be negated, which will turn on the red LED at D3 and disable load switches U15 and U17 on sheet 2 of the schematic, which will remove 5V power to the remainder of the PandaBoard circuitry. This is intended to prevent damage to onboard circuitry.



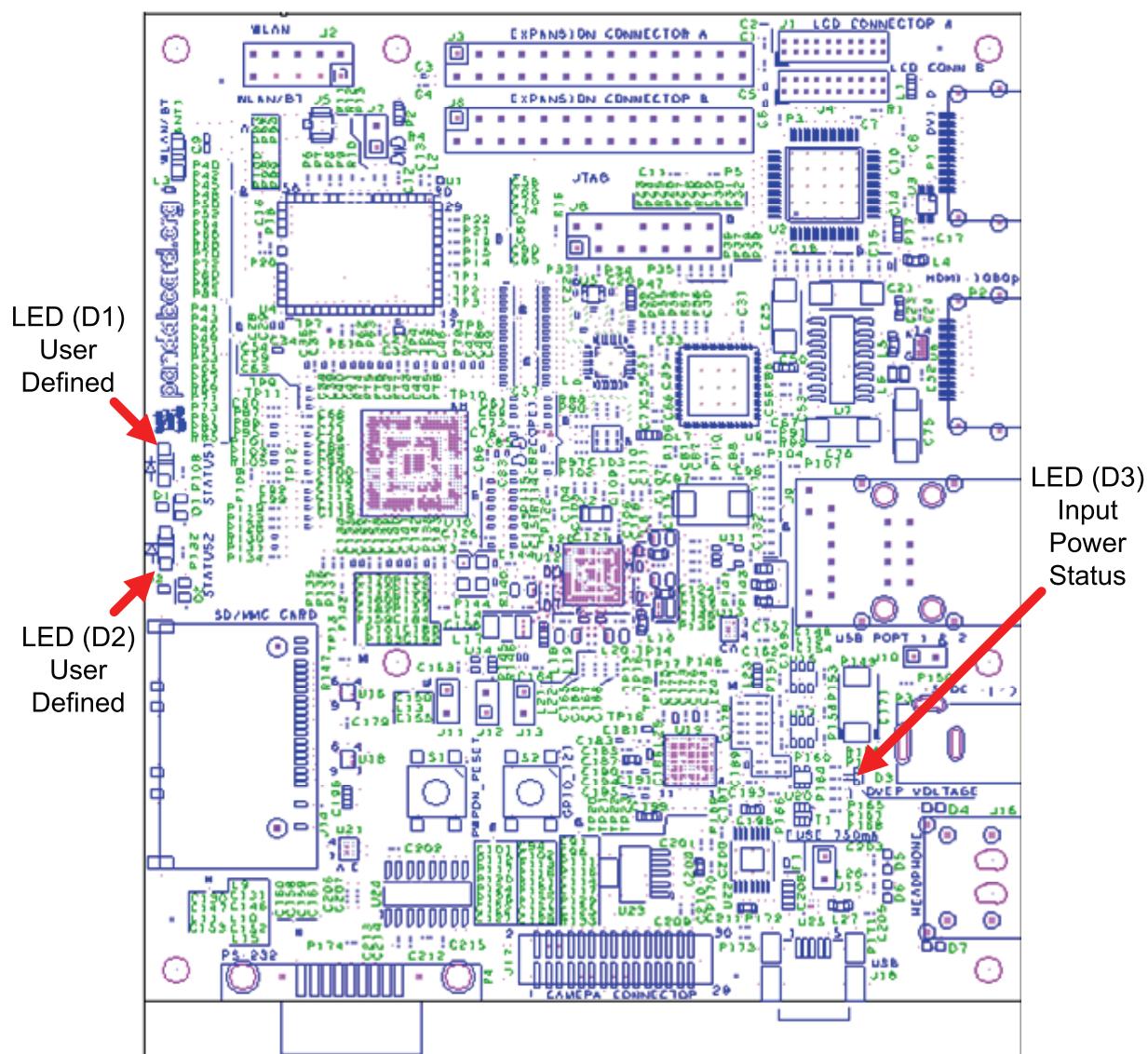


Figure 21 – PandaBoard LED Locations

## 2.21 User Interface Features

Described below are the user features that are incorporated in the OMAP4430 PandaBoard.





### 2.21.1 S1 – Push Button Switch

S1 is a momentary push-button switch that may be depressed to initiate a power-on reset of the PandaBoard. The normal power-on output from the TWL6030 is driven through an open-collector driver, and the output of this switch is tied to the output of the open-collector gate.

### 2.21.2 S2 - Push Button Switch

S2 is a momentary push-button switch that whose output is tied to GPIO\_121 on the PandaBoard. Depressing this switch will momentarily ground GPIO\_121. For proper operation of this switch, the internal pull on this signal must be enabled, and it must be set to a pull-up NOT a pull-down.

## 2.22 I<sup>2</sup>C Device Mapping

The OMAP4430 PandaBoard contains four different I<sup>2</sup>C busses that are provided by the OMAP4430 (I<sup>2</sup>C1, I<sup>2</sup>C2, I<sup>2</sup>C3, and I<sup>2</sup>C4). The paragraphs below detail the seven bit I<sup>2</sup>C addresses for each device on the different I<sup>2</sup>C busses. The write and read addresses are derived by adding a ‘0’ or ‘1’ respectively, to the LSB of the address given below.

### 2.22.1 OMAP I<sup>2</sup>C1

Device	Function	I2C Address
TWL6030	Phoenix Power IC	0x48, 0x49, 0x4A
TWL6040	Phoenix Audio IC	0x4B

Table 14: OMAP I<sup>2</sup>C1 Device Addresses

### 2.22.2 OMAP I<sup>2</sup>C2

Device	Function	I2C Address
Display Expansion Connector	External LCD Control (e.g. touchscreen)	TBD

Table 15: OMAP I<sup>2</sup>C2 Device Addresses





### 2.22.3 OMAP I<sup>2</sup>C3

Device	Function	I2C Address
DVI-D connector (P1)	Control of television set connected via P1	TBD
Camera Expansion connector (J17)	Camera Module Control	TBD

**Table 16: OMAP I<sup>2</sup>C3 Device Addresses**

### 2.22.4 OMAP I<sup>2</sup>C4

Device	Function	I2C Address
WL1271 (on module @ U4)	BT/FM Device Control	???
Expansion Connectors (J6)	Future expansion	TBD

**Table 17: OMAP I<sup>2</sup>C4 Device Addresses**





## 3 PandaBoard S/W Interface

This chapter provides details of interest regarding the SW interface of the PandaBoard implementation.

### 3.1 Readable Board Revision

The Panda Board provides a three-bit board revision that may be read by Software to determine what board is being used. These board ID bits are provided by GPIO\_171 (BOARD\_ID2), GPIO\_101 (BOARD\_ID1), and GPIO\_182 (BOARD\_ID0). Values are as shown in Table 18 below.

BOARD_ID2	BOARD_ID1	BOARD_ID0	Board Type Definition
0	0	0	750-2151-001 (6-layer board - <i>Obsolete</i> )
0	0	1	750-2152-001 (8-layer board) – Early adapter board/PandaBoard Rev. EA1
0	1	0	750-2152-010 (8-layer board) – Production board/PandaBoard Rev. A1
0	1	1	Reserved for future use
1	X	X	Reserved for future use

**Table 18: Board ID Read Values**

PandaBoards that will be used for the early adopter program will have the following model number:  
Model #: PandaBoard Rev EA1

Production versions of PandaBoards will contain the below model number:  
Model #: PandaBoard Rev A1

Model #s are printed on a label on the back of the board.

### 3.2 PandaBoard Pin Multiplexing

#### 3.2.1 Panda Base Platform Pin Multiplexing

See Table 19 for a listing of the OMAP pin multiplexing required for the OMAP4430 processor on the PandaBoard. This table only includes the GPIOs that are connected and required for operation of the as-shipped configuration of the PandaBoard. Unused pins are not included here as well as any GPIOs that go to the onboard connectors. GPIOs that are connected to the Camera Expansion connector at J17 are listed in Table 20 on page 57, while the signals connected to the Generic Expansion connectors at J3 and J6 may be found in Table 21 on page 58.





GPIO	OMAP Ball #	Mux Mode	Signal Name	Description of PandaBoard Usage
0	J27	3	H_GPIO_0	DVI-D Transmitter (TFP410) Power Down
1	H27	3	HUB_NPD	Ethernet/USB Hub LDO Power Enable
11	M2	0	DPM_EMU0	JTAG Emulator 0 I/O
12	N2	0	DPM_EMU1	JTAG Emulator 1 I/O
14	V1	5	DISPC2_DATA10	Parallel Display Data Bit 10
15	V2	5	DISPC2_DATA9	Parallel Display Data Bit 9
16	W1	5	DISPC2_DATA16	Parallel Display Data Bit 16
17	W2	5	DISPC2_DATA17	Parallel Display Data Bit 17
18	W3	5	DISPC2_HSYNC	Parallel Display Horizontal Sync
19	W4	5	DISPC2_PCLK	Parallel Display Pixel Clock
20	Y2	5	DISPC2_VSYNC	Parallel Display Vertical Sync
21	Y3	5	DISPC2_DE	Parallel Display Data Enable
22	Y4	5	DISPC2_DATA8	Parallel Display Data Bit 8
23	AA1	5	DISPC2_DATA7	Parallel Display Data Bit 7
24	AA2	5	DISPC2_DATA6	Parallel Display Data Bit 6
25	AA3	5	DISPC2_DATA5	Parallel Display Data Bit 5
26	AA4	5	DISPC2_DATA4	Parallel Display Data Bit 4
27	AB2	5	DISPC2_DATA3	Parallel Display Data Bit 3
28	AB3	5	DISPC2_DATA2	Parallel Display Data Bit 2
41	A18	3	GPIO_41	HDMI Transceiver Level Shifter Output Enable
43	A19	3	GPIO_43	Wireless LAN Enable
46	A21	3	GPIO_46	Bluetooth Enable
48	C20	3	GPIO_48	FM Enable
49	D20	3	GPIO_49	Bluetooth Wakeup
52	D21	3	GPIO_52	FM Interrupt In
53	C22	3	GPIO_53	WLAN Interrupt In
60	D22	3	GPIO_60	HDMI DC/DC-Hot Plug Enable
62	B23	3	GPIO_62	Ethernet/USB Hub Reset
63	B9	0	HDMI_HPD	HDMI Hot Plug Detect
64	B10	0	HDMI_CEC	HDMI Consumer Electronic Control
65	A8	0	HDMI_DDC_SCL	Display Data Channel Serial Clock
66	B8	0	HDMI_DDC_SDA	Display Data Channel Serial Data
84	AE18	4	ULPIPHY_CLK	USBB1 ULPI Clock (Hub)
85	AG19	4	ULPIPHY_STP	USBB1 ULPI Stop (Hub)
86	AF19	4	ULPIPHY_DIR	USBB1 ULPI Direction (Hub)
87	AE19	4	ULPIPHY_NXT	USBB1 ULPI Next (Hub)
88	AF18	4	ULPIPHY_DAT0	USBB1 ULPI Data Bit 0 (Hub)
89	AG18	4	ULPIPHY_DAT1	USBB1 ULPI Data Bit 1 (Hub)
90	AE17	4	ULPIPHY_DAT2	USBB1 ULPI Data Bit 2 (Hub)





GPIO	OMAP Ball #	Mux Mode	Signal Name	Description of PandaBoard Usage
91	AF17	4	ULPIPHY_DAT3	USBB1 ULPI Data Bit 3 (Hub)
92	AH17	4	ULPIPHY_DAT4	USBB1 ULPI Data Bit 4 (Hub)
93	AE16	4	ULPIPHY_DAT5	USBB1 ULPI Data Bit 5 (Hub)
94	AF16	4	ULPIPHY_DAT6	USBB1 ULPI Data Bit 6 (Hub)
95	AG16	4	ULPIPHY_DAT7	USBB1 ULPI Data Bit 7 (Hub)
100	D2	0	SDMMC1_CLK	SDMMC Card Cage Clock (1.8v/3.0V)
101	E3	0	SDMMC1_CMD	SDMMC Card Cage Command (1.8v/3.0V)
101	A24	3	GPIO_101	Board ID Input Bit 1
102	E4	0	SDMMC1_DAT0	SDMMC Card Cage Data Bit 0 (1.8v/3.0V)
103	E2	0	SDMMC1_DAT1	SDMMC Card Cage Data Bit 1 (1.8v/3.0V)
104	E1	0	SDMMC1_DAT2	SDMMC Card Cage Data Bit 2 (1.8v/3.0V)
105	F4	0	SDMMC1_DAT3	SDMMC Card Cage Data Bit 3 (1.8v/3.0V)
106	F3	0	SDMMC1_DAT4	SDMMC Card Cage Data Bit 4 (1.8v/3.0V)
107	F1	0	SDMMC1_DAT5	SDMMC Card Cage Data Bit 5 (1.8v/3.0V)
108	G4	0	SDMMC1_DAT6	SDMMC Card Cage Data Bit 6 (1.8v/3.0V)
109	G3	0	SDMMC1_DAT7	SDMMC Card Cage Data Bit 7 (1.8v/3.0V)
110	AD27	0	MCBSP2_CLKX	FM I2S Digital Audio Clock
111	AD26	0	MCBSP2_DR	FM I2S Digital Audio Receive Data
112	AD25	0	MCBSP2_DX	FM I2S Digital Audio Transmit Data
113	AC28	0	MCBSP2_FSX	FM I2S Digital Audio Frame Sync
114	AC26	0	MCBSP1_CLKX	BT Audio I2S Clock
115	AC25	0	MCBSP1_DR	BT Audio I2S Data Out
116	AB25	0	MCBSP1_DX	BT Audio I2S Data In
117	AC27	0	MCBSP1_FSX	BT Audio I2S Frame Sync
118	AH26	0	ABE_CLKS	Clock input from TWL6030 Audio Companion IC
121	AG24	3	GPIO_121	Input from push-button switch S2
122	AH24	3	GPIO_122	DVI-D Monitor Sense Input
123	AB26	0	UART2_CTS	Bluetooth Host Control Interface Request to Send
124	AB27	0	UART2_RTS	Bluetooth Host Control Interface Clear to Send
125	AA25	0	UART2_RX	Bluetooth Host Control Interface Transmit Data
126	AA26	0	UART2_TX	Bluetooth Host Control Interface Receive Data
127	AA27	3	GPIO_127	TWL6040 Audio Power On
128	C26	0	I2C2_SCL	I2C2 Serial Clock
129	D26	0	I2C2_SDA	I2C2 Serial Data
130	W27	0	I2C3_SCL	I2C3 Serial Clock
131	Y27	0	I2C3_SDA	I2C3 Serial Data
132	AG21	0	I2C4_SCL	I2C4 Serial Clock
133	AH22	0	I2C4_SDA	I2C4 Serial Data
141	F27	0	UART3_CTS	Debug Terminal RS-232 Clear to Send





GPIO	OMAP Ball #	Mux Mode	Signal Name	Description of PandaBoard Usage
142	F28	0	UART3 RTS	Debug Terminal RS-232 Request to Send
143	G27	0	UART3 RX	Debug Terminal RS-232 Receive Data
144	G28	0	UART3 TX	Debug Terminal RS-232 Transmit Data
145	AE5	0	SDMMC5 CLK	WLAN SDIO Clock Line
146	AF5	0	SDMMC5 CMD	WLAN SDIO Command Line
147	AE4	0	SDMMC5 DAT0	WLAN SDIO Data Bit 0
148	AF4	0	SDMMC5 DAT1	WLAN SDIO Data Bit 1
149	AG3	0	SDMMC5 DAT2	WLAN SDIO Data Bit 2
150	AF3	0	SDMMC5 DAT3	WLAN SDIO Data Bit 3
158	AF12	5	DISPC DATA23	Parallel Display Data Bit 23
159	AE12	5	DISPC DATA22	Parallel Display Data Bit 22
160	AG13	5	DISPC DATA21	Parallel Display Data Bit 21
161	AE11	5	DISPC DATA20	Parallel Display Data Bit 20
162	AF11	5	DISPC DATA19	Parallel Display Data Bit 19
163	AG11	5	DISPC DATA18	Parallel Display Data Bit 18
164	AH11	5	DISPC DATA15	Parallel Display Data Bit 15
165	AE10	5	DISPC DATA14	Parallel Display Data Bit 14
166	AF10	5	DISPC DATA13	Parallel Display Data Bit 13
167	AG10	5	DISPC DATA12	Parallel Display Data Bit 12
168	AE9	5	DISPC DATA11	Parallel Display Data Bit 11
171	G26	3	GPIO_171	Board ID Bit 2
179	B5	0	USBA0 OTG DP	Internal USB Transceiver Data Plus
180	B4	0	USBA0 OTG DM	Internal USB Transceiver Data Minus
181	AA28	0	FREF CLK1 OUT	Camera Expansion Connector
182	Y28	0	GPIO_182	Board ID Bit 0
183	AF6	0	SYS NIRQ2	System Interrupt from TWL6040 Audio IC
184	F26	0	SYS BOOT0	SYSBOOT Input 0
185	E27	0	SYS BOOT1	SYSBOOT Input 1
186	E26	0	SYS BOOT2	SYSBOOT Input 2
187	E25	0	SYS BOOT3	SYSBOOT Input 3
188	D28	0	SYS BOOT4	SYSBOOT Input 4
189	D27	0	SYS BOOT5	SYSBOOT Input 5
190	AB4	5	DISPC2 DATA1	Parallel Display Data Bit 1
191	AC4	5	DISPC2 DATA0	Parallel Display Data Bit 0
WK5	AG8	0	FREF SLICER IN	38.4MHz Clock Input
WK6	AD2	2	GPIO WK6	MSECURE output to TWL6030 (RTC related)
WK7	AC2	3	GPIO WK7	LED D1 On/Off Control
WK8	AC3	3	GPIO WK8	LED D2 On/Off Control
WK9	AF8	0	SYS BOOT6	SYSBOOT Input 6





GPIO	OMAP Ball #	Mux Mode	Signal Name	Description of PandaBoard Usage
WK10	AE8	0	SYS_BOOT7	SYSBOOT Input 7
WK31	AD4	0	FREF_CLK3_OUT	USBB1 Phy Reference Clock (19.2 MHz)

Table 19: PandaBoard OMAP4430 Pin Multiplexing

### 3.2.2 Camera Expansion Connector Pin Multiplexing

See Table 20 for a description of the pin multiplexing possibilities for the camera expansion board signals.





GPIO	OMAP Ball #	Mux Mode	Signal Name	Description of PandaBoard Usage
40	B17	3	GPIO_40	Camera Expansion Connector (pin 16)
42	B18	3	GPIO_42	Camera Expansion Connector (pin 28)
44	B19	3	GPIO_44	Camera Expansion Connector (pin 26)
45	B20	3	GPIO_45	Camera Expansion Connector (pin 18)
47	B21	3	GPIO_47	Camera Expansion Connector (pin 25)
67	R26	0	CSI21_DX0	Camera Expansion Connector (pin 3)
68	R25	0	CSI21_DY0	Camera Expansion Connector (pin 5)
69	T26	0	CSI21_DX1	Camera Expansion Connector (pin 9)
70	T25	0	CSI21_DY1	Camera Expansion Connector (pin 11)
71	U26	0	CSI21_DX2	Camera Expansion Connector (pin 15)
72	U25	0	CSI21_DY2	Camera Expansion Connector (pin 17)
73	V26	0	CSI21_DX3	Camera Expansion Connector (pin 4)
74	V25	0	CSI21_DY3	Camera Expansion Connector (pin 6)
75	W26	0	CSI21_DX4	Camera Expansion Connector (pin 10)
76	W25	0	CSI21_DY4	Camera Expansion Connector (pin 12)
81	T27	0/3	CAM_SHUTTER	Camera shutter or GPIO_81 (pin 22)
82	U27	0/3	CAM_STROBE	Camera strobe or GPIO_82 (pin 24)
83	V27	0	CAM_GLOBALRESET	Camera Expansion Connector (pin 20)
130	W27	0	I2C3_SCL	I2C3 Serial Clock (pin 21)
131	Y27	0	I2C3_SDA	I2C3 Serial Data (pin 23)
181	AA28	0	FREF_CLK1_OUT	Camera Expansion Connector (pin 27)

**Table 20: Camera Expansion Connector (J17) Pin Multiplexing Options**

### 3.2.3 Expansion Connector (J3 & J6) Pin Multiplexing

See Table 21 below for a listing of the IOs connected to the expansion connectors at J3 and J6. GPIOs with multiple mux modes listed have multiple functions that can be supported, depending on the requirements of the particular expansion board being utilized.





GPIO	OMAP Ball #	Mux Mode	Function1	Function2	Function3	Function4
32	C16	0/1/3/5	GPMC AD8	KPD ROW0	GPIO 32	SDMMC1 DAT0
33	D16	0/1/3/5	GPMC AD9	KPD ROW1	GPIO 33	SDMMC1 DAT1
34	C17	0/1/3/5	GPMC AD10	KPD ROW2	GPIO 34	SDMMC1 DAT2
35	D17	0/1/3/5	GPMC AD11	KPD ROW3	GPIO 35	SDMMC1 DAT3
36	C18	0/1/3/5	GPMC AD12	KPD COL0	GPIO 36	SDMMC1 DAT4
37	D18	0/1/3/5	GPMC AD13	KPD COL1	GPIO 37	SDMMC1 DAT5
38	C19	0/1/3/5	GPMC AD14	KPD COL2	GPIO 38	SDMMC1 DAT6
39	D19	0/1/3/5	GPMC AD15	KPD COL3	GPIO 39	SDMMC1 DAT7
50	B25	0/3	GPMC NCS0	GPIO 50	----	----
51	C21	0/3	GPMC NCS1	GPIO 51	----	----
54	C25	0/3/4	GPMC NWP	GPIO 54	SYS_NDMAREQ1	----
55	B22	0/3/4/5	GPMC CLK	GPIO 55	SYS_NDMAREQ2	SDMMC1 CMD
56	D25	0/3/4/5	GPMC_NADV_ALE	GPIO 56	SYS_NDMAREQ3	SDMMC1 CLK
59	C23	0/3	GPMC_NBE0_CLE	GPIO 59	----	----
61	B26	0/3	GPMC_WAIT0	GPIO 61	----	----
132	AG21	0/3	I2C4 SCL	GPIO 132	----	----
133	AH22	0/3	I2C4 SDA	GPIO 133	----	----
134	AF22	0/3	MCSPI1_CLK	GPIO 134	----	----
135	AE22	0/3	MCSPI1_SOMI	GPIO 135	----	----
136	AG22	0/3	MCSPI1_SIMO	GPIO_136	----	----
137	AE23	0/3	MCSPI1_CS0	GPIO 137	----	----
138	AF23	0/3	MCSPI1_CS1	GPIO 138	----	----
139	AG23	0/2/3	MCSPI1_CS2	SLIMBUS2_CLOCK	GPIO 139	----
140	AH23	0/2/3	MCSPI1_CS3	SLIMBUS2_DATA	GPIO 140	----
155	AG20	0/2/3	UART4_RX	KPD_ROW8	GPIO 155	----
156	AH19	0/2/3	UART4_TX	KPD_COL8	GPIO 156	----
None	C12	0/1	GPMC AD0	SDMMC2_DAT0	----	----
None	D12	0/1	GPMC AD1	SDMMC2_DAT1	----	----
None	C13	0/1	GPMC AD2	SDMMC2_DAT2	----	----
None	D13	0/1	GPMC AD3	SDMMC2_DAT3	----	----
None	C15	0/1	GPMC AD4	SDMMC2_DAT4	----	----
None	D15	0/1	GPMC AD5	SDMMC2_DAT5	----	----
None	A16	0/1	GPMC AD6	SDMMC2_DAT6	----	----
None	B16	0/1	GPMC AD7	SDMMC2_DAT0	----	----
None	B11	0/1	GPMC_NOE	SDMMC2_CLK	----	----
None	B12	0/1	GPMC_NWE	SDMMC2_CMD	----	----

Table 21: Expansion Connector (J3 &amp; J6) Pin Multiplexing Options





### 3.3 OMAP4430 PandaBoard Key Components

See Table 22 for a listing of the manufacturers and manufacturer part numbers for some of the key components used on the OMAP4430 PandaBoard.

Device / Interface	Under NDA?	Manufacture P/N
<b>Application Processor</b>		
Processor	Yes	TI OMAP4430 ES2.1
<b>Memories/Storage</b>		
DDR	Yes	Elpida 8Gb (POP, S4B) EDB8064B1PB-8D-F
Removable card support	No	KingConn 6-in-One SD/MMC (8 bit Cardcage) SDMM-B0-0016
Removable card ESD protection	No	Texas Instruments TPD6E001RSER
<b>Power</b>		
Power Management (U12)	Yes	Texas Instruments TWL6030
DC Input Connector (P3)	No	CUI, Inc. PJ-002A
USB Power Switch/LDO (U22)	No	Texas Instruments TPS2141IPWP
Input Power LDO (U23)	No	Texas Instruments TL1963ADCQR
Input Voltage Supervisor (U20)	No	Texas Instruments TPS3803G15DCKR
USB/Ethernet Hub Power (U11)	No	Texas Instruments TPS73633DBVR
<b>Clocking</b>		
38.4 MHz oscillator	No	TXC 7X-38.400MBB-T
<b>Video/Display</b>		
HDMI Transceiver + ESD protection	No	Texas Instruments TPD12S015YFFR
HDMI Connector & DVI-D Connector	No	FCI Connectors 10029449-001RLF





DVI-D Transmitter	No	Texas Instruments TFP410PAP
<b>Audio</b>		
Audio Management	Yes	TI TWL6040
Dual Stacked Audio Jack	No	Kycon STX-4235-3/3-N
<b>MCS</b>		
Wilink™6 Module	No	LS Research, Inc. LS240-WI-01-A20
<b>USB/Ethernet</b>		
Ethernet + 2x USB Host Port Connector	No	Tyco (6620004-1) Belfuse (08C2-1X1T-03)
ULPI USB Phy	No	SMSC USB3320C-EZK
USB/Ethernet Hub Controller	No	SMSC LAN9514-JZX
USB OTG ESD Protection	No	Texas Instruments TPD3E001
<b>Camera Expansion</b>		
30-pin Camera Expansion Connector	No	Samtec TFM-115-32-S-D-A

**Table 22: OMAP4430 PandaBoard Key H/W Components**

### 3.4 OMAP4430 PandaBoard Key Component Datasheet URLs

Shown below for convenience are links to datasheets for key PandaBoard components.

#### 3.4.1 Connector Datasheets

- Combo Ethernet/2x USB Host Port Connector (J9)
  - <http://www.tycoelectronics.com/catalog/products/en?q=6620004-1>
- Power Input Connector (P3)





- <http://products.cui.com/adtemplate.asp?brand=electronic-components&invky=7106&catky=619701&subcatky1=447353&subcatky2=632366&subcatky3=405514>
- Dual Audio Jack (J16)
  - [http://domino2.kycon.com/catalog\\_PDF/STX4235.pdf](http://domino2.kycon.com/catalog_PDF/STX4235.pdf)
- DVI-D & HDMI Connectors (P1 & P2)
  - [http://portal.fciconnect.com/portal/page/portal/FcicntPublic/Product\\_Type?appname=catLanding](http://portal.fciconnect.com/portal/page/portal/FcicntPublic/Product_Type?appname=catLanding)
- Camera Expansion Connector (J17)
  - [http://www.samtec.com/documents/webfiles/pdf/TFM\\_SM.PDF](http://www.samtec.com/documents/webfiles/pdf/TFM_SM.PDF)

### 3.4.2 Key Electronic Component Datasheets

- DVI Transmitter (U2)
  - <http://focus.ti.com/docs/prod/folders/print/tfp410.html>
- HDMI Companion Chip – ESD, Level Translator, Charge Pump (U6)
  - <http://focus.ti.com/docs/prod/folders/print/tpd12s015.html>
- USB Power Switch w/ Integrated LDO (U22)
  - <http://focus.ti.com/docs/prod/folders/print/tps2141.html>
- Single Output LDO, 1.5A (U23)
  - <http://focus.ti.com/docs/prod/folders/print/tl1963a.html>
- Single Output LDO, 400mA (U11)
  - <http://focus.ti.com/docs/prod/folders/print/tps73633.html>
- Single Voltage Detector, (U20)
  - <http://focus.ti.com/docs/prod/folders/print/tps3803g15.html>
- USB ULPI Phy (U8)
  - <http://www.smsc.com/index.php?tid=143&pid=211>
- USB/Ethernet Hub Controller (U9)
  - <http://www.smsc.com/index.php?tid=300&pid=135&cid=&tab=5>
- Wilink™6 Module (U4)
  - [http://www.lsr.com/products/radio\\_modules/802.11\\_BGN\\_BT/tiwi.shtml](http://www.lsr.com/products/radio_modules/802.11_BGN_BT/tiwi.shtml)





## 4 Test/Debug Information

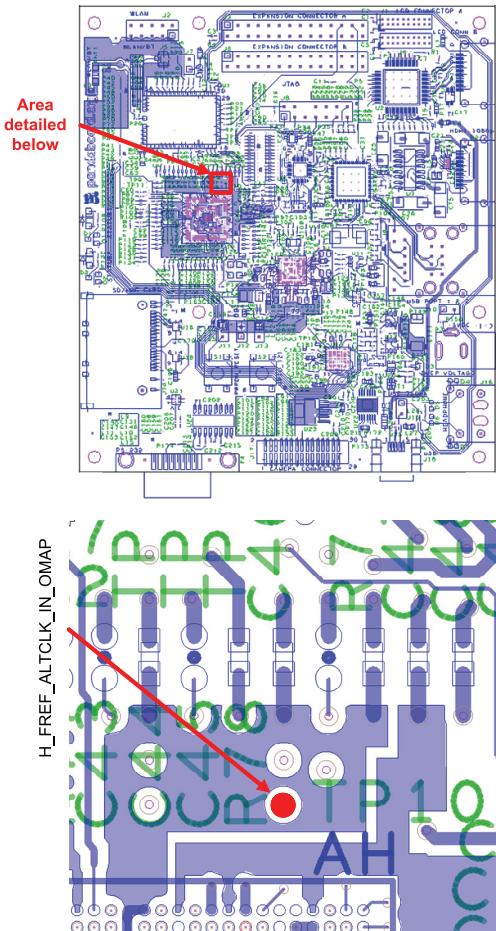
This chapter contains information to allow easier debug access to signals on the OMAP4430 PandaBoard.

### 4.1 PandaBoard Clock Signal Access

The following sections show where various clock signals on the PandaBoard may be accessed.

#### 4.1.1 H\_FREF\_ALTCLK\_IN\_OMAP Probe Point

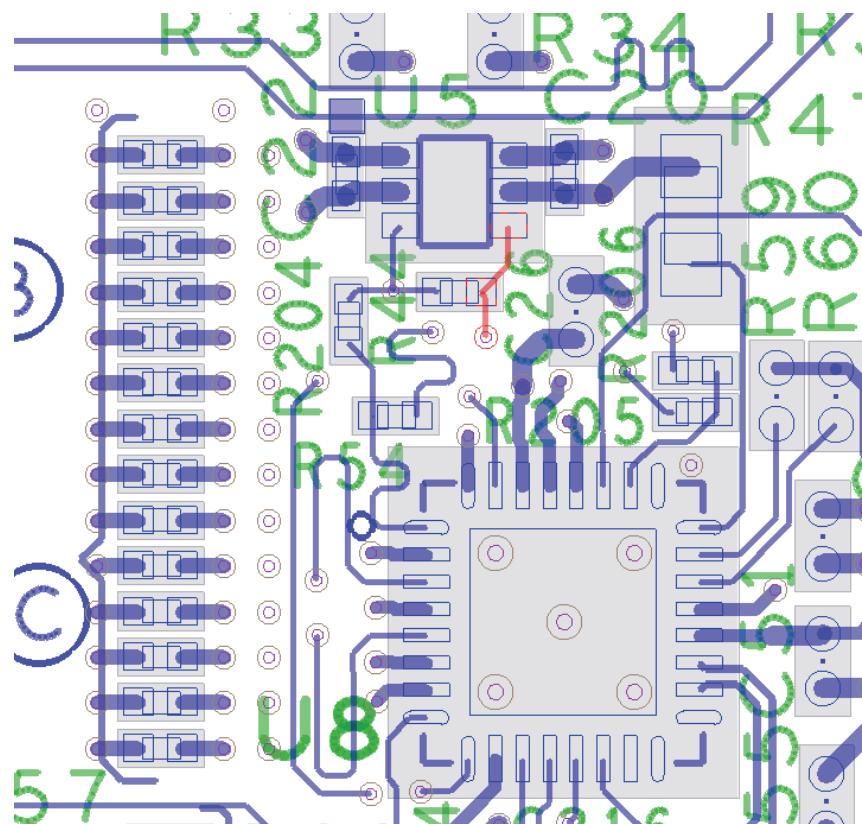
This signal is the input clock to OMAP and the TWL6040 Audio Companion IC from the onboard 38.4 MHz oscillator. It may be probed at TP10 in the area above OMAP as shown in Figure 22 below.



**Figure 22 – 38.4 MHz Input Clock Probe Point (h FREF ALTCLK IN OMAP)**

#### 4.1.2 USBB1 PHY REFCLK Probe Point

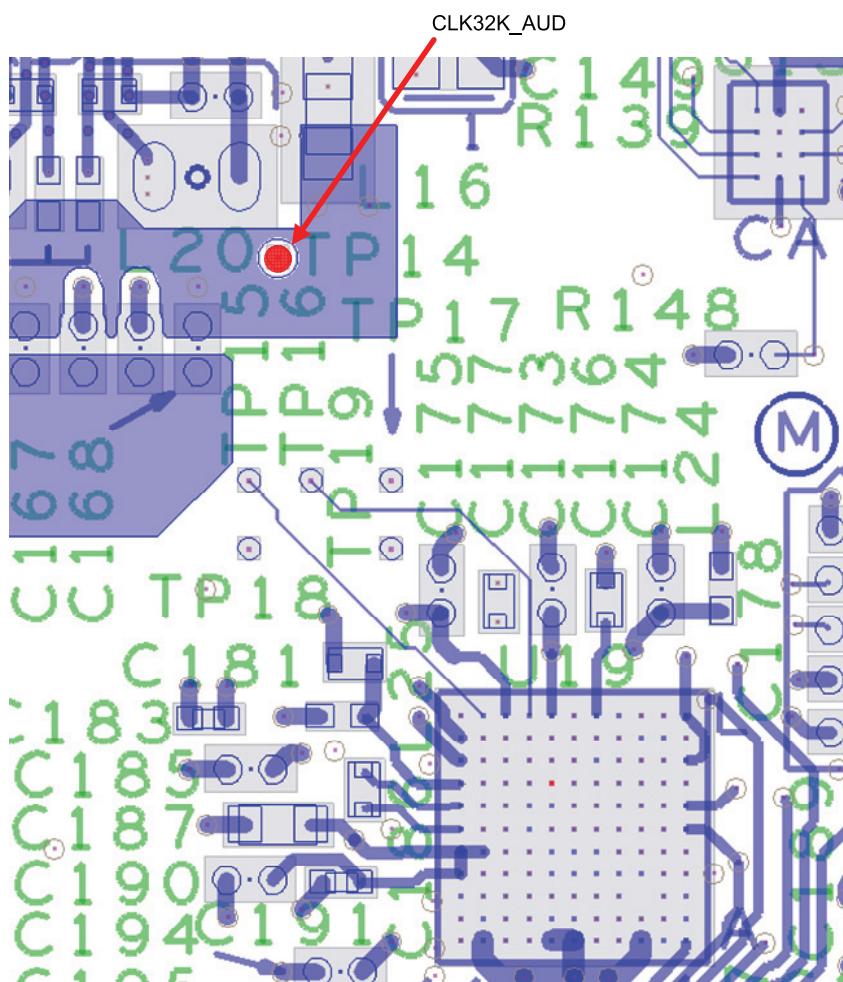
The 19.2 MHz reference input clock to the USBB1 Phy device may be probed at R44-1 or U5-4 as shown below in red. These parts are located directly below the 14-pin JTAG connector J8.



**Figure 23 – USB Phy Ref Clock In Probe Point (USBB1\_PHY\_REFCLK)**

#### 4.1.3 CLK32K AUD Probe Point

The 32.768KHz input clock to the TWL6040 Audio Companion IC may be probed at TP14 as shown in Figure 24. This testpoint may be located between the TWL6040 device at U19 and the TWL6030 Power Companion device at U12.



**Figure 24 – 32KHz Audio Clock Probe Point (CLK32K\_AUD)**

## 4.2 PandaBoard Power Rail Signal Access

#### **4.2.1 TWL6030 SMPS Output Probe Points**

The outputs of the seven Phoenix SMPS output supplies may be probed around the TWL6030 IC at U12 as shown in Figure 25 below.

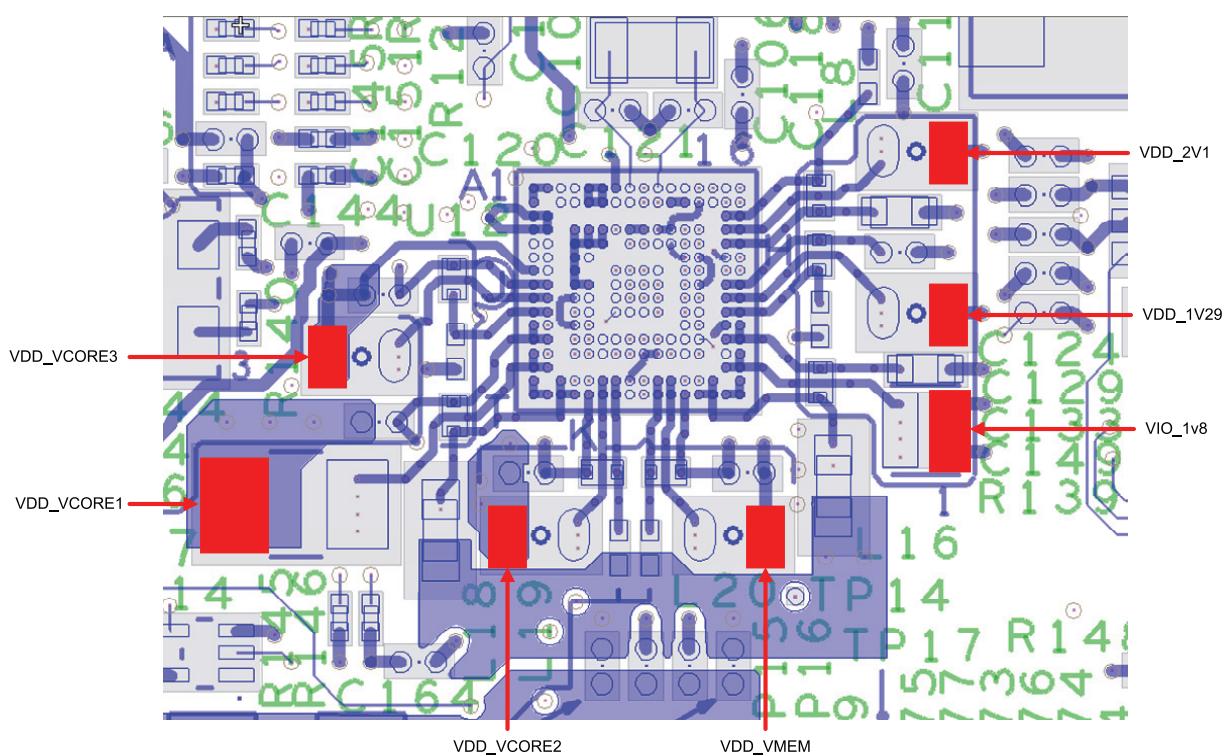


Figure 25 – TWL6030 SMPS Output Probe Points

#### 4.2.2 VCXIO LDO Output Probe Point

The outputs of the TWL6030 VCXIO LDO may be probed at SMPS output supplies may be probed around the bottom of the OMAP4430 and near the oscillator Y3 as shown in Figure 26 below. The possible probe points are at C142-2, R144-1, C126-2, C144-2, or C123-2 as shown highlighted in red from left to right in Figure 26.



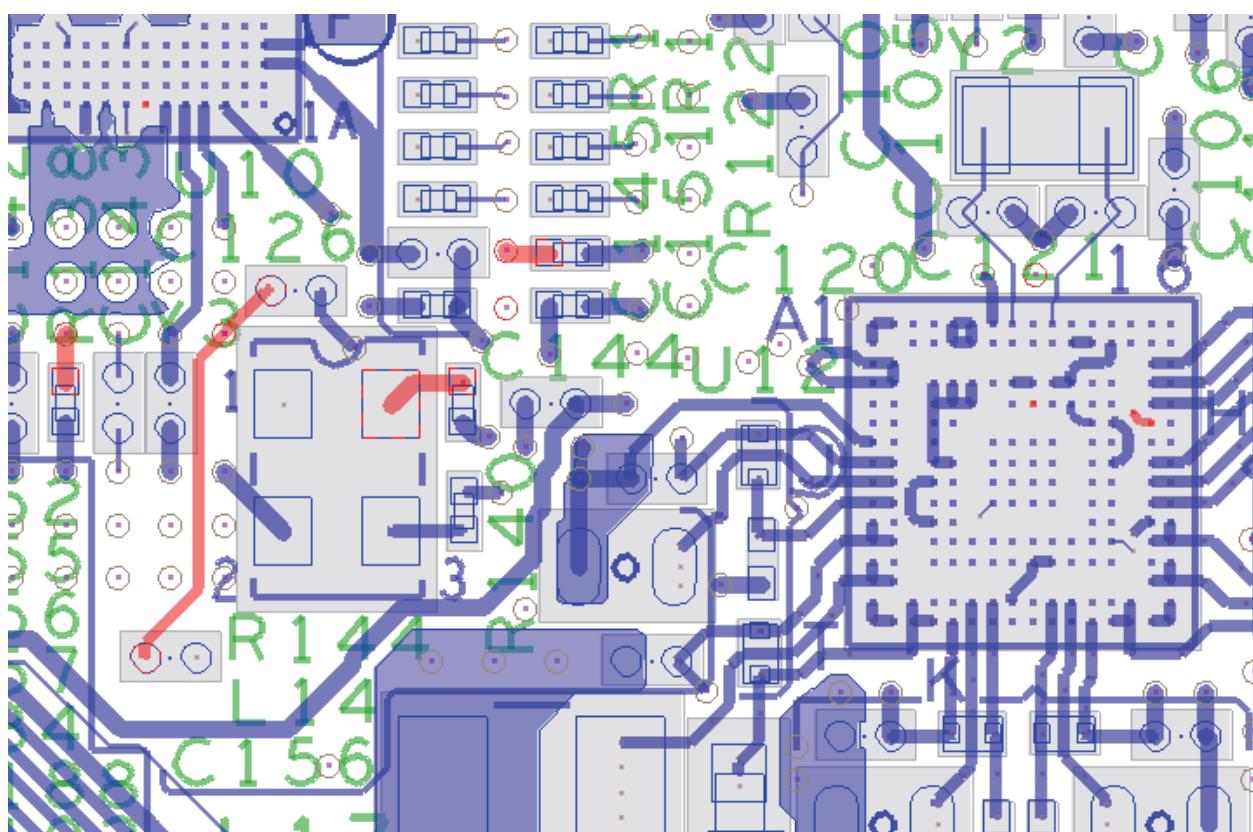


Figure 26 – TWL6030 VCXIO LDO Output Probe Points

#### 4.3 PandaBoard Interface Signal Access

##### 4.3.1 TWL6040 PDM Interface Probe Points

The PDM interface which is the digital audio interface between the OMAP4430 and the TWL6040 Audio Companion IC, may be probed at testpoints above the TWL6040 IC at U19 as shown in Figure 27 below.



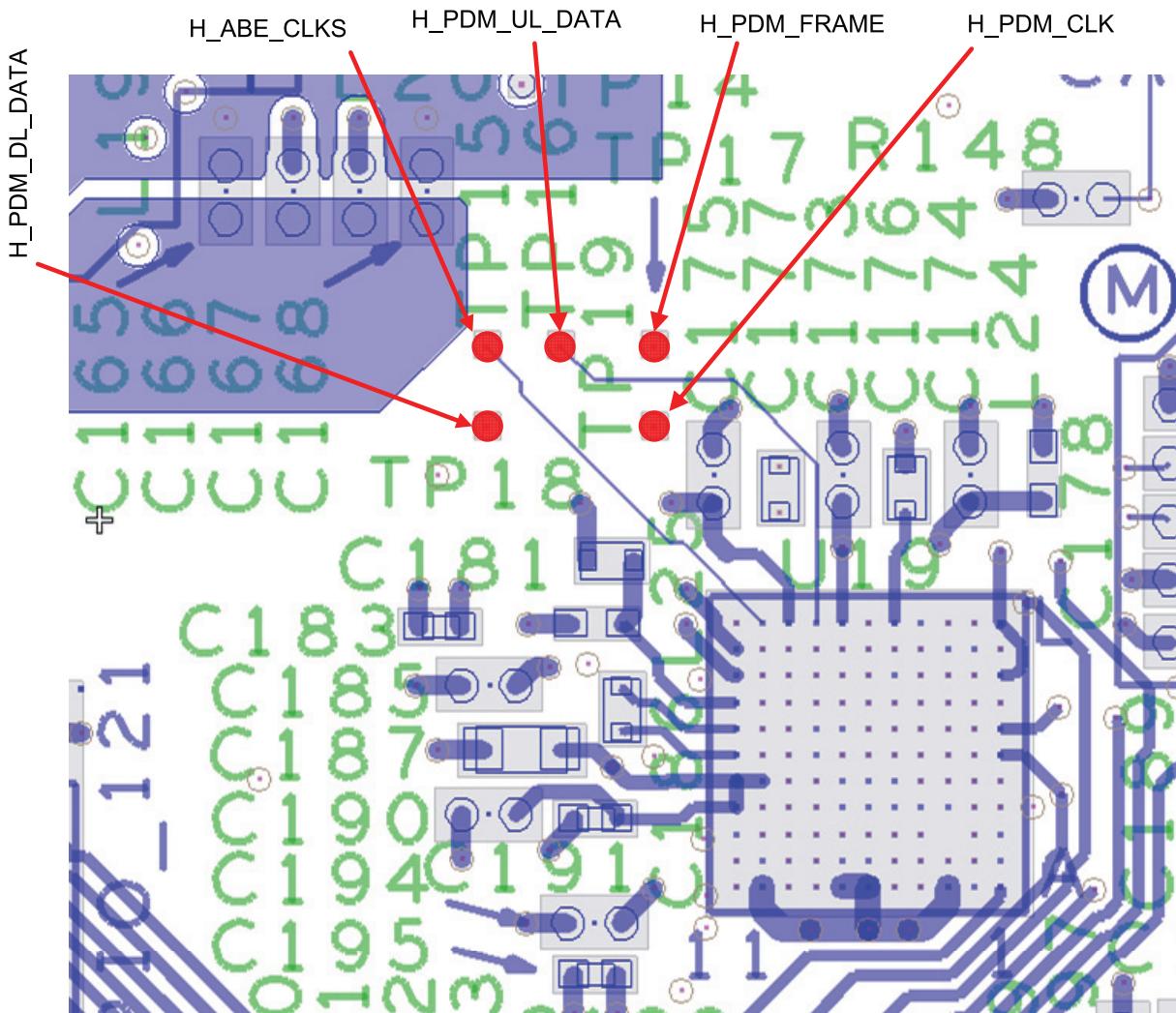


Figure 27 – TWL6040 PDM Interface Probe Points

#### 4.4 PandaBoard Schematic

The following pages contain the PDF schematics for the PandaBoard. The schematics are included in this document for convenience, and this manual will be periodically updated, but for the latest information be sure and check on the PandaBoard.org website. OrCAD 16.2 source files are provided for the PandaBoard at the following URL:

<http://pandaboard.org/content/resources/references>





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## OMAP™ 4 PandaBoard System Reference Manual

Revision 0.4  
September 22, 2010  
DOC-21010

Rev	Date	Notes
A	7/28/2010	ECN-13097 - Released to Rev. A
A1	7/30/2010	ECN-13101 - No wiring changes, changed the UX10 symbol to reflect the Micron LPDDR2 device
A2	8/11/2010	ECN-13113 - No wiring changes, changed the LPDDR2 back to Elpida. DNI_J2, correct notes on sh. 14 for WLAN_EN and BT_EN.
B	8/13/2010	ECN-13116 - Enable FM operation (sheet 14 - DNI_R01, install R14, R15, R19, R62, and R63)
B1	9/22/2010	ECN-13116 - Change out to new Pandaboard title blocks and add comments

**Table of Contents**

Pg# - Schematic Page Name

1 - Title Page

2 - Input Power

3 - Phoenix Power Component

4 - Phoenix Audio Component

5 - OMAP4430 Symbol A

6 - OMAP4430 Symbol B

7 - OMAP4430 Symbol C

8 - OMAP4430 Debug Interface

9 - SDMMC Card Interface + USB Phy (Hub)

10 - DVI & HDMI Connector

11 - Debug Ethernet

12 - Audio Jack/RS-232 Connection

13 - Expansion Connectors

14 - WLAN Subsystem

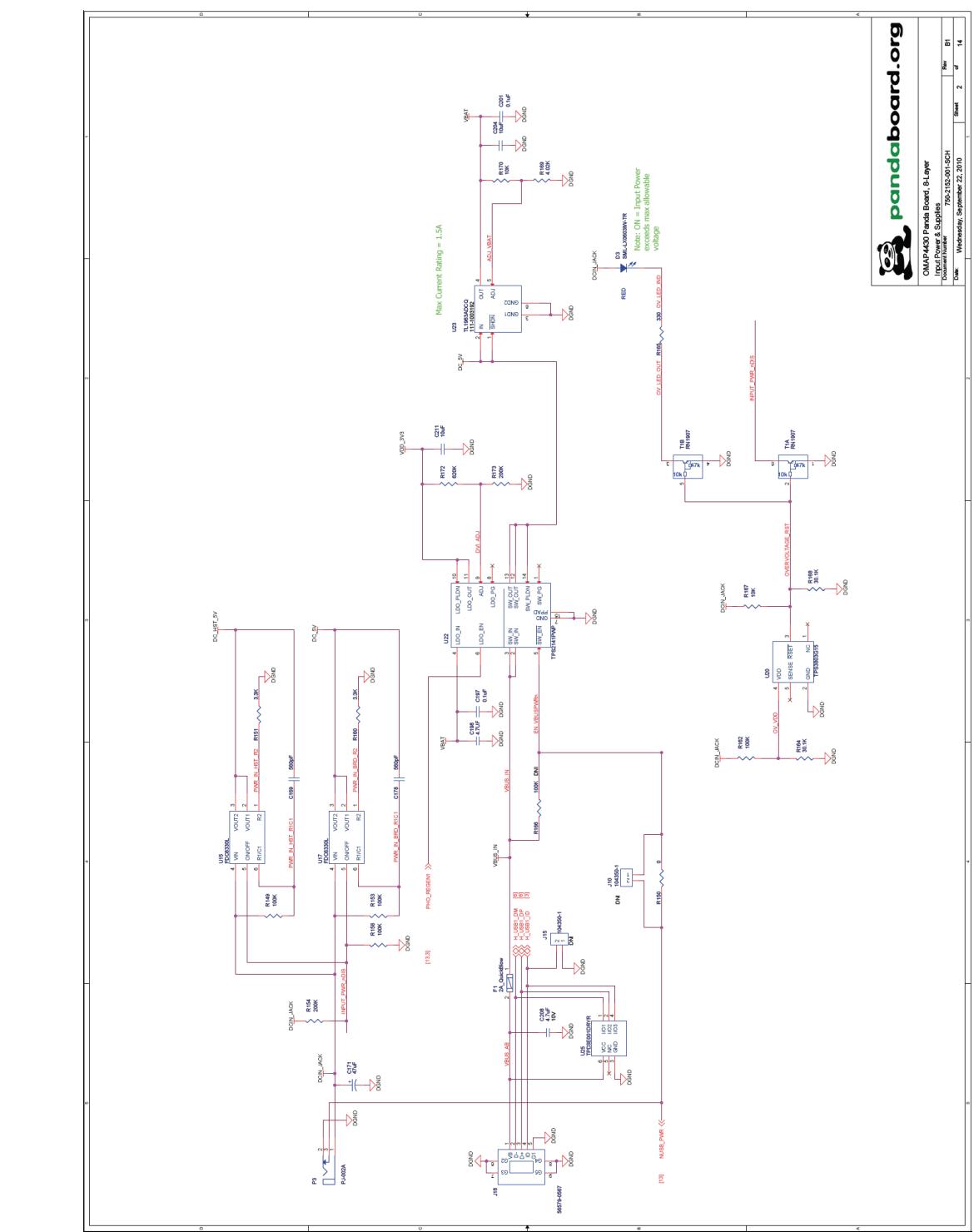
**NOTES LEGEND:**

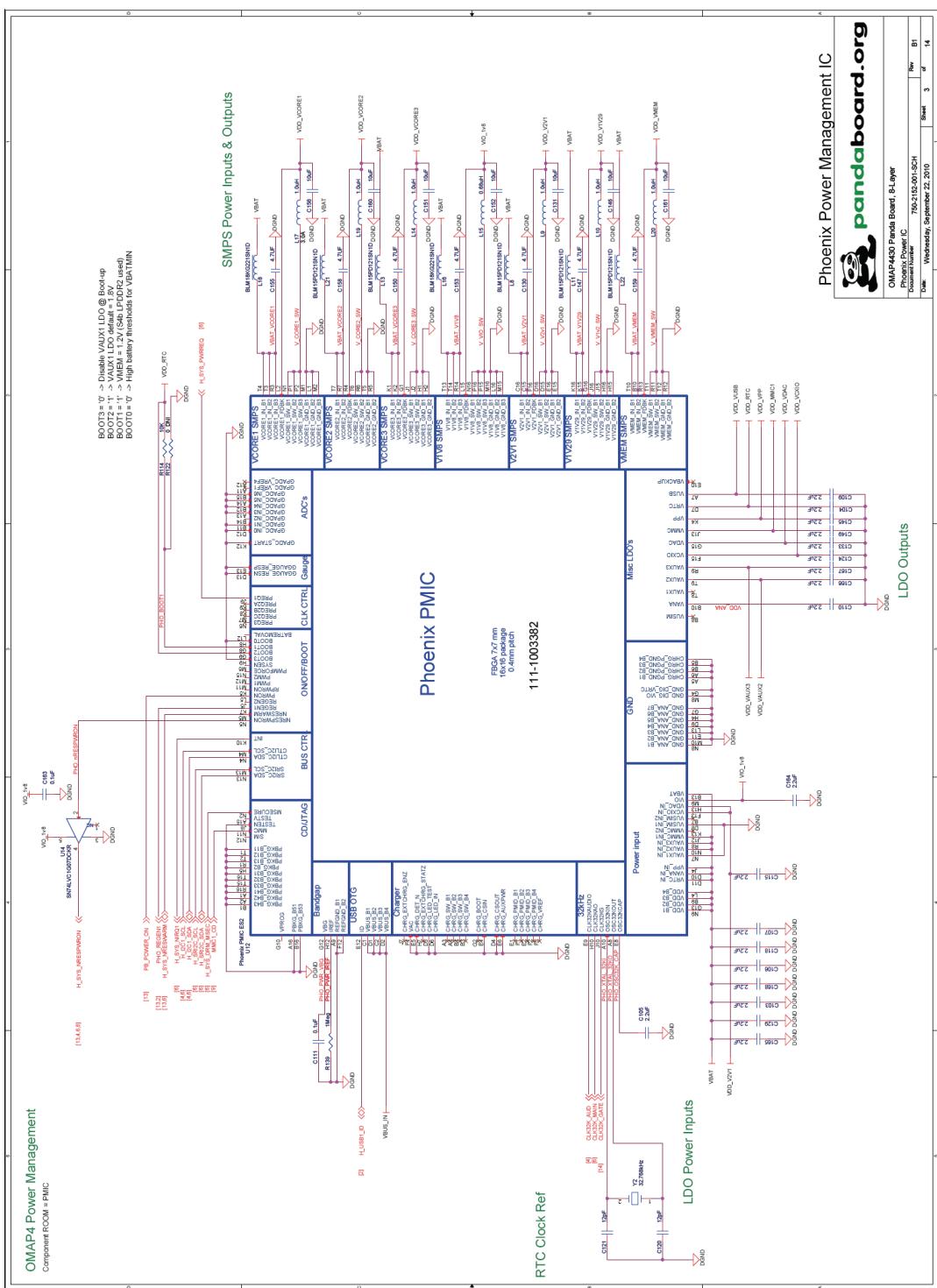
Schematic Page Titles  
Functional Block Labels  
Circuit Design Notes

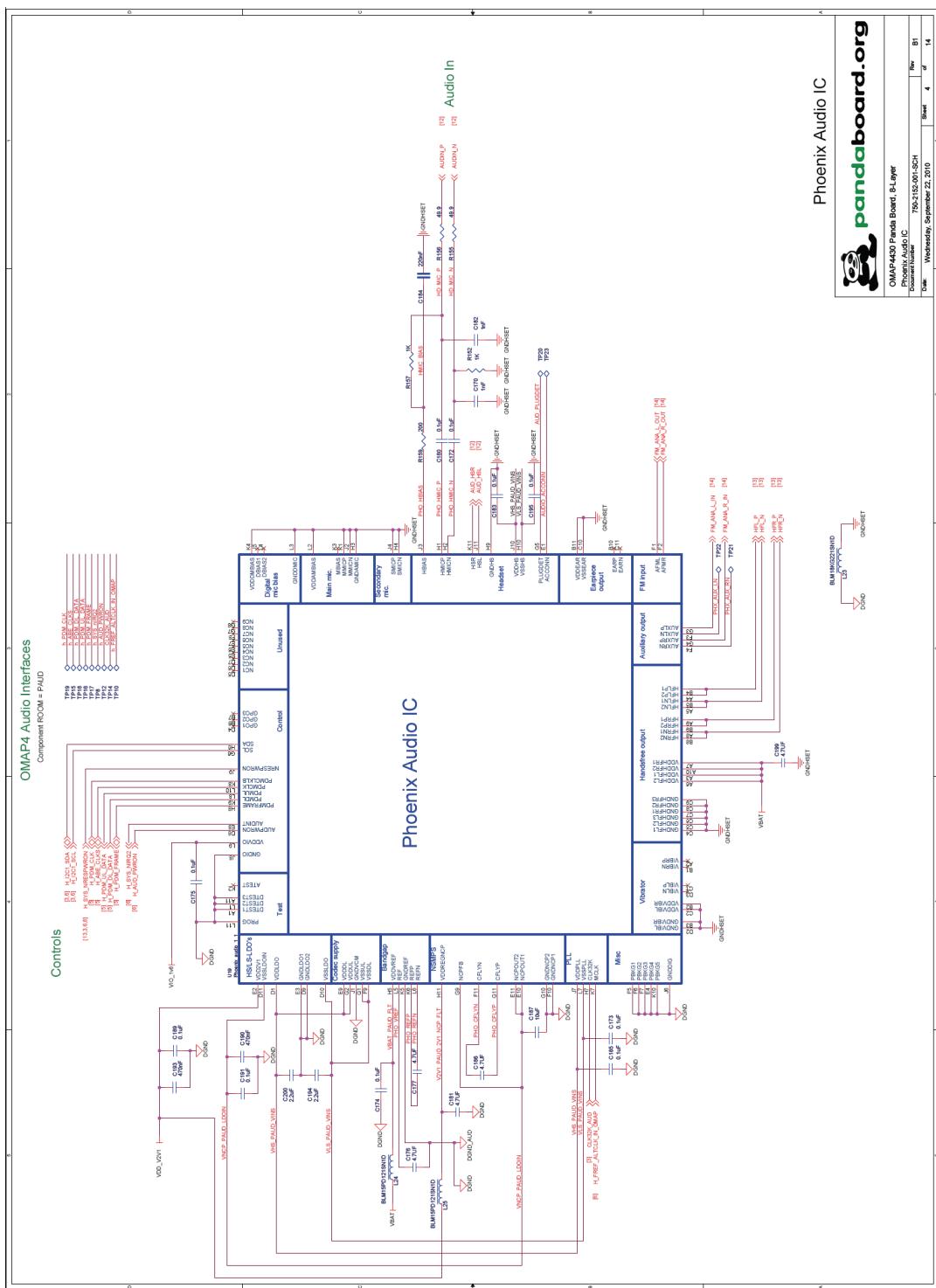
**OMAP4430 Panda Board, 8-Layer**  
Title: OMAP4430\_PandaBoard  
Version: 0.4  
Date: 09/22/2010  
Author: Wadsworth, September 22, 2010  
Status: 1  
Rev: B  
Ed: 14



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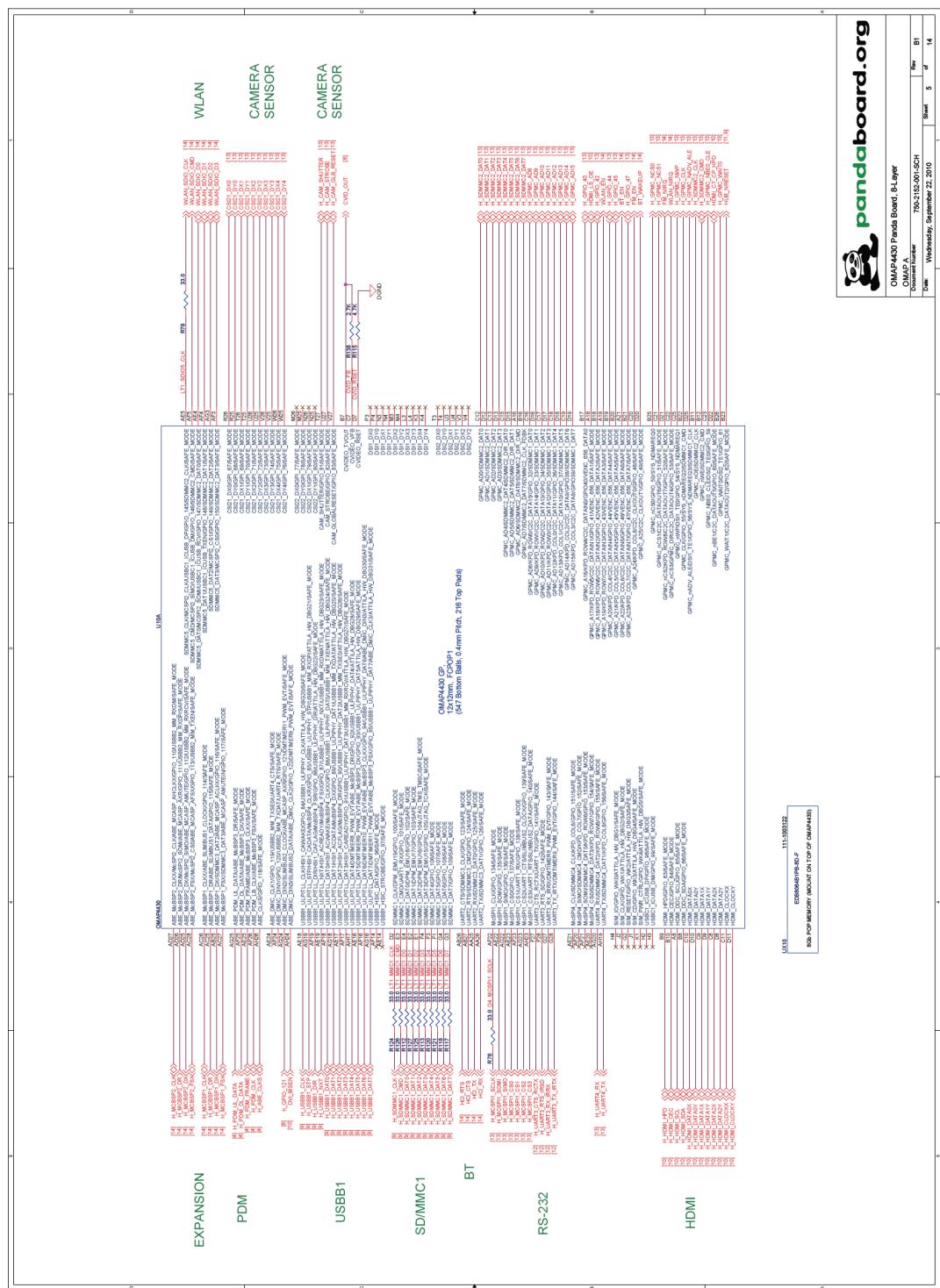






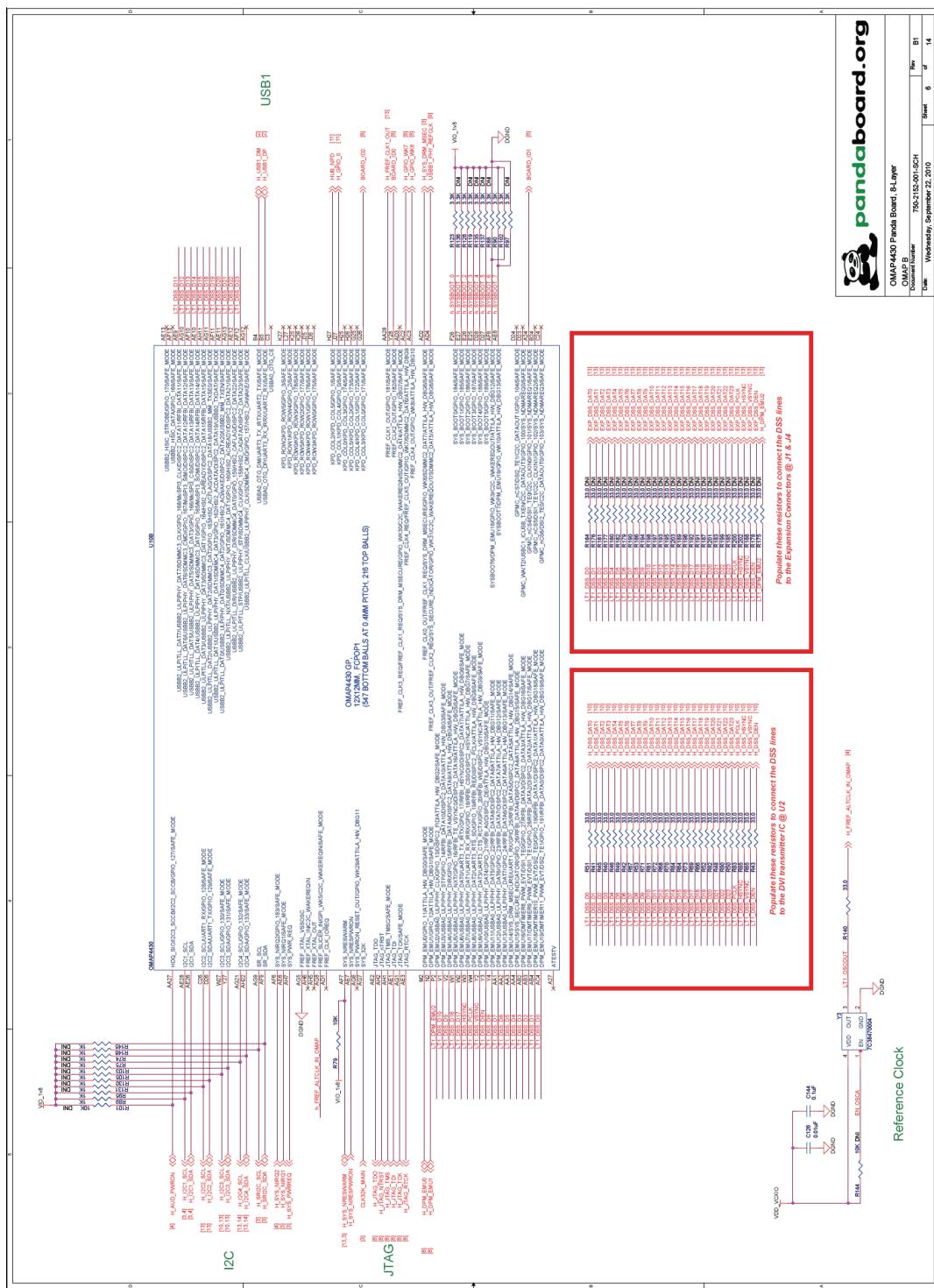


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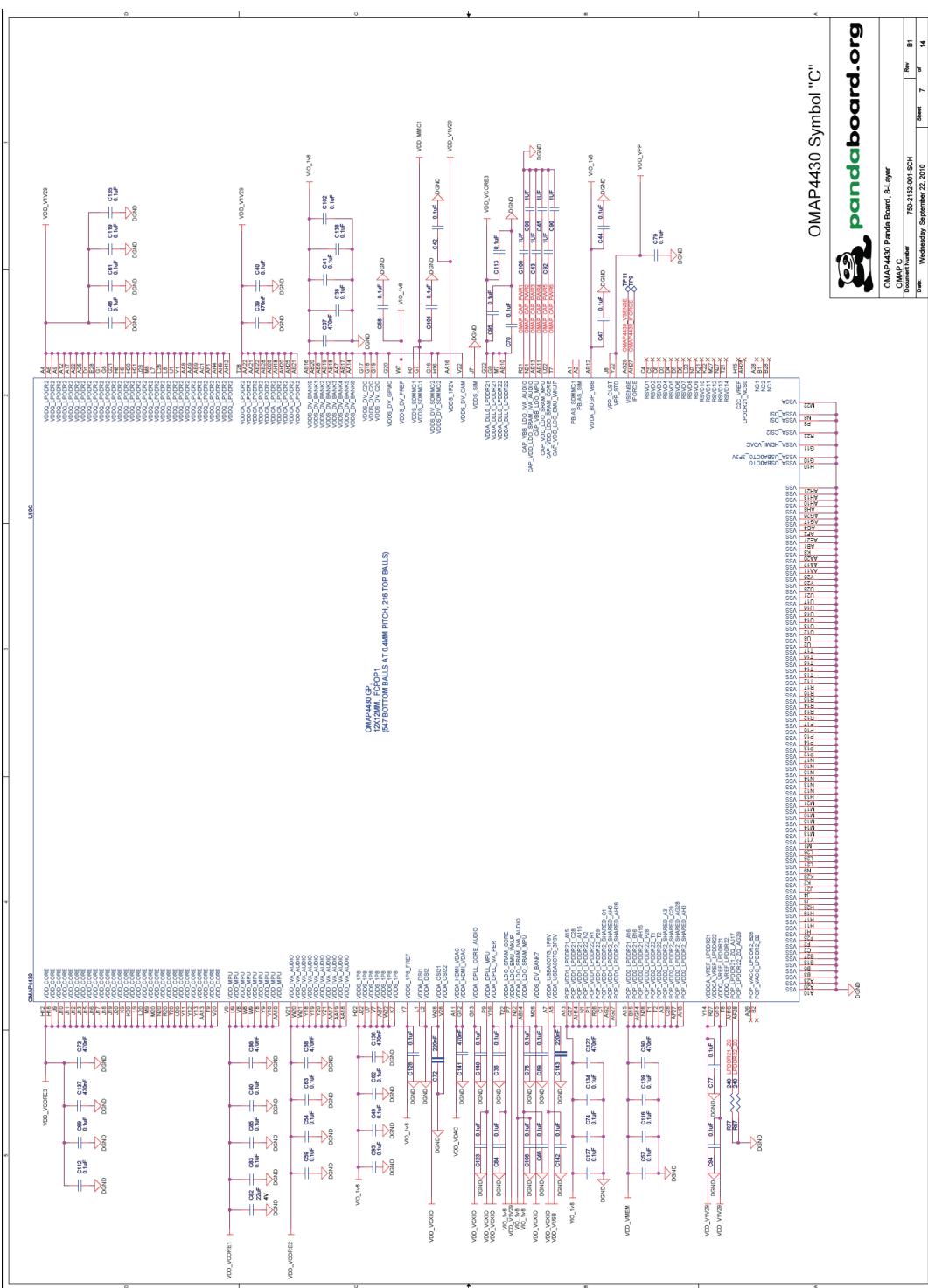


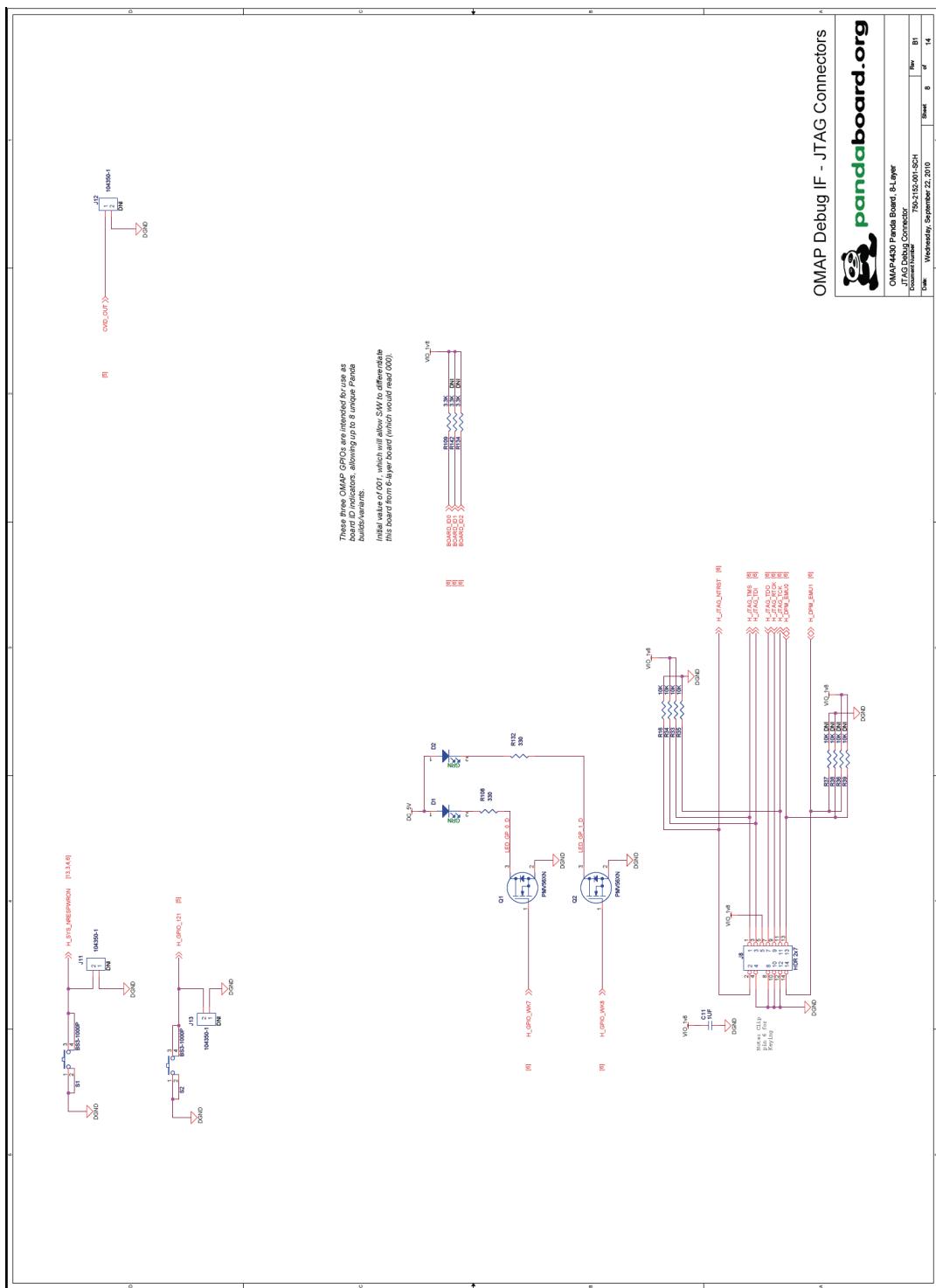
# **OMAP™ 4 PandaBoard System Reference Manual**



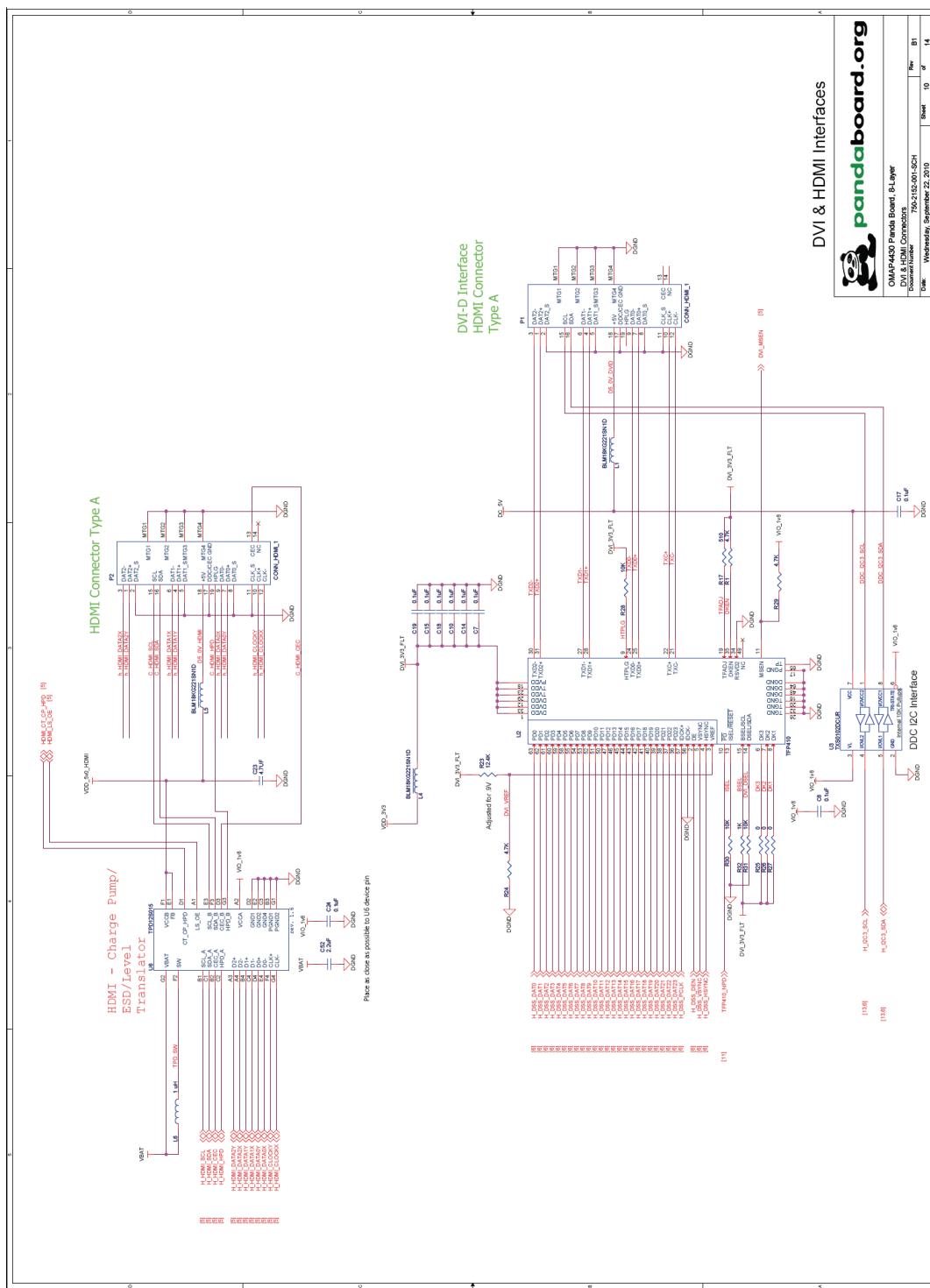


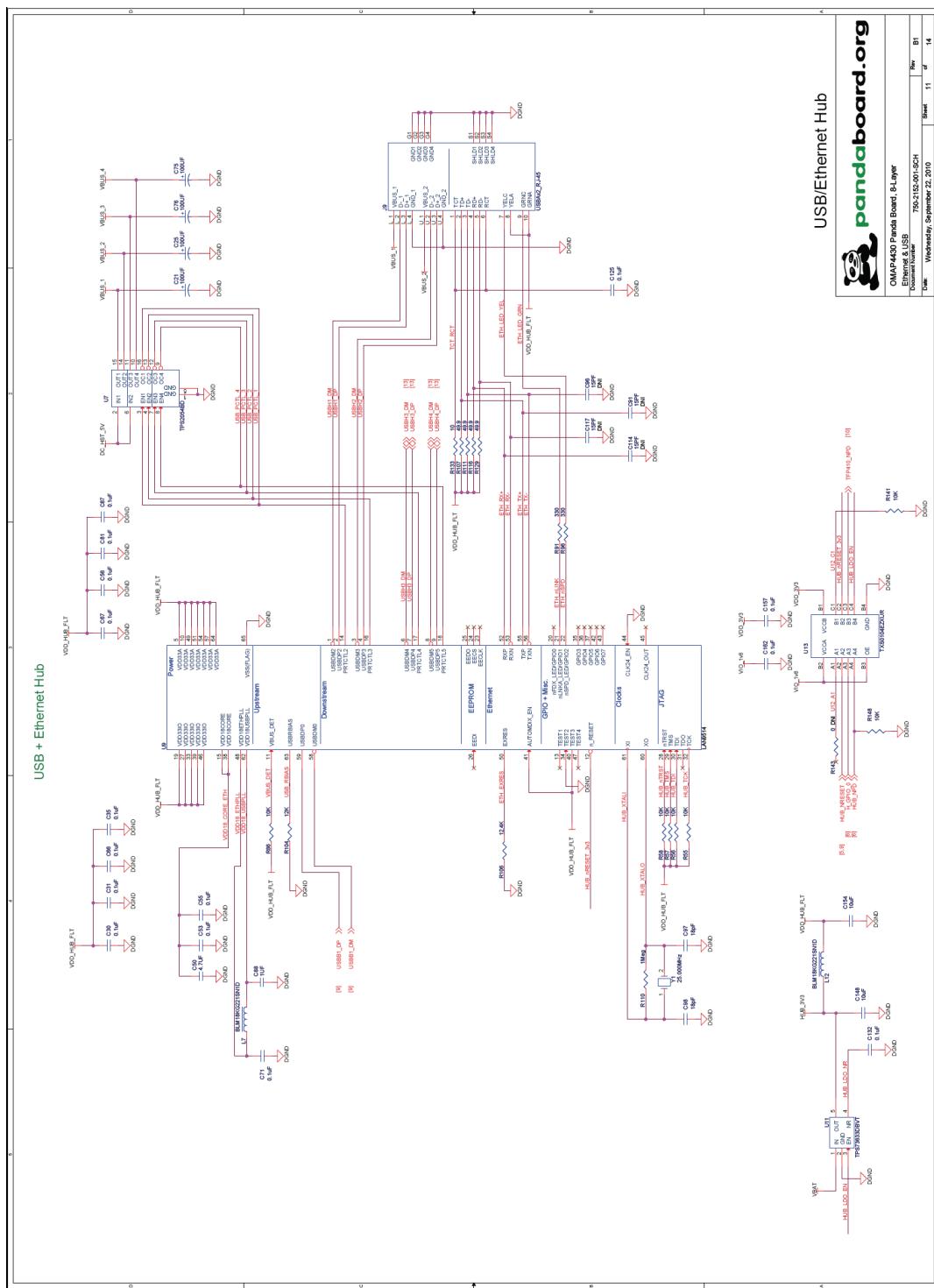
# **OMAP™ 4 PandaBoard System Reference Manual**

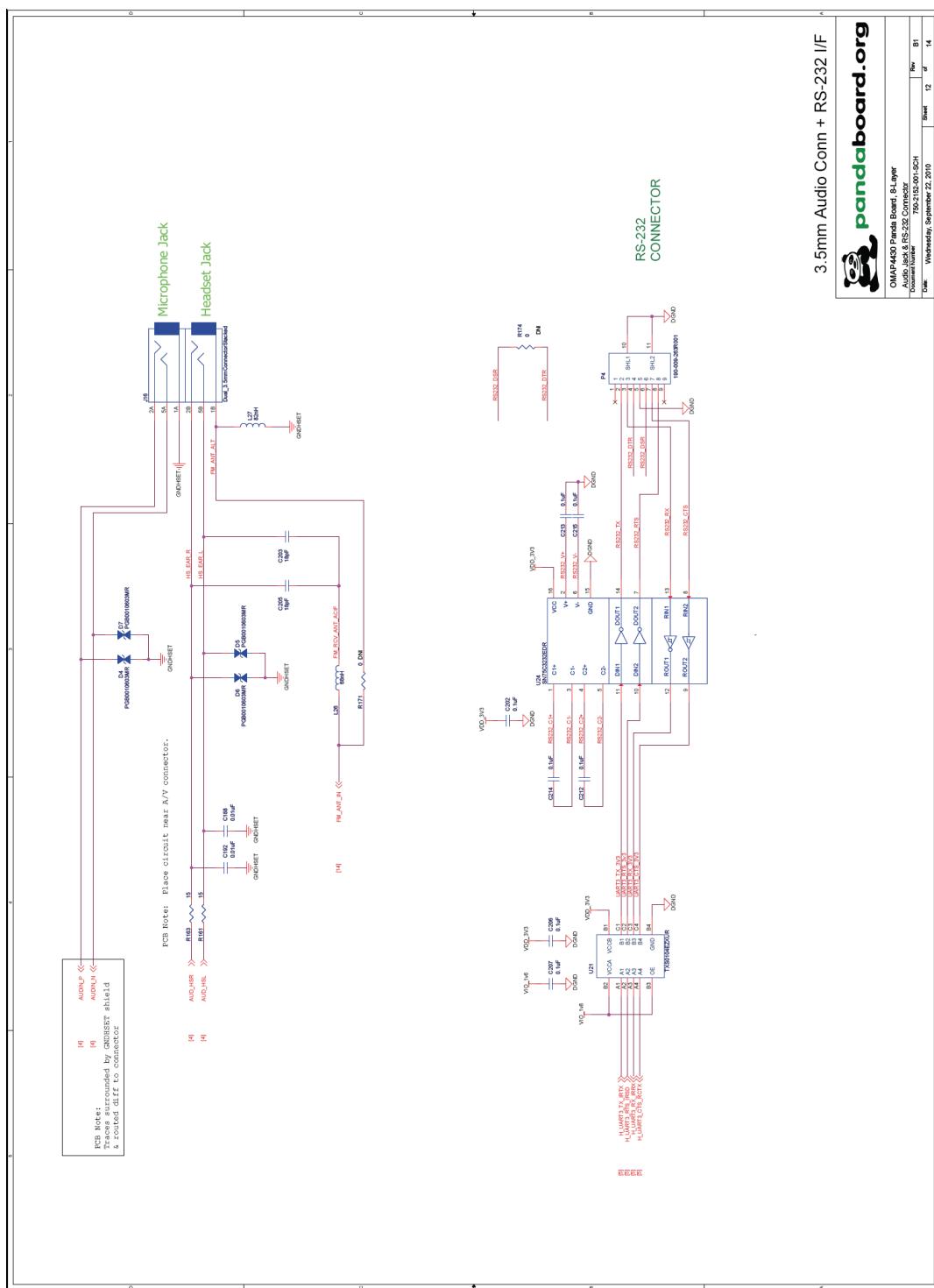


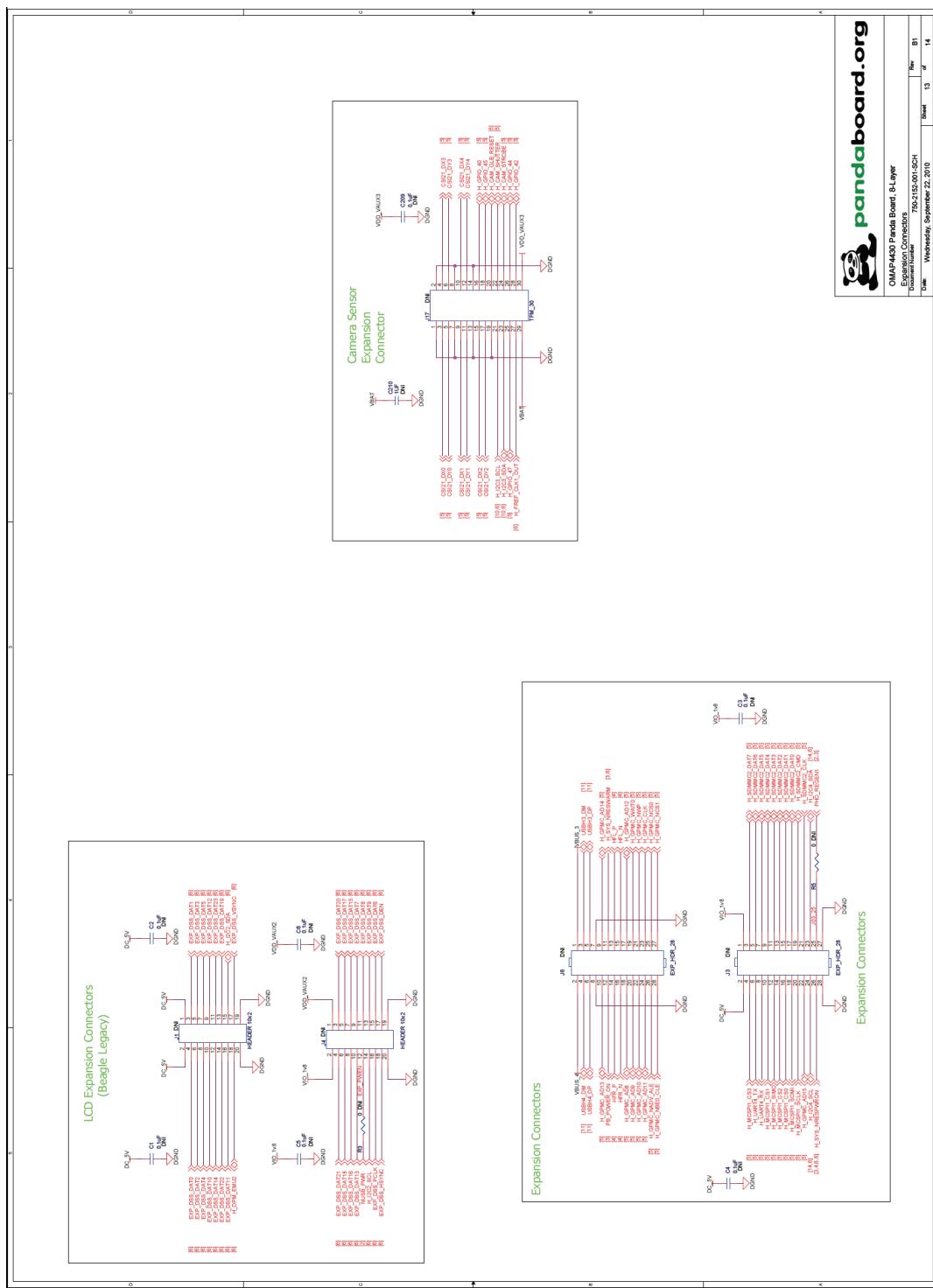


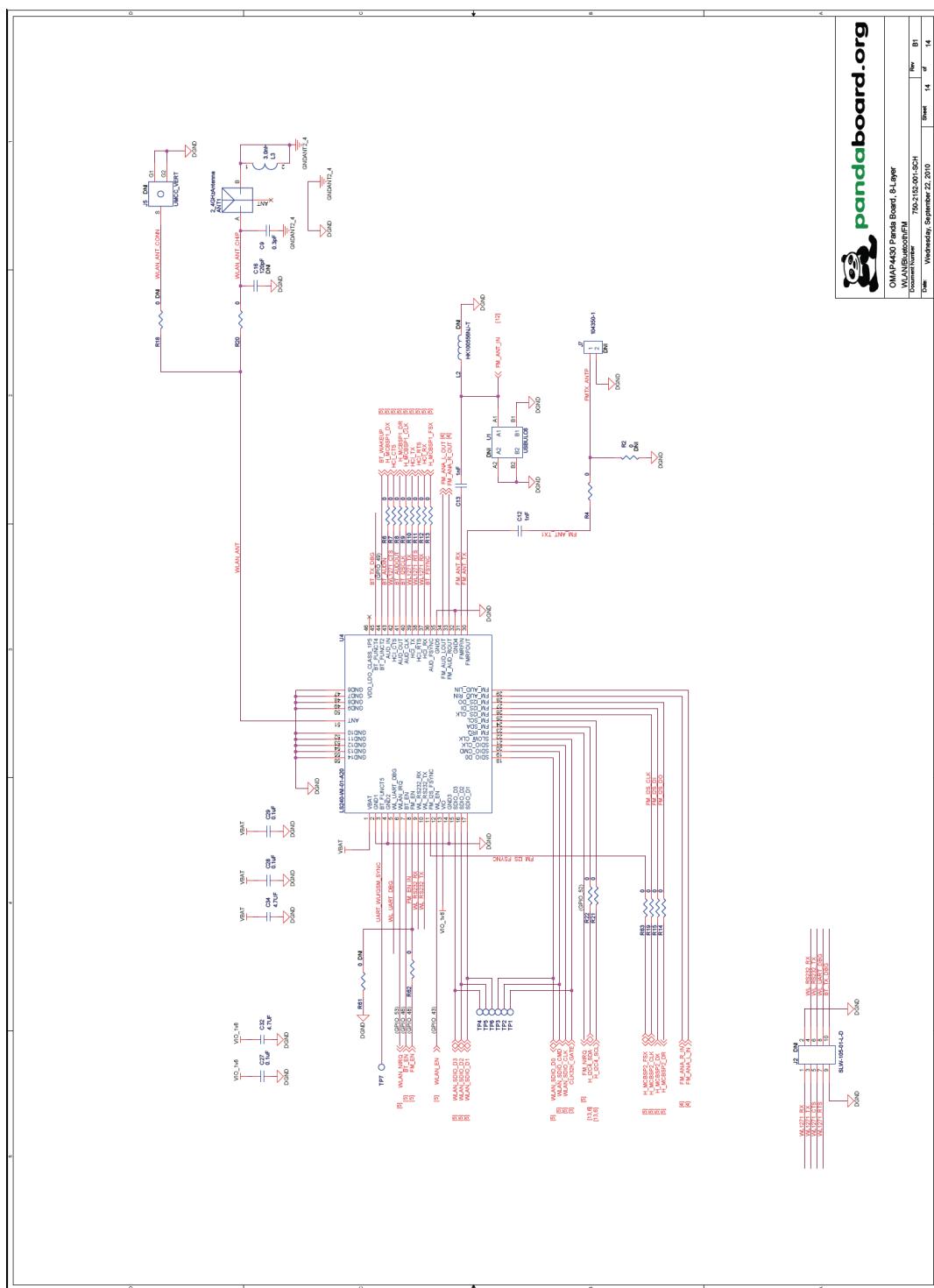














#### 4.5 PandaBoard Bill of Materials

The Bill of Material for the PandaBoard is provided at the following location:

<http://pandaboard.org/content/resources/references>

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#### 4.6 PandaBoard PCB Design Information

The PCB Design information (including the Cadence Allegro 16.2 Board file (.brd file) and PCB Gerber design files) are provided at the following location:

<http://pandaboard.org/content/resources/references>

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