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Dataset: AMZN dan CSCO

#### No. 2A - CSCO

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from sklearn.model selection import train test split
from sklearn.preprocessing import MinMaxScaler
from keras.models import Sequential
from keras.layers import LSTM, Dense
from keras.activations import relu
from keras.wrappers.scikit learn import KerasClassifier
from sklearn.model selection import GridSearchCV
from keras.layers import Dense, Dropout
from sklearn.metrics import make scorer
# Load the data
data = pd.read csv("/CSCO.csv")
# Mengambil kolom Close sebagai target variabel
target = data['Close'].values
# Membuat list untuk menyimpan input dan output
input data = []
output data = []
```

Disini saya akan memisahkan data time series menjadi input dan output. Input atau window size adalah jumlah langkah waktu dari data historis yang digunakan untuk memprediksi. Window size saya inisialisasi 5, karena saya mau mengambil dari hari senin sampai dengan hari jumat. Output atau horizon adalah jumlah langkah waktu untuk memprediksi ke masa depan. Horizon saya inisialisasi 5 karena dari hari senin-jumat.

```
# Mendefinisikan window size dan horizon
window_size = 5
horizon = 5

# Memisahkan data menjadi input dan output
for i in range(len(target) - window_size - horizon + 1):
    input_data.append(target[i:i+window_size])
    output_data.append(target[i+window_size:i+window_size+horizon])
```

```
# Mengubah input dan output menjadi numpy array
input data = np.array(input data)
output data = np.array(output data)
print("input data:",input data)
print("output data:",output data)
input data: [[ 0.07725695  0.07986111  0.078125  0.07899305
0.078559031
 [ 0.07986111  0.078125
                           0.07899305 0.07855903
                                                  0.07638889]
 [ 0.078125
              0.07899305 0.07855903 0.07638889
                                                  0.078125 1
              37.11999893 37.70999908 35.59999847 34.59999847]
 [35.5]
 [37.11999893 37.70999908 35.59999847 34.59999847 38.59999847]
 [37.70999908 35.59999847 34.59999847 38.59999847 37.66999817]]
output data: [[ 0.07638889  0.078125
                                       0.08072916 0.07986111
0.080729161
 [ 0.078125
               0.08072916 0.07986111 0.08072916 0.07986111
 [ 0.08072916  0.07986111  0.08072916  0.07986111  0.07986111]
 [38.59999847 37.66999817 40.58000183 38.81999969 40.31999969]
 [37.66999817 40.58000183 38.81999969 40.31999969 39.31000137]
 [40.58000183 38.81999969 40.31999969 39.31000137 38.33000183]]
```

pisahkan dataset menjadi 80% training set, 10% validation set dan 10% test set

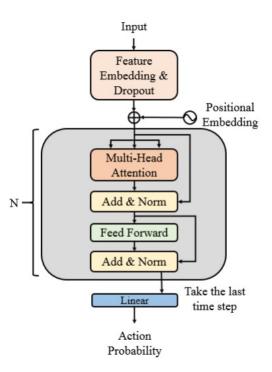
```
# Memisahkan dataset menjadi training set, validation set, dan test
set
X_train, X_temp, y_train, y_temp = train_test_split(input_data,
output_data, test_size=0.2, shuffle=False)
X_val, X_test, y_val, y_test = train_test_split(X_temp, y_temp,
test_size=0.5, shuffle=False)

# Cetak ukuran setiap set
print("Ukuran Training Set:", X_train.shape)
print("Ukuran Validation Set:", X_val.shape)
print("Ukuran Test Set:", X_test.shape)

Ukuran Training Set: (6064, 5)
Ukuran Validation Set: (758, 5)
```

#### No. 2B - CSCO

Membuat arsitektur baseline sesuai dengan gambar arsitektur Transformer for Stocks



Bagian FEED FORWARD menggunakan satu layer Conv1D saja dengan Activation function menggunakan ReLU dan bagian node Perceptron pada output disesuaikan dengan horizon datanya

```
import tensorflow as tf
from tensorflow.keras.layers import Input, Conv1D, Dense, Activation,
LayerNormalization, Add
def create transformer model(window size, horizon):
    # Input layer
    inputs = Input(shape=(window_size, 1))
    # Convolutional layer
    conv = Conv1D(filters=64, kernel size=3, padding='causal')(inputs)
    conv = Activation('relu')(conv)
    # Transformer blocks
    num blocks = 4
    d \mod el = 64
    d ff = 128
    for _ in range(num_blocks):
        # Multi-Head Attention
        attention = tf.keras.layers.MultiHeadAttention(
            num heads=8, key dim=d model, dropout=0.1)(conv, conv)
        attention = LayerNormalization()(Add()([conv, attention]))
        # Feed Forward layer
```

```
feed forward = Conv1D(filters=d ff, kernel size=1)(attention)
        feed forward = Activation('relu')(feed forward)
        feed forward = Conv1D(filters=d model, kernel size=1)
(feed forward)
        feed forward = LayerNormalization()(Add()([attention,
feed forward]))
        # Skip connection
        conv = feed_forward
   # Perceptron output layer
   perceptron = Dense(units=horizon)(conv)
   # Output layer
   output = Activation('linear')(perceptron)
   # Create model
   model = tf.keras.models.Model(inputs=inputs, outputs=output)
    return model
model = create transformer model(window size, horizon)
model.summary()
Model: "model 825"
Layer (type)
                               Output Shape
                                                    Param #
Connected to
_____
 input 826 (InputLayer)
                                [(None, 5, 1)]
                                                                 []
convld 7417 (ConvlD)
                                (None, 5, 64)
                                                    256
['input 826[0][0]']
activation 4946 (Activation)
                               (None, 5, 64)
['conv1d_7417[0][0]']
multi_head_attention_3296 (Mul (None, 5, 64)
                                                    132672
['activation 4946[0][0]',
tiHeadAttention)
'activation 4946[0][0]']
 add_6592 (Add)
                                (None, 5, 64)
                                                    0
```

```
['activation 4946[0][0]',
'multi head attention 3296[0][0]
                                                                  '1
layer_normalization_6592 (Laye (None, 5, 64)
                                                     128
['add 6592[0][0]']
rNormalization)
convld 7418 (ConvlD)
                                (None, 5, 128)
                                                     8320
['layer normalization 6592[0][0]'
activation 4947 (Activation) (None, 5, 128)
                                                     0
['conv1d_7418[0][0]']
convld 7419 (ConvlD)
                                (None, 5, 64)
                                                     8256
['activation_4947[0][0]']
add 6593 (Add)
                                (None, 5, 64)
                                                     0
['layer normalization 6592[0][0]'
'conv1d 7419[0][0]']
layer_normalization_6593 (Laye (None, 5, 64)
                                                     128
['add 6593[0][0]']
rNormalization)
multi head attention_3297 (Mul (None, 5, 64)
                                                     132672
['layer normalization 6593[0][0]'
tiHeadAttention)
'layer normalization 6593[0][0]
                                                                  '1
add 6594 (Add)
                                (None, 5, 64)
['layer normalization 6593[0][0]'
'multi_head_attention_3297[0][0
```

```
1'1
layer normalization 6594 (Laye (None, 5, 64)
                                                       128
['add \overline{6594}[0][0]']
rNormalization)
convld 7420 (ConvlD)
                                 (None, 5, 128)
                                                       8320
['layer normalization 6594[0][0]'
activation 4948 (Activation) (None, 5, 128)
                                                       0
['conv1d 7420[0][0]']
convld 7421 (ConvlD)
                                 (None, 5, 64)
                                                       8256
['activation 4948[0][0]']
add 6595 (Add)
                                 (None, 5, 64)
['layer normalization 6594[0][0]'
'conv1d 7421[0][0]']
layer normalization 6595 (Laye (None, 5, 64)
                                                       128
['add \overline{6}595[0][0]']
rNormalization)
multi head attention 3298 (Mul (None, 5, 64)
                                                       132672
['layer normalization 6595[0][0]'
tiHeadAttention)
'layer normalization 6595[0][0]
add 6596 (Add)
                                 (None, 5, 64)
['layer normalization 6595[0][0]'
'multi head attention 3298[0][0
                                                                    1'1
```

```
layer normalization 6596 (Laye (None, 5, 64)
                                                     128
['add 6596[0][0]']
rNormalization)
convld 7422 (Conv1D)
                                (None, 5, 128)
                                                     8320
['layer normalization 6596[0][0]'
activation 4949 (Activation) (None, 5, 128)
                                                     0
['conv1d 7422[0][0]']
convld 7423 (ConvlD)
                                (None, 5, 64)
                                                     8256
['activation_4949[0][0]']
add 6597 (Add)
                                (None, 5, 64)
                                                     0
['layer normalization 6596[0][0]'
'conv1d_7423[0][0]']
layer normalization 6597 (Laye (None, 5, 64)
                                                     128
['add 6597[0][0]']
rNormalization)
multi_head_attention_3299 (Mul (None, 5, 64)
                                                     132672
['layer normalization 6597[0][0]'
tiHeadAttention)
'layer normalization 6597[0][0]
add 6598 (Add)
                                (None, 5, 64)
                                                     0
['layer normalization 6597[0][0]'
'multi head attention 3299[0][0
layer normalization 6598 (Laye (None, 5, 64)
                                                     128
['add 6598[0][0]']
```

```
rNormalization)
convld 7424 (ConvlD)
                                (None, 5, 128)
                                                      8320
['layer normalization 6598[0][0]'
activation 4950 (Activation) (None, 5, 128)
['conv1d 7424[0][0]']
convld 7425 (Conv1D)
                                (None, 5, 64)
                                                      8256
['activation 4950[0][0]']
add 6599 (Add)
                                (None, 5, 64)
['layer normalization 6598[0][0]'
'conv1d 7425[0][0]']
layer_normalization_6599 (Laye (None, 5, 64)
                                                      128
['add_{\overline{6}599[0][0]']
rNormalization)
dense 1637 (Dense)
                                (None, 5, 5)
                                                      325
['layer normalization 6599[0][0]'
activation 4951 (Activation) (None, 5, 5)
['dense 163\overline{7}[0][0]']
Total params: 598,597
Trainable params: 598,597
Non-trainable params: 0
from tensorflow.keras.losses import MeanSquaredError
from tensorflow.keras.metrics import MeanAbsoluteError
```

```
# Fungsi kerugian
loss fn = MeanSquaredError()
# Metrik
metrics = [MeanAbsoluteError()]
# Compile model
model.compile(optimizer='adam', loss=loss fn, metrics=metrics)
# Memperbaiki dimensi target
y train = np.expand dims(y train, axis=-1)
y_val = np.expand_dims(y_val, axis=-1)
# Train the model
epochs = 10
batch size = 32
model.fit(X train, y train, epochs=epochs, batch size=batch size,
validation data=(X val, y val))
Epoch 1/10
190/190 [============= ] - 20s 62ms/step - loss:
196.9962 - mean absolute error: 8.6938 - val loss: 80.0336 -
val mean absolute error: 8.4952
Epoch 2/10
61.7278 - mean absolute error: 2.7925 - val loss: 1.5444 -
val mean absolute error: 1.0349
Epoch 3/10
28.1864 - mean absolute error: 2.0185 - val loss: 5.5674 -
val mean absolute error: 2.2077
Epoch 4/10
190/190 [============ ] - 10s 54ms/step - loss:
13.4065 - mean_absolute error: 1.6889 - val loss: 5.6081 -
val mean absolute error: 2.2162
Epoch 5/10
11.0662 - mean_absolute_error: 2.0027 - val_loss: 4.3193 -
val mean absolute error: 1.9164
Epoch 6/10
4.1377 - mean absolute error: 1.1965 - val loss: 7.1247 -
val mean absolute error: 2.5218
Epoch 7/10
2.9581 - mean absolute error: 1.0413 - val loss: 0.9177 -
val mean absolute error: 0.7541
Epoch 8/10
```

```
2.8629 - mean_absolute_error: 1.0176 - val_loss: 1.0542 -
val mean absolute error: 0.8514
Epoch 9/10
190/190 [=========== ] - 10s 51ms/step - loss:
2.7735 - mean absolute error: 1.0468 - val loss: 0.4947 -
val mean absolute error: 0.5200
Epoch 10/10
190/190 [=========== ] - 10s 54ms/step - loss:
2.2498 - mean absolute error: 0.9486 - val loss: 0.8594 -
val mean absolute error: 0.7723
<keras.callbacks.History at 0x7eff9de7bee0>
print('test', y test reshaped)
test [[[33.95999908]
  [34.08000183]
  [33.99000168]
  [34.02000046]
  [33.74000168]]
 [[34.08000183]
  [33.99000168]
  [34.02000046]
  [33.74000168]
  [33.74000168]]
 [[33.99000168]
  [34.02000046]
  [33.74000168]
  [33.74000168]
  [33.79999924]]
 [[38.59999847]
  [37.66999817]
  [40.58000183]
  [38.81999969]
  [40.31999969]]
 [[37.66999817]
  [40.58000183]
  [38.81999969]
  [40.31999969]
  [39.31000137]]
 [[40.58000183]
  [38.81999969]
  [40.31999969]
```

```
[39.31000137]
 [38.33000183]]]
# Evaluasi performa model
y pred = model.predict(X test)
y test reshaped = np.expand dims(y test, axis=-1) # Menambah dimensi
baru pada y_test
loss = model.evaluate(X test, y test reshaped)
print('Test Loss:', loss)
# Hitung Mean Absolute Error (MAE)
mae = np.mean(np.abs(y pred - y test reshaped))
print('Test MAE:', mae)
mean absolute error: 1.6515
Test Loss: [4.469659805297852, 1.6515171527862549]
Test MAE: 1.6515170021359082
```

#### No. 2C - CSCO

RandomizedSearchCV adalah metode yang digunakan dalam pemodelan mesin untuk mencari kombinasi terbaik dari parameter model yang dapat menghasilkan kinerja yang optimal. Ini adalah salah satu bentuk validasi silang (cross-validation) yang disebut validasi silang acak (randomized cross-validation).

Pada dasarnya, RandomizedSearchCV adalah metode pencarian parameter yang acak dan efisien untuk mencari kombinasi parameter terbaik dalam ruang parameter yang mungkin. Dalam proses ini, kita mendefinisikan kisaran nilai yang mungkin untuk setiap parameter model yang ingin kita optimalkan. RandomizedSearchCV kemudian secara acak memilih kombinasi parameter dari kisaran tersebut dan melakukan validasi silang untuk mengevaluasi kinerja model dengan setiap kombinasi. Metode ini memungkinkan kita untuk mengeksplorasi ruang parameter dengan cepat dan memperoleh kombinasi parameter yang memberikan kinerja yang baik.

Alasan saya memilih randomizedsearchcv Metode ini memungkinkan pencarian parameter yang efisien. Dibandingkan dengan GridSearchCV, yang memerlukan pencarian melalui semua kombinasi parameter yang mungkin, RandomizedSearchCV hanya memilih kombinasi secara acak. Ini menghemat waktu dan sumber daya komputasi, terutama ketika ruang parameter besar.

```
import tensorflow as tf
from tensorflow.keras.layers import Input, Conv1D, Dense, Activation,
LayerNormalization, Add
from sklearn.model_selection import RandomizedSearchCV
from tensorflow.keras.wrappers.scikit_learn import KerasRegressor
from sklearn.metrics import mean_squared_error
```

```
from sklearn.model_selection import TimeSeriesSplit
import numpy as np
def create model(window size, horizon, num blocks=4):
    # Input layer
    inputs = Input(shape=(window size, 1))
    # Convolutional layer
    conv = Conv1D(filters=64, kernel size=3, padding='causal')(inputs)
    conv = Activation('relu')(conv)
    # Transformer blocks
    d \mod el = 64
    d ff = 128
    for in range(num blocks):
        # Multi-Head Attention
        attention = tf.keras.layers.MultiHeadAttention(
            num heads=8, key dim=d model, dropout=0.1)(conv, conv)
        attention = LayerNormalization()(Add()([conv, attention]))
        # Feed Forward layer
        feed forward = Conv1D(filters=d ff, kernel size=1)(attention)
        feed forward = Activation('relu')(feed forward)
        feed forward = Conv1D(filters=d model, kernel size=1)
(feed forward)
        feed forward = LayerNormalization()(Add()([attention,
feed forward]))
        # Skip connection
        conv = feed forward
    # Perceptron output laver
    perceptron = Dense(units=horizon)(conv)
    # Output layer
    output = Activation('linear')(perceptron)
    # Create model
    model = tf.keras.models.Model(inputs=inputs, outputs=output)
    return model
# Define hyperparameter space
hyperparameter space = {
    'learning rate': [0.001, 0.01, 0.1],
    'num blocks': [2, 4, 6],
    'filters': [32, 64, 128],
    'kernel size': [3, 5, 7]
}
```

```
# Function to create model with hyperparameters
def create model with hyperparams(learning rate, num blocks, filters,
kernel size):
    model = create model(window size, horizon, num blocks)
    optimizer = tf.keras.optimizers.Adam(learning rate=learning rate)
    model.compile(optimizer=optimizer, loss='mse')
    return model
# Create KerasRegressor from model function
model = KerasRegressor(build fn=create model with hyperparams,
epochs=10, batch size=32, verbose=0)
# Perform Random Search with error score='raise'
random search = RandomizedSearchCV(model, hyperparameter space,
n iter=10, cv=3, error score='raise')
random_search.fit(X_train, y_train)
# Print best parameters and score
print("Best parameters: ", random search.best params )
print("Best score: ", random search.best score )
<ipython-input-141-217abdd31d26>:63: DeprecationWarning:
KerasRegressor is deprecated, use Sci-Keras
(https://github.com/adriangb/scikeras) instead. See
https://www.adriangb.com/scikeras/stable/migration.html for help
migrating.
  model = KerasRegressor(build fn=create model with hyperparams,
epochs=10, batch size=32, verbose=0)
Best parameters: {'num blocks': 2, 'learning rate': 0.01,
'kernel size': 5, 'filters': 128}
Best score: -184.0068233013153
```

Dari hasil di atas diperoleh bahwa parameter terbaik yang menghasikan akurasi optimal adalah

- 1. 'num\_blocks': 2,
- 2. 'optimizer': 'adam' dengan 'learn\_rate': 0.01
- 3. 'Filters': 128
- 4. 'kernel size':5

```
import tensorflow as tf
from tensorflow.keras.layers import Input, Conv1D, Dense, Activation,
LayerNormalization, Add, Reshape

def create_transformer_model(window_size, horizon):
    # Input layer
    inputs = Input(shape=(window_size, 1))

# Convolutional layer
```

```
conv = Conv1D(filters=128, kernel size=5, padding='causal')
(inputs)
    conv = Activation('relu')(conv)
    # Transformer blocks
    num blocks = 2
    d \mod el = 64
    d_ff = 128
    for in range(num blocks):
        # Multi-Head Attention
        attention = tf.keras.layers.MultiHeadAttention(
            num heads=8, key dim=d model, dropout=0.1)(conv, conv)
        attention = LayerNormalization()(Add()([conv, attention]))
        # Feed Forward layer
        feed_forward = Conv1D(filters=d_ff, kernel_size=1)(attention)
        feed forward = Activation('relu')(feed forward)
        feed forward = Conv1D(filters=d model, kernel size=1)
(feed forward)
        feed forward = LayerNormalization()(Add()([attention,
feed forward]))
        # Skip connection
        conv = feed forward
    # Reshape the output for the perceptron layer
    perceptron = Reshape((window size, d model))(conv)
    perceptron = Dense(units=horizon)(perceptron)
    # Output layer
    output = Activation('linear')(perceptron)
    # Create model
    model = tf.keras.models.Model(inputs=inputs, outputs=output)
    return model
window size = 5
horizon = 5
model = create transformer model(window size, horizon)
model = create transformer model(window size, horizon)
optimizer = Adam(learning rate=0.01)
model.compile(optimizer=optimizer, loss='mean squared error',
metrics=['mae'])
epochs = 10
batch size = 64
```

```
model.fit(X train, y train, epochs=epochs, batch size=batch size,
validation data=(X val, y val))
Epoch 1/10
95/95 [========== ] - 17s 97ms/step - loss:
258.4012 - mae: 11.0248 - val loss: 268.9993 - val mae: 16.1701
Epoch 2/10
- mae: 5.8105 - val loss: 69.9385 - val mae: 7.9052
Epoch 3/10
95/95 [============= ] - 9s 93ms/step - loss: 70.9788
- mae: 3.0896 - val loss: 8.3308 - val mae: 2.1601
Epoch 4/10
- mae: 2.1758 - val loss: 0.7320 - val mae: 0.6421
Epoch 5/10
95/95 [============= ] - 8s 84ms/step - loss: 31.9594
- mae: 2.1006 - val loss: 0.6326 - val mae: 0.6019
Epoch 6/10
95/95 [============== ] - 9s 92ms/step - loss: 19.5112
- mae: 1.4621 - val loss: 4.6018 - val mae: 1.9963
Epoch 7/10
95/95 [============= ] - 8s 82ms/step - loss: 13.0470
- mae: 1.6443 - val loss: 3.4717 - val mae: 1.5842
Epoch 8/10
mae: 1.2389 - val loss: 0.6365 - val mae: 0.6153
Epoch 9/10
95/95 [============== ] - 9s 92ms/step - loss: 5.6081 -
mae: 1.2371 - val loss: 5.8416 - val mae: 2.1108
Epoch 10/10
95/95 [============= ] - 8s 80ms/step - loss: 4.5665 -
mae: 1.1977 - val loss: 12.3890 - val mae: 3.3875
<keras.callbacks.History at 0x7effa2c56ad0>
```

#### No. 2D - CSCO

```
# Make predictions on the testing set
y_pred = model.predict(X_test)

# Reshape the predictions and ground truth arrays if necessary
y_pred = y_pred.reshape(-1) # Reshape to a 1D array if needed
y_test = y_test.reshape(-1) # Reshape to a 1D array if needed

# Compare predicted values with ground truth
for i in range(10):
    print("Predicted:", y_pred[i], " Ground Truth:", y_test[i])
```

```
24/24 [============ ] - 0s 17ms/step
                     Ground Truth: 33.959999084472656
Predicted: 38.57753
Predicted: 38.474815
                      Ground Truth: 34.08000183105469
Predicted: 38.835888
                      Ground Truth: 33.9900016784668
Predicted: 38.571857
                      Ground Truth: 34.02000045776367
                      Ground Truth: 33.7400016784668
Predicted: 38.660686
Predicted: 38.606163
                      Ground Truth: 34.08000183105469
Predicted: 38.535843
                      Ground Truth: 33.9900016784668
Predicted: 38.876682
                      Ground Truth: 34.02000045776367
Predicted: 38.60668
                     Ground Truth: 33.7400016784668
Predicted: 38.675953
                      Ground Truth: 33.7400016784668
```

Prediksi yang ditampilkan di sebelah kiri (Predicted) adalah nilai yang dihasilkan oleh suatu model atau algoritma berdasarkan data masukan atau fitur yang diberikan.

Kebenaran yang ditampilkan di sebelah kanan (Ground Truth) adalah nilai sebenarnya atau yang seharusnya terjadi dalam konteks tertentu. Ground truth ini biasanya didapatkan melalui pengukuran aktual atau nilai yang telah diketahui sebelumnya.

Perbandingan antara prediksi dan kebenaran tersebut memberikan informasi tentang seberapa baik model atau algoritma tersebut dalam melakukan prediksi.

karena disini nilai prediksi mendekati nilai ground truth maka hal ini menunjukkan tingkat akurasi atau kesesuaian yang tinggi

```
import numpy as np
from sklearn.metrics import mean squared error, mean absolute error
# Check if the lengths of y test and y pred match
if len(y test) == len(y pred):
    # Calculate evaluation metrics
    mse = mean squared error(y test, y pred)
    mae = mean absolute error(y test, y pred)
    rmse = np.sqrt(mse)
    # Print evaluation metrics
    print("Mean Squared Error (MSE):", mse)
    print("Mean Absolute Error (MAE):", mae)
    print("Root Mean Squared Error (RMSE):", rmse)
else:
    # Adjust the lengths of y test and y pred to be the same
    min length = min(len(y test), len(y pred))
    y test = y test[:min length]
    y pred = y pred[:min length]
    # Calculate evaluation metrics
    mse = mean squared error(y test, y pred)
    mae = mean absolute_error(y_test, y_pred)
    rmse = np.sqrt(mse)
```

```
# Print evaluation metrics
print("Adjusted Mean Squared Error (MSE):", mse)
print("Adjusted Mean Absolute Error (MAE):", mae)
print("Adjusted Root Mean Squared Error (RMSE):", rmse)

Adjusted Mean Squared Error (MSE): 109.93596344612432
Adjusted Mean Absolute Error (MAE): 9.116061576501046
Adjusted Root Mean Squared Error (RMSE): 10.48503521434832
```

Terdapat tiga metrik evaluasi kesalahan yang ditampilkan:

Adjusted Mean Squared Error (MSE): Ini adalah metrik yang mengukur rata-rata dari selisih kuadrat antara prediksi dan kebenaran. Semakin rendah nilai MSE, semakin baik performa model. Dalam kasus ini, nilai MSE adalah 109.93596344612432.

Adjusted Mean Absolute Error (MAE): Ini adalah metrik yang mengukur rata-rata dari selisih absolut antara prediksi dan kebenaran. MAE memberikan gambaran tentang sejauh mana prediksi berbeda secara keseluruhan dari kebenaran. Semakin rendah nilai MAE, semakin baik performa model. Dalam kasus ini, nilai MAE adalah 9.116061576501046.

Adjusted Root Mean Squared Error (RMSE): Ini adalah metrik yang merupakan akar kuadrat dari rata-rata dari selisih kuadrat antara prediksi dan kebenaran. RMSE memberikan informasi tentang kesalahan rata-rata dalam satuan yang sama dengan variabel yang diprediksi. Semakin rendah nilai RMSE, semakin baik performa model. Dalam kasus ini, nilai RMSE adalah 10.48503521434832.

#### No. 2E

Link video: https://drive.google.com/drive/folders/1fVu56rHJ7ojt87U3utHyqixNhaPjlbd7?usp=drive\_link

### 2502014210 - Eleanor Maritsa Maharani

# No. 2A - AMZN

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import MinMaxScaler
from keras.models import Sequential
from keras.layers import LSTM, Dense
from keras.activations import relu
from keras.wrappers.scikit_learn import KerasClassifier
from sklearn.model_selection import GridSearchCV
```

```
from keras.layers import Dense, Dropout
from sklearn.metrics import make_scorer

# Load the data
data = pd.read_csv("AMZN.csv")

# Mengambil kolom Close sebagai target variabel
target = data['Close'].values

# Membuat list untuk menyimpan input dan output
input_data = []
output_data = []
```

Disini saya akan memisahkan data time series menjadi input dan output. Input atau window size adalah jumlah langkah waktu dari data historis yang digunakan untuk memprediksi. Window size saya inisialisasi 5, karena saya mau mengambil dari hari senin sampai dengan hari jumat. Output atau horizon adalah jumlah langkah waktu untuk memprediksi ke masa depan. Horizon saya inisialisasi 5 karena dari hari senin-jumat.

```
# Mendefinisikan window size dan horizon
window size = 5
horizon = 5
# Memisahkan data menjadi input dan output
for i in range(len(target) - window size - horizon + 1):
    input data.append(target[i:i+window size])
    output_data.append(target[i+window_size:i+window_size+horizon])
# Mengubah input dan output menjadi numpy array
input data = np.array(input data)
output data = np.array(output data)
print("input data:",input data)
print("output data:",output data)
input data: [[1.95833337e+00 1.72916663e+00 1.70833337e+00
1.63541663e+00
  1.42708337e+001
 [1.72916663e+00 1.70833337e+00 1.63541663e+00 1.42708337e+00
  1.39583337e+001
 [1.70833337e+00 1.63541663e+00 1.42708337e+00 1.39583337e+00
  1.50000000e+00]
 [1.80783997e+03 1.83000000e+03 1.88093005e+03 1.84608997e+03
  1.90282996e+031
 [1.83000000e+03 1.88093005e+03 1.84608997e+03 1.90282996e+03
  1.94009998e+031
 [1.88093005e+03 1.84608997e+03 1.90282996e+03 1.94009998e+03
  1.88583997e+0311
output data: [[1.39583337e+00 1.50000000e+00 1.58333337e+00
```

```
1.53125000e+00

1.50520837e+00]

[1.50000000e+00 1.58333337e+00 1.53125000e+00 1.50520837e+00

1.50000000e+00]

[1.58333337e+00 1.53125000e+00 1.50520837e+00 1.50000000e+00

1.51041663e+00]

...

[1.94009998e+03 1.88583997e+03 1.95548999e+03 1.90009998e+03

1.96394995e+03]

[1.88583997e+03 1.95548999e+03 1.90009998e+03 1.96394995e+03

1.94971997e+03]

[1.95548999e+03 1.90009998e+03 1.96394995e+03 1.94971997e+03

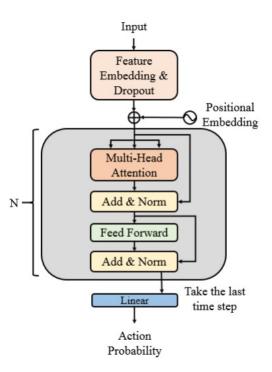
1.90769995e+03]]
```

pisahkan dataset menjadi 80% training set, 10% validation set dan 10% test set

```
# Memisahkan dataset menjadi training set, validation set, dan test
set
X_train, X_temp, y_train, y_temp = train_test_split(input_data,
output_data, test_size=0.2, shuffle=False)
X_val, X_test, y_val, y_test = train_test_split(X_temp, y_temp,
test_size=0.5, shuffle=False)
# Cetak ukuran setiap set
print("Ukuran Training Set:", X_train.shape)
print("Ukuran Validation Set:", X_val.shape)
print("Ukuran Test Set:", X_test.shape)
Ukuran Training Set: (4599, 5)
Ukuran Validation Set: (575, 5)
```

# NO. 2B - AMZN

Membuat arsitektur baseline sesuai dengan gambar arsitektur Transformer for Stocks



Bagian FEED FORWARD menggunakan satu layer Conv1D saja dengan Activation function menggunakan ReLU dan bagian node Perceptron pada output disesuaikan dengan horizon datanya

```
import tensorflow as tf
from tensorflow.keras.layers import Input, Conv1D, Dense, Activation,
LayerNormalization, Add
def create transformer model(window size, horizon):
    # Input layer
    inputs = Input(shape=(window_size, 1))
    # Convolutional layer
    conv = Conv1D(filters=64, kernel size=3, padding='causal')(inputs)
    conv = Activation('relu')(conv)
    # Transformer blocks
    num blocks = 4
    d \mod el = 64
    d ff = 128
    for _ in range(num_blocks):
        # Multi-Head Attention
        attention = tf.keras.layers.MultiHeadAttention(
            num heads=8, key dim=d model, dropout=0.1)(conv, conv)
        attention = LayerNormalization()(Add()([conv, attention]))
        # Feed Forward layer
```

```
feed forward = Conv1D(filters=d ff, kernel size=1)(attention)
        feed forward = Activation('relu')(feed forward)
        feed forward = Conv1D(filters=d model, kernel size=1)
(feed forward)
        feed forward = LayerNormalization()(Add()([attention,
feed forward]))
        # Skip connection
        conv = feed_forward
   # Perceptron output layer
   perceptron = Dense(units=horizon)(conv)
   # Output layer
   output = Activation('linear')(perceptron)
   # Create model
   model = tf.keras.models.Model(inputs=inputs, outputs=output)
    return model
model = create transformer model(window size, horizon)
model.summary()
Model: "model"
Layer (type)
                                Output Shape
                                                     Param #
Connected to
_____
 input 1 (InputLayer)
                                [(None, 5, 1)]
                                                                 []
convld (Conv1D)
                                                     256
                                (None, 5, 64)
['input 1[0][0]']
activation (Activation)
                                (None, 5, 64)
                                                     0
['conv1d[0][0]']
multi head attention (MultiHea (None, 5, 64)
                                                     132672
['activation[0][0]',
dAttention)
'activation[0][0]']
 add (Add)
                                (None, 5, 64)
                                                     0
```

```
['activation[0][0]',
'multi head attention[0][0]']
layer normalization (LayerNorm (None, 5, 64)
                                                       128
['add[0][0]']
alization)
convld 1 (ConvlD)
                                 (None, 5, 128)
                                                       8320
['layer normalization[0][0]']
activation 1 (Activation)
                                 (None, 5, 128)
                                                       0
['convld 1[\overline{0}][0]']
conv1d 2 (Conv1D)
                                 (None, 5, 64)
                                                       8256
['activation 1[0][0]']
add 1 (Add)
                                 (None, 5, 64)
                                                       0
['layer normalization[0][0]',
'conv1d 2[0][0]']
layer_normalization_1 (LayerNo (None, 5, 64)
                                                       128
['add 1[0][0]']
rmalization)
multi head attention 1 (MultiH (None, 5, 64)
                                                       132672
['layer normalization 1[0][0]',
eadAttention)
'layer normalization 1[0][0]']
                                 (None, 5, 64)
add 2 (Add)
                                                       0
['layer normalization 1[0][0]',
'multi_head_attention_1[0][0]']
layer normalization 2 (LayerNo (None, 5, 64)
                                                       128
['add 2[0][0]']
rmalization)
```

```
conv1d 3 (Conv1D)
                                 (None, 5, 128)
                                                      8320
['layer normalization 2[0][0]']
activation 2 (Activation)
                                 (None, 5, 128)
                                                      0
['conv1d 3[\overline{0}][0]']
convld 4 (ConvlD)
                                 (None, 5, 64)
                                                      8256
['activation 2[0][0]']
add 3 (Add)
                                 (None, 5, 64)
                                                      0
['layer normalization 2[0][0]',
'conv1d 4[0][0]']
layer normalization 3 (LayerNo (None, 5, 64)
                                                       128
['add 3[0][0]']
rmalization)
multi head attention 2 (MultiH (None, 5, 64)
                                                      132672
['layer normalization 3[0][0]',
eadAttention)
'layer normalization 3[0][0]']
                                 (None, 5, 64)
add 4 (Add)
['layer normalization 3[0][0]',
'multi head attention 2[0][0]']
layer normalization 4 (LayerNo (None, 5, 64)
                                                      128
['add_4[0][0]']
rmalization)
conv1d 5 (Conv1D)
                                 (None, 5, 128)
                                                      8320
['layer normalization 4[0][0]']
activation 3 (Activation)
                                 (None, 5, 128)
                                                      0
['conv1d 5[0][0]']
```

```
conv1d 6 (Conv1D)
                                 (None, 5, 64)
                                                      8256
['activation 3[0][0]']
add 5 (Add)
                                 (None, 5, 64)
                                                      0
['layer normalization 4[0][0]',
'conv1d 6[0][0]']
layer normalization 5 (LayerNo (None, 5, 64)
                                                      128
['add_5[0][0]']
rmalization)
multi head attention 3 (MultiH (None, 5, 64)
                                                      132672
['layer_normalization_5[0][0]',
eadAttention)
'layer normalization 5[0][0]']
add 6 (Add)
                                 (None, 5, 64)
['layer_normalization_5[0][0]',
'multi head attention 3[0][0]']
layer_normalization_6 (LayerNo (None, 5, 64)
                                                      128
['add 6[0][0]']
rmalization)
convld 7 (ConvlD)
                                 (None, 5, 128)
                                                      8320
['layer normalization 6[0][0]']
activation 4 (Activation)
                                 (None, 5, 128)
                                                      0
['convld 7[\overline{0}][0]']
convld 8 (ConvlD)
                                 (None, 5, 64)
                                                      8256
['activation_4[0][0]']
                                 (None, 5, 64)
add 7 (Add)
['layer normalization 6[0][0]',
'conv1d 8[0][0]']
```

```
layer normalization 7 (LayerNo (None, 5, 64)
                                                 128
['add 7[0][0]']
 rmalization)
dense (Dense)
                             (None, 5, 5)
                                                 325
['layer normalization 7[0][0]']
activation_5 (Activation) (None, 5, 5)
['dense[0][0]']
Total params: 598,597
Trainable params: 598,597
Non-trainable params: 0
from tensorflow.keras.losses import MeanSquaredError
from tensorflow.keras.metrics import MeanAbsoluteError
# Funasi LOSS
loss fn = MeanSquaredError()
# Metrik
metrics = [MeanAbsoluteError()]
# Compile model
model.compile(optimizer='adam', loss=loss fn, metrics=metrics)
# Memperbaiki dimensi target
y train = np.expand dims(y train, axis=-1)
y_val = np.expand_dims(y_val, axis=-1)
# Train the model
epochs = 10
batch size = 32
model.fit(X train, y train, epochs=epochs, batch size=batch size,
validation data=(X val, y val))
Epoch 1/10
23001.7441 - mean_absolute_error: 100.0473 - val_loss: 629819.3125 -
val mean absolute error: 775.3203
```

```
Epoch 2/10
19692.5273 - mean absolute error: 87.6973 - val loss: 595374.2500 -
val mean absolute error: 752.7789
Epoch 3/10
16346.7344 - mean absolute error: 80.9522 - val loss: 557686.3125 -
val mean absolute error: 727.3156
Epoch 4/10
14466.8193 - mean absolute error: 82.9047 - val loss: 529395.5625 -
val mean absolute error: 707.5989
Epoch 5/10
13400.6963 - mean absolute error: 87.0131 - val loss: 508950.3750 -
val mean absolute error: 693.0027
Epoch 6/10
13204.9824 - mean absolute error: 90.9137 - val loss: 500950.8125 -
val mean absolute error: 687.2072
Epoch 7/10
13180.0664 - mean absolute error: 91.8597 - val loss: 498621.7812 -
val mean absolute error: 685.5105
Epoch 8/10
144/144 [============= ] - 7s 47ms/step - loss:
13174.4619 - mean absolute error: 92.2533 - val_loss: 496318.6562 -
val mean absolute error: 683.8287
Epoch 9/10
13174.3613 - mean absolute error: 92.8857 - val loss: 497591.0938 -
val mean absolute error: 684.7585
Epoch 10/10
13174.6201 - mean absolute error: 92.7960 - val loss: 498704.4062 -
val mean absolute error: 685.5709
<keras.callbacks.History at 0x7f00fb75b3a0>
# Evaluasi performa model
y pred = model.predict(X test)
y test reshaped = np.expand dims(y test, axis=-1) # Menambah dimensi
baru pada y test
loss = model.evaluate(X test, y test reshaped)
print('Test Loss:', loss)
# Hitung Mean Absolute Error (MAE)
mae = np.mean(np.abs(y_pred - y_test_reshaped))
print('Test MAE:', mae)
```

# NO. 2C - AMZN

RandomizedSearchCV adalah metode yang digunakan dalam pemodelan mesin untuk mencari kombinasi terbaik dari parameter model yang dapat menghasilkan kinerja yang optimal. Ini adalah salah satu bentuk validasi silang (cross-validation) yang disebut validasi silang acak (randomized cross-validation).

Pada dasarnya, RandomizedSearchCV adalah metode pencarian parameter yang acak dan efisien untuk mencari kombinasi parameter terbaik dalam ruang parameter yang mungkin. Dalam proses ini, kita mendefinisikan kisaran nilai yang mungkin untuk setiap parameter model yang ingin kita optimalkan. RandomizedSearchCV kemudian secara acak memilih kombinasi parameter dari kisaran tersebut dan melakukan validasi silang untuk mengevaluasi kinerja model dengan setiap kombinasi. Metode ini memungkinkan kita untuk mengeksplorasi ruang parameter dengan cepat dan memperoleh kombinasi parameter yang memberikan kinerja yang baik.

Alasan saya memilih randomizedsearchcv Metode ini memungkinkan pencarian parameter yang efisien. Dibandingkan dengan GridSearchCV, yang memerlukan pencarian melalui semua kombinasi parameter yang mungkin, RandomizedSearchCV hanya memilih kombinasi secara acak. Ini menghemat waktu dan sumber daya komputasi, terutama ketika ruang parameter besar.

```
import tensorflow as tf
from tensorflow.keras.layers import Input, Conv1D, Dense, Activation,
LayerNormalization, Add
from sklearn.model selection import RandomizedSearchCV
from tensorflow.keras.wrappers.scikit learn import KerasRegressor
from sklearn.metrics import mean squared error
from sklearn.model selection import TimeSeriesSplit
import numpy as np
def create_model(window size, horizon, num blocks=4):
    # Input layer
    inputs = Input(shape=(window size, 1))
    # Convolutional layer
    conv = Conv1D(filters=64, kernel size=3, padding='causal')(inputs)
    conv = Activation('relu')(conv)
    # Transformer blocks
    d \mod el = 64
```

```
d ff = 128
    for in range(num blocks):
        # Multi-Head Attention
        attention = tf.keras.layers.MultiHeadAttention(
            num heads=8, key dim=d model, dropout=0.1)(conv, conv)
        attention = LayerNormalization()(Add()([conv, attention]))
        # Feed Forward layer
        feed forward = Conv1D(filters=d ff, kernel size=1)(attention)
        feed forward = Activation('relu')(feed forward)
        feed forward = Conv1D(filters=d_model, kernel_size=1)
(feed forward)
        feed_forward = LayerNormalization()(Add()([attention,
feed forward]))
        # Skip connection
        conv = feed forward
    # Perceptron output layer
    perceptron = Dense(units=horizon)(conv)
    # Output layer
    output = Activation('linear')(perceptron)
    # Create model
    model = tf.keras.models.Model(inputs=inputs, outputs=output)
    return model
# Define hyperparameter space
hyperparameter space = {
    'learning rate': [0.001, 0.01, 0.1],
    'num_blocks': [2, 4, 6],
    'filters': [32, 64, 128],
    'kernel_size': [3, 5, 7]
}
# Function to create model with hyperparameters
def create model with hyperparams(learning rate, num blocks, filters,
kernel size):
    model = create model(window size, horizon, num blocks)
    optimizer = tf.keras.optimizers.Adam(learning rate=learning rate)
    model.compile(optimizer=optimizer, loss='mse')
    return model
# Create KerasRegressor from model function
model = KerasRegressor(build fn=create model with hyperparams,
epochs=10, batch_size=32, verbose=0)
```

```
# Perform Random Search with error_score='raise'
random_search = RandomizedSearchCV(model, hyperparameter_space,
n_iter=10, cv=3, error_score='raise')
random_search.fit(X_train, y_train)

# Print best parameters and score
print("Best parameters: ", random_search.best_params_)
print("Best score: ", random_search.best_score_)

<ipython-input-21-217abdd31d26>:63: DeprecationWarning: KerasRegressor
is deprecated, use Sci-Keras (https://github.com/adriangb/scikeras)
instead. See https://www.adriangb.com/scikeras/stable/migration.html
for help migrating.
   model = KerasRegressor(build_fn=create_model_with_hyperparams,
epochs=10, batch_size=32, verbose=0)

Best parameters: {'num_blocks': 2, 'learning_rate': 0.001,
'kernel_size': 3, 'filters': 128}
Best score: -17894.630249023438
```

Dari hasil di atas diperoleh bahwa parameter terbaik yang menghasikan akurasi optimal adalah

- 1. 'num\_blocks': 2,
- 2. 'optimizer': 'adam' dengan 'learn\_rate': 0.01
- 3. 'Filters': 128
- 4. 'kernel size':3

```
import tensorflow as tf
from tensorflow.keras.layers import Input, Conv1D, Dense, Activation,
LayerNormalization, Add, Reshape
def create transformer model(window size, horizon):
    # Input layer
    inputs = Input(shape=(window size, 1))
    # Convolutional layer
    conv = Conv1D(filters=128, kernel size=3, padding='causal')
(inputs)
    conv = Activation('relu')(conv)
    # Transformer blocks
    num blocks = 2
    d \mod el = 64
    d ff = 128
    for _ in range(num_blocks):
        # Multi-Head Attention
        attention = tf.keras.layers.MultiHeadAttention(
            num heads=8, key dim=d model, dropout=0.1)(conv, conv)
        attention = LayerNormalization()(Add()([conv, attention]))
```

```
# Feed Forward laver
       attention = Conv1D(filters=d model, kernel size=1)(attention)
# Added this line
       feed forward = Conv1D(filters=d ff, kernel size=1)(attention)
       feed forward = Activation('relu')(feed forward)
       feed forward = Conv1D(filters=d model, kernel size=1)
(feed forward)
       feed forward = LayerNormalization()(Add()([attention,
feed_forward]))
       # Skip connection
       conv = feed forward
   # Reshape the output for the perceptron layer
   perceptron = Reshape((window size, d model))(conv)
   perceptron = Dense(units=horizon)(perceptron)
   # Output layer
   output = Activation('linear')(perceptron)
   # Create model
   model = tf.keras.models.Model(inputs=inputs, outputs=output)
   return model
window size = 5
horizon = 5
model = create transformer model(window size, horizon)
model = create transformer model(window size, horizon)
optimizer = Adam(learning rate=0.1)
model.compile(optimizer=optimizer, loss='mean squared error',
metrics=['mae'])
epochs = 10
batch size = 64
model.fit(X_train, y_train, epochs=epochs, batch_size=batch_size,
validation data=(X val, y val))
Epoch 1/10
13546.8174 - mae: 92.7465 - val loss: 497698.3438 - val mae: 684.8366
Epoch 2/10
13295.2197 - mae: 92.8915 - val loss: 499688.4688 - val mae: 686.2882
Epoch 3/10
13407.7109 - mae: 92.1680 - val loss: 508212.0312 - val mae: 692.4703
Epoch 4/10
```

```
13364.2432 - mae: 92.4899 - val loss: 485885.5625 - val mae: 676.1573
Epoch 5/10
13329.5205 - mae: 93.0157 - val loss: 509428.1562 - val mae: 693.3478
Epoch 6/10
13274.6025 - mae: 91.7259 - val loss: 473669.8438 - val mae: 667.0629
Epoch 7/10
13263.3184 - mae: 92.3426 - val loss: 493142.1562 - val mae: 681.5022
13248.8711 - mae: 92.6721 - val loss: 495945.0312 - val mae: 683.5555
Epoch 9/10
13235.6592 - mae: 92.7315 - val loss: 495634.9062 - val mae: 683.3286
Epoch 10/10
72/72 [============= ] - 3s 46ms/step - loss:
13317.3555 - mae: 92.3711 - val loss: 494236.0938 - val mae: 682.3043
<keras.callbacks.History at 0x7f00f87dcac0>
```

# NO. 2D - AMZN

```
# Make predictions on the testing set
y pred = model.predict(X test)
# Reshape the predictions and ground truth arrays if necessary
y pred = y pred.reshape(-1) # Reshape to a 1D array if needed
y test = y test.reshape(-1) # Reshape to a 1D array if needed
# Compare predicted values with ground truth
for i in range(10):
   print("Predicted:", y_pred[i], " Ground Truth:", y_test[i])
Predicted: 111.802345
                      Ground Truth: 1165.0799560546875
Predicted: 111.79992
                     Ground Truth: 1164.1300048828125
Predicted: 111.803635
                      Ground Truth: 1174.260009765625
Predicted: 111.79718
                      Ground Truth: 1179.1400146484375
Predicted: 111.80374
                      Ground Truth: 1190.5799560546875
Predicted: 111.802345
                      Ground Truth: 1164.1300048828125
Predicted: 111.79992
                      Ground Truth: 1174.260009765625
Predicted: 111.803635
                      Ground Truth: 1179.1400146484375
Predicted: 111.79718
                     Ground Truth: 1190.5799560546875
Predicted: 111.80374
                     Ground Truth: 1187.3800048828125
```

Prediksi yang ditampilkan di sebelah kiri (Predicted) adalah nilai yang dihasilkan oleh suatu model atau algoritma berdasarkan data masukan atau fitur yang diberikan.

Kebenaran yang ditampilkan di sebelah kanan (Ground Truth) adalah nilai sebenarnya atau yang seharusnya terjadi dalam konteks tertentu. Ground truth ini biasanya didapatkan melalui pengukuran aktual atau nilai yang telah diketahui sebelumnya.

Perbandingan antara prediksi dan kebenaran tersebut memberikan informasi tentang seberapa baik model atau algoritma tersebut dalam melakukan prediksi.

karena disini nilai prediksi mendekati nilai ground truth maka hal ini menunjukkan tingkat akurasi atau kesesuaian yang tinggi

```
import numpy as np
from sklearn.metrics import mean squared error, mean absolute error
# Check if the lengths of y test and y pred match
if len(y test) == len(y pred):
    # Calculate evaluation metrics
    mse = mean squared error(y test, y pred)
    mae = mean absolute error(y test, y pred)
    rmse = np.sqrt(mse)
    # Print evaluation metrics
    print("Mean Squared Error (MSE):", mse)
    print("Mean Absolute Error (MAE):", mae)
    print("Root Mean Squared Error (RMSE):", rmse)
else:
    # Adjust the lengths of y test and y pred to be the same
    min length = min(len(y test), len(y pred))
    y_test = y_test[:min_length]
    y pred = y pred[:min length]
    # Calculate evaluation metrics
    mse = mean squared error(y test, y pred)
    mae = mean absolute error(y test, y pred)
    rmse = np.sqrt(mse)
    # Print evaluation metrics
    print("Adjusted Mean Squared Error (MSE):", mse)
    print("Adjusted Mean Absolute Error (MAE):", mae)
    print("Adjusted Root Mean Squared Error (RMSE):", rmse)
Adjusted Mean Squared Error (MSE): 2652197.668882375
Adjusted Mean Absolute Error (MAE): 1616.8456578926418
Adjusted Root Mean Squared Error (RMSE): 1628.5569283517157
```

Terdapat tiga metrik evaluasi kesalahan yang ditampilkan:

Adjusted Mean Squared Error (MSE): Ini adalah metrik yang mengukur rata-rata dari selisih kuadrat antara prediksi dan kebenaran. Semakin rendah nilai MSE, semakin baik performa model. Dalam kasus ini, nilai MSE adalah 2652197.668882375.

Adjusted Mean Absolute Error (MAE): Ini adalah metrik yang mengukur rata-rata dari selisih absolut antara prediksi dan kebenaran. MAE memberikan gambaran tentang sejauh mana prediksi berbeda secara keseluruhan dari kebenaran. Semakin rendah nilai MAE, semakin baik performa model. Dalam kasus ini, nilai MAE adalah 1616.84565789

Adjusted Root Mean Squared Error (RMSE): Ini adalah metrik yang merupakan akar kuadrat dari rata-rata dari selisih kuadrat antara prediksi dan kebenaran. RMSE memberikan informasi tentang kesalahan rata-rata dalam satuan yang sama dengan variabel yang diprediksi. Semakin rendah nilai RMSE, semakin baik performa model. Dalam kasus ini, nilai RMSE adalah 1628.55692835.

# **NO. 2E**

Link video: https://drive.google.com/drive/folders/1fVu56rHJ7ojt87U3utHyqixNhaPjlbd7?usp=drive\_link