EPISEN – ING3. SI Machine Learning



Abdallah EL HIDALI

Tech Lead Sita For Aircraft abdallah.el-hidali@sita.aero

EPISEN

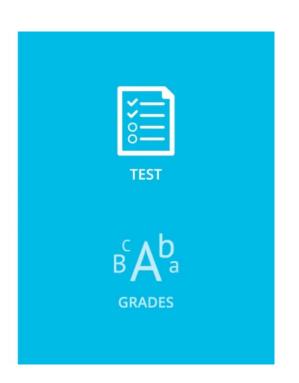
2024/2025



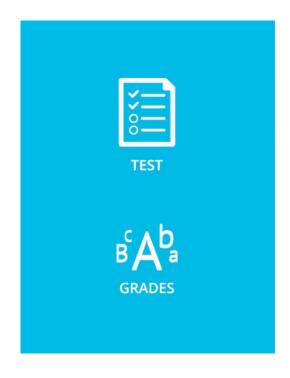
III. La classification

Acceptance at a University











STUDENT 1 Test: 9/10 Grades: 8/10

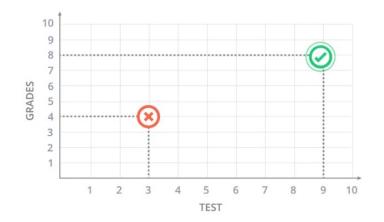


STUDENT 2 Test: 3/10 Grades: 4/10



STUDENT 3 Test: 7/10 Grades: 6/10





On analyse ensuite les données historiques





Acceptance at a University



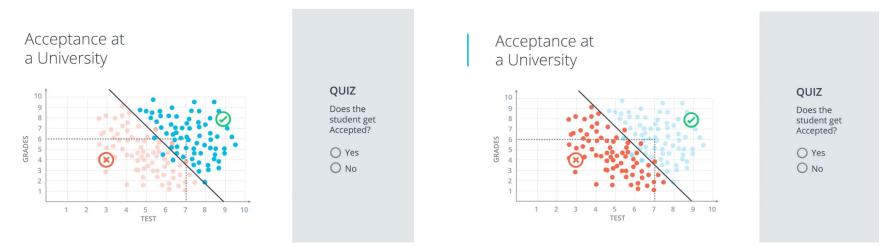
QUIZ

Does the student get Accepted?

O Yes

O No





Dans notre modèle de classification binaire (régression logistique) :

- La droite représente la frontière de décision.
- Les points au-dessus de la droite sont classés comme positifs (étudiants acceptés).
- Les points en dessous de la droite sont classés comme négatifs (étudiants rejetés).

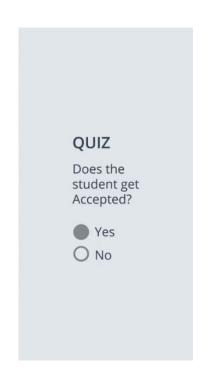
Cette droite est notre modèle de décision. Elle détermine si un étudiant est accepté ou non en fonction de sa position dans l'espace.

SITA

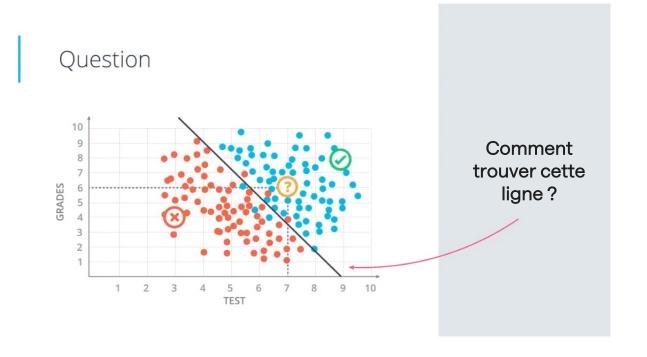
La distance d'un point à la droite indique le degré de confiance du modèle dans sa décision.

Acceptance at a University









Acceptance at a University



BOUNDARY:

A LINE

$$2x_1 + x_2 - 18 = 0$$

2*Test + Grades - 18

PREDICTION:

Score > 0: Accept

Score < 0: Reject

Acceptance at a University



BOUNDARY:

A LINE

 $W_1X_1 + W_2X_2 + b = 0$ Wx + b = 0

 $W = (W_1, W_2)$

 $x = (x_1, x_2)$

y = label: 0 or 1

PREDICTION:

$$\hat{y} = \begin{cases} 1 \text{ if } Wx + b \ge 0 \\ 0 \text{ if } Wx + b < 0 \end{cases}$$

La classification – dimensions > 2

Acceptance at a University

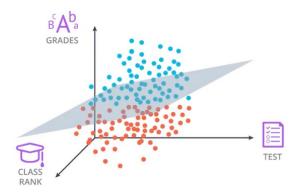






La classification – dimensions > 2

Acceptance at a University



BOUNDARY:

A PLANE

$$W_1X_1 + W_2X_2 + W_3X_3 + b = 0$$

 $Wx + b = 0$

PREDICTION:

$$\hat{y} = \begin{cases} 1 \text{ if } Wx + b \ge 0 \\ 0 \text{ if } Wx + b < 0 \end{cases}$$

La classification – dimensions > 2

Acceptance at a University

	X ₁	X ₂	X ₃	X _n	У
	EXAM 1	EXAM 2	GRADES	ESSAY	PASS?
STUDENT 1	9	6	5	 6	1(yes)
STUDENT 2	8	4	8	 3	0(no)
STUDENT N	6	7	2	 8	1(yes)
	4	n	columns		

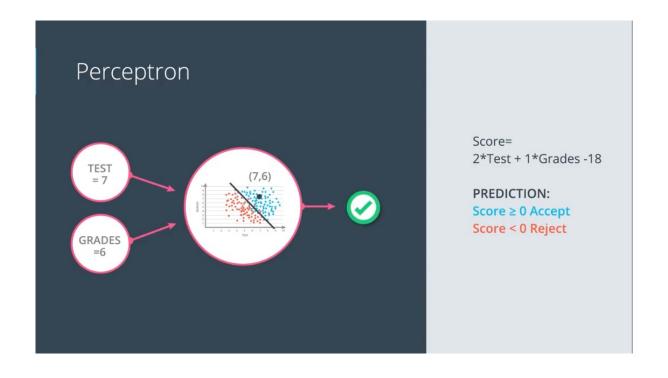
n-dimensional space $x_1, x_2,...,x_n$

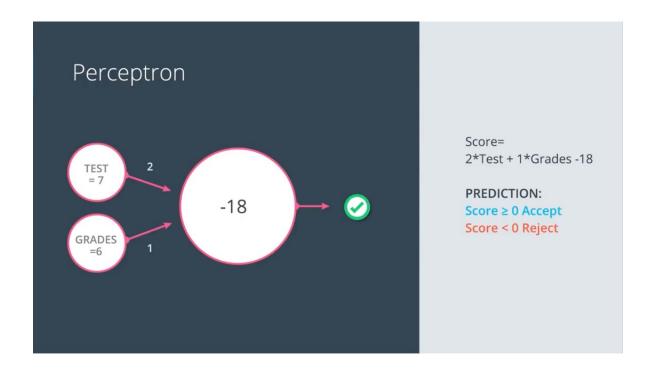
BOUNDARY:

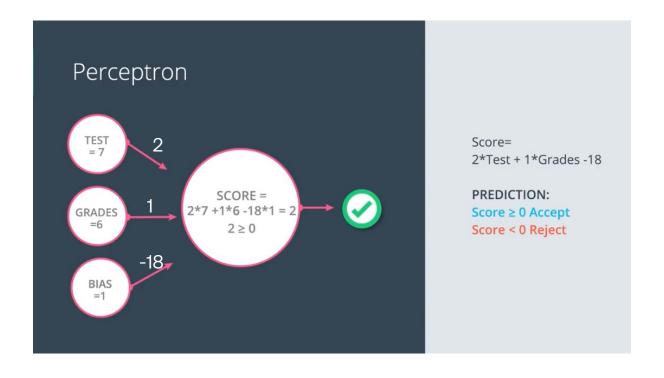
n-1 dimensional hyperplane $w_1x_1 + w_2x_2 + w_nx_n + b = 0$ Wx + b = 0

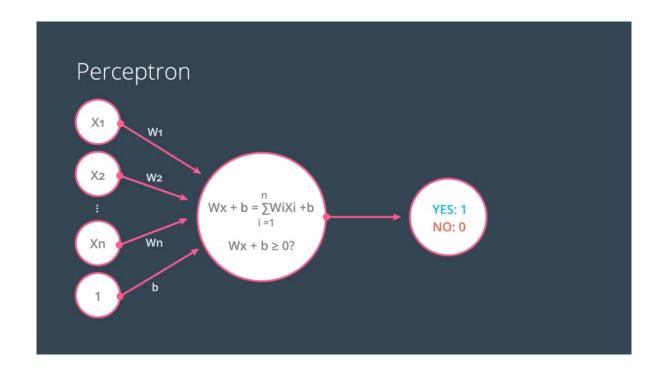
PREDICTION:

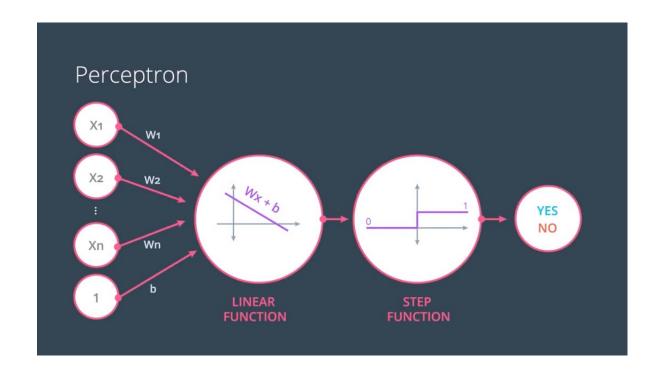
$$\hat{y} = \begin{cases} 1 \text{ if } Wx + b \ge 0 \\ 0 \text{ if } Wx + b < 0 \end{cases}$$





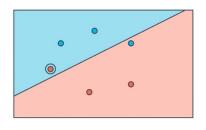




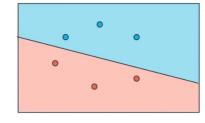


Algorithme du Perceptron

Perceptron Algorithm



Perceptron Algorithm



Start with random weights: w₁, ..., w_n, b
 For every misclassified point (x₁,...,x_n):
 If prediction = 0:

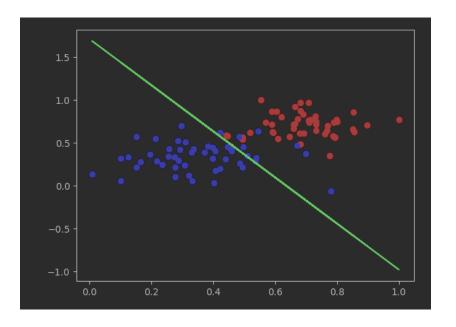
 For i = 1 ...n
 Change w_i + α x_i
 Change b to b + α

 If prediction = 1:

 For i = 1 ...n
 Change w_i - α x_i
 Change b to b - α

Algorithme du Perceptron - Exercice

```
import numpy as np
# Setting the random seed, feel free to change it and see different solutions.
np.random.seed(42)
def stepFunction(t):
   if t >= 0:
        return 1
    return 0
def prediction(X, W, b):
    return stepFunction((np.matmul(X,W)+b)[0])
# TODO: Fill in the code below to implement the perceptron trick.
# The function should receive as inputs the data X, the labels y,
# the weights W (as an array), and the bias b,
# update the weights and bias W, b, according to the perceptron algorithm,
# and return W and b.
def perceptronStep(X, y, W, b, learn_rate = 0.01):
   # Fill in code
    return W, b
# This function runs the perceptron algorithm repeatedly on the dataset,
# and returns a few of the boundary lines obtained in the iterations,
# for plotting purposes.
# Feel free to play with the learning rate and the num_epochs,
# and see your results plotted below.
def trainPerceptronAlgorithm(X, y, learn_rate = 0.01, num_epochs = 25):
    x_min, x_max = min(X.T[0]), max(X.T[0])
    y_min, y_max = min(X.T[1]), max(X.T[1])
    W = np.array(np.random.rand(2,1))
    b = np.random.rand(1)[0] + x_max
    # These are the solution lines that get plotted below.
    boundary_lines = []
    for i in range(num_epochs):
        # In each epoch, we apply the perceptron step.
        W, b = perceptronStep(X, y, W, b, learn_rate)
        boundary_lines.append((-W[0]/W[1], -b/W[1]))
     return boundary lines
```



https://github.com/elhidali/EPISEN-2024