

Algunas identidades de álgebra y análisis vectorial

En lo que sigue, ϕ y ψ representan escalares; \mathbf{a} , \mathbf{b} y \mathbf{c} vectores.

1. Triples productos y productos mixtos

- i) $\mathbf{a} \times (\mathbf{b} \times \mathbf{c}) = \mathbf{b}(\mathbf{a} \cdot \mathbf{c}) - \mathbf{c}(\mathbf{a} \cdot \mathbf{b})$
- ii) $\mathbf{a} \times (\mathbf{b} \times \mathbf{c}) + \mathbf{b} \times (\mathbf{c} \times \mathbf{a}) + \mathbf{c} \times (\mathbf{a} \times \mathbf{b}) = \mathbf{0}$
- iii) $\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c}) = \mathbf{b} \cdot (\mathbf{c} \times \mathbf{a}) = \mathbf{c} \cdot (\mathbf{a} \times \mathbf{b}) \quad (\equiv [\mathbf{a}, \mathbf{b}, \mathbf{c}])$
- iv) $(\mathbf{a} \times \mathbf{b}) \cdot (\mathbf{c} \times \mathbf{d}) = (\mathbf{a} \cdot \mathbf{c})(\mathbf{b} \cdot \mathbf{d}) - (\mathbf{a} \cdot \mathbf{d})(\mathbf{b} \cdot \mathbf{c})$

2. Identidades cuadráticas en ∇

- i) $\nabla \cdot (\nabla \times \mathbf{a}) = 0$
- ii) $\nabla \times (\nabla \phi) = \mathbf{0}$
- iii) $\nabla^2 \mathbf{a} \equiv \nabla(\nabla \cdot \mathbf{a}) - \nabla \times (\nabla \times \mathbf{a})$
(Laplaciano de un campo vectorial).

3. Reglas de producto

- i) $\nabla(\phi\psi) = \phi\nabla\psi + \psi\nabla\phi$
- ii) $\nabla(\mathbf{a} \cdot \mathbf{b}) = \mathbf{a} \times (\nabla \times \mathbf{b}) + \mathbf{b} \times (\nabla \times \mathbf{a}) + (\mathbf{a} \cdot \nabla)\mathbf{b} + (\mathbf{b} \cdot \nabla)\mathbf{a}$
- iii) $\nabla \cdot (\phi\mathbf{a}) = \phi\nabla \cdot \mathbf{a} + \mathbf{a} \cdot \nabla\phi$
- iv) $\nabla \cdot (\mathbf{a} \times \mathbf{b}) = \mathbf{b} \cdot (\nabla \times \mathbf{a}) - \mathbf{a} \cdot (\nabla \times \mathbf{b})$
- v) $\nabla \times (\phi\mathbf{a}) = \phi\nabla \times \mathbf{a} - \mathbf{a} \times \nabla\phi$
- vi) $\nabla \times (\mathbf{a} \times \mathbf{b}) = (\mathbf{b} \cdot \nabla)\mathbf{a} - (\mathbf{a} \cdot \nabla)\mathbf{b} + \mathbf{a}\nabla \cdot \mathbf{b} - \mathbf{b}\nabla \cdot \mathbf{a}$
- vii) $\nabla \times (\mathbf{a} \times \mathbf{b}) = \mathbf{a} \times (\nabla \times \mathbf{b}) - \mathbf{b} \times (\nabla \times \mathbf{a}) - (\mathbf{a} \times \nabla) \times \mathbf{b} + (\mathbf{b} \times \nabla) \times \mathbf{a}$

4. Teoremas integrales

- i) $\int_{\mathbf{r}_1}^{\mathbf{r}_2} (\nabla\phi) \cdot d\mathbf{l} = \phi(\mathbf{r}_2) - \phi(\mathbf{r}_1)$
- ii) $\int_V (\nabla \cdot \mathbf{a}) d^3r = \int_{S(V)} \mathbf{a} \cdot d\mathbf{s}$
- iii) $\int_{S(C)} (\nabla \times \mathbf{a}) \cdot d\mathbf{s} = \oint_C \mathbf{a} \cdot d\mathbf{l}$
- iv) $\int_V (\nabla\phi) d^3r = \int_{S(V)} d\mathbf{s} \phi$
- v) $\int_V (\nabla \times \mathbf{a}) d^3r = \int_{S(V)} d\mathbf{s} \times \mathbf{a}$

5. Coordenadas curvilíneas ortogonales

Son sistemas de coordenadas $u_i(x, y, z)$ ($i = 1, 2, 3$) tales que las líneas coordenadas que pasan por cada punto, son ortogonales. Es decir, para un desplazamiento infinitesimal $d\mathbf{l}$, la longitud de arco correspondiente ds verifica: $ds^2 = h_1^2 du_1^2 + h_2^2 du_2^2 + h_3^2 du_3^2$ (donde los h_i son, en gral., funciones de u_1, u_2 y u_3). El elemento de volumen será entonces: $d^3r = h_1 h_2 h_3 du_1 du_2 du_3$

Operadores vectoriales

$$\nabla\phi = \frac{1}{h_1} \frac{\partial\phi}{\partial u_1} \hat{\mathbf{u}}_1 + \frac{1}{h_2} \frac{\partial\phi}{\partial u_2} \hat{\mathbf{u}}_2 + \frac{1}{h_3} \frac{\partial\phi}{\partial u_3} \hat{\mathbf{u}}_3, \quad \nabla \cdot \mathbf{a} = \frac{1}{h_1 h_2 h_3} \left(\frac{\partial(a_1 h_2 h_3)}{\partial u_1} + \frac{\partial(a_2 h_1 h_3)}{\partial u_2} + \frac{\partial(a_3 h_1 h_2)}{\partial u_3} \right)$$
$$\nabla \times \mathbf{a} = \frac{1}{h_2 h_3} \left[\frac{\partial(a_3 h_3)}{\partial u_2} - \frac{\partial(a_2 h_2)}{\partial u_3} \right] \hat{\mathbf{u}}_1 + \frac{1}{h_1 h_3} \left[\frac{\partial(a_1 h_1)}{\partial u_3} - \frac{\partial(a_3 h_3)}{\partial u_1} \right] \hat{\mathbf{u}}_2 + \frac{1}{h_1 h_2} \left[\frac{\partial(a_2 h_2)}{\partial u_1} - \frac{\partial(a_1 h_1)}{\partial u_2} \right] \hat{\mathbf{u}}_3$$

Ejemplos

Coordenadas cartesianas

$$d\mathbf{l} = dx \hat{\mathbf{x}} + dy \hat{\mathbf{y}} + dz \hat{\mathbf{z}}$$

$$d^3r = dx dy dz$$

$$\nabla\phi = \partial_x\phi \hat{\mathbf{x}} + \partial_y\phi \hat{\mathbf{y}} + \partial_z\phi \hat{\mathbf{z}}$$

$$\nabla \cdot \mathbf{a} = \partial_x a_x + \partial_y a_y + \partial_z a_z$$

$$\nabla \times \mathbf{a} = (\partial_y a_z - \partial_z a_y) \hat{\mathbf{x}} + (\partial_z a_x - \partial_x a_z) \hat{\mathbf{y}} + (\partial_x a_y - \partial_y a_x) \hat{\mathbf{z}}$$

$$\nabla^2\phi = \partial_x^2\phi + \partial_y^2\phi + \partial_z^2\phi$$

Coordenadas cilíndricas

$$d\mathbf{l} = dr \hat{\mathbf{r}} + r d\varphi \hat{\varphi} + dz \hat{\mathbf{z}}$$

$$d^3r = r dr d\varphi dz$$

$$\nabla\phi = \partial_r\phi \hat{\mathbf{r}} + r^{-1}\partial_\varphi\phi \hat{\varphi} + \partial_z\phi \hat{\mathbf{z}}$$

$$\nabla \cdot \mathbf{a} = r^{-1}\partial_r(ra_r) + r^{-1}\partial_\varphi a_\varphi + \partial_z a_z$$

$$\nabla \times \mathbf{a} = [r^{-1}\partial_\varphi a_z - \partial_z a_\varphi] \hat{\mathbf{r}} + [\partial_z a_r - \partial_r a_z] \hat{\varphi} + r^{-1}[\partial_r(ra_\varphi) - \partial_\varphi a_r] \hat{\mathbf{z}}$$

$$\nabla^2\phi = r^{-1}\partial_r(r\partial_r\phi) + r^{-2}\partial_\varphi^2\phi + \partial_z^2\phi$$

Coordenadas esféricas

$$d\mathbf{l} = dr \hat{\mathbf{r}} + r d\theta \hat{\theta} + r \sin \theta d\varphi \hat{\varphi}$$

$$d^3r = r^2 \sin \theta dr d\theta d\varphi$$

$$\nabla\phi = \partial_r\phi \hat{\mathbf{r}} + r^{-1}\partial_\theta\phi \hat{\theta} + (r \sin \theta)^{-1}\partial_\varphi\phi \hat{\varphi}$$

$$\nabla \cdot \mathbf{a} = r^{-2}\partial_r(r^2 a_r) + (r \sin \theta)^{-1}\partial_\theta(\sin \theta a_\theta) + (r \sin \theta)^{-1}\partial_\varphi a_\varphi$$

$$\nabla \times \mathbf{a} = (r \sin \theta)^{-1}[\partial_\theta(\sin \theta a_\varphi) - \partial_\varphi a_\theta] \hat{\mathbf{r}} + r^{-1}[(\sin \theta)^{-1}\partial_\varphi a_r - \partial_r(ra_\varphi)] \hat{\theta} + r^{-1}[\partial_r(ra_\theta) - \partial_\theta a_r] \hat{\varphi}$$

$$\nabla^2\phi = r^{-2}\partial_r(r^2\partial_r\phi) + (r^2 \sin \theta)^{-1}\partial_\theta(\sin \theta \partial_\theta\phi) + (r^2 \sin^2\theta)^{-1}\partial_\varphi^2\phi$$