

# DSC40B: Theoretical Foundations of Data Science II

## Lecture 8: *Binary search tree*

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# Set operations

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- ▶ Imagine you are maintaining a database indexed by some keys (real values), and you hope to support the following operations:

First approach: sort the array of keys

- ▶ Search
- ▶ Maximum
- ▶ Minimum
- ▶ Successor
- ▶ Predecessor

$\Theta(\lg n)$

$\Theta(1)$

$\Theta(1)$

$\Theta(1)$

$\Theta(1)$

- ▶ Insert
- ▶ Delete
- ▶ Extract-Max
- ▶ Increase-key

Can we use a linked list instead?

$\Theta(n)$

How to have a good data structure so we can support all these operations efficiently?

# Today

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- ▶ Binary search tree
  - ▶ support all the operations from previous slide
    - ▶ in time proportional to height of tree
- ▶ (Review): how to implement key operations, and time complexity
  - ▶ search, insert (and delete)
- ▶ Extension to **balanced** binary search tree
- ▶ *Select* query: **augmenting** data structure
  - ▶ median, order statistics



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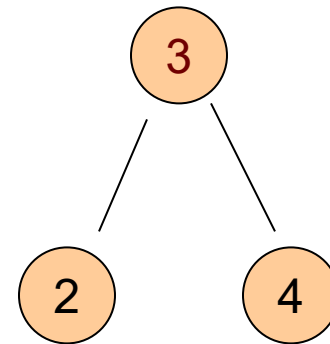
What is binary search tree?



# Binary tree

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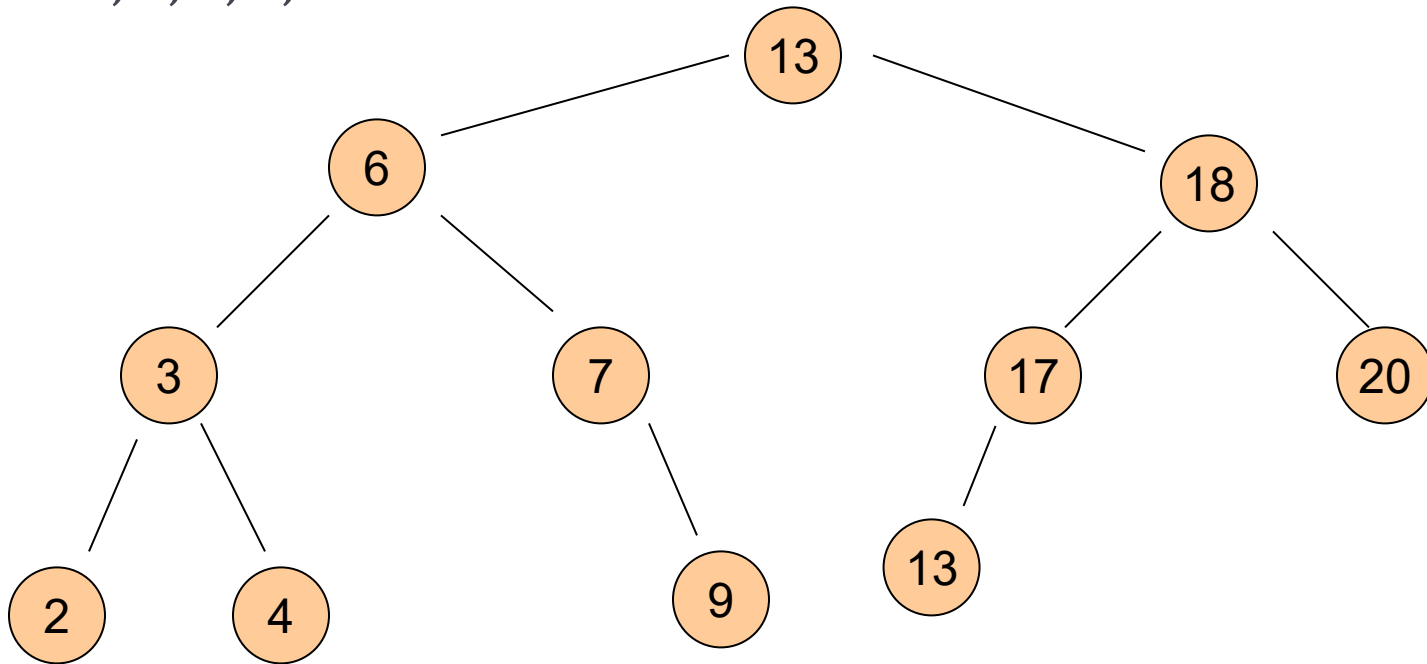
- ▶ A binary tree is a rooted tree
  - ▶ where each node has at most 2 children
- ▶ Represented by a linked data structure
- ▶ Each node contains at least fields:
  - ▶ *Key*
  - ▶ *Left*
  - ▶ *Right*
  - ▶ *Parent*



# Example

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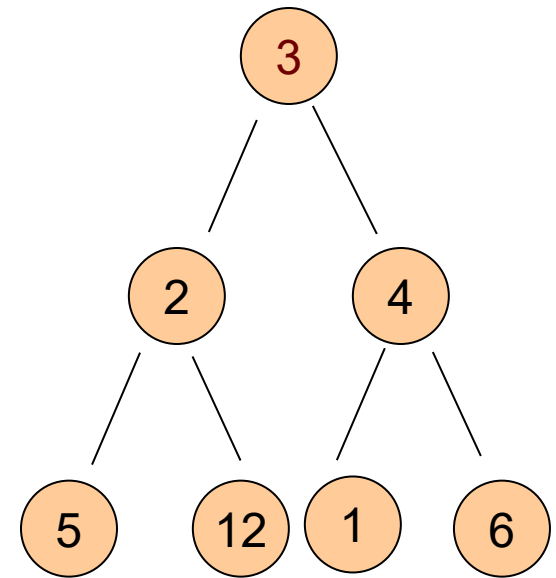
- ▶ From root, following left pointers, we will visit
  - ▶ 13, 6, 3, 2, *Nil*



# Binary tree

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- ▶ A binary tree is a rooted tree where
    - ▶ each node has at most 2 children
  - ▶ A node is the root of the tree
    - ▶ if its parent is Nil
  - ▶ A node is a leaf
    - ▶ if both children are Nil
  - ▶ Left sub-tree, right sub-tree
- 
- ▶ A **complete binary tree**
    - ▶ is a binary tree where each node has two children other than leaves



# Binary search tree (BST)

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- ▶ **Binary-search-tree property**

- ▶ For any node  $x \in T$ ,

- $x.Key \geq (x.Left).Key$  and  $x.Key \leq (x.Right).Key$

- ▶ A binary tree  $T$  is a **binary search tree (BST)** if

- ▶ it satisfies the binary search tree property

## Fact

Given a binary search tree  $T$ , for any node  $x \in T$ , we have

$x.Key \geq y.Key$  if  $y$  is in the left subtree of  $x$ ; and

$x.Key \leq y.Key$  if  $y$  is in the right subtree of  $x$

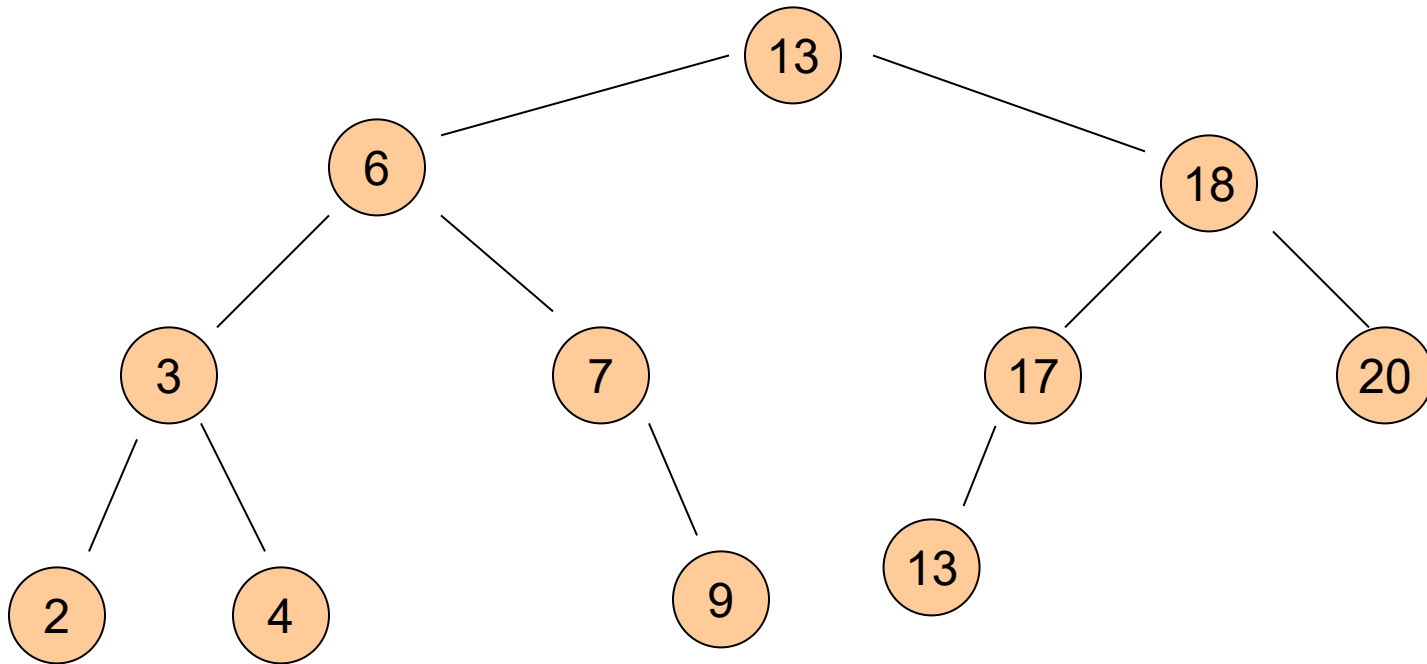




# Example

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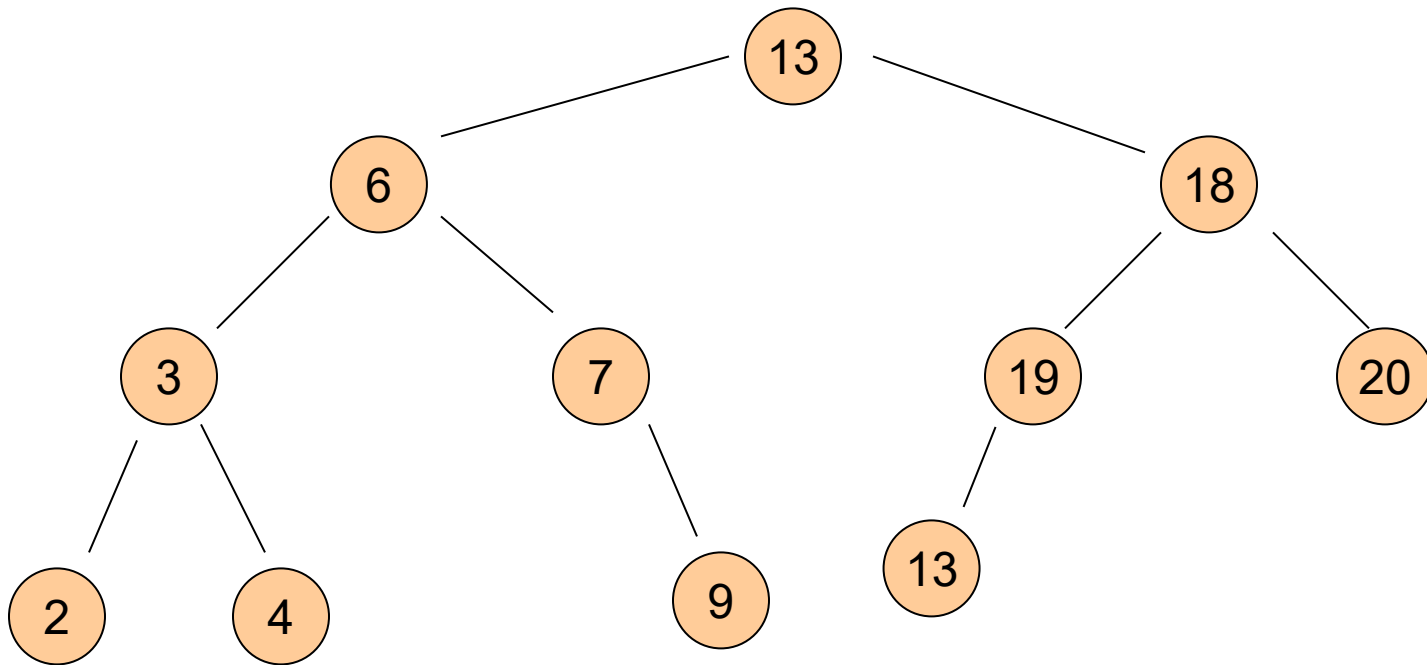
## ► A valid BST



# Example

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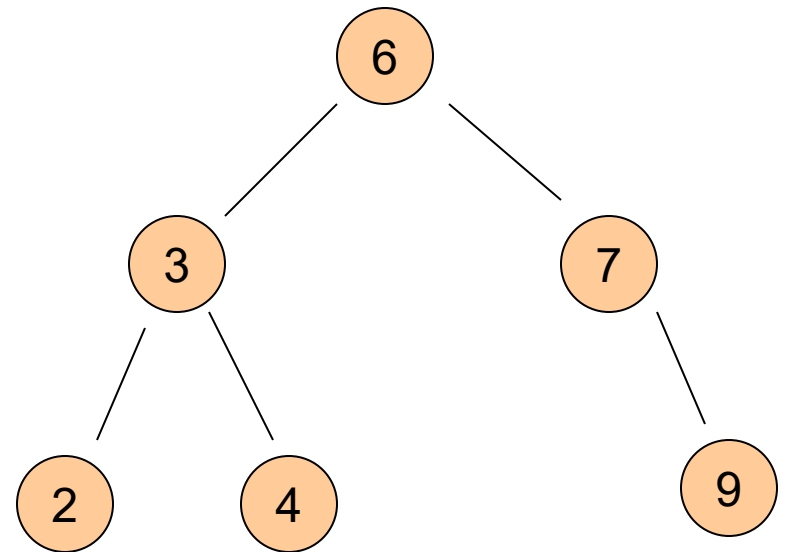
► ?



# Properties

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- ▶ **Given the same set of elements**
  - ▶ there are many possible BSTs over them
- ▶ **Minimum?**
  - ▶ Does it have to be a leaf?



# Properties

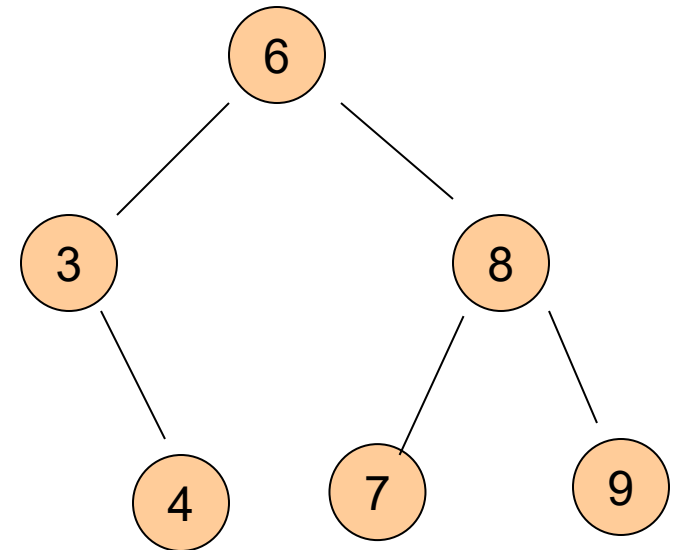
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- ▶ Given the same set of elements
  - ▶ there are many possible BSTs over them

- ▶ Minimum?
  - ▶ Does it have to be a leaf?

- ▶ Maximum?

- ▶ Given  $n$  nodes,
  - ▶ Tallest possible BST tree has height  $h = \underline{\quad n \quad}$
  - ▶ Shortest possible BST tree has height  $h = \underline{\log_2 n} = \Theta(\lg n)$



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# Operations in BST



# Search operation

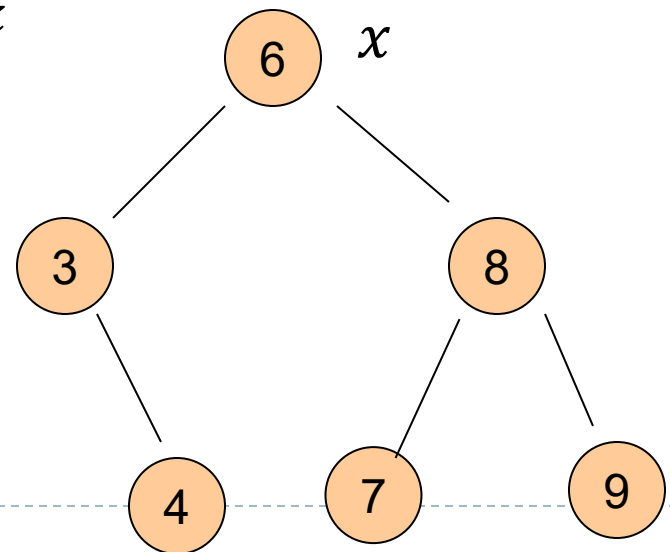
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- ▶ A BST  $T$  with  $n$  nodes can be viewed as a way to store  $n$  keys in a smart way, so that queries among these keys become easy.
- ▶  $\text{Tree-search}(x, k)$ 
  - ▶ Input: given a tree node  $x$  and a query key  $k$
  - ▶ Output: search whether  $k$  is in the tree rooted at  $x$ 
    - ▶ if it is in, return a node  $y$  s.t.  $y.\text{key} = k$
    - ▶ otherwise, returns  $NIL$

$\text{Tree-search}(x, 8)$

$\text{Tree-search}(x, 4)$

$\text{Tree-search}(x, 5)$



# Tree-search algorithm, recursive version

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Tree-search (  $x$ ,  $k$  )

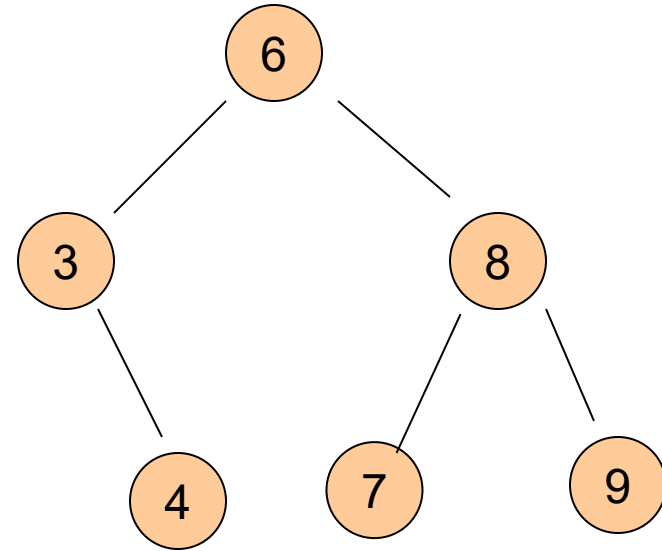
if  $x = \text{Nil}$  or  $k = x.\text{key}$

then return  $x$

if  $k < x.\text{key}$

then return Tree-search(  $x.\text{left}$ ,  $k$  )

else return Tree-search(  $x.\text{right}$ ,  $k$  )



- ▶ Given an input tree  $T$  and a key  $k$ 
  - ▶ we will start by calling Tree-search( $T.\text{root}$ ,  $k$ )



# Tree-search algorithm, recursive version

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Tree-search (  $x$ ,  $k$  )

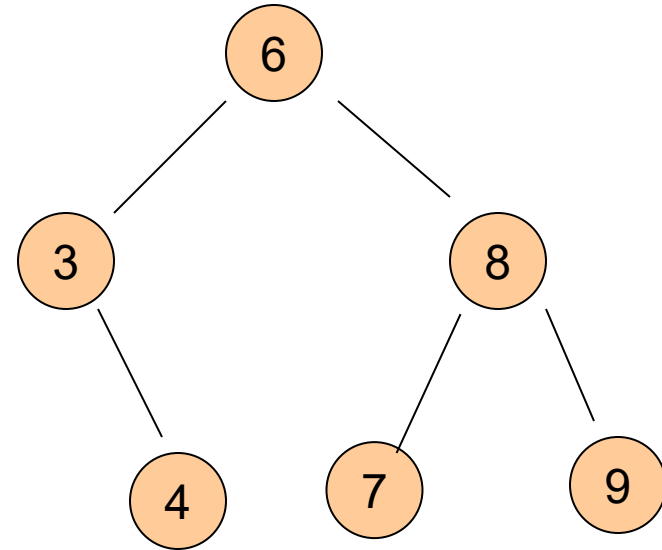
if  $x = \text{Nil}$  or  $k = x.\text{key}$

then return  $x$

if  $k < x.\text{key}$

then return Tree-search(  $x.\text{left}$ ,  $k$  )

else return Tree-search(  $x.\text{right}$ ,  $k$  )



## ► Time complexity analysis

- let  $T(n)$  denote the worst case time complexity of procedure Tree-search() on any tree of  $n$  nodes





# Tree-search algorithm, recursive version

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Tree-search (  $x$ ,  $k$  )

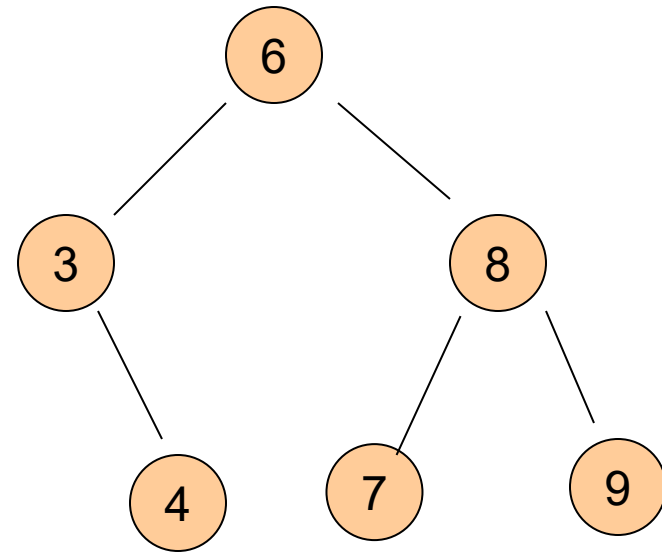
if  $x = \text{Nil}$  or  $k = x.\text{key}$

then return  $x$

if  $k < x.\text{key}$

then return Tree-search(  $x.\text{left}$ ,  $k$  )

else return Tree-search(  $x.\text{right}$ ,  $k$  )



## ► Time complexity analysis

- other than recursive call,  $\Theta(1)$  within each Tree-search call
- thus,  $T(n)$  is proportional to the number of nodes  $x$  we will call Tree-search on
- $T(n) = \Theta(\text{tree-height}) = O(n)$



# Tree-search: iterative version

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```
procedure IterativeTreeSearch( $x, K$ )  
1 while ( $x = \text{NIL}$ ) and ( $K \neq x.\text{key}$ ) do  
2   |   if ( $K \leq x.\text{key}$ ) then  
3     |    $x \leftarrow x.\text{left};$   
4   |   else  
5     |    $x \leftarrow x.\text{right};$   
6   |   end  
7 end  
8 return ( $x$ );
```

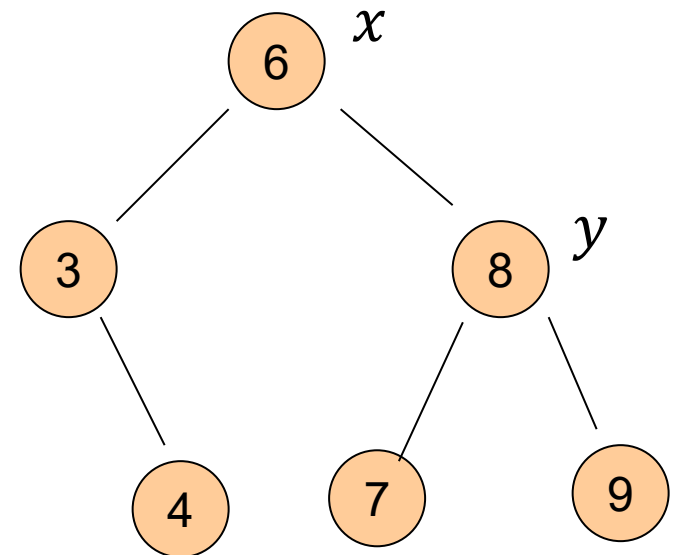


# Minimum / Maximum

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## ▶ Tree-minimum( $x$ )

- ▶ Input: a node  $x$  of a BST  $T$
- ▶ Output: return the node containing minimum key in the subtree rooted at  $x$



# Minimum / Maximum

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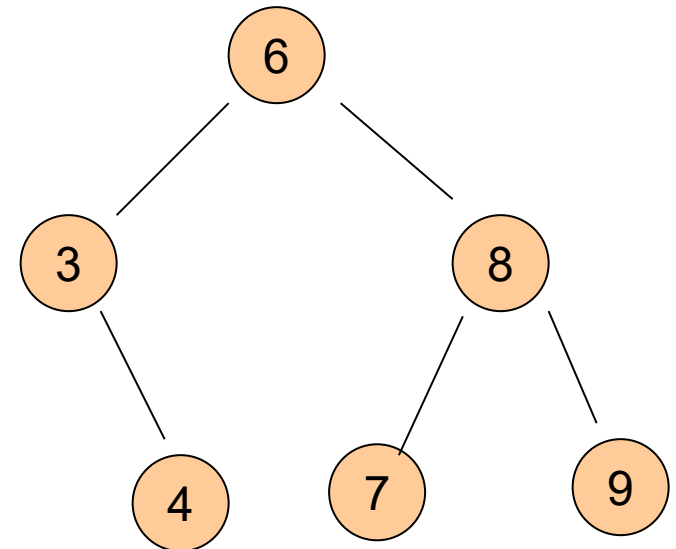
## ▶ Tree-minimum( $x$ )

- ▶ Input: a node  $x$  of a BST  $T$
- ▶ Output: return the node containing a minimum key in the subtree rooted at  $x$

```
Tree-minimum( $x$ )  
    while (  $x.\text{left} \neq \text{Nil}$  )  
        do  $x = x.\text{left};$   
    return  $x$ ;
```

## ▶ Time complexity

- ▶  $T(n) = \Theta(h)$  where  $h$  is height of input tree



# Minimum / Maximum

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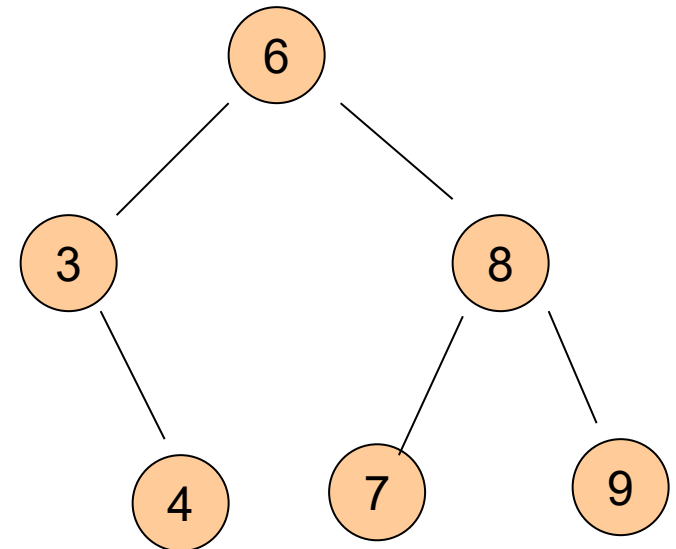
## ▶ Tree-maximum( $x$ )

- ▶ Input: a node  $x$  of a BST  $T$
- ▶ Output: return the node containing a maximum key in the subtree rooted at  $x$

```
Tree-maximum( $x$ )  
    while (  $x.right \neq \text{Nil}$  )  
        do  $x = x.right$ ;  
    return  $x$ ;
```

## ▶ Time complexity

- ▶  $T(n) = \Theta(h)$  where  $h$  is height of input tree



# Tree-insert

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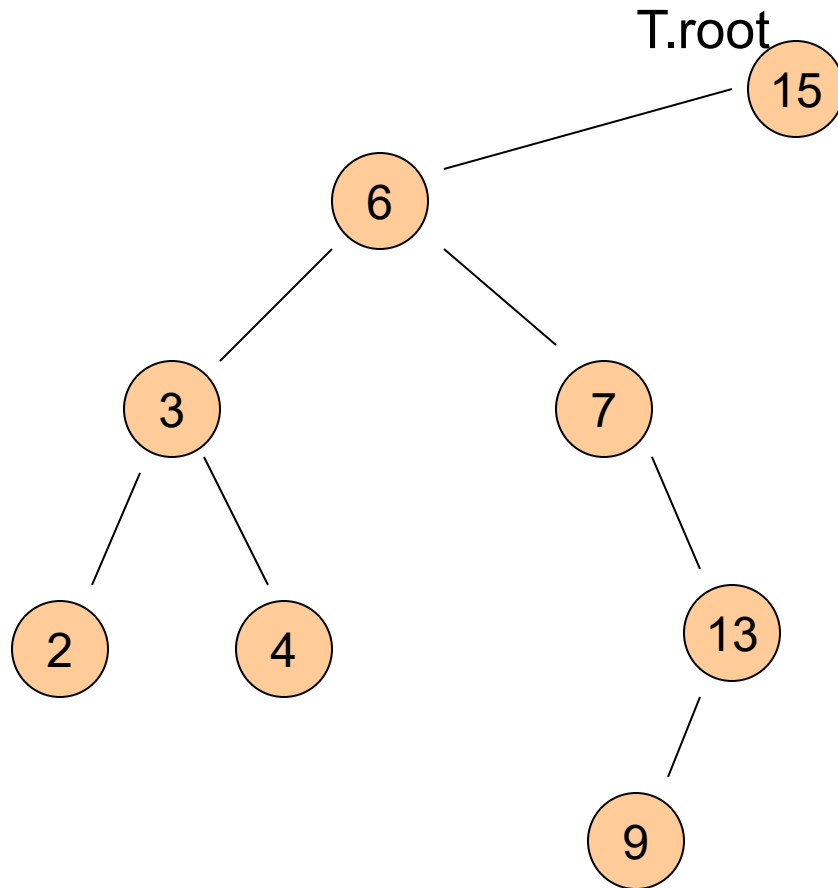
- ▶ **Tree-insert( $x, k$ )**

- ▶ Input: a BST tree node  $x$  and a key  $k$
- ▶ Output: insert  $k$  to the tree rooted at  $x$  such that the resulting tree is still a binary search tree



# Examples

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Tree-Insert(T.root, 8)

Tree-Insert(T.root, 6.5)

Use tree-search !



# Tree-insert

## Tree-insert( $T, k$ )

$y = \text{Nil}; x = T.\text{root}$

$z.\text{key} = k; z.\text{left} = \text{Nil}; z.\text{right} = \text{Nil}$

while ( $x \neq \text{Nil}$ ) do

$y = x$

    if ( $z.\text{key} < x.\text{key}$ )

        then  $x = x.\text{left}$

        else  $x = x.\text{right}$

$z.\text{parent} = y$

if ( $y = \text{Nil}$ ) then  $T.\text{root} = z$

else if ( $z.\text{key} < y.\text{key}$ )

    then  $y.\text{left} = z$

    else  $y.\text{right} = z$

- $z$  is the new node to be inserted
- Locate potential parent  $y$  of  $z$ .

- Set up  $z$  as appropriate child of  $y$



# Tree-insert

Tree-insert( $T, k$ )

$y = \text{Nil}; x = T.\text{root}$

$z.\text{key} = k; z.\text{left} = \text{Nil}; z.\text{right} = \text{Nil}$

while ( $x \neq \text{Nil}$ ) do

$y = x$

    if ( $z.\text{key} < x.\text{key}$ )

        then  $x = x.\text{left}$

        else  $x = x.\text{right}$

$z.\text{parent} = y$

if ( $y = \text{Nil}$ ) then  $T.\text{root} = z$

else if ( $z.\text{key} < y.\text{key}$ )

    then  $y.\text{left} = z$

    else  $y.\text{right} = z$

► Time complexity

►  $T(n) = \Theta(h)$ , where  $h$  is height of input tree

# Summary

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- ▶ Suppose  $n$  input keys are already stored in a BST of height  $h$

	Time complexity
▶ Search	$\Theta(h)$
▶ Maximum	$\Theta(h)$
▶ Minimum	$\Theta(h)$
▶ Successor	$\Theta(h)$
▶ Predecessor	$\Theta(h)$
▶ Insert	$\Theta(h)$
▶ Delete	$\Theta(h)$
▶ Extract-Max	$\Theta(h)$
▶ Increase-key	$\Theta(h)$

- However, performance depending on height!
- Height  $h = O(n)$  and  $h = \Omega(\lg n)$

- To have good performance, we want to keep the tree height low!



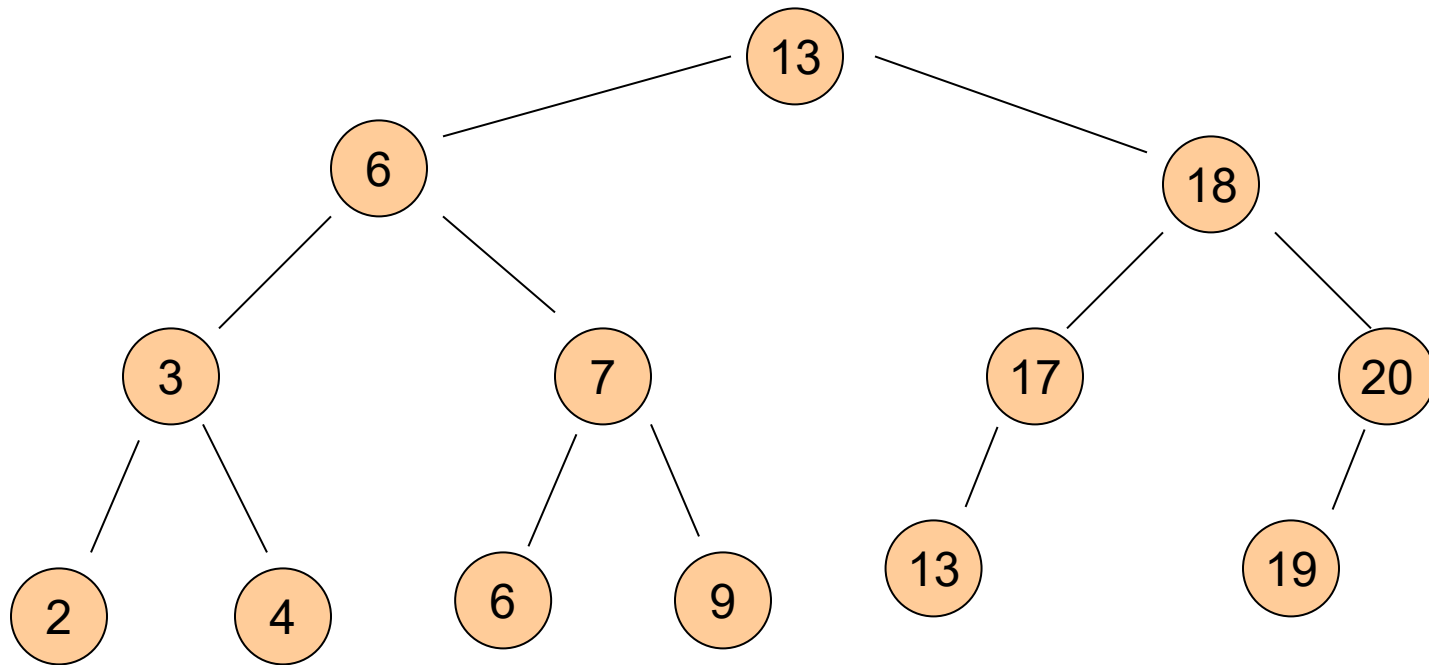
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# Balanced binary search tree



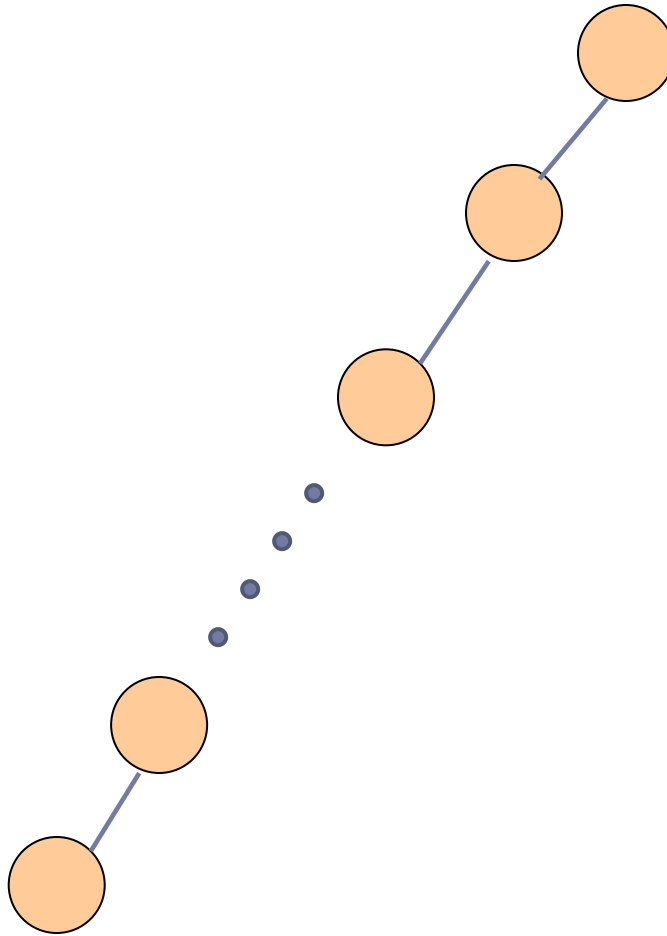
# Good tree

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# Bad Tree

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# Balanced binary search tree

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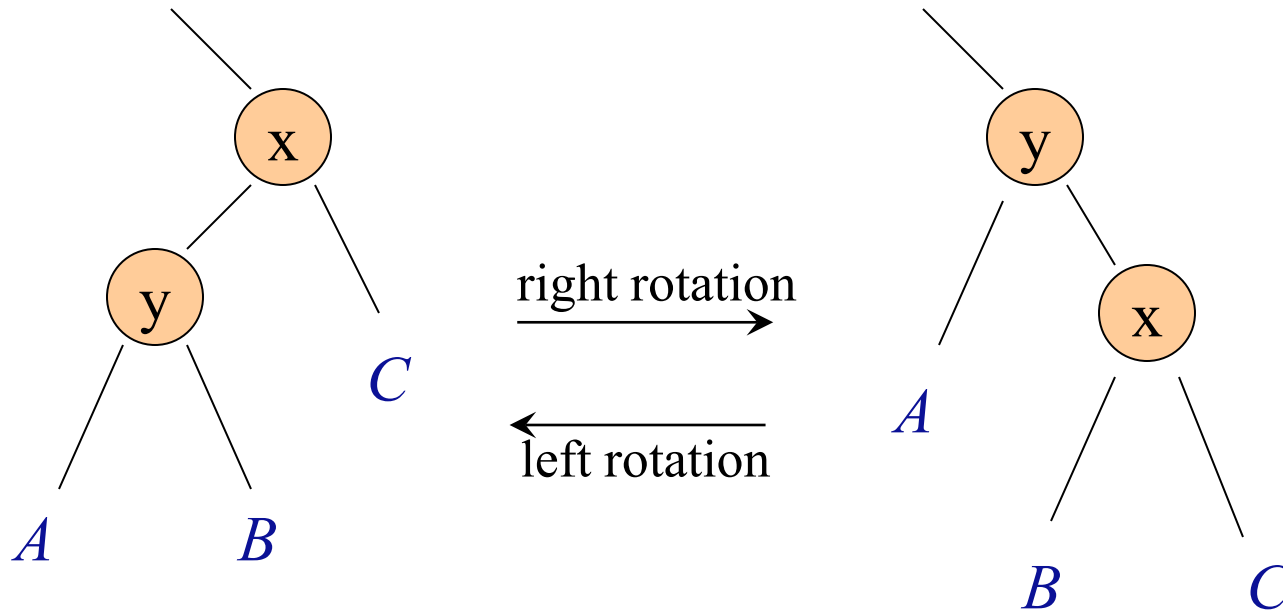
- ▶ It turns out that there are ways to add extra conditions to binary search trees, so that their height is  $\Theta(\lg n)$ 
  - ▶ E.g, red-black tree, AVL tree, etc
- ▶ Once such a tree is created,
  - ▶ it can support search, minimum, maximum etc in  $\Theta(h) = \Theta(\lg n)$  time using the same algorithms described before
  - ▶ the extra work comes at handling dynamic operations: insertion, deletion, and so on. Re-balancing is needed
  - ▶ however, for standard balanced BSTs, all these operations can be handled in  $\Theta(\lg n)$  time.



# Rotation operation

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- ▶ Left rotation or Right rotation to keep tree height low



# With balanced BST

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- ▶ Suppose  $n$  input keys are already stored in a balanced BST

Time complexity	
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▶ Search	$\Theta(\lg n)$
▶ Maximum	$\Theta(\lg n)$
▶ Minimum	$\Theta(\lg n)$
▶ Successor	$\Theta(\lg n)$
▶ Predecessor	$\Theta(\lg n)$
▶ Insert	$\Theta(\lg n)$
▶ Delete	$\Theta(\lg n)$
▶ Extract-Max	$\Theta(\lg n)$
▶ Increase-key	$\Theta(\lg n)$

- |  |
|--|
| <ul style="list-style-type: none"><li>• Height of tree will be <math>\Theta(\lg n)</math>, where <math>n</math> is number of nodes in the tree</li></ul> |
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*Select* queries  
augmenting data structure



- 
- ▶ What if we also want to perform Select operation
  - ▶ Select (  $T, k$  ):
    - ▶ Given a list of records whose keys are stored in  $T$ , return the node whose key has rank  $k$ .
  - ▶ We can do linear search to find it. But can we do better?
  - ▶ Goal:
    - ▶ **Augment** the binary search tree data structure so as to support Select (  $T, k$  ) efficiently
- 



# In particular,

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- ▶ **Select (  $T, k$  )**
- ▶ **Goal:**
  - ▶ Augment the binary search tree data structure so as to support Select (  $T, k$  ) efficiently
- ▶ **Ordinary binary search tree**
  - ▶  $O(h)$  time for Select( $T, k$ )
- ▶ **Using balanced search tree)**
  - ▶  $O(\lg n)$  time for Select( $T, k$ )



# How do we augment a BST $T$ ?

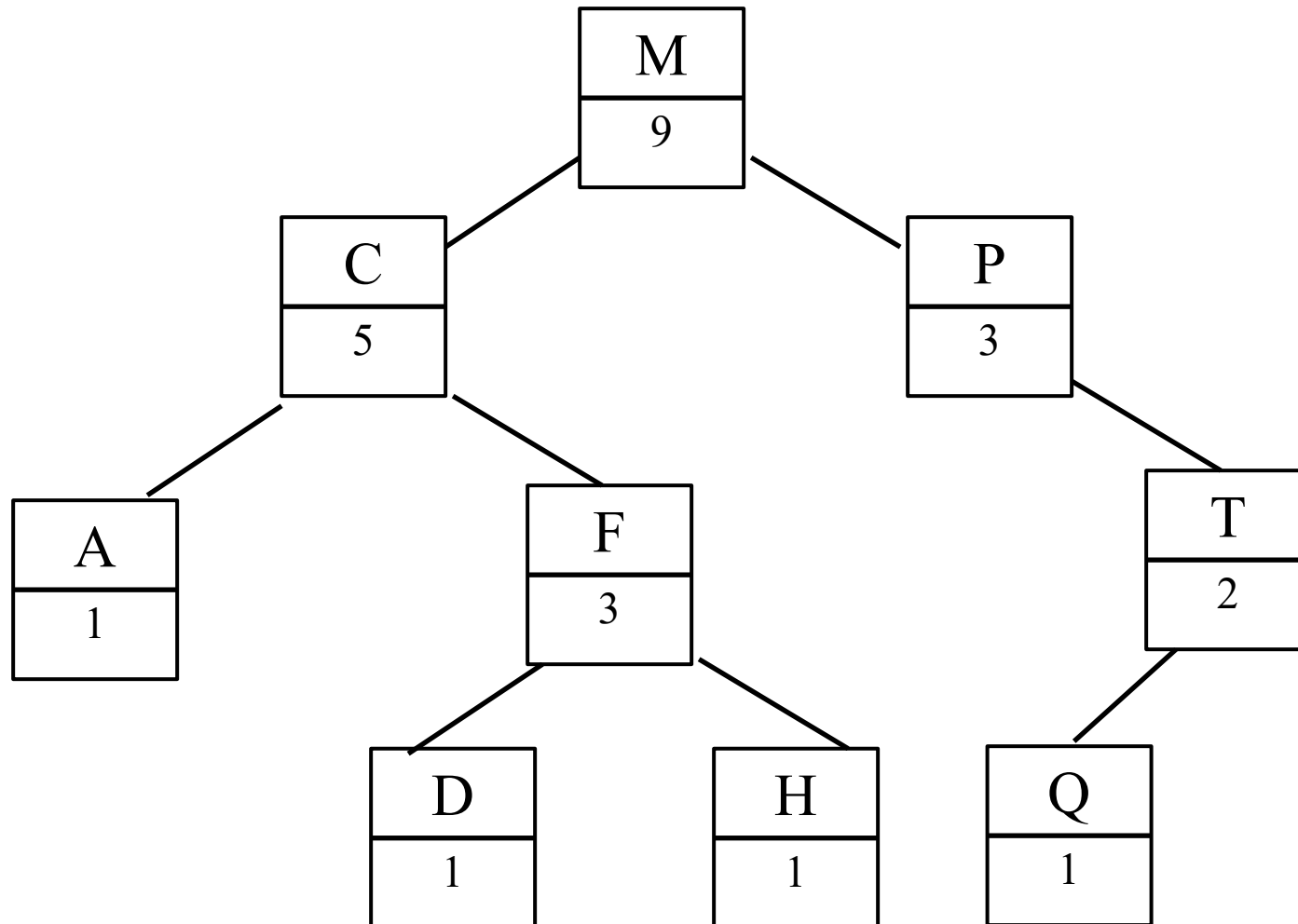
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- ▶ At each node  $x$  of the tree  $T$ 
  - ▶ store  $x.size = \#$  nodes in the subtree rooted at  $x$ 
    - ▶ Include  $x$  itself
    - ▶ If a node (leaf) is NIL, its size is 0.
- ▶ Space of an augmented tree:
  - ▶  $\Theta(n)$
- ▶ Basic property:
  - ▶  $x.size = x.left.size + x.right.size + 1$



# An example

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# How to setup size information?

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► procedure *AugmentSize*( *treenode*  $x$  )

  If ( $x \neq NIL$ ) then

$Lsize = \text{AugmentSize}(x.left);$

$Rsize = \text{AugmentSize}(x.right);$

$x.size = Lsize + Rsize + 1;$

    Return(  $x.size$  );

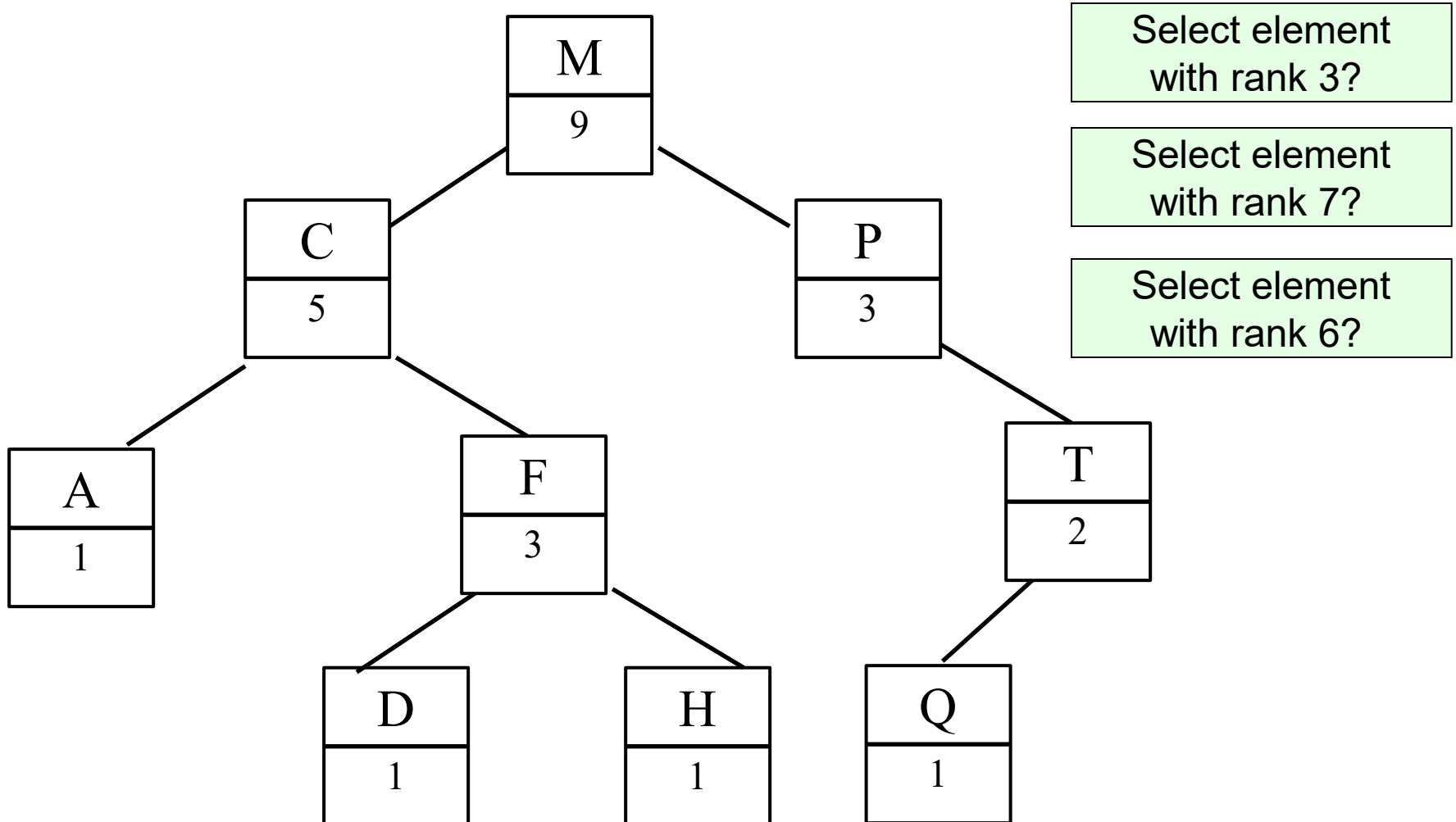
  end

Return (0);

Postorder traversal  
of the tree !



# How to perform select with aug-BST?



- 
- ▶ Let  $T$  be an augmented binary search tree
  - ▶  $BST\text{-}Select(x, k)$ :
    - ▶ Return the  $k$ -th smallest element in the subtree rooted at  $x$
    - ▶  $BST\text{-}Select(T.root, k)$  returns the  $k$ -th smallest elements in the entire tree.





► procedure *BST-Select*( *treenode*  $x$ ,  $k$  )

$\ell = x.\text{left.size} + 1$

    If ( $k == \ell$ ) then

        Return  $x$

    elseif ( $k < \ell$ )

        Return *BST-Select*(  $x.\text{left}$ ,  $k$  )

    else Return *BST-Select*(  $x.\text{right}$ ,  $k - \ell$  )

► Initial call: *BST-Select*( $T.\text{root}$ ,  $k$ )

► Time complexity:

    ►  $T(n) = \Theta(\text{height of tree}) = O(n)$

    ► If  $T$  is balanced, then  $T(n) = \Theta(\lg n)$



# Are we done?

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- ▶ Need to maintain the augmented information under dynamic changes of the tree!
  - ▶ i.e, under insertions / deletions
  - ▶ in this case, just adjusting this size count as we update nodes, or under rotations, and it does not increase asymptotic time complexity of these operations
- ▶ Remark:
  - ▶ Select() in an sorted array can be done in  $\Theta(1)$  time.
  - ▶ However, an array does not support dynamic operations (insert/delete) efficiently. That's augmented BST is a better data structure in this case.



# Summary

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- ▶ Simple example of augmenting data structures
- ▶ In general, the augmented information can be quite complicated
  - ▶ Can be a separate data structure!
- ▶ Need to consider how to maintain such information under dynamic changes



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FIN

