

Intro to Neural Networks

BA865 – Mohannad Elhamod

CNNs

Convolutional Networks

A Problem of Scalability

- How many parameters in this network?
- Do we really need to learn all these parameters?

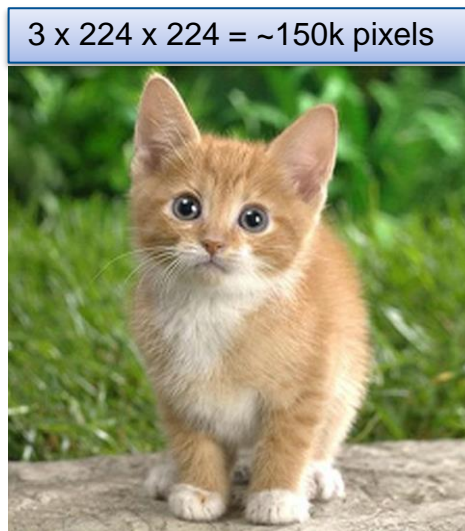


Figure courtesy of Robert Bond

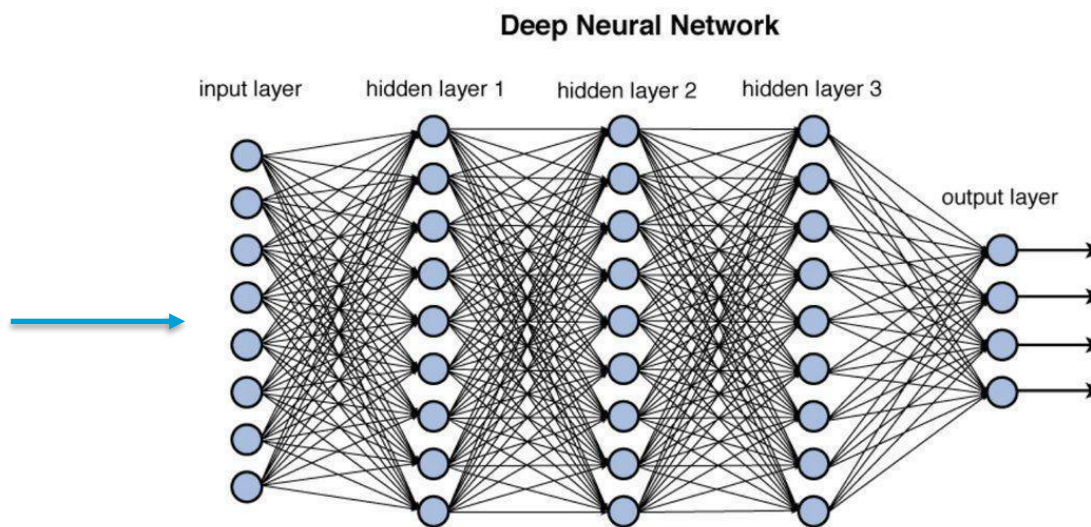


Figure 12.2 Deep network architecture with multiple layers.

Figure courtesy of Ravindra Pamar

Structure in Images

- Interesting images have:
 - Locality of information.
 - Spatial invariance.



Figure courtesy of Robert Brad

vs.

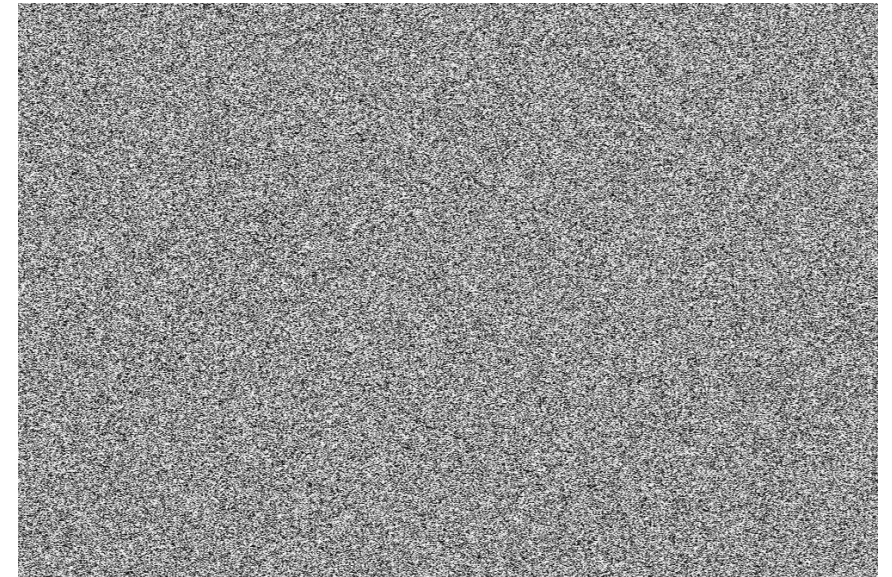


Figure courtesy of Jorge Stolfi

Convolutional Filters

- Instead of learning a mesh of all possible parameters, let's learn local descriptors (kernels or filters) that can be reused across the image!

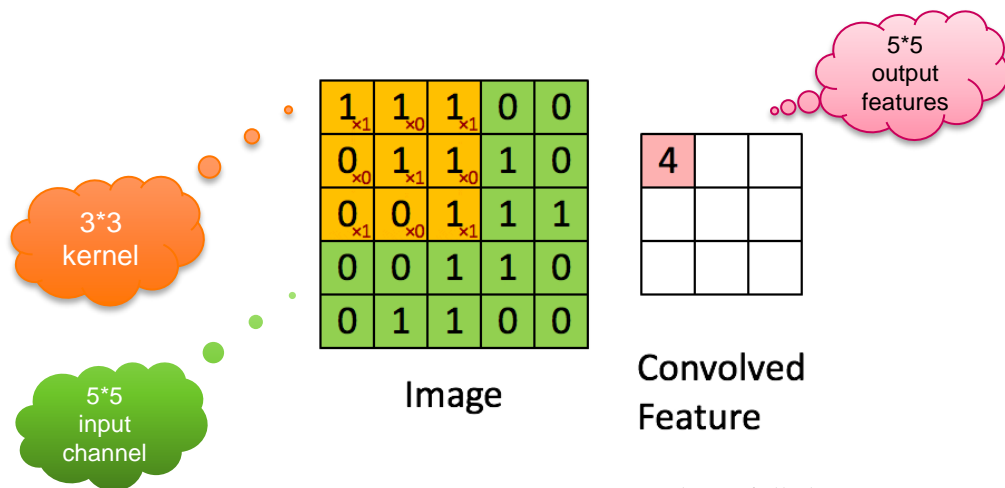


Figure courtesy of Daniel Nouri

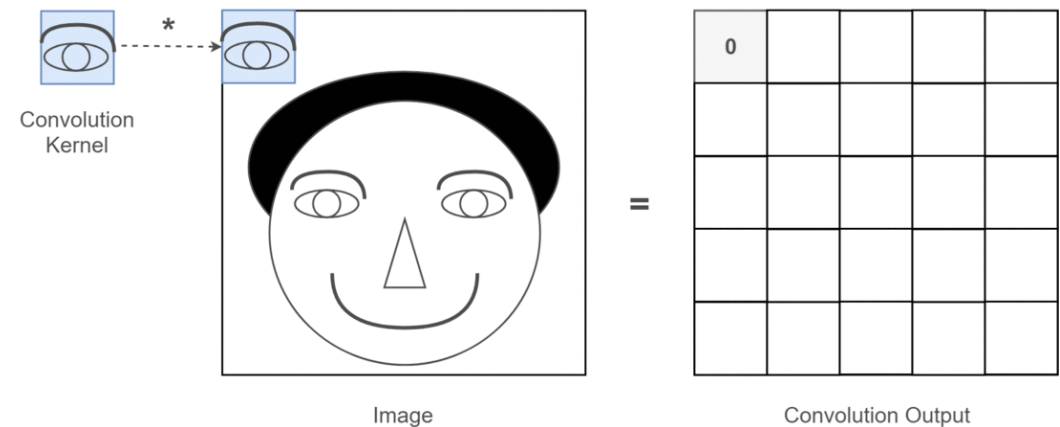
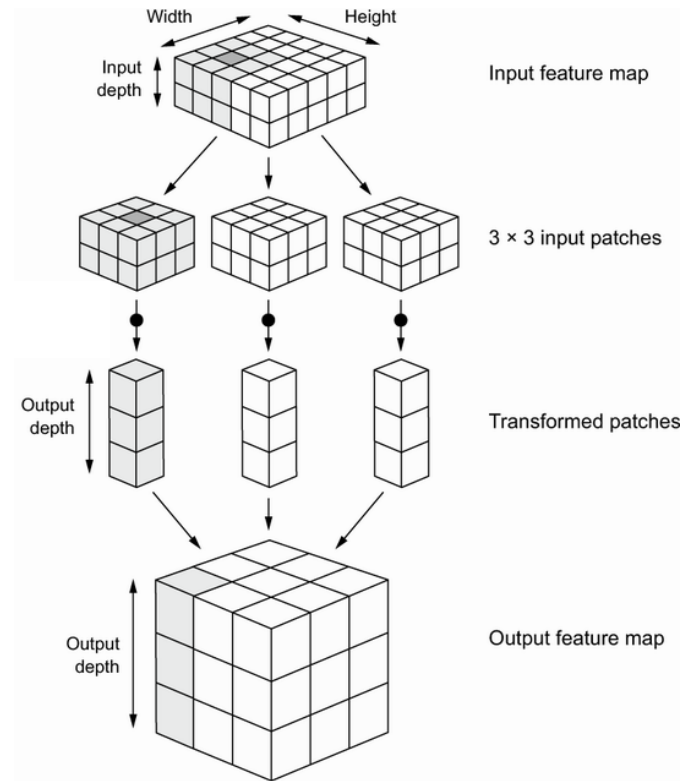


Figure courtesy of Thushan Ganegodara

Mathematically Speaking...

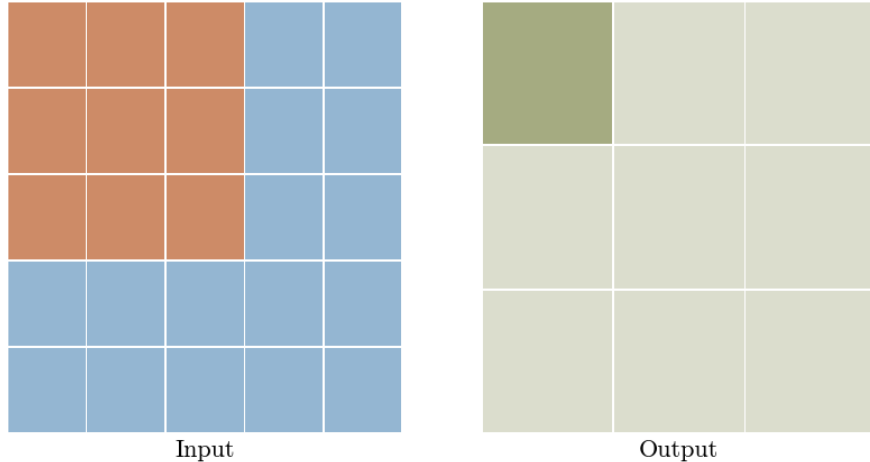


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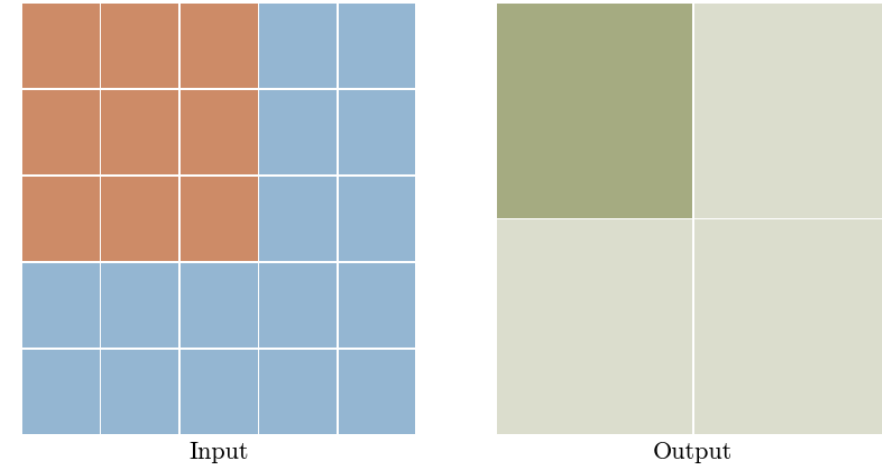
Stride and Padding

- Stride controls feature field overlap.
- Padding controls the down-sampling.

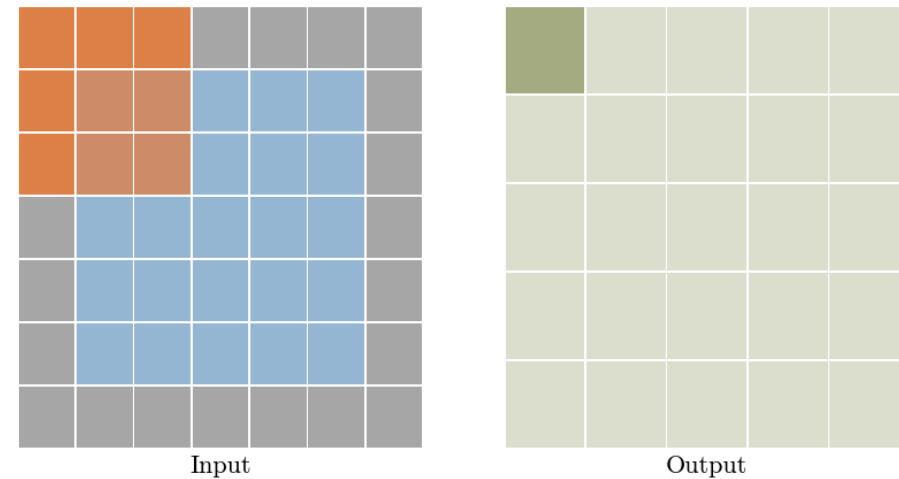
Type: conv - Stride: 1 Padding: 0



Type: conv - Stride: 2 Padding: 0



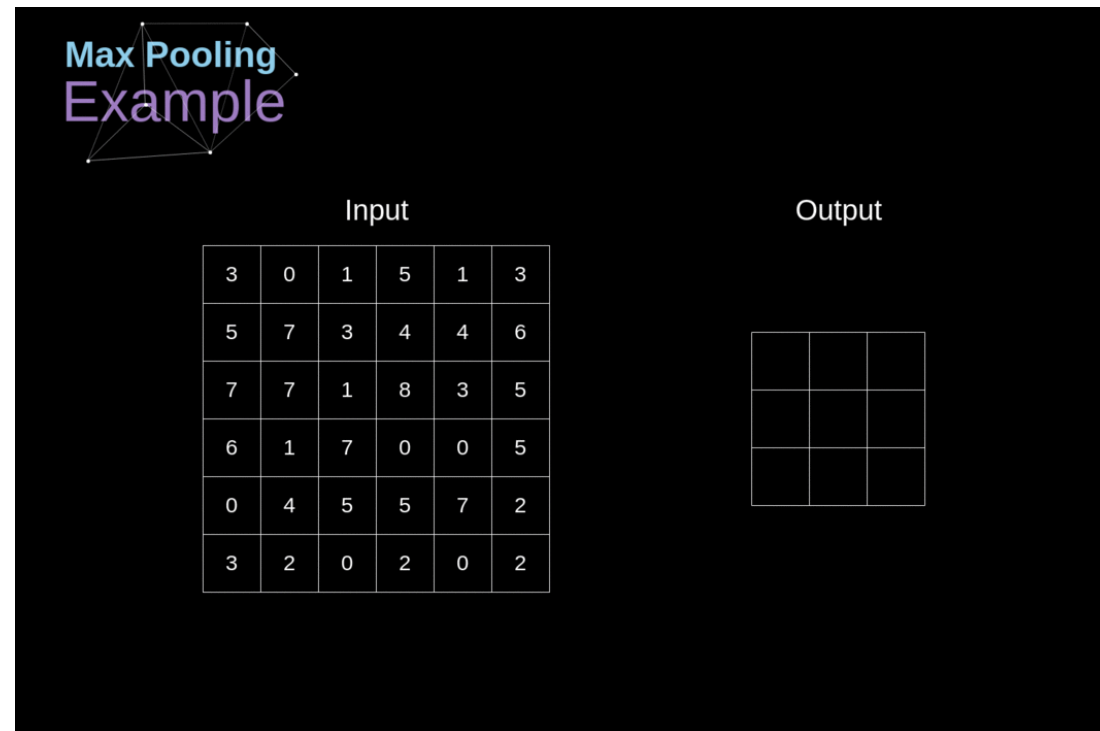
Type: conv - Stride: 1 Padding: 1



[Aqeel Anwar](#)

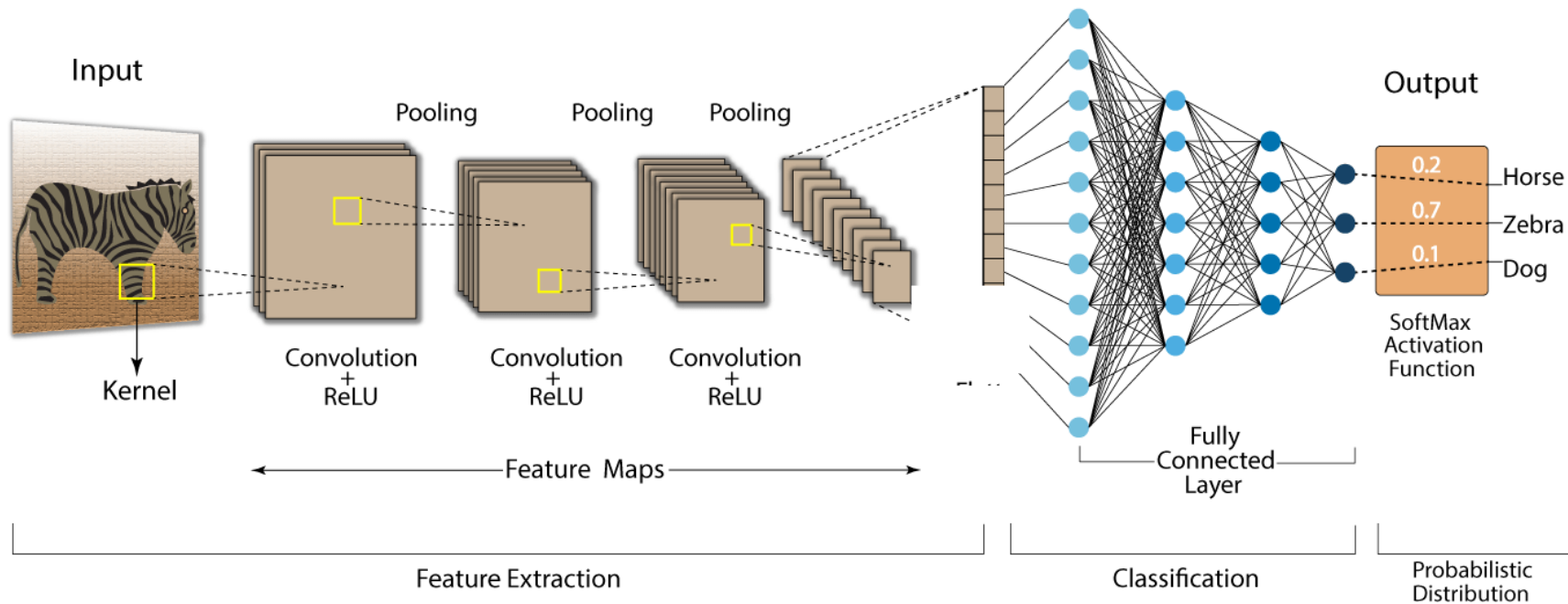
Non-Linearity: MaxPooling

- In addition to being a non-linearity...
 - it helps down-sample the image.
 - It helps summarize information in terms of larger blocks.



Putting It All Together

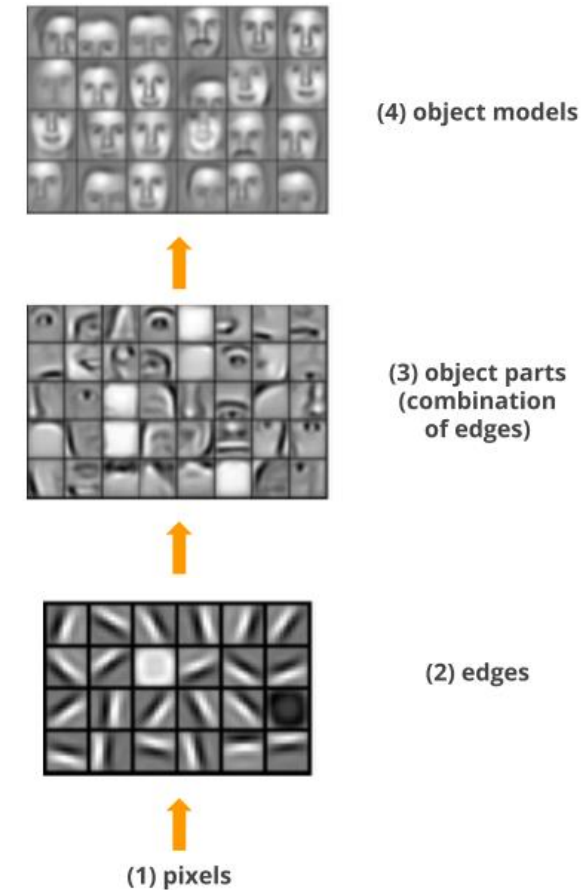
- Deeper layers generally have more kernels that are smaller.



[Afaq Umer](#)

Learned Features

- Early layers learn low-level features.
 - spots, edges, etc.
- Later layers learn to detect high-level features as a combination of low-level features.
 - Eyes, ears, hair, etc.
- [Demo](#)



<https://micro-dimensions.com>

Hyper-Parameters

Continued...

Batch Normalization

- Even if input data is properly normalized, the gradient in subsequent layers may vanish or explode.
- For that, you may add “batch normalization” at every layer.

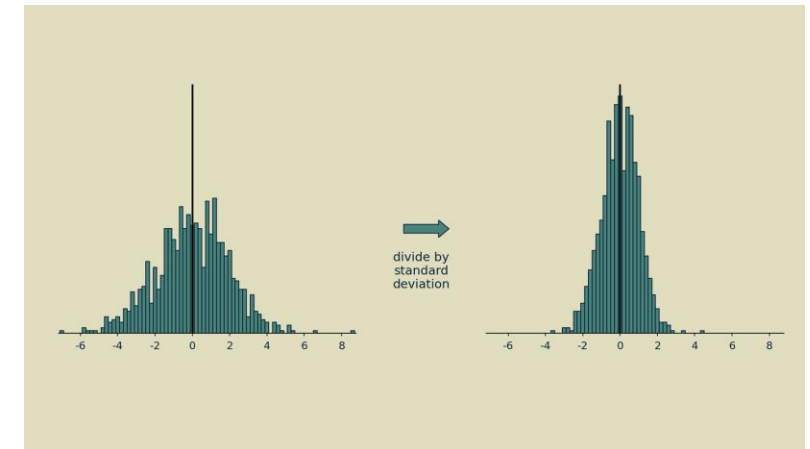
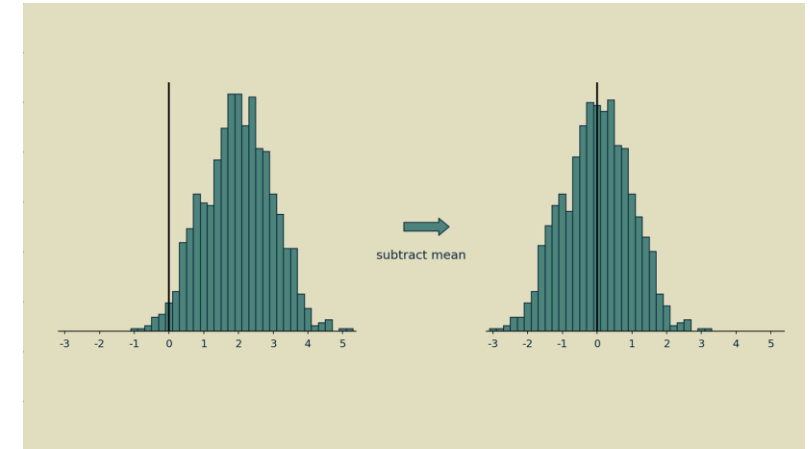


Figure courtesy of Brandon Rohrer

Learning Rate: Schedulers

- Since larger learning rates may converge faster but smaller ones are more stable, you could adjust the learning rate in phases to get the best of both worlds!
 - This way, you still converge but faster.
- Using a scheduler is a common practice.

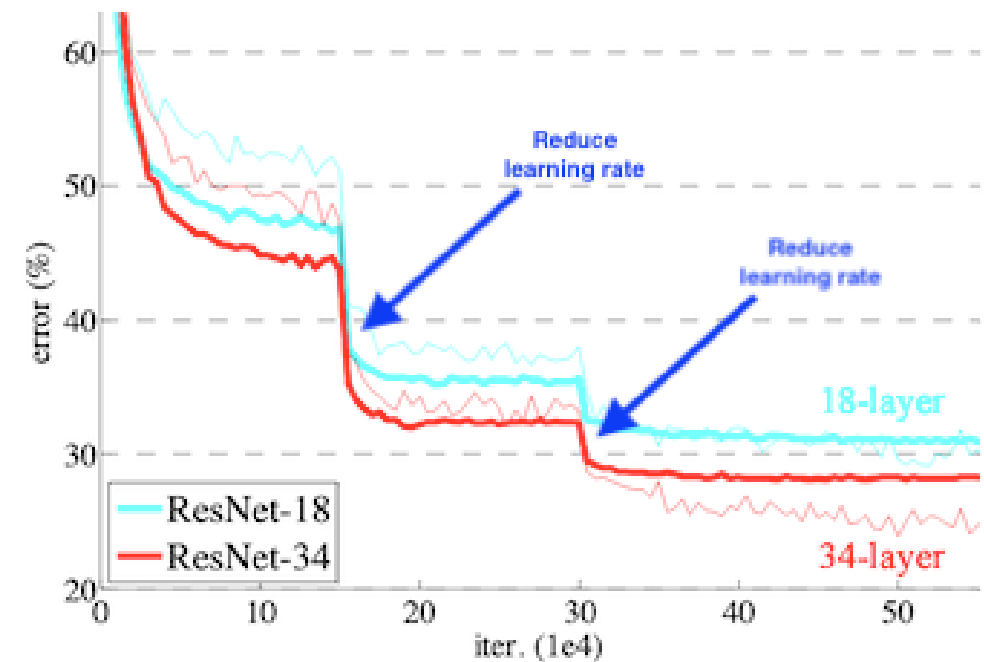


Figure courtesy of [B. D. Hammel](#)

Hyper- Parameter Tuning

Be Smart About It

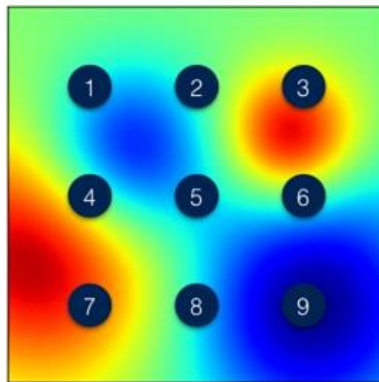
- It is expensive!
 - 1 hyper-parameter with 3 values → 3 experiments
 - 2 hyper-parameter with 3 values each → 9 experiments
 - 3 hyper-parameter with 3 values each → 27 experiments
 - ... exponential growth!

Be Smart About It

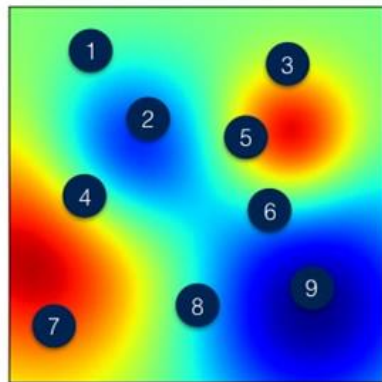
- It is expensive!
- Start with generally accepted wisdom:
 - Start with good initial guesses.
 - Different settings work better for different models/problems (e.g., SGD + momentum for computer vision vs. Adam otherwise)
- Be picky about what to fine-tune.
 - Use early stopping.
 - Learning rate is the most important parameter!

Hyper-Parameter Tuning Methods

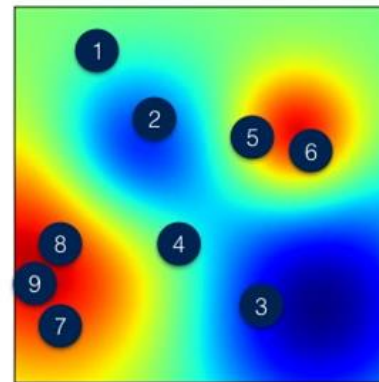
- Generally, use log-scale for numerical hyper-parameters.
- Random and Adaptive searches generally find optimal values faster than grid searches.



Grid Search



Random Search



Adaptive Selection

Figure courtesy of Liam Li