

# ELENA CORINA GRIGORE

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Senior Research Scientist, Motional (formerly nuTonomy)  
Boston, MA, USA

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## Research Interests

Robotics, autonomous driving, machine learning, deep learning, artificial intelligence, human-robot collaboration, adaptive systems, reinforcement learning, multi-agent systems.

## Education

- **Doctor of Philosophy, Computer Science, Yale University, USA** 2018  
Advisor: Brian Scassellati  
Area of study: Learning Supportive Behaviors for Adaptive Robots  
in Human-Robot Collaboration
- **Master of Philosophy, Computer Science, Yale University, USA** 2015
- **Master of Science, Computer Science, Yale University, USA** 2015
- **Master of Engineering with Study Abroad**  
**Computer Science, University of Bristol, UK** 2012  
Advisors: Kerstin Eder (University of Bristol, UK)  
Anthony G. Pipe (Bristol Robotics Laboratory, UK)  
Christopher Melhuish (Bristol Robotics Laboratory, UK)  
Thesis: “*I Robot, I Think*”  
4-year program encompassing my Bachelor’s degree  
Study Abroad at University of California, San Diego (2010/2011)  
Master of Engineering with First Class Honors
- **Coventry University, UK** 2009  
Completed first year of Computing Honors Degree  
Highest scoring student in my cohort  
Transfer to University of Bristol at the end of my first undergraduate year

## Recent Work

- **Senior Research Scientist at Motional, Boston, MA, USA** 2020 – present  
**Research Scientist at Motional, Boston, MA, USA** 2018 – 2020  
Working on the Prediction and Behavior Modeling team, applying machine learning techniques (notably, deep learning) to model and predict the trajectories and intentions of all the agents of interest in the environment of a self-driving vehicle [18], [17]
- **Research Intern at Uber Advanced Technologies Group, San Francisco, CA, USA** 2017  
Integrating temporal context into deep learning networks for self-driving vehicle perception
- **Recent Dissertation Work, Yale University, New Haven, CT, USA** 2017 – 2018  
Learning task and user preference models in human-robot collaboration for predicting useful supportive behaviors, tailored to a human peer [16], [15]

## Publications

- [18] T. Phan-Minh, **E. C. Grigore**, F. A. Boulton, O. Beijbom, and E. M. Wolff, “Covernet: Multimodal behavior prediction using trajectory sets”, in *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)*, Virtual, 2020, June 1419, pp. 14 074–14 083.
- [17] F. A. Boulton, **E. C. Grigore**, and E. M. Wolff, “Motion prediction using trajectory sets and self-driving domain knowledge”, Available at: arXiv preprint arXiv:2006.04767, 2020.

- [16] **E. C. Grigore**, A. Roncone, O. Mangin, and B. Scassellati, “Preference-based assistance prediction for human-robot collaboration tasks”, in *Proceedings of the 31st IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Madrid, Spain, 2018, October 1–5.
- [15] **E. C. Grigore**, O. Mangin, A. Roncone, and B. Scassellati, “Predicting supportive behaviors for human-robot collaboration”, in *Proceedings of the 17th International Conference on Autonomous Agents and Multiagent Systems (AAMAS)*, Extended Abstract, Stockholm, Sweden, 2018, July 10–15.
- [14] **E. C. Grigore** and B. Scassellati, “Discovering action primitive granularity from human motion for human-robot collaboration”, in *Robotics: Science and Systems (RSS)*, Boston, USA, 2017, July 12–16.
- [13] **E. C. Grigore** and B. Scassellati, “Hierarchical multi-agent reinforcement learning through communicative actions for human-robot collaboration”, in *Proceedings of the Future of Interactive Learning Machines (FILM) Workshop at the 30th Annual Conference on Neural Information Processing Systems (NIPS)*, Full paper, Barcelona, Spain, 2016, December 5–10.
- [12] **E. C. Grigore**, A. Pereira, I. Zhou, D. Wang, and B. Scassellati, “Talk to me: verbal communication improves perceptions of friendship and social presence in human-robot interaction”, in *Proceedings of the 16th International Conferences on Intelligent Virtual Agents (IVA)*, Los Angeles, USA: Springer, 51–63. **Best paper finalist.**
- [11] **E. C. Grigore**, A. Pereira, J. J. Yang, I. Zhou, D. Wang, and B. Scassellati, “Comparing ways to trigger migration between a robot and a virtually embodied character”, in *Proceedings of the 8th International Conference on Social Robotics (ICSR)*, Kansas City, USA: Springer, 2016, November 1–3, 839–849. **Best student paper finalist.**
- [10] A. Suman, R. Marvin, **E. C. Grigore**, H. Admoni, and B. Scassellati, “Prior behavior impacts human mimicry of robots”, in *Proceedings of the 25th IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN)*, New York, USA, 2016, August 26–31, pp. 1057–1062.
- [9] **E. C. Grigore** and B. Scassellati, “Constructing policies for supportive behaviors and communicative actions in human-robot teaming”, in *Proceedings of the HRI Pioneers Workshop at the 11th ACM/IEEE International Conference on Human-Robot Interaction (HRI)*, Christchurch, New Zealand, 2016, March 7–10, pp. 615–616.
- [8] **E. C. Grigore**, A. Pereira, and B. Scassellati, “Modeling motivational states in adaptive robot companions”, in *2015 AAAI Fall Symposium Series*, 2015, November 12–14.
- [7] **E. C. Grigore**, “Modeling motivational states through interpreting physical activity data for adaptive robot companions”, in *Proceedings of the 23rd International Conference on User Modelling, Adaptation and Personalization (UMAP)*, Dublin, Ireland: Springer, 2015, June 29–July 3, pp. 379–384.
- [6] **E. C. Grigore** and B. Scassellati, “Maintaining engagement in shared goals with a personal robot companion through motivational state modeling”, in *Proceedings of the Human-Robot Teaming Workshop at the 10th ACM/IEEE International Conference on Human-Robot Interaction (HRI)*, Portland, OR, 2015, March 2–5.
- [5] B. Hayes, **E. C. Grigore**, A. Litoiu, A. Ramachandran, and B. Scassellati, “A developmentally inspired transfer learning approach for predicting skill durations”, in *Proceedings of the 4th Joint IEEE International Conferences on Development and Learning and Epigenetic Robotics (ICDL-Epirob)*, IEEE, 2014, October 13–16, pp. 181–186.
- [4] E. Short, K. Swift-Spong, J. Greczek, A. Ramachandran, A. Litoiu, **E. C. Grigore**, D. Feil-Seifer, S. Shuster, J. J. Lee, S. Huang, *et al.*, “How to train your dragonbot: socially assistive robots for teaching children about nutrition through play”, in *Proceedings of the 23rd IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN)*, IEEE, 2014, August 25–29, pp. 924–929.
- [3] **E. C. Grigore** and B. Scassellati, “Feasibility of sar approaches – helping children with learning tasks”, in *Proceedings of International Workshop on Developmental Social Robotics (DevSor): Reasoning about Human, Perspective, Affordances and Effort for Socially Situated Robots at the 26th IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Tokyo, Japan, 2013, November 3–7, pp. 22–24.

- [2] **E. C. Grigore**, K. Eder, A. G. Pipe, C. Melhuish, and U. Leonards, “Joint action understanding improves robot-to-human object handover”, in *Proceedings of the 26th IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, IEEE, 2013, November 3–7, pp. 4622–4629.
- [1] **E. C. Grigore**, K. Eder, A. Lenz, S. Skachek, A. G. Pipe, and C. Melhuish, “Towards safe human-robot interaction”, in *Proceedings of the 12th Annual Towards Autonomous Robotic Systems (TAROS)*, Springer, 2011, August 31–September 2, pp. 323–335.

## Honors and Awards

- **Best Paper Finalist, Intelligent Virtual Agents (IVA)** 2016  
“Verbal Communication Improves Perceptions of Friendship and Social Presence in Human-Robot Interaction”
- **Best Student Paper Finalist, International Conference on Social Robotics (ICSR)** 2016  
“Comparing Ways to Trigger Migration between a Robot and a Virtually Embodied Character”
- **Human-Robot Interaction (HRI) Pioneer** 2016  
Highly selective workshop that seeks to foster creativity and collaboration across HRI
- **Tocher Fellowship, Yale University, USA** 2015
- **Tocher Fellowship, Yale University, USA** 2014
- **EPSRC (Engineering and Physical Sciences Research Council) Fellowship, UK** 2011  
Summer Research Project at the Bristol Robotics Lab, Bristol, UK
- **EPSRC Fellowship, UK** 2010  
Summer Research Project at the Bristol Robotics Lab, Bristol, UK
- **Head of Promotion Honorary Prize (Valedictorian), Piatra Neamț Computer Science High School, Romania** 2008

## Invited Talks

- Virtual Assistant Summit, San Francisco, CA 2017  
*Can You Lend Me a Hand? Helpers of the Future*
- STEM Coffee Hour Facilitator, Cheshire, CT 2017  
*How is AI Shaping Robotics?*
- IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2013  
International Workshop on Developmental Social Robotics (DevSor), Tokyo  
*Feasibility of SAR Approaches? Helping Children with Learning Tasks*

## Theses

- [Ph.D. Thesis] **E. C. Grigore**, “Learning Supportive Behaviors for Adaptive Robots in Human-Robot Collaboration”, Yale University, USA, 2018, Available at: [https://scazlab.yale.edu/sites/default/files/files/corina\\_dissertation.pdf](https://scazlab.yale.edu/sites/default/files/files/corina_dissertation.pdf).
- [Master’s Thesis] **E. C. Grigore**, “I Robot, I Think”, University of Bristol, UK (work performed at the Bristol Robotics Lab, Bristol, UK), 2012.

## Work Experience

- **Senior Research Scientist at Motional, Boston, MA, USA** 2020 – present  
**Research Scientist at Motional, Boston, MA, USA** 2018 – 2020

### **Prediction and Behavior Modeling team**

Working on the Prediction and Behavior Modeling team, focusing on the agents of interest present in the self-driving car's environment (e.g., vehicles, bicyclists, pedestrians, etc.). Applying machine learning techniques (notably, deep learning) to model and predict the trajectories and intentions of such agents [18], [17].

*Outcome:* Utilizing and expanding my research skills to develop models of how agents behave on the road, and to publish state-of-the-art solutions to top machine learning conferences. Applying large-scale deep learning models to real-world, large datasets involving temporal data. Utilizing my knowledge of Python and PyTorch, being part of the full process of creating and deploying deep learning models. Working in a dynamic and fast-paced team with strong collaboration practices, as well as working with other teams to understand data constraints and establish interfacing between modules.

- **Research Intern at Uber Advanced Technologies Group, San Francisco, USA** 2017  
**Deep learning for self-driving car perception team**

Worked on the perception module of the self-driving pipeline, where the aim was to detect all targets of interest in the environment of the autonomous vehicle. Researched introducing temporal context into deep learning networks, including the use of multi-frames and recurrent neural networks.

*Outcome:* Gained experience using large scale deep learning models for detection, and developed research skills relevant to working with region-based convolutional neural networks and recurrent neural networks. Gained experience using the Google Object Detection codebase, TensorFlow, and its associated utilities for working with large datasets (e.g., TFRecords). Worked in a fast-paced team, and collaborated with colleagues to implement novel ideas for the team's deep learning models.

- **Student-teacher at Sidney Stringer School, Coventry, UK** 2009  
**The Student Associates Scheme, UK**

Worked within the Mathematics Department as a student-teacher providing help for students during classes, raising students' aspirations for higher education. Produced and delivered presentations and a programming-based project and also delivered a lesson.

*Outcome:* Developed communication, presentation and leadership skills, effectively coordinated groups of students and worked together with teachers and other student-teachers in a motivating environment.

## Research Experience

- **Yale University, Social Robotics Laboratory, New Haven, CT, USA**

- *Learning Supportive Behaviors for Adaptive Robots in Human-Robot Collaboration*

2014 – 2018

Applying machine learning techniques to endow robots with learning capabilities needed when placed in new environments or faced with new tasks. This includes learning about the structure and progression of a physical task, as well as about the actions human workers perform during this task. Investigating techniques including Hidden Markov Models and reinforcement learning in single- and multi-agent settings, where the robot's aim is to provide supportive behaviors in human-robot collaboration scenarios.

- *User modeling for motivational states within a reinforcement learning framework* 2013 – 2015

Designed a system for long-term robot companions that employs a model of users' daily motivational states within a reinforcement learning framework.

- *Developed a robot for interaction with children in an educational setting* 2012 – 2014  
Built, assembled, and programmed research robot platform DragonBot for interaction with children. Performed human-robot interaction study at local schools.
- **University of Bristol and the Bristol Robotics Laboratory, Bristol, UK**
  - *Master of Engineering “I Robot, I Think” Thesis Project* 2011 – 2012  
Applied machine learning techniques to model users’ intentions for object handovers in human-robot interaction scenarios [2].
  - *“I Robot... I Learn” Summer Research Project* 2011  
Implemented a machine learning algorithm for estimating the state of object handovers in human-robot interaction scenarios.
  - *“I Robot... and Beyond” Summer Research Project* 2010  
Investigated safety and liveness properties rooted in design verification principles for a human-robot interaction system [1].

## Skills

- Programming languages: Python, R, Matlab, Java, C++, HTML, PHP, CSS, LaTeX
- Libraries: PyTorch, TensorFlow, NumPy, Brown-UMBC Reinforcement Learning and Planning (BURLAP)
- Software/IDEs: Git, PyCharm, Eclipse, Visual Studio, NetBeans, Xcode
- Robotics/hardware platforms: Baxter, Keepon, Nao, ROS, YARP, PhaseSpace Motion Capture System

## Academic Service and Membership

- Conference and Workshop Committee Leadership
  - AAAI Conference on Artificial Intelligence  
Program Committee Member 2020 – 2021
  - International Conference on Intelligent Virtual Agents  
Program Committee Member 2017 – 2020
  - ACM/IEEE International Conference on Human-Robot Interaction  
Program Committee Member 2017
  - IEEE/RSJ International Conference on Intelligent Robots and Systems  
Synergies Between Learning and Interaction (SBLI) Workshop  
Program Committee Member 2017
  - ACM/IEEE International Conference on Human-Robot Interaction  
Pioneers Workshop Panel Chair 2017
- Conference Refereeing service
  - International Conference on Machine Learning 2019
  - ACM/IEEE International Conference on Human-Robot Interaction 2015 – 2019
  - IEEE/RSJ International Conference on Robotics and Automation 2018
  - Springer International Journal of Social Robotics 2018
  - IEEE/RSJ International Conference on Intelligent Robots and Systems 2014, 2017 – 2018
  - ACM/IEEE Interaction Design and Children Conference 2018
  - IEEE-RAS International Conference on Humanoid Robots 2017

- IEEE Transactions on Automation Science and Engineering 2017
- IEEE/RSJ International Conference on Intelligent Robots and Systems 2017
- International Conference on Social Robotics 2016
- IEEE International Symposium on Robot and Human Interactive Communication 2016
- Elsevier Cognitive Systems Research Journal 2016
- Affective Computing and Intelligent Interaction 2015
- Membership in Professional Societies
  - Association for the Advancement of Artificial Intelligence 2014 – present
  - IEEE 2014 – present
  - Cognitive Science Society 2014 – present
- Outreach
  - World Science Festival, New York City 2014
  - Routine lab tours and open houses, Yale Social Robotics Lab, CT 2012 – present
  - Routine outreach activities involving robot demos at local schools, CT 2012 – present
- Book Reviewing
  - *Visual Analysis of Behaviour – From Pixels to Semantics*, by Gong S, Xiang T 2012

## Teaching Experience and Mentorship

- Mentoring students on internship research projects at Motional 2018 – present
- Mentoring high-school and undergraduate students on research projects 2013 – 2018
- Teaching Fellow (at Yale University, USA)
  - Natural Language Processing (CPSC 577) 2017
  - Mathematical Tools for Computer Science (CPSC 202A) 2014 – 2015
  - Intelligent Robotics (CPSC 473) 2013 – 2015
  - Intelligent Robotics Lab (CPSC 472) 2013
- Point of contact for incoming Romanian students, University of Bristol, UK 2009 – 2012
- Mathematics student-teacher at Sydney Stringer School, Coventry, UK  
Students Associates Scheme 2009
- Course Representative, Coventry University, Coventry, UK  
Speaking on behalf of the student body 2008 – 2009

## Conferences and Summer Schools Attended

- IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)  
Attended conference for accepted paper 2020
- IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)  
Presented talk for accepted paper 2018
- International Conference on Autonomous Agents and Multiagent Systems (AAMAS)  
Presented talk for accepted paper 2018
- Robotics: Science and Systems  
Presented talk for accepted paper (RSS) 2017

- ACM/IEEE International Conference on Human-Robot Interaction (HRI)  
Organized and moderated the Pioneers Workshop Panel 2016
- Annual Conference on Neural Information Processing Systems (NIPS)  
Presented talk for workshop full paper 2016
- International Conference on Intelligent Virtual Agents (IVA)  
Presented paper for best paper finalist category 2016
- International Conference on Social Robotics (ICSR)  
Presented paper for best student paper finalist category 2016
- International Conference on Machine Learning (ICML) 2016
- International Joint Conference on Artificial Intelligence (IJCAI) 2016
- AAAI Fall Symposium Series  
Presented talk for accepted paper 2015
- Max Planck Institute for Intelligent Systems Machine Learning Summer School, Germany  
(**20% acceptance rate**) 2015
- International Conference on User Modelling, Adaptation and Personalization (UMAP)  
Presented talk for accepted paper 2015
- ACM/IEEE International Conference on Human-Robot Interaction (HRI)  
Presented talk for accepted paper 2015
- AAAI Conference on Artificial Intelligence (AAAI)  
Presented robot demo 2014
- Cognitive Science Society Annual Conference (CogSci)  
Presented robot demo 2014
- IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)  
Presented talk for accepted paper and invited talk for the DevSor Workshop 2013
- The First Summer School on Social Human-Robot Interaction, UK 2013
- Conference Towards Autonomous Robotic Systems (TAROS)  
Presented talk for accepted paper 2011

## Languages

- Romanian – native language
- English – fluent: written and spoken
- Spanish – conversational: spoken
- French – basic: written and spoken