

Lab 1: Git version-control system, AVR tools

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1. The link to my repository is:

<https://github.com/elenaab16/Digital-Electronics2>

2. Blink example.

- | : represents the logic OR.
- & : represents the logic AND.
- ^ : represents the logic XOR.
- ~ : represents one's complement.
- << : represents left shifting.

3. Morse Code application.

```
/*
```

```
* MorseCode.c
```

```
*
```

```
* Created: 29/09/2020 13:24:45
```

```
* Author : Elena Arjona Bustos
```

```
*/
```

```
/* Defines -----*/
```

```
#define LED_GREEN PB5 // AVR pin where green LED is connected
```

```
#define SHORT_DELAY 500 // Delay in milliseconds
```

```
#define LONG_DELAY 1000 // Delay in milliseconds
```

```
#ifndef F_CPU
```

```
#define F_CPU 16000000 // CPU frequency in Hz required for delay
```

```
#endif
```

```
/* Includes -----*/
```

```
#include <util/delay.h> // Functions for busy-wait delay loops
```

```
#include <avr/io.h> // AVR device-specific IO definitions
```

```
#include <avr/io.h>
```

```
/* Functions -----*/
```

```
/**
```

```
* Long wait function. Turns on the LED for the long period of time and then,
```

```
* it turn it off.
```

```
*/
```

```
void long_wait(void);
```

```
/**
```

```
* Short wait function. Turns on the LED for the short period of time and then,
```

```
* it turn it off.
```

```
*/
```

```
void short_wait(void);
```

```
/**
```

```
* Main function where the program execution begins. Toggle one LED
```

```
* and use function from the delay library.
```

```
*/
```

```

int main(void)

{

    // Set pin as output in Data Direction Register

    // DDRB = DDRB or 0010 0000

    DDRB = DDRB | (1<<LED_GREEN);


    // Set pin LOW in Data Register (LED off)

    // PORTB = PORTB and 1101 1111

    PORTB = PORTB & ~(1<<LED_GREEN);


    while (1)

    {


        // Letter D -> _ . .

        long_wait();

        short_wait();

        short_wait();


        // Letter E -> - - .

        long_wait();

        short_wait();

```

```

// Number 2 -> . . _ _ _

short_wait();

short_wait();

long_wait();

long_wait();

long_wait();

}

}

void long_wait(void){

    // Set pin HIGH in Data Register (LED on)

    // PORTB = PORTB and 1101 1111
    PORTB = PORTB | (1<<LED_GREEN);

    // Pause several milliseconds
    _delay_ms(LONG_DELAY);

    // Set pin LOW in Data Register (LED off)
    // PORTB = PORTB and 1101 1111
    PORTB = PORTB & ~(1<<LED_GREEN);

    // Pause several milliseconds
    _delay_ms(SHORT_DELAY);

```

```
}
```

```
void short_wait(void){
```

```
    // Set pin HIGH in Data Register (LED on)
```

```
    // PORTB = PORTB and 1101 1111
```

```
    PORTB = PORTB | (1<<LED_GREEN);
```

```
    // Pause several milliseconds
```

```
    _delay_ms(SHORT_DELAY);
```

```
    // Set pin LOW in Data Register (LED off)
```

```
    // PORTB = PORTB and 1101 1111
```

```
    PORTB = PORTB & ~(1<<LED_GREEN);
```

```
    // Pause several milliseconds
```

```
    _delay_ms(SHORT_DELAY);
```

```
}
```