

**DSC 40A**

Lecture 05

Learning via Optimization, pt II

## Last Week: Empirical Risk Minimization

- ▶ To learn, pick a **loss function**  $L$  and minimize the **empirical risk**:

$$R(h) = \frac{1}{n} \sum_{i=1}^n L(h, y_i)$$

- ▶ Absolute loss:  $L_{\text{abs}}(h, y) = |h - y|$  (gives the **median**)
- ▶ Square loss:  $L_{\text{sq}}(h, y) = (h - y)^2$  (gives the **mean**)

## Last Week: The UCSD Loss

- ▶ We defined the “UCSD Loss”:

$$L_{\text{ucsd}}(h, y) = 1 - e^{-(h-y)^2/\sigma^2}$$

- ▶ Goal: minimize the “UCSD Risk”,

$$R_{\text{ucsd}}(h, y) = \frac{1}{n} \sum_{i=1}^n \left[ 1 - e^{-(h-y_i)^2/\sigma^2} \right]$$

- ▶ We tried taking a derivative and solving, but we couldn't solve for  $h$ .

## Last Week: Gradient Descent

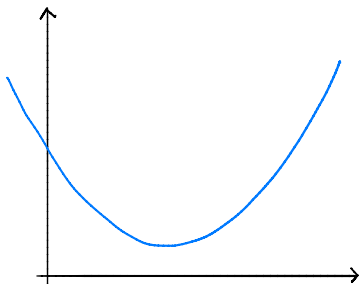
- ▶ Pick  $\alpha$  to be a positive number. It is the **learning rate**.
- ▶ Pick a starting prediction,  $h_0$ .
- ▶ On step  $i$ , perform update  $h_i = h_{i-1} - \alpha \cdot \frac{dR}{dh}(h_{i-1})$
- ▶ Repeat until convergence (when  $h$  doesn't change much).

Demo notebook on [DataHub](#)

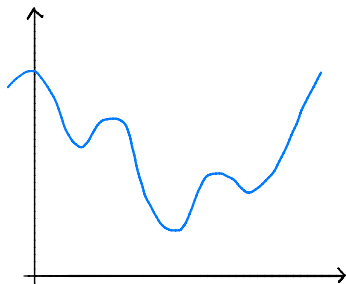
# Today

When is gradient descent guaranteed to work?

# Convex Functions



Convex



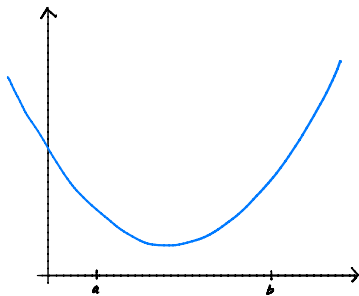
Non-convex

## Convexity: Definition

- $f$  is **convex** if for **every**  $a, b$  the line segment between

$$(a, f(a)) \quad \text{and} \quad (b, f(b))$$

does not go below the plot of  $f$ .



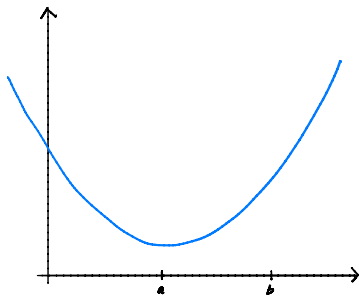


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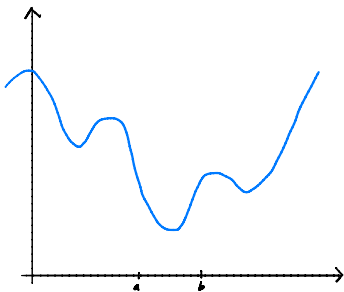
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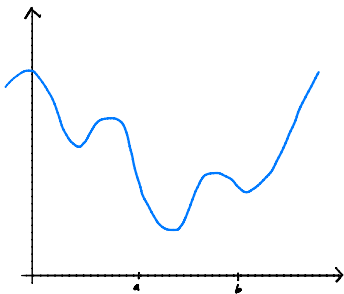


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## Deriving a More Useful/Formal Definition

- ▶ Walk from  $a$  at time  $t = 0$  to  $b$  at time  $t = 1$ .
- ▶ Let  $\text{height}_f(t)$  be height of  $f$  at time  $t$ .
- ▶ Let  $\text{height}_{\text{line}}(t)$  be height of line segment at time  $t$ .
- ▶ If  $f$  is convex, then for every  $t \in [0, 1]$ :

$$\text{height}_{\text{line}}(t) \geq \text{height}_f(t)$$

## Position at time $t$

- ▶ Let  $x(t)$  be horizontal position at time  $t$ .
- ▶ At time  $t = 0$ , we're at  $a$ , so  $x(0) = a$ .
- ▶ At time  $t = 1$ , we're at  $b$ , so  $x(1) = b$ .
- ▶ This formula works:

$$x(t) =$$

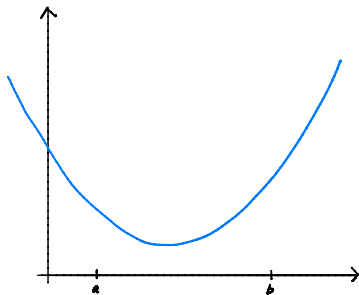
$$=$$

## Height of $f$ at time $t$

- ▶ We want a formula for  $\text{height}_f(t)$
- ▶ Remember  $x(t) = (1 - t)a + bt$ . So:

$$\text{height}_f(t) =$$

=



## Height of line segment at time $t$

- ▶ We want a formula for  $\text{height}_{\text{line}}(t)$
- ▶ It is a linear function:  $\text{height}_{\text{line}}(t) = w_1 t + w_0$
- ▶ We know  $\text{height}_{\text{line}}(0) = f(a)$  and  $\text{height}_{\text{line}}(1) = f(b)$ .

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### Discussion Question

What is the formula for  $\text{height}_{\text{line}}(t)$ ?

- a)  $at + (1 - b)t$
- b)  $(1 - t)f(a) + tf(b)$
- c)  $(a \cdot f(t) + b \cdot f(t))/2$
- d)  $t[f(b) - f(a)]$



## Height of line segment at time $t$

$$\text{height}_{\text{line}}(t) = w_1 t + w_0$$

$$\text{height}_{\text{line}}(0) = f(a) \quad \text{height}_{\text{line}}(1) = f(b)$$

## Convexity: Formal Definition

$$\text{height}_{\text{line}}(t) \geq \text{height}_f(t)$$

$$(1 - t)f(a) + tf(b) \geq f((1 - t)a + tb)$$

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- A function  $f : \mathbb{R} \rightarrow \mathbb{R}$  is **convex** if for every choice of  $a, b \in \mathbb{R}$  and  $t \in [0, 1]$ :

$$(1 - t)f(a) + tf(b) \geq f((1 - t)a + tb).$$

## Convexity: Formal Definition

$$\begin{aligned}\text{height}_{\text{line}}(t) &\geq \text{height}_f(t) \\ (1-t)f(a) + tf(b) &\geq f((1-t)a + tb)\end{aligned}$$

- ▶ A function  $f : \mathbb{R} \rightarrow \mathbb{R}$  is **convex** if for every choice of  $a, b \in \mathbb{R}$  and  $t \in [0, 1]$ :

$$(1-t)f(a) + tf(b) \geq f((1-t)a + tb).$$

- ▶ A function  $f$  is **nonconvex** if it is not convex.

## Discussion Question

Is  $f(x) = |x|$  convex?

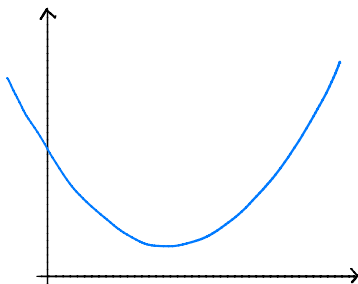
- a) Yes.
- b) No.
- c) Maybe.

**Example: Prove that  $f(x) = |x|$  is convex**

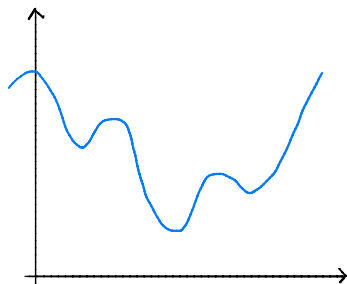
Hint: remember triangle inequality,  $|\alpha + \beta| \leq |\alpha| + |\beta|$ .

## Proving Convexity: Second Derivative Test

- ▶ If  $\frac{d^2f}{dx^2}(x) \geq 0$  for all  $x$ , then  $f$  is convex.
- ▶ Example:  $f(x) = x^4$  is convex.
- ▶ Only works if  $f$  is twice differentiable!



Convex



Non-convex

## Proving Convexity: Using Properties

Suppose that  $f(x)$  and  $g(x)$  are convex. Then:

- ▶  $w_1 f(x) + w_2 g(x)$  is convex, provided  $w_1, w_2 \geq 0$ 
  - ▶ Example:  $3x^2 + |x|$  is convex
- ▶  $g(f(x))$  is convex, provided  $g$  is non-decreasing.
  - ▶ Example:  $e^{x^2}$  is convex
- ▶  $\max\{f(x), g(x)\}$  is convex
  - ▶ Example:  $\begin{cases} 0, & x < 0 \\ x, & x \geq 0 \end{cases}$  is convex (max of 0 and  $x$ )



## Convex Losses

- ▶ If  $L(h, y)$  is a convex function (when  $y$  is fixed) then

$$R(h) = \frac{1}{n} \sum_{i=1}^n L(h, y_i)$$

is convex.

- ▶ Proof: sums of convex functions are convex.

# Convexity and Gradient Descent

- ▶ Convex functions are (relatively) easy to optimize.
- ▶ **Theorem:** if  $R(h)$  is convex and differentiable<sup>1</sup> then gradient descent converges to a **global optimum** of  $R$  *provided* that the step size is small enough<sup>2</sup>.

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<sup>1</sup>and its derivative is not too wild

<sup>2</sup>step size related to steepness.

# Convexity and Gradient Descent

- ▶ Convex functions are (relatively) easy to optimize.
- ▶ **Theorem:** if  $R(h)$  is convex and differentiable<sup>1</sup> then gradient descent converges to a **global optimum** of  $R$  *provided* that the step size is small enough<sup>2</sup>.
- ▶ We can even modify GD to work with convex, non-differentiable functions.

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<sup>1</sup>and its derivative is not too wild

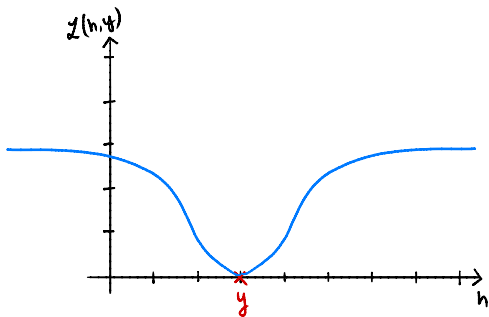
<sup>2</sup>step size related to steepness.

## Nonconvexity and Gradient Descent

- ▶ Nonconvex functions are (relatively) hard to optimize.
- ▶ Gradient descent can still be useful.
- ▶ But not guaranteed to converge to a global minimum.

# Convexity of Losses

- ▶ Is  $L_{\text{sq}}(h, y) = (h - y)^2$  convex? Yes or No.
- ▶ Is  $L_{\text{abs}}(h, y) = |h - y|$  convex? Yes or No.
- ▶ Is  $L_{\text{ucsd}}(h, y)$  convex? Yes or No.



## Convexity of UCSD Risk

- ▶ A function can be convex in a region.
- ▶ If  $\sigma$  is large,  $R_{\text{UCSD}}(h)$  is convex in a big region around data.
- ▶ If  $\sigma$  is small,  $R_{\text{UCSD}}(h)$  is convex in only small regions.

# Status Update

- ▶ We learned what it means for a function to be **convex**.
- ▶ Convex functions are (relatively) **easy** to optimize with gradient descent.
- ▶ We like **convex loss functions**, like the square loss and absolute loss.

## What's Left?

- ▶ We've been predicting salary without using any information about the individual.
- ▶ Making predictions using some information.