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## CSE 151A - Discussion 09

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### Problem 1.

Given a direction  $\vec{u}$ , calculate the projection of  $\vec{x} = \begin{pmatrix} 3 \\ -1 \\ 2 \end{pmatrix}$  onto  $\vec{u}$  and the angle between  $\vec{x}$  and  $\vec{u}$ .

Note that in class we assumed  $\vec{u}$  to be a unit vector, but that may not necessarily be the case here!

1.  $\vec{u}$  is the  $x_1$  axis

2.  $\vec{u} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

3.  $\vec{u} = \begin{pmatrix} 1.5 \\ -0.5 \\ 1 \end{pmatrix}$

4.  $\vec{u} = \begin{pmatrix} 3 \\ 1 \\ -4 \end{pmatrix}$

**Solution:** From lecture, we have been shown that the projection of  $\vec{x} \in \mathbb{R}^d$  along the direction  $\vec{u} \in \mathbb{R}^d$  is given by  $(\vec{x} \cdot \vec{u})\vec{u}$ , where  $\vec{u}$  is a unit vector.

However, in the above examples,  $\vec{u}$  is not a unit vector. To rectify this discrepancy, we can simply normalize  $\vec{u}$  by dividing each component of  $\vec{u}$  by  $\|\vec{u}\|$ , which will result in a vector of unit length in the same direction as the original  $\vec{u}$ .

This yields the following equation for the projection of  $\vec{x}$  onto any vector  $\vec{u}$ :  $(\vec{x} \cdot \frac{\vec{u}}{\|\vec{u}\|}) \frac{\vec{u}}{\|\vec{u}\|}$

We can rewrite this more clearly as  $(\frac{\vec{x} \cdot \vec{u}}{\|\vec{u}\|^2})\vec{u}$  and use it to solve each projection.

We also saw in class this useful property of dot product:  $\vec{a} \cdot \vec{b} = \|\vec{a}\| \|\vec{b}\| \cos(\theta)$ . We can rearrange this equation to solve for the angle between vectors  $\vec{a}$  and  $\vec{b}$  as  $\theta = \cos^{-1} \left( \frac{\vec{a} \cdot \vec{b}}{\|\vec{a}\| \|\vec{b}\|} \right)$ .

We will now use these two formulas to solve each problem.

We will also need  $\|\vec{x}\| = \sqrt{3^2 + (-1)^2 + 2^2} = \sqrt{14} = 3.74$  for each problem, so we define it here.

1. Here  $\vec{u}$  is the  $x_1$  axis, meaning  $\vec{u} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ . Since we defined this ourselves to be of unit length, we

can use the original projection formula without normalization.

$$(\vec{x} \cdot \vec{u})\vec{u} = (3 \cdot 1 + (-1) \cdot 0 + 2 \cdot 0) \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = 3 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 3 \\ 0 \\ 0 \end{pmatrix}$$

$$\text{Solving for } \theta = \cos^{-1} \left( \frac{\vec{x} \cdot \vec{u}}{\|\vec{x}\| \|\vec{u}\|} \right) = \cos^{-1} \left( \frac{3}{(\sqrt{14})(1)} \right) = 36.7^\circ$$

$$2. \left( \frac{\vec{x} \cdot \vec{u}}{\|\vec{u}\|^2} \right) \vec{u} = \frac{(3 \cdot 1 + (-1) \cdot 1 + 2 \cdot 1)}{(1^2 + 1^2 + 1^2)} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \frac{4}{3} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{4}{3} \\ \frac{4}{3} \\ \frac{4}{3} \end{pmatrix}$$

$$\theta = \cos^{-1} \left( \frac{\vec{x} \cdot \vec{u}}{\|\vec{x}\| \|\vec{u}\|} \right) = \cos^{-1} \left( \frac{4}{(\sqrt{14})\sqrt{3}} \right) = 51.89^\circ$$

$$3. \left( \frac{\vec{x} \cdot \vec{u}}{\|\vec{u}\|^2} \right) \vec{u} = \frac{(3 \cdot (1.5) + (-1) \cdot (-0.5) + 2 \cdot (1))}{(1.5^2 + (-0.5)^2 + 1^2)} \begin{pmatrix} 1.5 \\ -0.5 \\ 1 \end{pmatrix} = \frac{7}{3.5} \begin{pmatrix} 1.5 \\ -0.5 \\ 1 \end{pmatrix} = 2 \begin{pmatrix} 1.5 \\ -0.5 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ -1 \\ 2 \end{pmatrix}$$

$$\theta = \cos^{-1} \left( \frac{\vec{x} \cdot \vec{u}}{\|\vec{x}\| \|\vec{u}\|} \right) = \cos^{-1} \left( \frac{7}{(\sqrt{14})\sqrt{3.5}} \right) = \cos^{-1}(1) = 0^\circ$$

$\vec{u}$  and  $\vec{x}$  are in the same direction, so the angle between them is  $0^\circ$  and the projection of  $\vec{x}$  onto  $\vec{u}$  is just  $\vec{x}$ !

$$4. \left( \frac{\vec{x} \cdot \vec{u}}{\|\vec{u}\|^2} \right) \vec{u} = \frac{(3 \cdot (3) + (-1) \cdot (1) + 2 \cdot (-4))}{(3^2 + 1^2 + (-4)^2)} \begin{pmatrix} 3 \\ 1 \\ -4 \end{pmatrix} = \frac{0}{26} \begin{pmatrix} 3 \\ 1 \\ -4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\theta = \cos^{-1} \left( \frac{\vec{x} \cdot \vec{u}}{\|\vec{x}\| \|\vec{u}\|} \right) = \cos^{-1} \left( \frac{0}{(\sqrt{14})\sqrt{26}} \right) = \cos^{-1}(0) = 90^\circ$$

The dot product between  $\vec{u}$  and  $\vec{x}$  is 0 which tells us that they are orthogonal to one another. This also means that no component of  $\vec{x}$  lies on  $\vec{u}$  and that the projection of  $\vec{x}$  onto  $\vec{u}$  is the zero vector!

### Problem 2.

Given the covariance matrix  $C = \begin{pmatrix} 4 & 1.5 \\ 1.5 & 1 \end{pmatrix}$ , calculate the variance in the direction of  $\vec{u}$  for each of the following settings :  $\vec{u}^{(1)} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ ,  $\vec{u}^{(2)} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ , and  $\vec{u}^{(3)} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ .

If we wanted to map each data point  $\vec{x}^{(i)}$  to a single feature  $z_i = \vec{x}^{(i)} \cdot \vec{u}$ , what choice of  $\vec{u}^{(i)}$  would be best?

**Solution:**  $\vec{u}^{(3)}$

We would like to choose the direction  $\vec{u}$  in which the variance is maximized. As seen in class, this is equivalent to finding the unit vector in the same direction as  $\vec{u}$  that maximizes  $\vec{u}^T C \vec{u}$ .

The first step here is to ensure that each of our candidate direction vectors is of unit length.

$\vec{u}^{(1)}$  and  $\vec{u}^{(2)}$  have length 1, but  $\vec{u}^{(3)}$  must be rewritten as  $\vec{u}^{(3)} = \begin{pmatrix} \frac{2}{\sqrt{5}} \\ \frac{1}{\sqrt{5}} \end{pmatrix}$ .

Calculating the variance for each  $\vec{u}^{(i)}$  yields the following :

$$(\vec{u}^{(1)})^T C \vec{u}^{(1)} = (1, 0) \begin{pmatrix} 4 & 1.5 \\ 1.5 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 4$$

$$(\vec{u}^{(2)})^T C \vec{u}^{(2)} = (0, 1) \begin{pmatrix} 4 & 1.5 \\ 1.5 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 1$$

$$(\vec{u}^{(3)})^T C \vec{u}^{(3)} = \left( \frac{2}{\sqrt{5}}, \frac{1}{\sqrt{5}} \right) \begin{pmatrix} 4 & 1.5 \\ 1.5 & 1 \end{pmatrix} \begin{pmatrix} \frac{2}{\sqrt{5}} \\ \frac{1}{\sqrt{5}} \end{pmatrix} = 4.6$$

The variance for the direction defined by  $\vec{u}^{(3)}$  is the maximum among our three choices, so it should be chosen.

Another noteworthy fact is that the variance calculation with direction  $\vec{u}^{(1)}$  is identical to the top-left entry of  $C$ . This is to be expected because this entry corresponds directly to the variance of our data in the  $x_1$  direction. The same is true for  $x_2$ .

If we were not bounded to just these three options, the best direction is that of the first eigenvector of  $C$ , which in this case is the direction  $\begin{pmatrix} 1 + \sqrt{2} \\ 1 - \sqrt{2} \end{pmatrix}$ .