

CSE2037 Kendimce Çözümler

1. Vizedeki Sorunun Gelişmiş

```
1  #include "mbed.h"
2
3  #define WAIT_MSEC 20 PwmOut LED(p20);
4
5  InterruptIn enter_Sensor(p10);
6  InterruptIn enter_Sensor(p10);
7
8  int totalNumberOfCustomers = 0;
9  float brightness = 0;
10 // This ISR will be add 1 to
11 // the totalNumberOfCustomers.
12
13 void enter_ISR() {
14     extern int totalNumberOfCustomers;
15     totalNumberOfCustomers += 1;
16 }
17
18 // This ISR will be substract 1 from
19 // the totalNumberOfCustomers.
20 void exit_ISR() {
21     extern int totalNumberOfCustomers;
22     totalNumberOfCustomers -= 1;
23 }
24
25 int main() {
26     enter_Sensor.fall(callback(&enter_ISR));
27     exit_Sensor.fall(callback(&enter_ISR));
28
29     while(true)
30         extern int totalNumberOfCustomers;
31         extern float brightness;
32         if !(totalNumberOfCustomers) brightness = 0;
33         else {
34             // Because we want 20 people for
35             // most bright state, the step
36             // should be 1/20 = 0.05
37             // This will be the increment for
38             // duty cycle at every person enters.
39             // LED is a PwmOut pin.
40             brightness = totalNumberOfCustomers * 0.05f;
41         }
42         LED = brightness;
43         wait_ms(WAIT_MSEC);
44 }
```

2. Riemman İntegrali Alma

```
1  #include "mbed.h"
2
3  #define 5MIN_SEC 300
4
5  AnalogIn source(p20);
6
7  Timeout tout;
8
9  volatile int cond = 1;
10 int total = 0;
11
12 void timeout_ISR() {
13     extern volatile int cond;
14     cond = 0;
15 }
16
17 int main() {
18     extern volatile int cond;
19     tout.attach(callback(&timeout_ISR), 5MIN_SEC);
20
21     while (cond) {
22         total += source.read();
23         wait_ms(20); // 0.02sec = 20ms
24     }
25
26     wait_ms(oswaitForever);
27 }
```

3. Bit Değişim Sorusu

```
1  #include <iostream>
2
3  int main() {
4      uint16_t x = 0b1101111011101111;
5      uint16_t mask = 0b0000000011111111;
6      uint16_t newV = x & mask;
7      uint8_t x_low = newV;
8
9      uint8_t x_high = x >> 8;
10
11     uint16_t x_swap = x_low;
12     x_swap = x_swap << 8;
13     x_swap += x_high;
14
15     return 0;
16 }
```

4. Assembly Sorusu

```
1  sum_ADDR equ    0x200020
2
3          LDR      R0, =sum_ADDR
4          MOV      R1, #0
5          STR      R1, [R0]
```

```
6
7      LDR      R2, =0x20000010
8      LDR      R3, =0x20000014
9      LDR      R4, =0x20000018
10
11     LDR      R2, [R2]
12     LDR      R3, [R3]
13     LDR      R4, [R4]
14
15     MOV      R5, #2
16 adding
17     ADD      R1, R1, R2
18     ADD      R1, R1, R3
19     ADD      R1, R1, R4
20     SUBS     R5, R5, #1
21     BPL      adding
```