

Connected Embedded Rust

A Survey of system software and network stacks in Rust

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Embedded Rust

Rust Programming Language Hardware Abstraction Asynchronous Code

Survey of System Software Concurrency Frameworks

Tock Hubris

Networking stacks smoltcp Hubris' usage of smoltcp Tock's Network Stack



Embedded Rust Rust Programming Language

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Rust Programming Language



- Popular Alternative to C for low-level Systems Programming
- ► Focus on Reliability and Performance
- Compiler enforced Memory, Thread and Type Safety

Ownership and Mutability

C:

```
struct item {
    int n;
};
void inc_if_zero(struct item *var) {
  if (var->n == 0) {
    var->n += 1:
void foo(void) {
  struct item var = { n: 0 };
  struct item *ref1 = &var:
  struct item *ref2 = &var;
  create_thread(inc_if_zero, ref1):
  create_thread(inc_if_zero, ref2);
  return;
```

```
struct item {
    int n:
};
void inc_if_zero(struct item *var) {
  if (var->n == 0) {
    var->n += 1:
void foo(void) {
  struct item var = { n: 0 };
  struct item *ref1 = &var:
  struct item *ref2 = &var:
  create_thread(inc_if_zero, ref1):
  create_thread(inc_if_zero, ref2);
  return;
```

```
struct Item {
  n: u8
fn inc_if_zero(var: &Item) {
  if var.n == 0 {
    var.n += 1:
fn foo() {
  let var = Item { n: 0 };
  let ref1 = &var:
  let ref2 = &var;
  thread::spawn(move || inc_if_zero(ref1)):
  thread::spawn(move || inc_if_zero(ref2));
```



```
struct item {
                                                    struct Item {
    int n:
                                                      n: 118
};
void inc_if_zero(struct item *var) {
                                                    fn inc_if_zero(var: &Item) {
  if (var->n == 0) {
                                                      if var.n == 0 {
    var->n += 1:
                                                        var.n += 1:
void foo(void) {
                                                    fn foo() {
  struct item var = { n: 0 };
                                                      let var = Item { n: 0 };
  struct item *ref1 = &var:
                                                      let ref1 = &var:
  struct item *ref2 = &var:
                                                      let ref2 = &var:
  create_thread(inc_if_zero, ref1);
                                                      thread::spawn(move || inc_if_zero(ref1)):
  create_thread(inc_if_zero, ref2);
                                                      thread::spawn(move || inc_if_zero(ref2));
  return;
           error[E0594]: cannot assign to 'item.n', which is behind a '&' reference
          -> src/main.rs:7:9
             fn increase if zero(var: &Item) {
                                     --- help: consider changing this to be a mutable reference: '&mut Item'
          6
                 if var.n == 0 {
          7
                    var.n += 1:
                    ^^^^^^^ 'var' is a '&' reference, so the data it refers to cannot be written
```

```
struct item {
    int n:
};
void inc_if_zero(struct item *var) {
  if (var->n == 0) {
    var->n += 1:
void foo(void) {
  struct item var = { n: 0 };
  struct item *ref1 = &var:
  struct item *ref2 = &var:
  create_thread(inc_if_zero, ref1):
  create_thread(inc_if_zero, ref2);
  return;
```

```
struct Item {
  n: u8
fn inc_if_zero(var: &mut Item) {
  if var.n == 0 {
    var.n += 1:
fn foo() {
  let mut var = Item { n: 0 };
  let ref1 = &mut var:
  let ref2 = &mut var;
  thread::spawn(move || inc_if_zero(ref1)):
  thread::spawn(move || inc_if_zero(ref2));
```



struct item { int n: }; void inc_if_zero(struct item *var) { if (var->n == 0) { var->n += 1: void foo(void) { struct item var = { n: 0 }; struct item *ref1 = &var: struct item *ref2 = &var: create_thread(inc_if_zero, ref1): create_thread(inc_if_zero, ref2); return; error[E0499]: cannot borrow 'var' as mutable more than once at a time -> src/main.rs:17:16 16 let ref1 = &mut var:

let ref2 = &mut var:

Rust:

```
struct Item {
                     n: 118
                   fn inc_if_zero(var: &mut Item) {
                     if var.n == 0 {
                       var.n += 1:
                   fn foo() {
                     let mut var = Item { n: 0 };
                     let ref1 = &mut var:
                     let ref2 = &mut var:
                     thread::spawn(move || inc_if_zero(ref1)):
                     thread::spawn(move || inc_if_zero(ref2));
----- first mutable borrow occurs here
```

17



```
struct item {
    int n:
};
void inc_if_zero(struct item *var) {
  if (var->n == 0) {
    var->n += 1:
void foo(void) {
  struct item var = { n: 0 };
  struct item *ref1 = &var:
  struct item *ref2 = &var:
  create_thread(inc_if_zero, ref1):
  create_thread(inc_if_zero, ref2);
  return:
```

```
struct Item {
  n: u8
fn inc_if_zero(var: Mutex<Item>) {
  let mut var = var.lock().unwrap());
  if var.n == 0 {
    var.n += 1:
fn foo() {
  let var = Mutex::new(Item { n: 0 });
  let ref1 = &var:
  let ref2 = &var:
  thread::spawn(move || inc_if_zero(ref1)):
  thread::spawn(move || inc_if_zero(ref2));
```



```
pub trait Write <Word> {
    type Error;
    fn write(&mut self, word: Word) -> Result<(), Self::Error>;
    fn flush(&mut self) -> Result<(), Self::Error>;
fn write_all<S>(
  serial: &mut S,
  buffer: &[u8]
) -> Result<(), S::Error>
where
    S: Write<u8>
{
    for &byte in buffer {
        block!(serial.write(byte))?;
    0k(())
[5]
```



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Rust Programming Language Hardware Abstraction

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Hardware Abstraction Layers

Micro-architecture Layer:

- Processor-specific logic
- ▶ Processor calls, timer management, interrupt handling, ...
- ► Example: ARM Cortex-M Processors



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Peripheral Access Layer:

- Provide access to a chips memory-mapped registers and periphery
- ► GPIO, SPI, I2C, UART, ..
- Example: Nordic Conductor nRF52805 SoC



Micro-architecture Layer:

- Processor-specific logic
- Processor calls, timer management, interrupt handling, ...
- ► Example: ARM Cortex-M Processors

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- Provide access to a chips memory-mapped registers and periphery
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Board Layer:

- Configure underlying layers for one concrete Board
- ▶ Abstracts Hardware details, configures periphery &assigns drivers, ...
- Example: STM32 Nucleo-32 Board



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Asynchronous Code

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Challenge:

- Embedded Systems do a lot of I/O
- ► I/O is asynchronous => result not immediately available
- ▶ Program execution should continue with other work in the meantime



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- Embedded Systems do a lot of I/O
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```
pub enum Poll<T> {
    Ready(T),
    Pending,
}

pub trait Future {
    type Output;
    fn poll(...) -> Poll<Self::Output>;
}
```



Challenge:

- Embedded Systems do a lot of I/O
- ► I/O is asynchronous => result not immediately available
- ▶ Program execution should continue with other work in the meantime

```
pub enum Poll<T> {
    Ready(T),
    Pending,
}

pub trait Future {
    type Output;
    fn poll(...) -> Poll<Self::Output>;
}
```

- The await keyword allows blocking the current execution until a Future is ready
- Functions that use await themselves become a Future and must be annotated as async



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Embassy and RTIC



▶ Embedded platforms for apps with concurrent units of execution

Embassy:

```
#[embassv::task]
asvnc fn blink(pin: AnvPin) {
  let mut led = Output::new(pin.Level::Low.
    OutputDrive::Standard):
  loop {
    led.set_high():
    Timer::after(Duration::from_millis(150)).await:
    led.set_low():
    Timer::after(Duration::from_millis(150)).await:
#[embassv::main]
async fn main(spawner: Spawner, p: Peripherals) {
  spawner.spawn(blink(p.P0_13.degrade())).unwrap()
  loop { }
[2]
```

RTIC:

```
#[app(...)]
mod app {
  #[shared]
  struct Shared {}
  #[local]
  struct Local {
    led: PA5<Output<PushPull».
  #[init]
  fn init(_: init::Context) -> (Shared, Local) {
    // Setup RCC and timer
    // Setup LED
    let led = ...
    blink::spawn().ok():
    (Shared {}, Local { led })
  #[task(local = [led])]
  async fn blink(cx: blink::Context) {
    // blink led
[3]
```



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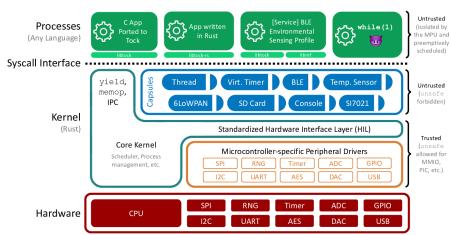
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- ► Goal: enable secure multi-programming on embedded system
- Monolithic kernel: units sand-boxed via Rust type system
- Supports dynamic loading of processes and memory management
- ▶ IPC implemented as Client-Server communication
- Own Hardware Interface-Layer

Tock Architecture





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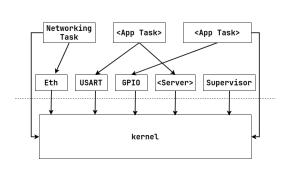
Hubris Operating System

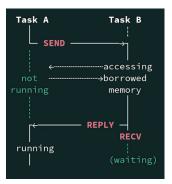


- Very small hubris kernel + collection of tasks
- ► Tasks: Separately-compiled Programs & Drivers
 - Unprivileged processor mode
 - Isolated in memory
 - No dynamic creation of tasks; fixed priorities
- "Aggressively static" for all allocatable or routable resources
- Synchronous IPC: Sender is blocked until receiver responded

Hubris Architecture







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Sockets

- Supported: raw Sockets, ICMP, UDP and TCP
- ▶ Implementation of socket logic: buffering, packet construction, ...
- Sans-IO: no actual I/O done by the socket

Device trait

- Methods for interacting with the actual device
- User-provided

Interfaces

- Supported: Ethernet, IP, IEEE 802.15.4 + 6LoWPAN
- Takes care of physical addressing, neighbour discovery, sending of control packets
- Implemented as state-machine



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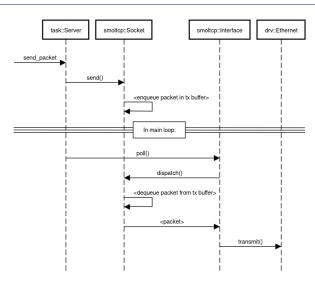
smoltcp

Hubris' usage of smoltcp

Tock's Network Stack

Sending a packet in Hubris







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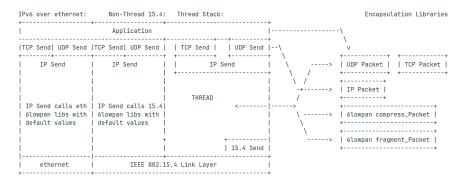
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Tock's Network Stack





[4]



- Rust offers powerful primitives for building secure and reliable low-level systems
- ► The type system can be leveraged in very different designs



- [1] Cliff L. Biffle. On Hubris and Humility: developing an OS for robustness in Rust.
- https://talks.osfc.io/osfc2021/talk/JTWYEH/. Nov. 2021.
- [2] Embassy. https://github.com/embassy-rs/embassy. June 2023.
- [3] Real-Time Interrupt-driven Concurrency (RTIC). https://github.com/rtic-rs/rtic. June 2023.
- [4] *Tock*. https://github.com/tock/tock. June 2023.
- [5] embedded-hal. https://crates.io/crates/embedded-hal. v0.2.7.