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## **DSC 40B - Discussion 08**

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**Problem 1.**

Two containers  $A$  and  $B$  have capacities of 3 liters and 5 liters, respectively. Describe how you can measure exactly one liter of water using only these two containers. You may 1) fill each container to the top using a faucet; 2) completely empty either container into a drain; and 3) pour one container into the other until it is empty or the other container is full. Both containers are empty to start.

### Problem 2.

What is the result of updating the edge  $(u,v)$  when the  $\text{est}[u]$ ,  $\text{est}[v]$  and  $\text{weight}(u,v)$  are given as follows?

Figure 1: "Full" DFS

```
def update(u, v, weights, est, predecessor):
    if est[v] > est[u] + weights(u,v):
        est[v]=est[u]+weights(u,v)
        predecessor[v]=u
    return True
else:
    return False
```

- a)  $\text{est}[u] = 7$ ,  $\text{est}[v] = 11$ ,  $\text{weight}(u,v) = 3$

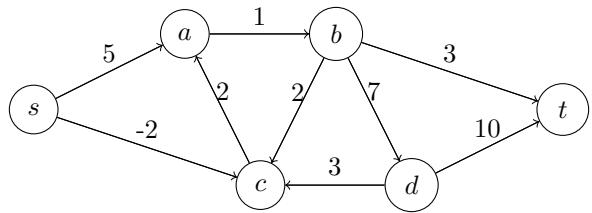
- b)  $\text{est}[u] = 15$ ,  $\text{est}[v] = 12$ ,  $\text{weight}(u,v) = -3$

- c)  $\text{est}[u] = 12$ ,  $\text{est}[v] = 14$ ,  $\text{weight}(u,v) = 3$

### Problem 3.

Run Bellman-Ford on the following graph using node  $s$  as the source. Below each node  $u$ , write the shortest path length from  $s$  to  $u$ . Mark the predecessor of  $u$  by highlighting it or making a bold arrow.

```
def bellman_ford(graph, weights, source):
    est={node:float('inf') for node in graph.nodes}
    est[source]=0
    predecessor={node: None for node in graph.nodes}
    for i in range(len(graph.nodes)-1):
        for(u, v) in graph.edges:
            update(u, v, weights, est, predecessor)
    return est, predecessor
```



**Problem 4.**

State TRUE or FALSE for the following statements:

- a) If  $(s, v_1, v_2, v_3, v_4)$  is a shortest path from  $s$  to  $v_4$  in a weighted graph, then  $(s, v_1, v_2, v_3)$  is a shortest path from  $s$  to  $v_3$

- b) Let  $P$  be a shortest path from some vertex  $s$  to some other vertex  $t$  in a directed graph. If the weight of each edge in the graph is increased by one,  $P$  will still be a shortest path from  $s$  to  $t$ .

- c) Suppose the update function is modified such the  $\text{est}[v]$  is updated when  $\text{est}[v] \geq \text{est}[u] + \text{weight}(u,v)$  instead of strictly greater than. The  $\text{est}$  values of all nodes at the end of the algorithm would still give the shortest distance from the source.

- d) Suppose the update function is modified such the  $\text{est}[v]$  is updated when  $\text{est}[v] \geq \text{est}[u] + \text{weight}(u,v)$  instead of strictly greater than. We can still find the shortest path from the source to any node using the predecessors using the new algorithm.