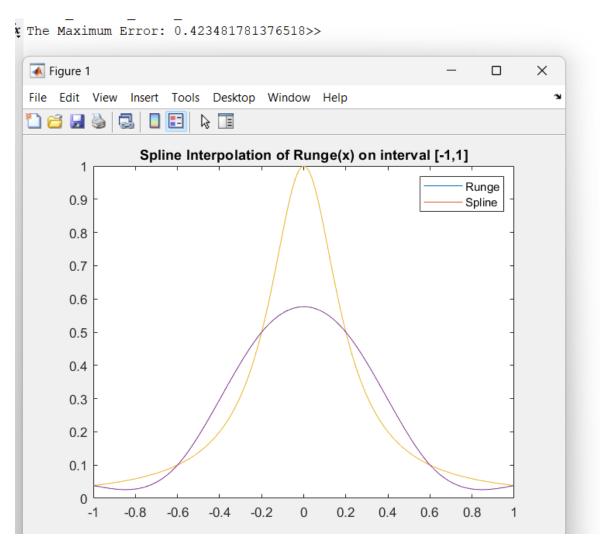
Problem 1.

(a-f) Initially using 5 knots to generate the spline, the maximum error of the spline approximation of the Runge function was .42



Increasing the number of knots to n=4,8,16,32,64..., we observe:

```
>> P1_Natural_Cubic_Spline

For n = 4, error = 0.279311381158094

For n = 8, error = 0.056073644925168, convergence rate = 5.0

For n = 16, error = 0.003710967584725, convergence rate = 15.1

For n = 32, error = 0.000637335632232, convergence rate = 5.8

For n = 64, error = 0.000036066324368, convergence rate = 17.7

For n = 128, error = 0.0000002053431999, convergence rate = 17.6

For n = 256, error = 0.000000159303183, convergence rate = 12.9

For n = 512, error = 0.000000000000331312, convergence rate = 16.5

For n = 1024, error = 0.0000000000331312, convergence rate = 29.2

For n = 2048, error = 0.000000000033131, convergence rate = 10.9

For n = 4096, error = 0.000000000000131, convergence rate = 14.2
```

The spline appears to converge quadratically to the runge function, as each time the size of the intervals are halfed, the error is atleast 4x smaller. The spline s appears to converge to f, and this agrees with the theoretical result that splines can converge to f.

Code:

```
P1_Natural_Cubic_Spline.m × +
1
          % Goal: Create a cubic spline that interpolate a function (Runge)
         % (0) Set up the interpolation problem
          \% (0.1) Sample the Runge function at (t_0,y_0)...(t_n,y_n)
5
          for n=2.^(2:14)
6
              t = linspace(-1, 1, n+1);
              y = arrayfun(@Runge, t);
8
              % (1) Compute spline coefficients
z = Spline_Coef(n, t, y);
9
10
11
12
              % (2) Evaluate the spline
              m = 200;
14
              X = linspace(-1, 1, m+1);
15
              Y_Runge = arrayfun(@Runge, X);
              Y_{\text{spline}} = \operatorname{arrayfun}(@(x) \operatorname{Spline}_{\text{Eval}}(x, n, t, y, z), X);
16
17
              % (3) Printout
18
19
              plot(X, Y_Runge)
20
              hold on
21
              plot(X, Y_Spline)
22
              hold on
              legend('Runge','Spline')
title("Spline Interpolation of Runge(x) on interval [-1,1]")
23
24
25
26
               error = max(abs(Y_Runge-Y_Spline));
27
                  fprintf("For n = %i, error = %.15f\n", n, error)
28
29
               else
30
                   fprintf("For n = %i, error = %.15f, convergence rate = %3.1f\n", n, error, prev_error/error)
31
32
              prev_error = error;
33
```

```
% Function Definitions
function sum = Spline_Eval(x, n, t, y, z)
for i=n:-1:1
   if x - t(i) >= 0
       break
   end
h = t(i+1) - t(i);
sum = z(i+1)/(6*h) * (x - t(i))^3 ...
  + z(i)/(6*h) * (t(i+1) - x)^3 + ...
          (y(i+1) / h - h/6 *z(i+1))*(x-t(i)) + (y(i) / h - h/6 * z(i)) *(t(i+1) - x);
function z = Spline_Coef(n, t, y)
   for i=1:n
      h(i) = t(i+1) - t(i);
                                    % Length of ith interval
       b(i) = (y(i+1) - y(i))/h(i); % Average slope in ith interval
   u(2) = 2 * (h(1) + h(2));
    v(2) = 6 * (b(2)-b(1));
    for i=3:n
      u(i) = 2 * (h(i) + h(i-1)) - h(i-1)^2/u(i-1);
       v(i) = 6 * (b(i) - b(i-1)) - h(i-1)*v(i-1) / u(i-1);
    z(n+1) = 0;
    z(1) = 0;
    for i = n:-1:2
      z(i) = (v(i) - h(i) * z(i+1)) / u(i);
function y = Runge(x)
y = 1/(1 + 25*x^2);
end
```

Problem 2