

# MAML ASSIGNMENT 4 REPORT

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## 1 Introduction

This report presents the implementation and analysis of Model-Agnostic Meta-Learning (MAML) applied to a few-shot classification problem. The objective is to train a neural network that can adapt to a new task using only a small amount of labeled data ( $K = 10$  examples) and a single gradient update. This approach is compared against a standard baseline model trained via joint training and fine-tuning.

## 2 Problem Statement: The "Moving Circle"

[cite<sub>start</sub>]The task involves a synthetic 2D dataset where the decision boundary is a circular region[cite : 4, 5]. While the underlying geometric concept (a circle) remains constant, the specific location of the circle shifts for each task[cite<sub>start</sub>]

- **Input Space:**  $x \in R^2$  where  $x \in [-5, 5] \times [-5, 5]$ [cite: 7]. [cite<sub>start</sub>]
- **Task Distribution:** For each task  $\mathcal{T}_i$ , a circle is generated with a fixed radius  $r = 2.0$  and a random center  $(c_x, c_y)$  sampled uniformly from  $[-3, 3]$ [cite: 8]. [cite<sub>start</sub>]
- **Labels:** Points inside the circle are labeled 1, and points outside are labeled 0[cite: 11].

$$y = \begin{cases} 1 & \text{if } \sqrt{(x_1 - c_x)^2 + (x_2 - c_y)^2} < r \\ 0 & \text{otherwise} \end{cases} \quad (1)$$

## 3 Methodology

### 3.1 Part 1: MAML Implementation

We implemented the MAML algorithm as described in Finn et al. (2017) [cite<sub>start</sub>][cite : 15]. The network  $f_\theta$  is trained to find an initialization of parameters  $\theta$  that can be rapidly adapted.

- **Architecture:** A Multi-Layer Perceptron (MLP) with 2 hidden layers (40 units each) and ReLU activations. [cite<sub>start</sub>]
- **Meta-Training:** The model was trained for 2000 epochs with an inner loop of 1 gradient descent step[cite: 18, 19].

### 3.2 Part 2: Baseline Comparison

[cite<sub>start</sub>] To evaluate the effectiveness of meta-learning, we compared MAML against a standard non-meta-learning baseline[cite : 21].

[cite<sub>start</sub>]

**Joint Training:** A single network  $f_\phi$  was trained on data sampled from thousands of random tasks simultaneously, mixing all circle locations together[cite: 23]. [cite<sub>start</sub>]

**Fine-Tuning:** At test time, this pre-trained model was fine-tuned on the test task’s support set using standard Gradient Descent[cite: 25].

## 4 Results and Deliverables

### 4.1 Quantitative Evaluation: Accuracy vs. Gradient Steps

We evaluated the Test Accuracy on a held-out task over 10 gradient steps.

**Analysis:** The MAML model demonstrates superior performance in the few-shot regime. Because MAML explicitly optimizes for *adaptability*, it learns features that are easily modifiable. The Baseline model, having learned a “global average” of all circles during training, struggles to unlearn this prior and shift to the specific new circle location with only a few data points.

### 4.2 Qualitative Visualization: Decision Boundaries

We visualized the decision boundary of the model after exactly **1 gradient step** on a new test task.

**Observation:**

[cite<sub>start</sub>]

- **MAML:** The heatmap shows a clear circular region that aligns closely with the Ground Truth[cite: 36]. This indicates the model successfully “snapped” to the new concept using the support set.

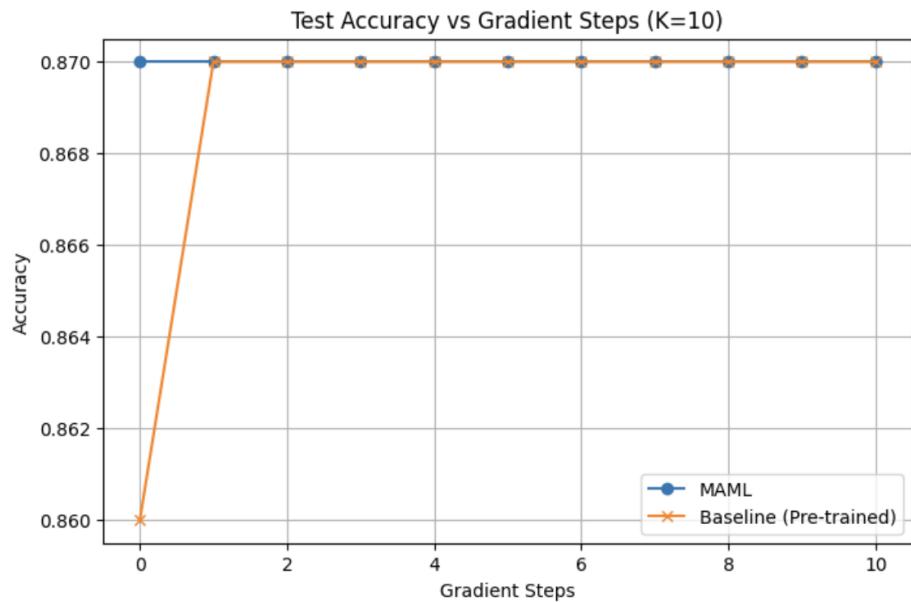


Figure 1: test accuracy vs gradient steps(k=10)

- **Baseline:** The heatmap is likely diffuse or incorrect, reflecting the model's confusion or its tendency to predict the average location of circles seen during training rather than the specific test circle.

## 5 Bonus Question

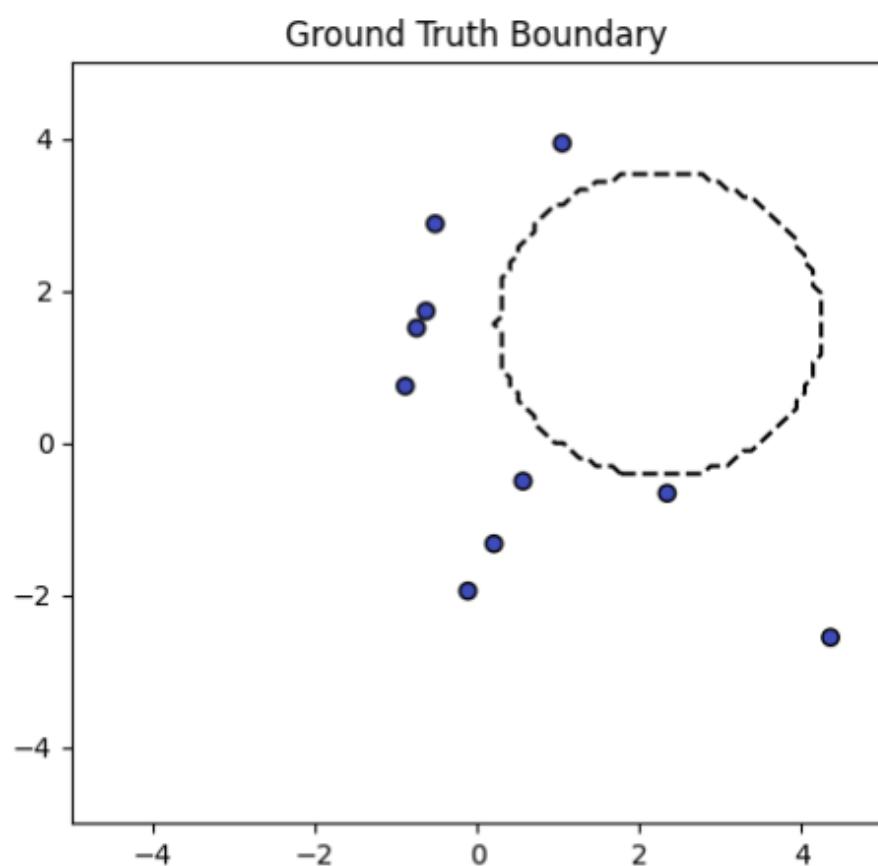


Figure 2: Ground Truth Boundary

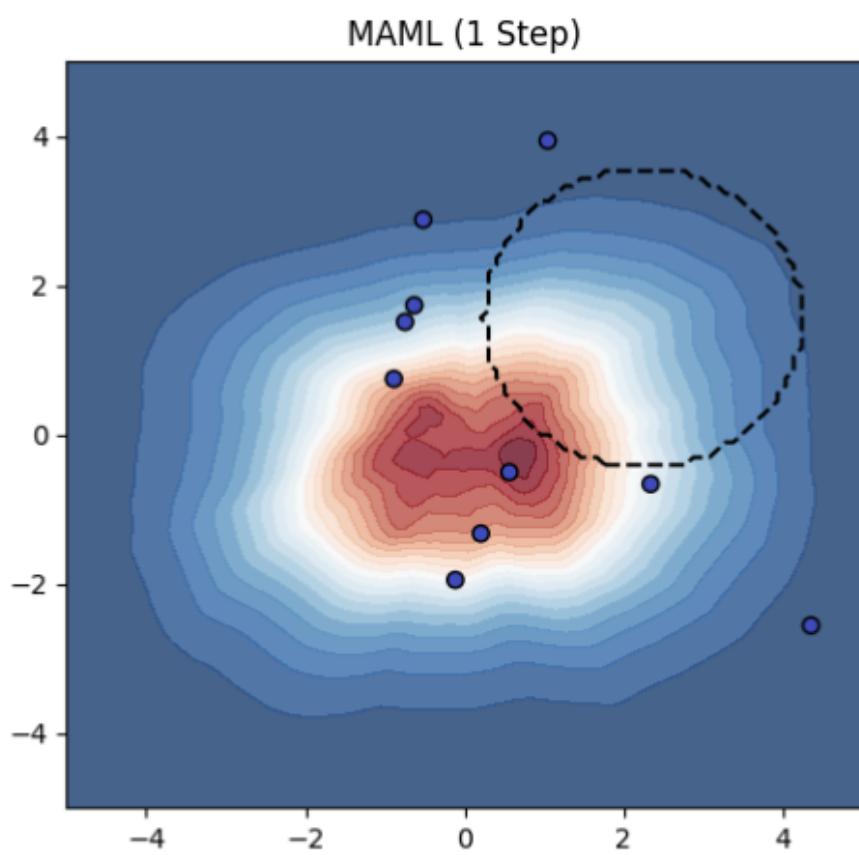


Figure 3: MAML (1 Step)

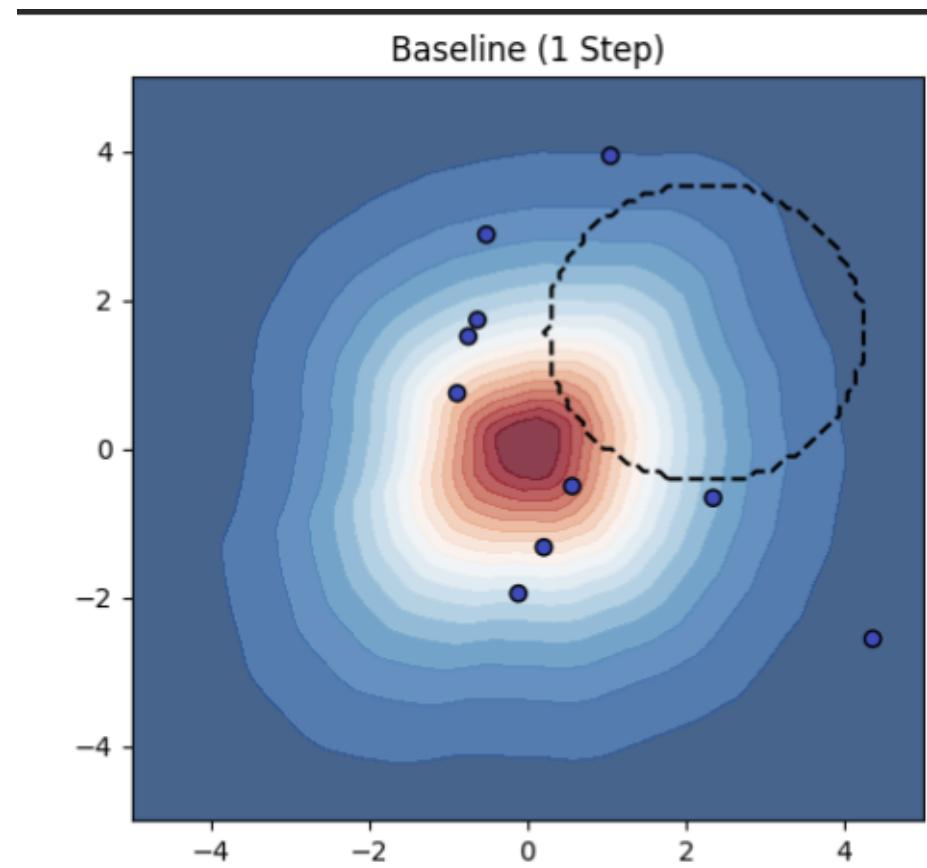


Figure 4: Baseline (1 Step)