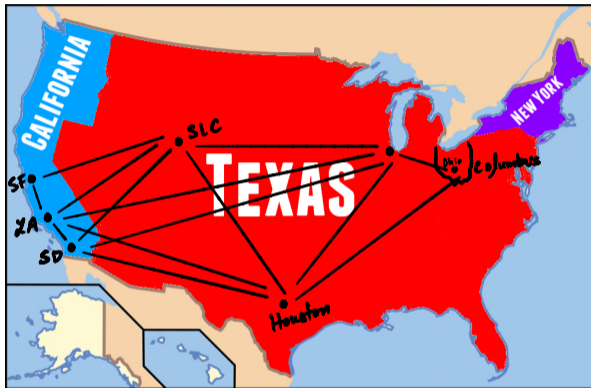


DSC 40B

Theoretical Foundations II

Shortest Paths



Recall

- ▶ The **length** of a path is

$$(\# \text{ of nodes}) - 1$$

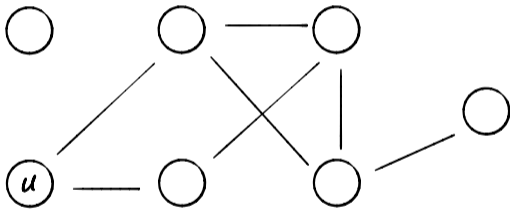
Definitions

- ▶ A **shortest path** between u and v is a path between u and v with smallest possible length.
 - ▶ There may be several, or none at all.
- ▶ The **shortest path distance** is the length of a shortest path.
 - ▶ Convention: ∞ if no path exists.
 - ▶ “the distance between u and v ” means spd .

Today: Shortest Paths

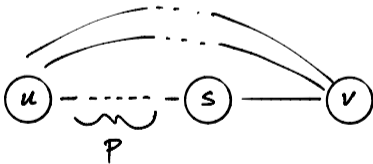
- ▶ **Given:** directed/undirected graph G , source u
- ▶ **Goal:** find shortest path from u to every other node

Example



Key Property

- ▶ A shortest path of length k is composed of:
 - ▶ A **shortest path** of length $k - 1$.
 - ▶ Plus one edge.



Algorithm Idea

- ▶ Find all nodes distance 1 from source.
- ▶ Use these to find all nodes distance 2 from source.
- ▶ Use these to find all nodes distance 3 from source.
- ▶ ...

It turns out...

...this is exactly what BFS does.

DSC 40B

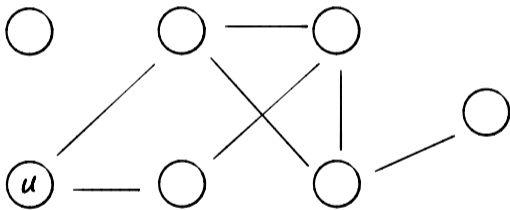
Theoretical Foundations II

BFS for Shortest Paths

Key Property of BFS

- ▶ For any $k \geq 1$ you choose:
- ▶ All nodes distance $k - 1$ from source are added to the queue before any node of distance k .
- ▶ Therefore, nodes are “processed” (popped from queue) in order of distance from source.

Example



Discovering Shortest Paths

- ▶ We “discover” shortest paths when we pop a node from queue and look at its neighbors.
- ▶ But the neighbor's status matters!

Consider This

- ▶ We pop a node s .
- ▶ It has a neighbor v whose status is **undiscovered**.
- ▶ We've discovered a **shortest path** to v through s !

Consider This

- ▶ We pop a node s .
- ▶ It has a neighbor v whose status is **pending** or **visited**.
- ▶ We already have a shortest path to v .

Modifying BFS

- ▶ Use BFS “framework”.
- ▶ Return dictionary of **search predecessors**.
 - ▶ If v is discovered while visiting u , we say that u is the **BFS predecessor** of v .
 - ▶ This encodes the shortest paths.
- ▶ Also return dictionary of shortest path distances.

```

def bfs_shortest_paths(graph, source):
    """Start a BFS at `source`."""
    status = {node: 'undiscovered' for node in graph.nodes}
    distance = {node: float('inf') for node in graph.nodes}
    predecessor = {node: None for node in graph.nodes}

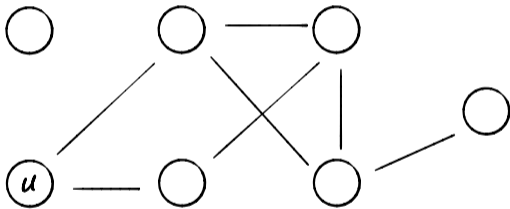
    status[source] = 'pending'
    distance[source] = 0
    pending = deque([source])

    # while there are still pending nodes
    while pending:
        u = pending.popleft()
        for v in graph.neighbors(u):
            # explore edge (u,v)
            if status[v] == 'undiscovered':
                status[v] = 'pending'
                distance[v] = distance[u] + 1
                predecessor[v] = u
                # append to right
                pending.append(v)
        status[u] = 'visited'

    return predecessor, distance

```

Example



DSC 40B

Theoretical Foundations II

BFS Trees

Result of BFS

- ▶ Each node reachable from source has a single BFS predecessor.
 - ▶ Except for the source itself.
- ▶ The result is a **tree** (or forest).

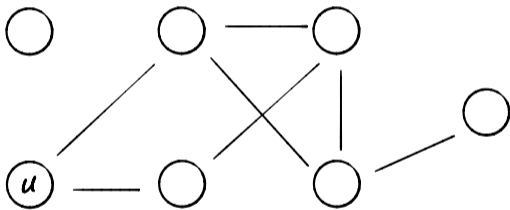
Trees

- ▶ A (free) **tree** is an undirected graph $T = (V, E)$ such that T is connected and $|E| = |V| - 1$.
- ▶ A **forest** is graph in which each connected component is a tree.

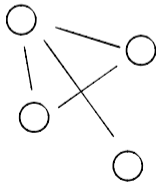
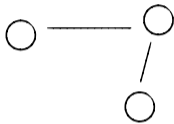
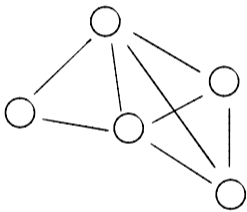
BFS Trees (Forests)

- ▶ If the input is connected, BFS produces a **tree**.
- ▶ If the input is not connected, BFS produces a **forest**.

Example



Example



BFS Trees

- ▶ BFS trees and forests encode shortest path distances.