## **Homework 7 (due Friday Nov 11)**

#### introduce Q1 today (will introduce Q2 on Thu)

This assignment asks you to create multi-layer networks that learn to classify images of clothing. Fashion-MNIST is a dataset of clothing images consisting of a training set of 60,000 examples and a test set of 10,000 examples. Each example is a 28x28 grayscale image, associated with a label from 10 classes.

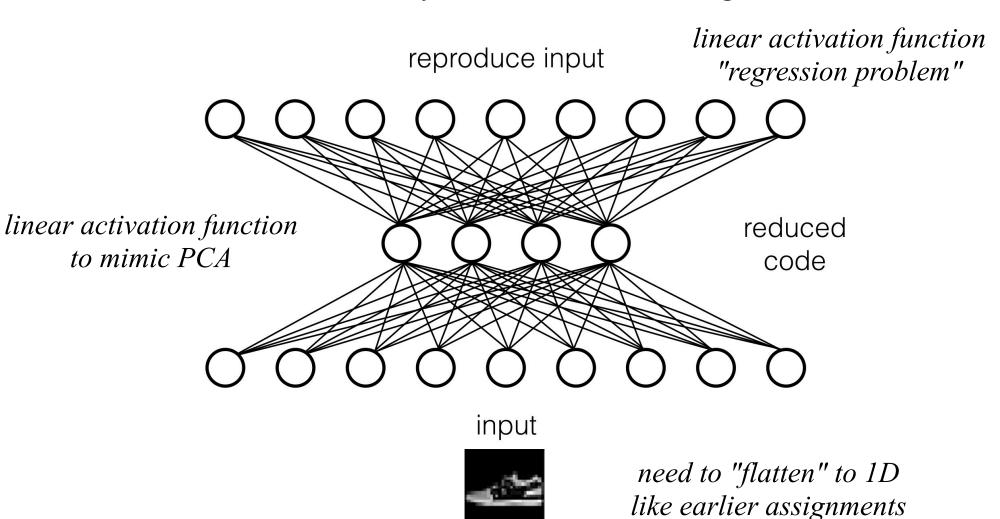
see Homework7\_2022.ipynb



## Homework 7 (due Fri Nov 11)

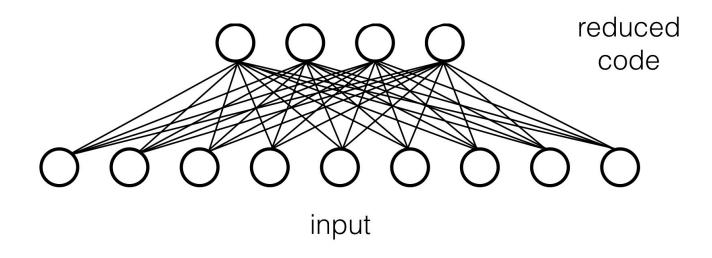
**Q1a (5 points).** Create an autoassociator network that produces a lower-dimensional representation of the Fashion-MNIST images on its hidden layer. It will use a "flattened" (one-dimensional) version of these images ...

train with 1/2 of the Fashion-MNIST images



... After you train your autoassociator, you will need to create a reduceddimensionality versions of the remaining 1/2 of the Fashion-MNIST training set. ...

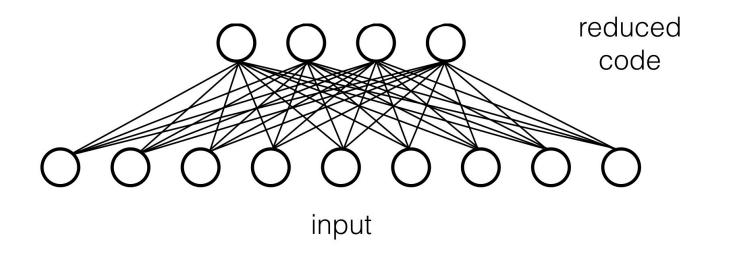
remaining 1/2 of the Fashion-MNIST images



... After you train your autoassociator, you will need to create a reduceddimensionality versions of the remaining 1/2 of the Fashion-MNIST training set. ...

... The easiest way to do this is to use the weights and biases from the trained autoassociator to calculate the activation values on the hidden layer

```
# get weights and biases from the aa network
aaW = aanetwork.layers[0].get_weights()[0]
aaB = aanetwork.layers[0].get_weights()[1]
```



**Q1b (3 points).** Now, use these lower-dimensional (PCA-like) representations of the clothing images (remaining 1/2 of the original set) as the inputs to train a densely-connected multi-layered neural network that learns, via backpropagation, to classify the images as one of the 10 types of clothing.

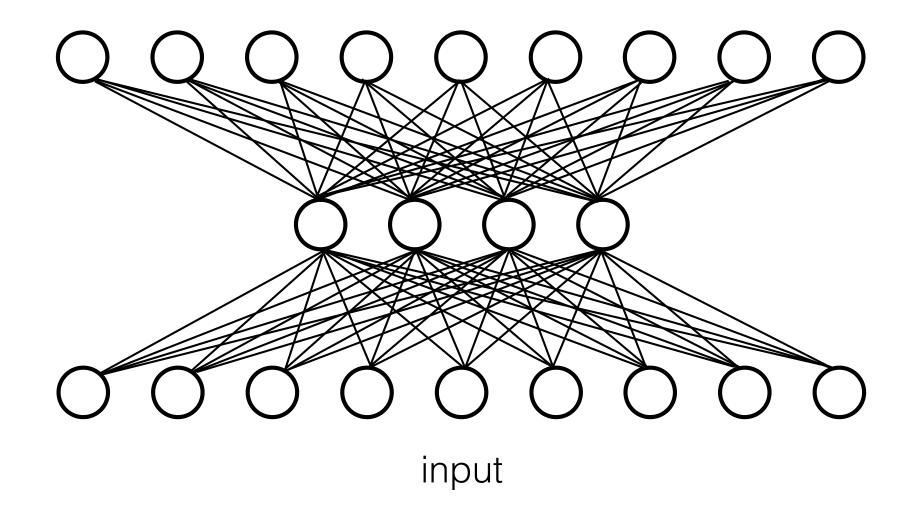
```
# get weights and biases from the aa network
aaW = aanetwork.layers[0].get_weights()[0]
aaB = aanetwork.layers[0].get_weights()[1]
```

using hidden layer activations from the autoassociator as input to a multi-layer classification network

#### autoassociator

# from Week10a

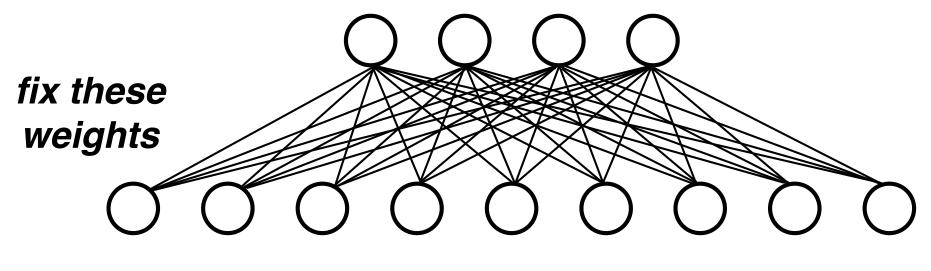
once the reduced code is learned, that code can be used as input to a backprop network



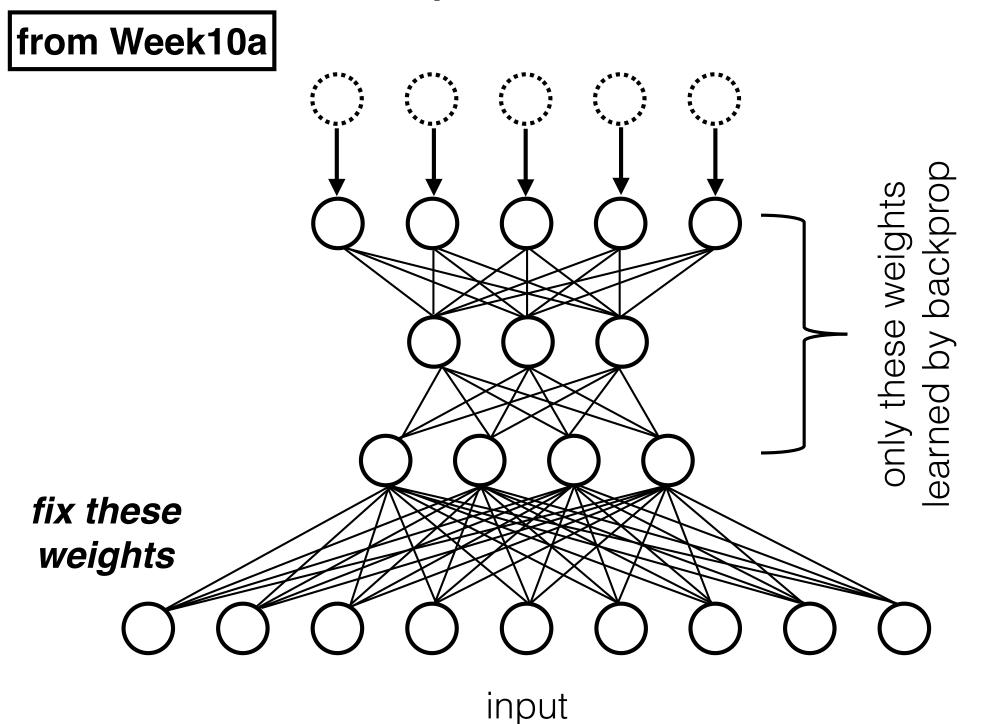
#### autoassociator

### from Week10a

(instead of "fixing these weights", just use the weights and biases to calculate the activations, which will then be used as inputs to a trained network)



### use autoassociator representations in feedforward net



## autoassociators and principal components analysis (PCA)

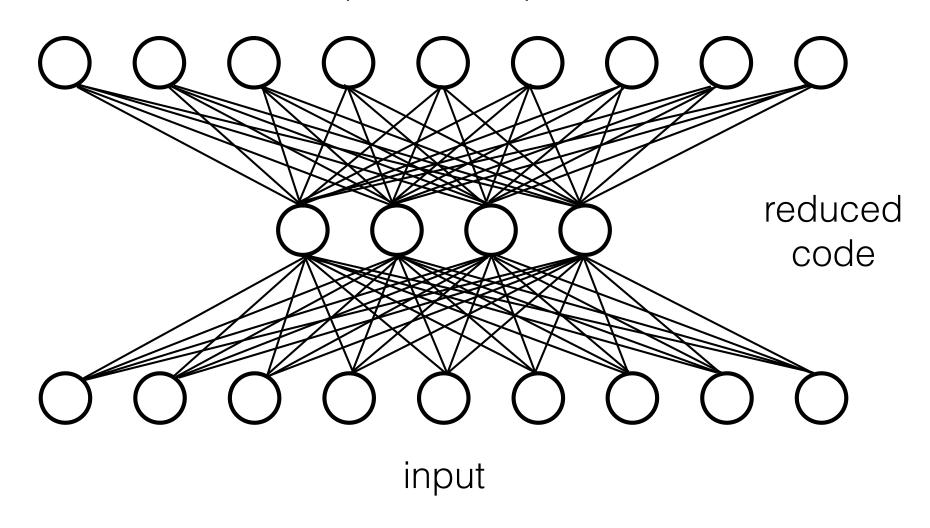
type of neural network

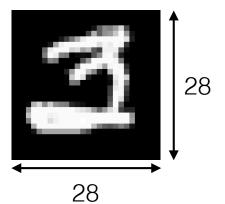
statistical technique

#### autoassociator

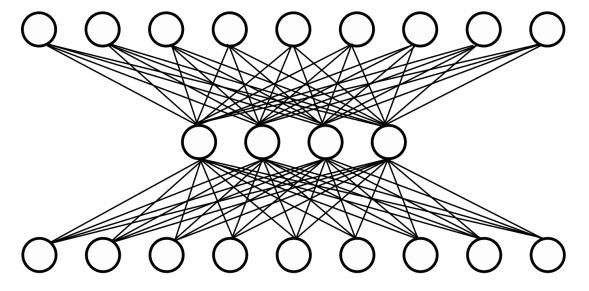
using supervised learning to do unsupervised learning

reproduce input

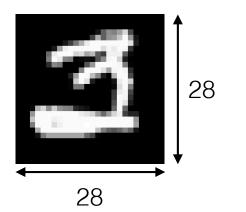




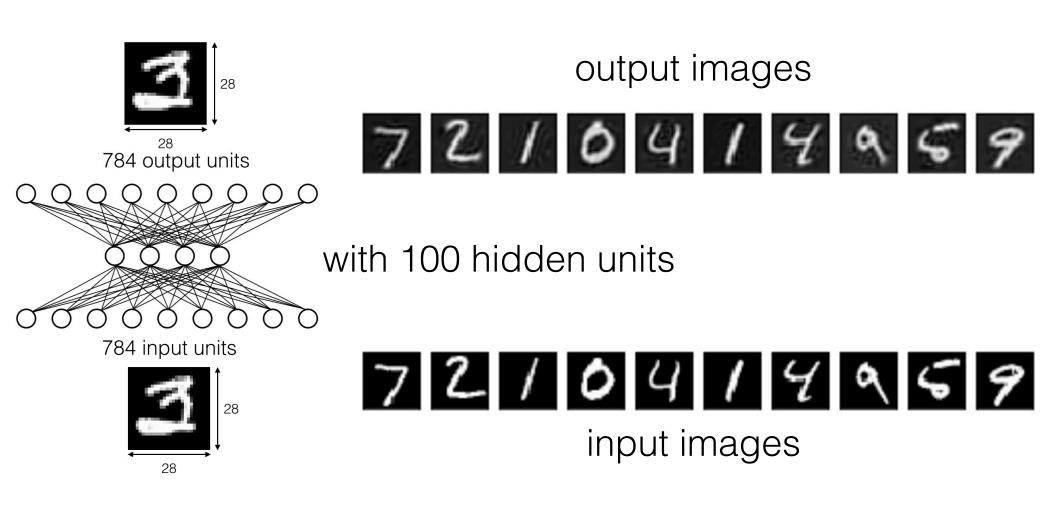
784 output units

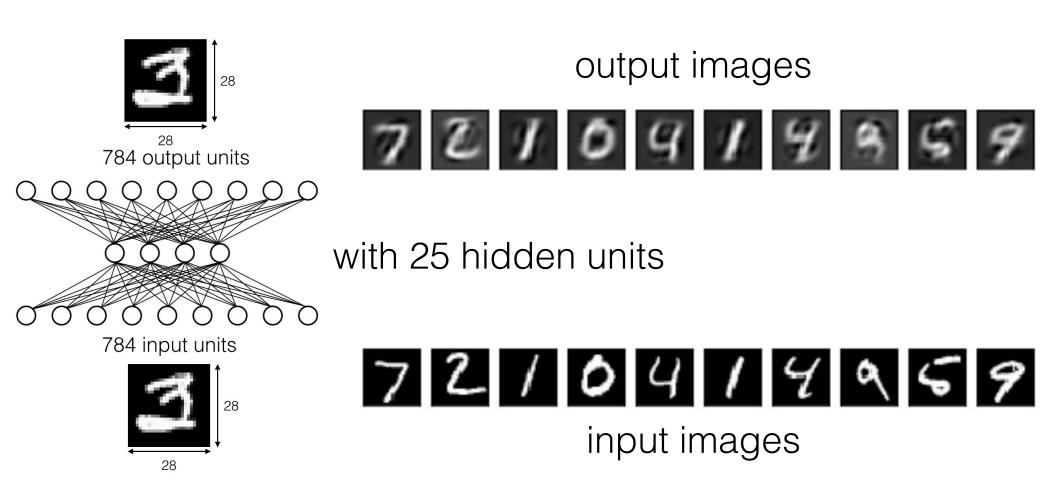


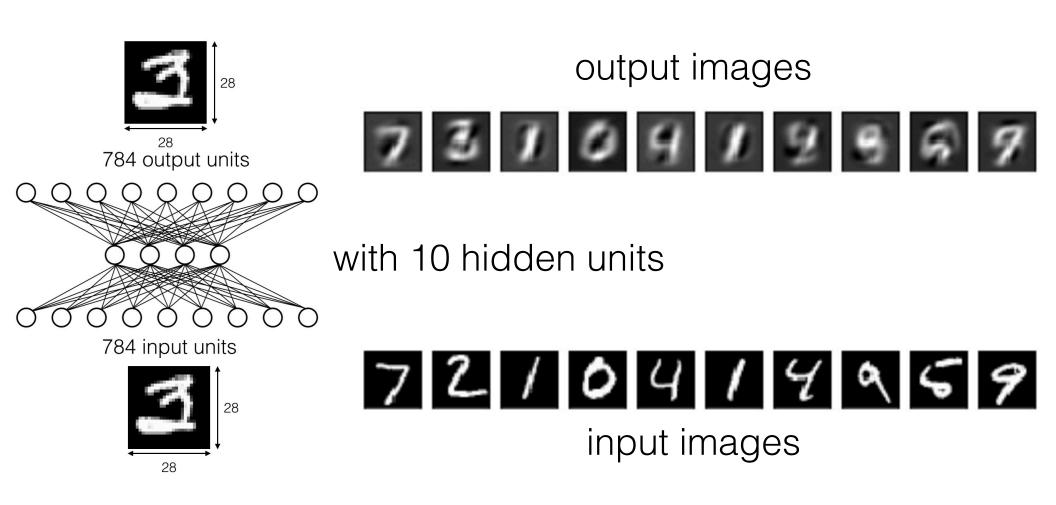
784 input units

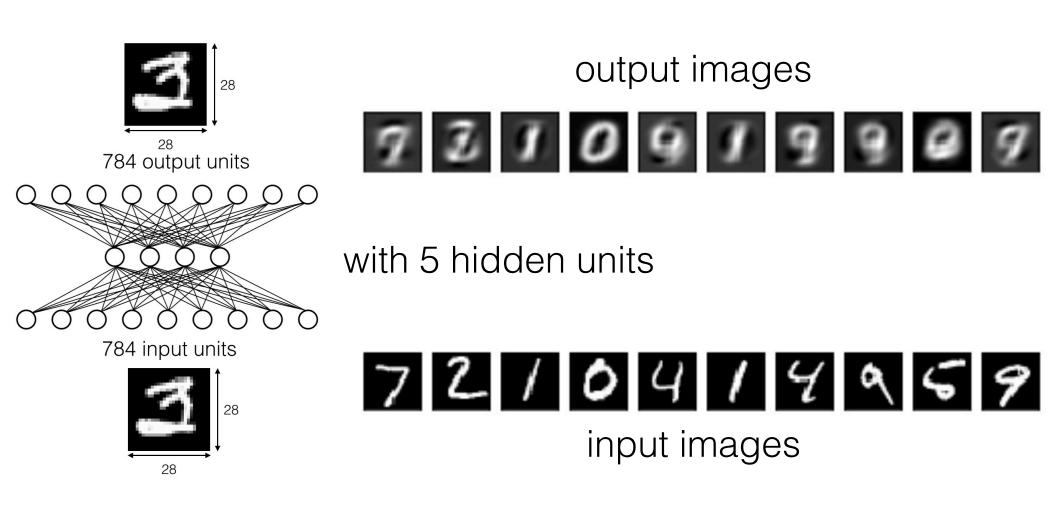


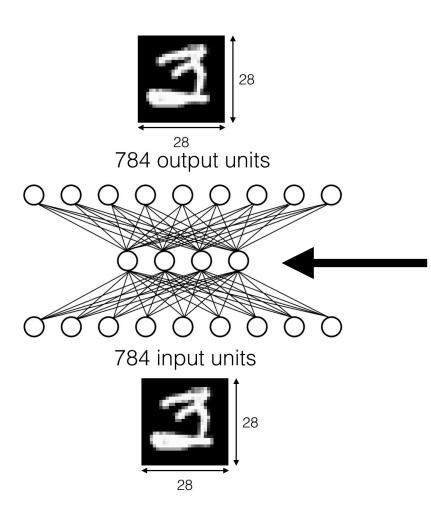
represent images in 784-dimensional space using fewer hidden unit dimensions





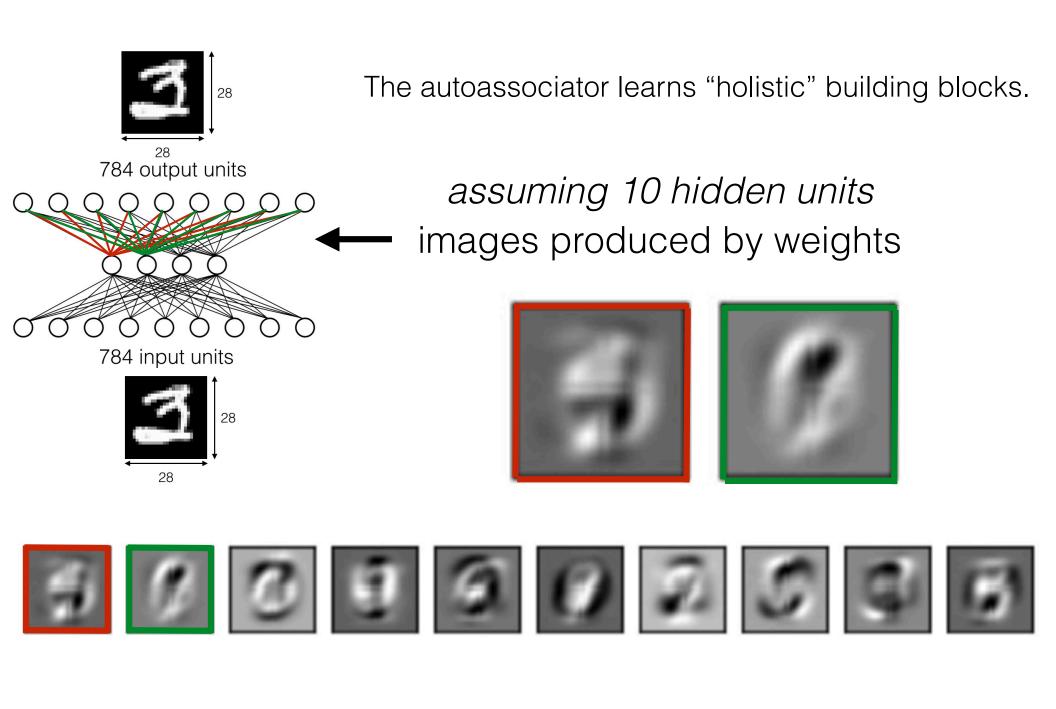






What kinds of representations does the autoassociator learn?

Does it try to learn the "parts" that make up different letters?



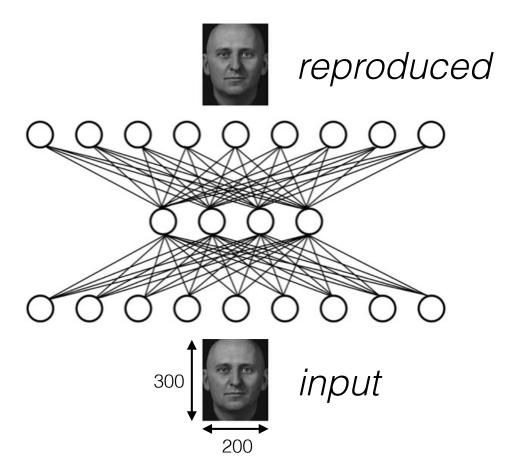
training faces

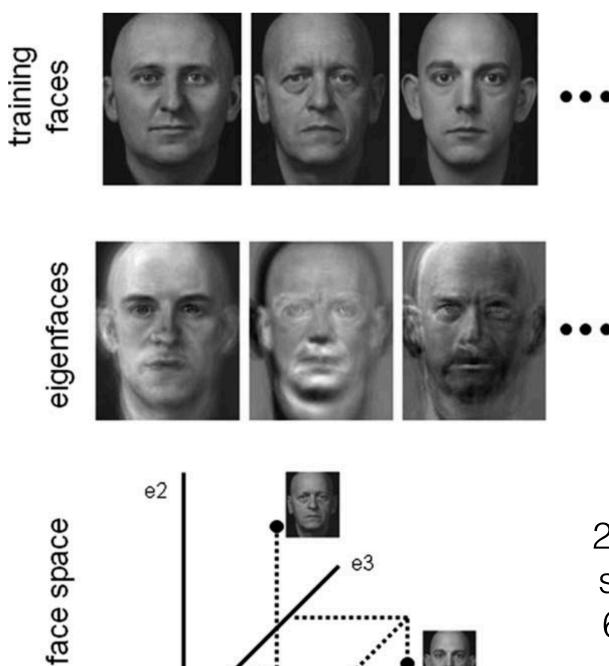






•••



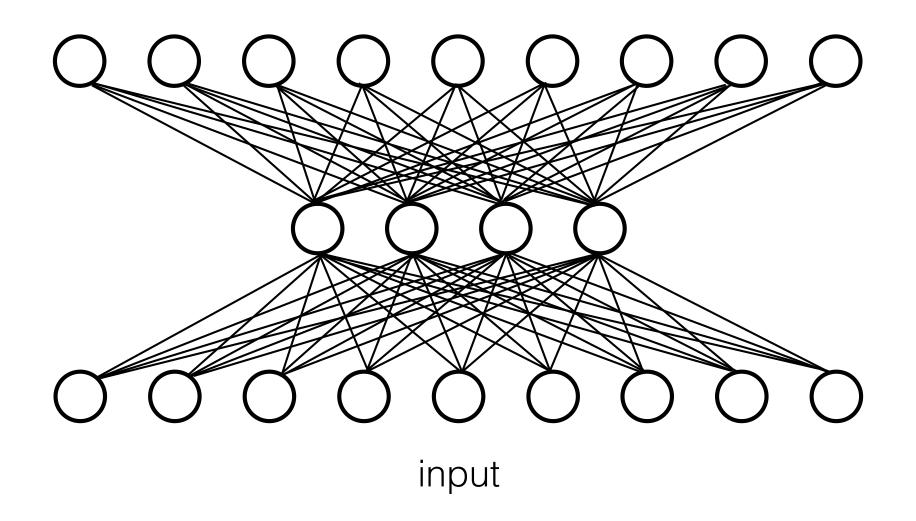


e1

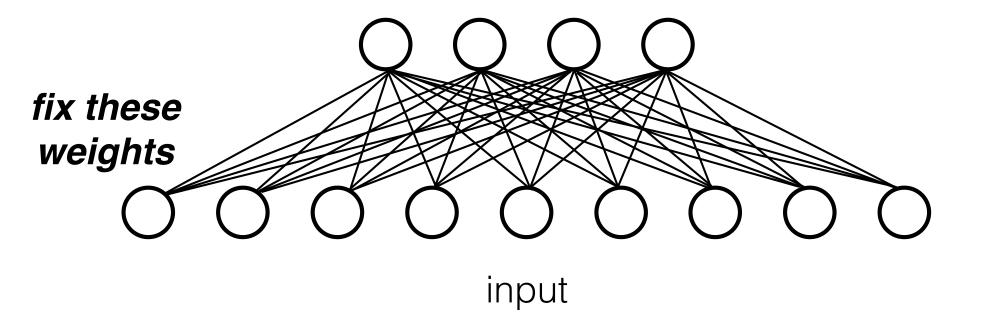
20-dimensional face space rather than a 60000-dimensional pixel image space

#### autoassociator

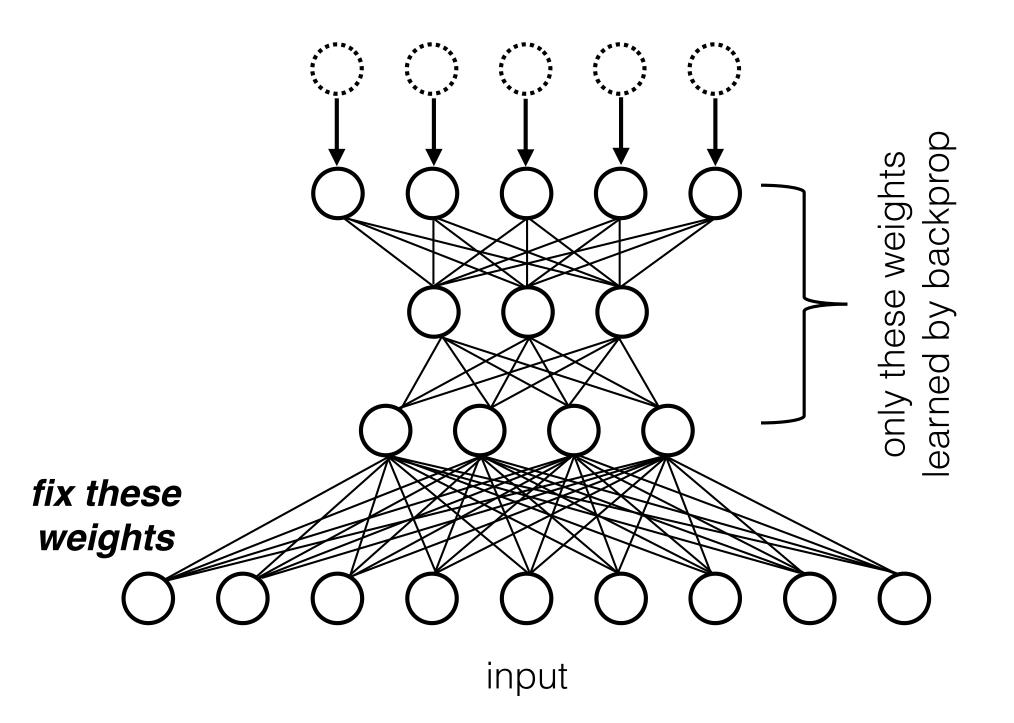
once the reduced code is learned, that code can be used as input to a backprop network



#### autoassociator



#### use autoassociator representations in feedforward net



**Q2 (10 points).** Create a convolutional neural network that classifies the Fashion-MNIST images. ...

(how to do this will be described today and Thu)

# Programming Deep Convolutional Neural Networks using Keras / Tensorflow

# this initializes a blank Sequential network network = models.Sequential()

```
# this initializes a blank Sequential network
network = models.Sequential()
```

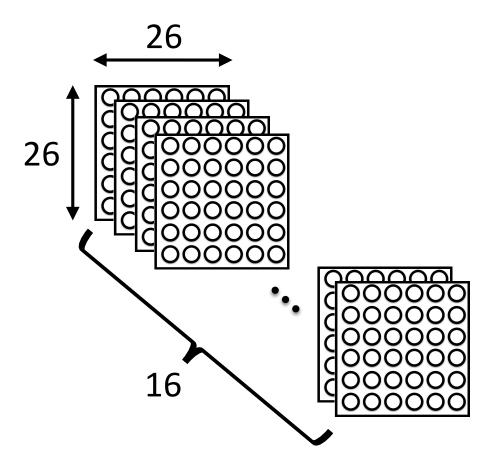
```
# first convolutional layer network.add(layers.Conv2D(16, (3,3), activation='relu', input_shape=(sz,sz,1)))
```

layers.Conv2D is a type of layer (before we used layers.Dense)

# this initializes a blank Sequential network network = models.Sequential()

# first convolutional layer network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))

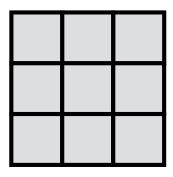
number of feature maps



# this initializes a blank Sequential network network = models.Sequential()

# first convolutional layer network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))

dimensions of the convolution



```
# this initializes a blank Sequential network
network = models.Sequential()
```

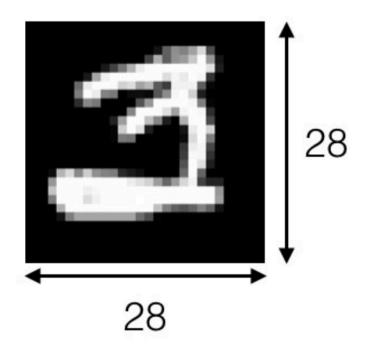
# first convolutional layer
network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))

activation
function

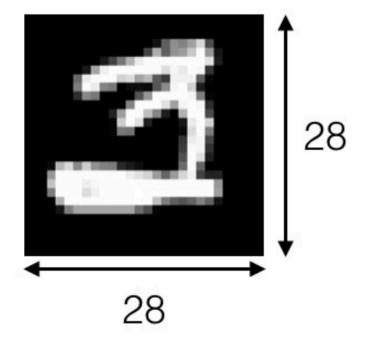
# this initializes a blank Sequential network network = models.Sequential()

# first convolutional layer network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))

first layer requires input shape







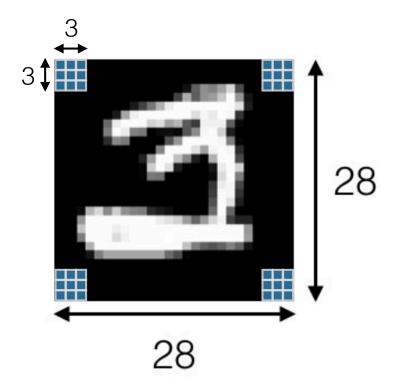
```
network = models.Sequential()
network.add(layers.Conv2D(16, (3,3) activation='relu', input_shape=(sz,sz,1)))
```

for layer in network.layers:

print('layer name : {} | input shape : {} | output shape : {}'.

format(layer.name, layer.input.shape, layer.output.shape))

layer name: conv2d\_1 | input shape: (None, 28, 28, 1) | output shape: (None, 26, 26, 16)



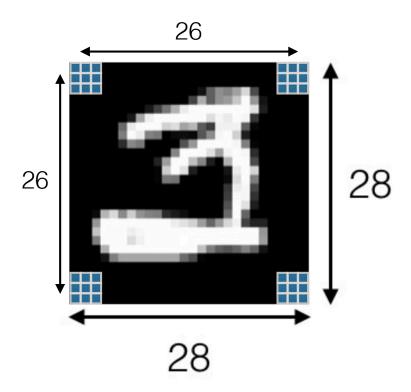
```
network = models.Sequential()
network.add(layers.Conv2D(16, (3,3), activation='relu', input_shape=(sz,sz,1)))
```

for layer in network.layers:

print('layer name : {} | input shape : {} | output shape : {}'.

format(layer.name, layer.input.shape, layer.output.shape))

layer name : conv2d\_1 | input shape : (None, 28, 28, 1) | output shape : (None, 26, 26, 16)



```
# this initializes a blank Sequential network
network = models.Sequential()
```

# first convolutional layer network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))

required with
Conv2D layer
what is this
third dimension?

# load fashion mnist dataset from tensorflow.keras.datasets import fashion\_mnist

(train\_images, train\_labels), (test\_images, test\_labels) = fashion\_mnist.load\_data()



remember that we reshape this from a matrix to a vector when training Dense networks

now we're keeping the 2D structure, but ...

```
# load fashion mnist dataset
from tensorflow.keras.datasets import fashion_mnist

(train_images, train_labels), (test_images, test_labels) = fashion_mnist.load_data()

print(train_images.shape)
  (60000, 28, 28)
```

```
# load fashion mnist dataset
from tensorflow.keras.datasets import fashion_mnist
(train_images, train_labels), (test_images, test_labels) = fashion_mnist.load_data()
print(train_images.shape)
                                                                     error without
(60000, 28, 28)
                                                                          this
network = models.Sequential()
network.add(layers.Conv2D(16, (3,3), activation='relu', input_shape=(sz,sz,1)))
for layer in network.layers:
  print('layer name : {} | input shape : {} | output shape : {}'.
                            format(layer.name, layer.input.shape, layer.output.shape))
```

layer name: conv2d\_1 | input shape: (?, 28, 28, 1) | output shape: (?, 26, 26, 16)

```
# load fashion mnist dataset
from tensorflow.keras.datasets import fashion_mnist
(train_images, train_labels), (test_images, test_labels) = fashion_mnist.load_data()
print(train images.shape)
(60000, 28, 28)
network = models.Sequential()
network.add(layers.Conv2D(16, (3,3), activation='relu', input_shape=(sz,sz,1)))
for layer in network.layers:
  print('layer name : {} | input shape : {} | output shape : {}'.
                            format(layer.name, layer.input.shape, layer.output.shape))
layer name: conv2d_1 | input shape: (None, 28, 28, 1) | output shape: (None, 26, 26, 16)
need to reshape the train_images (and test_images)
train images = train images.reshape((60000, 28, 28, 1))
                        (use variables rather than hard-code)
```

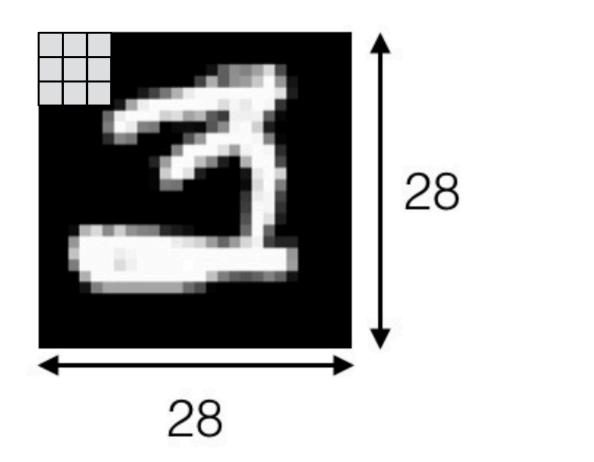
# first convolutional layer

network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))

optional parameter

, padding='valid', default is 'valid'

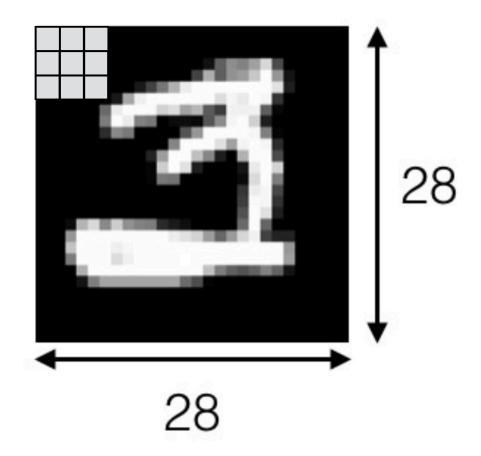
with 'valid' it stays inside previous layer



# first convolutional layer network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))

what will be the dimensions of the Conv2D layer?

with 'valid' it stays inside previous layer



```
# this initializes a blank Sequential network

network = models.Sequential()

may want to use 'same'

# first convolutional layer

in Homework 7

network.add(layers.Conv2D(16, (3,3), activation='relu', input_shape=(sz,sz,1)))

optional parameter

, padding='same', default is 'valid'
```

with 'same' it goes outside previous layer # this initializes a blank Sequential network

network = models.Sequential()

may want to use 'same'

# first convolutional layer

in Homework 7

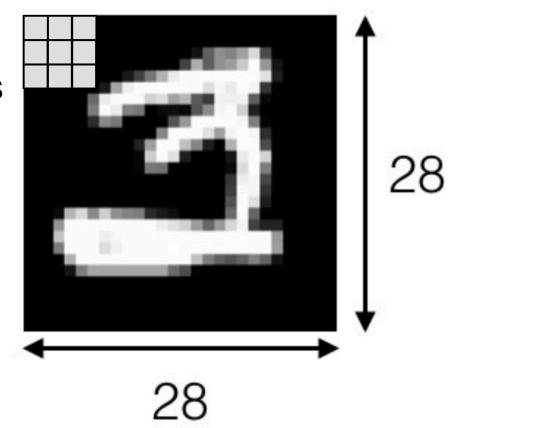
network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))

what will be the dimensions of the Conv2D layer?

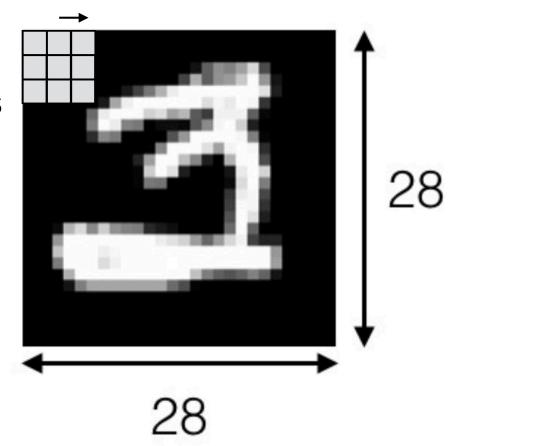
with 'same' it goes outside previous layer

layer name: conv2d\_1 | input shape: (None, 28, 28, 1) | output shape: (None, 28, 28, 16)

# first convolutional layer network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1))) optional parameter , strides=(1, 1), default is (1,1)

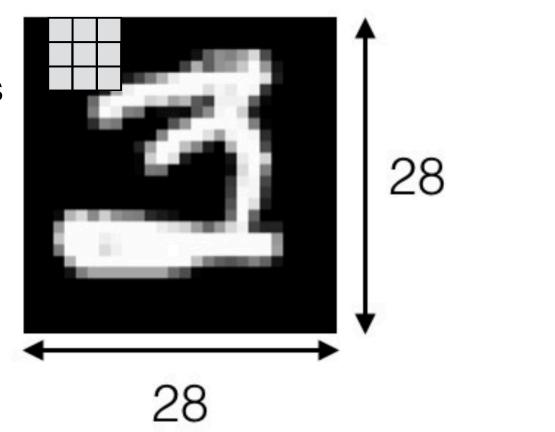


# first convolutional layer network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1))) optional parameter , strides=(1, 1), default is (1,1)

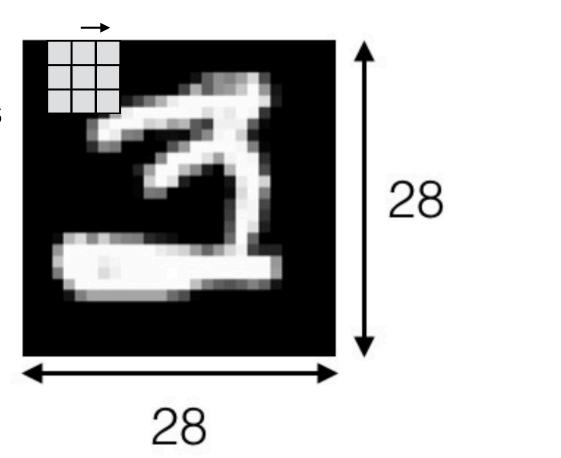


# first convolutional layer
network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))

optional parameter
, strides=(1, 1), default is (1,1)



# first convolutional layer network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1))) optional parameter , strides=(1, 1), default is (1,1)



```
# this initializes a blank Sequential network
network = models.Sequential()
```

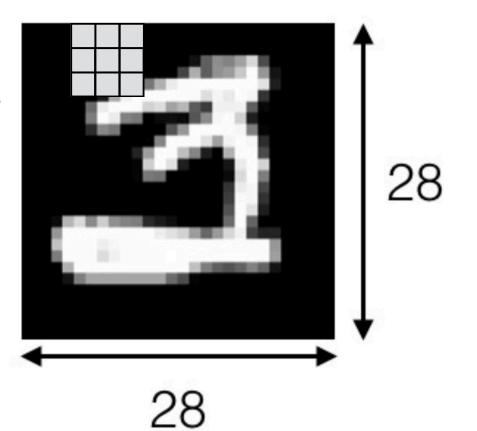
# usually use full stride

# first convolutional layer

network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))

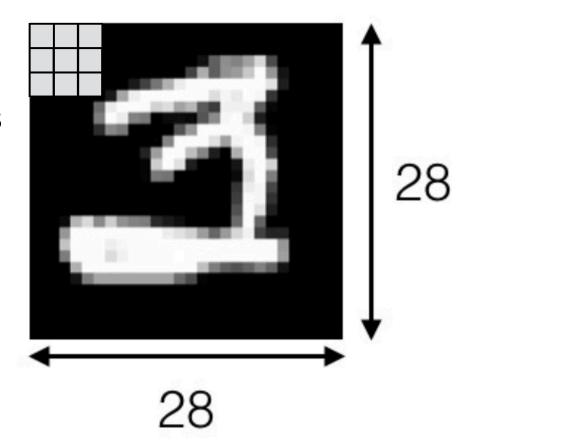
optional parameter

, strides=(1, 1), default is (1,1)



# first convolutional layer
network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))

optional parameter
, strides=(2, 2), default is (1,1)

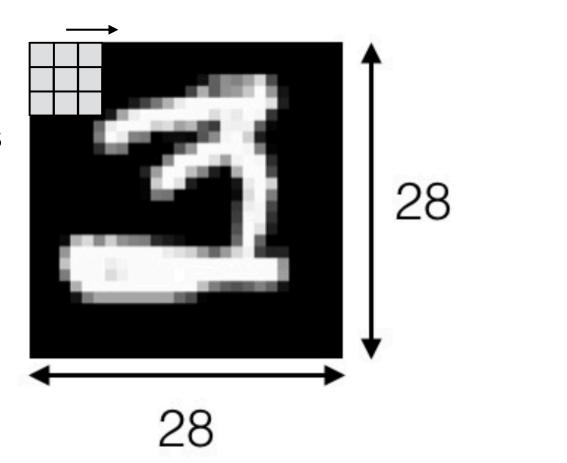


# first convolutional layer

network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))

optional parameter

, strides=(2, 2), default is (1,1)

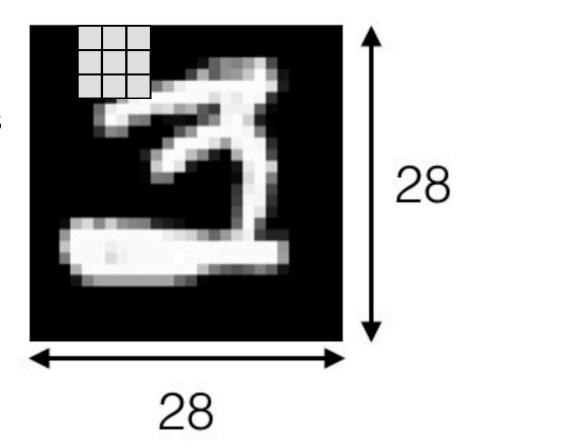


# first convolutional layer

network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))

optional parameter

, strides=(2, 2), default is (1,1)

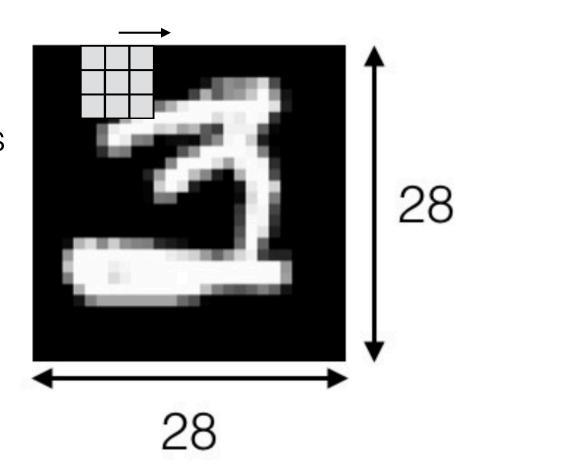


# first convolutional layer

network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))

optional parameter

, strides=(2, 2), default is (1,1)

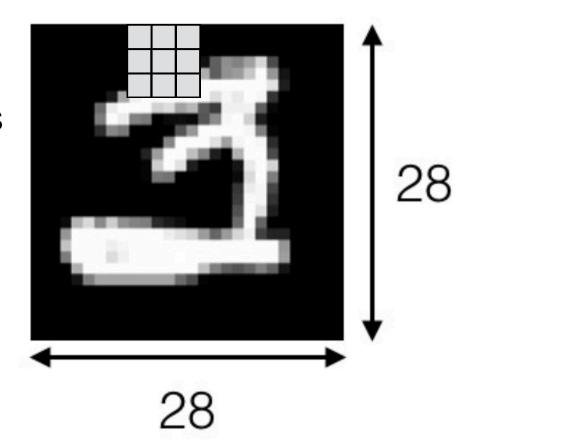


# first convolutional layer

network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))

optional parameter

, strides=(2, 2), default is (1,1)



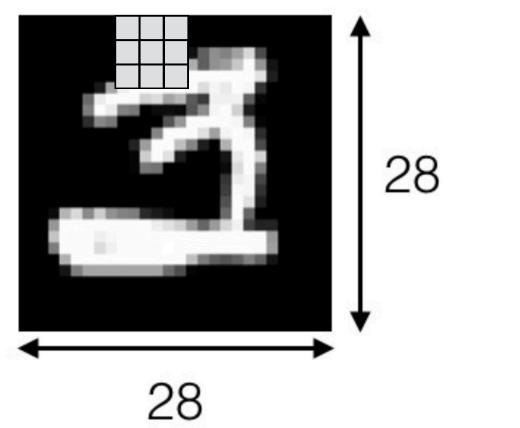
# first convolutional layer

network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))

optional parameter

, strides=(2, 2), default is (1,1)

what will be the dimensions of the Conv2D layer?



layer name: conv2d\_1 | input shape: (None, 28, 28, 1) | output shape: (None, 13, 13, 16)

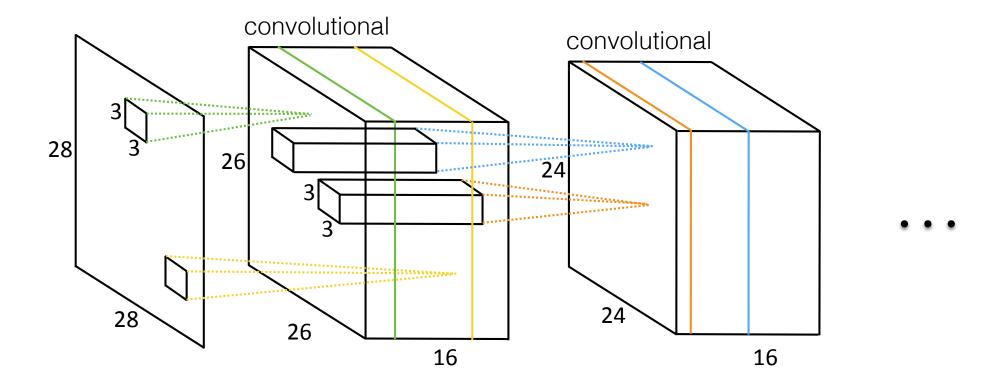
```
network = models.Sequential()
network.add(layers.Conv2D(16, (3,3), activation='relu', input_shape=(sz,sz,1)))
network.add(layers.Conv2D(16, (3,3), activation='relu'))
```

```
for layer in network.layers:

print('layer name : {} | input shape : {} | output shape : {}'.
```

format(layer.name, layer.input.shape, layer.output.shape))

```
layer name : conv2d_1 | input shape : (None, 28, 28, 1) | output shape : (None, 26, 26, 16) | layer name : conv2d_2 | input shape : (None, 26, 26, 16) | output shape : (None, 24, 24, 16)
```



network = models.Sequential()
network.add(layers.Conv2D(16, (3,3), activation='relu', input\_shape=(sz,sz,1)))
network.add(layers.Conv2D(16, (3,3), activation='relu'))
network.add(layers.MaxPooling2D((2,2)))

### Max Pooling

29	15	28	184
0	100	70	38
12	12	7	2
12	12	45	6
	,	2 x 2 pool size	
	100	184	

45

what will be the dimensions of the max\_pooling2d layer?

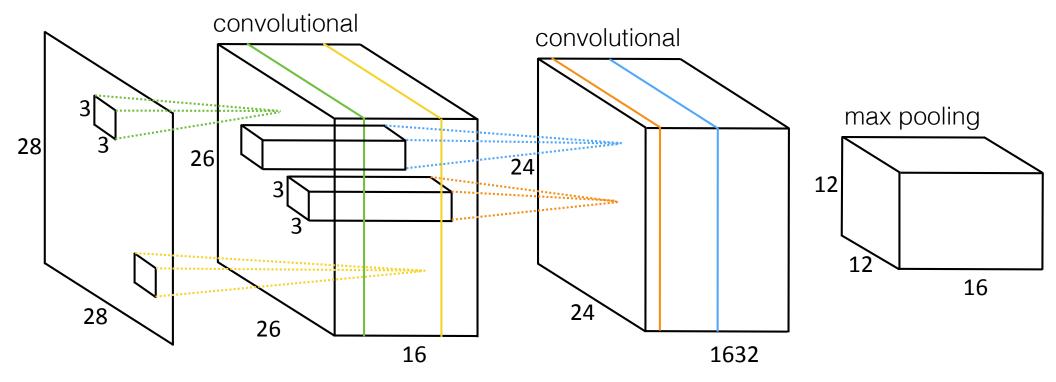
```
network = models.Sequential()
network.add(layers.Conv2D(16, (3,3), activation='relu', input_shape=(sz,sz,1)))
network.add(layers.Conv2D(16, (3,3), activation='relu'))
network.add(layers.MaxPooling2D((2,2)))
```

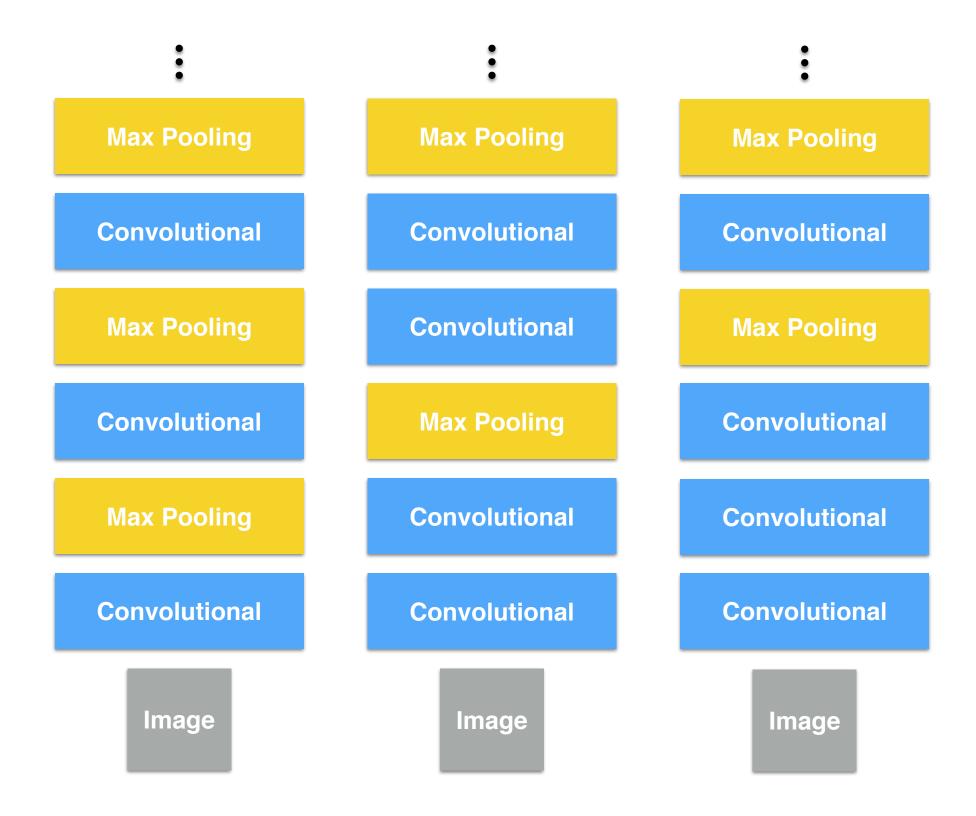
```
for layer in network.layers:

print('layer name : {} | input shape : {} | output shape : {}'.

format(layer.name, layer.input.shape, layer.output.shape))
```

```
layer name: conv2d_1 | input shape: (None, 28, 28, 1) | output shape: (None, 26, 26, 16) layer name: conv2d_2 | input shape: (None, 26, 26, 16) | output shape: (None, 24, 24, 16) layer name: max_pooling2d_3 | input shape: (None, 24, 24, 16) | output shape: (None, 12, 12, 16)
```





#### **AlexNet** 3/ 3 dense 2048 2048 192 192 128 48 128 \55 13 ... 224 dense densé 13: \*\* 13 1000 128 Max pooling 192 192 2048 2048 Max

Max

pooling

128

pooling

48

3

# just an example

Classification

Dense

Dense

**Flatten** 

**Max Pooling** 

Convolutional

**Max Pooling** 

Convolutional

Image

```
network = models.Sequential()
network.add(layers.Conv2D(16, (3,3), activation='relu', input_shape=(sz,sz,1)))
network.add(layers.MaxPooling2D((2,2)))
network.add(layers.Conv2D(16, (3,3), activation='relu'))
network.add(layers.MaxPooling2D((2,2)))
network.add(layers.Flatten())
network.add(layers.Dense(20, activation='relu'))
network.add(layers.Dense(nout, activation='softmax'))
for layer in network.layers:
  print('layer name : {} | input shape : {} | output shape : {}'.
                              format(layer.name, layer.input.shape, layer.output.shape))
layer name: conv2d_1 | input shape: (None, 28, 28, 1) | output shape: (None, 26, 26, 16)
layer name: max_pooling2d_2 | input shape: (None, 26, 26, 16) | output shape: (None, 13, 13, 16)
layer name: conv2d 3 | input shape: (None, 13, 13, 16) | output shape: (None, 11, 11, 16)
layer name: max_pooling2d_4 | input shape: (None, 11, 11, 16) | output shape: (None, 5, 5, 16)
layer name: flatten_5 | input shape: (None, 5, 5, 16) | output shape: (None, 400)
layer name: dense_6 | input shape: (None, 400) | output shape: (None, 20)
layer name: dense 7 | input shape: (None, 20) | output shape: (None, 10)
```

## print(network.summary())

Layer (type)	Output Shape	Param #
conv2d_1 (Conv2D)	(None, 26, 26, 16)	160
max_pooling2d_2 (MaxPooling	(None, 13, 13, 16)	0
conv2d_3 (Conv2D)	(None, 11, 11, 16)	2320
max_pooling2d_4 (MaxPooling	(None, 5, 5, 16)	0
flatten_5 (Flatten)	(None, 400)	0
dense_6 (Dense)	(None, 20)	8020
dense_7 (Dense)	(None, 10)	210

Total params: 10,710

Trainable params: 10,710 Non-trainable params: 0

```
network = models.Sequential()
network.add(layers.Conv2D(16, (3,3), activation='relu', input_shape=(sz,sz,1)))
network.add(layers.MaxPooling2D((2,2)))
network.add(layers.Conv2D(16, (3,3), activation='relu'))
network.add(layers.MaxPooling2D((2,2)))
network.add(layers.Flatten())
network.add(layers.Dense(20, activation='relu'))
network.add(layers.Dense(nout, activation='softmax'))
network.compile(optimizer='adam', loss='categorical_crossentropy',
                        metrics=['accuracy'])
history = network.fit(train_images, train_labels_onehot, verbose=True,
                                 validation split=.1, epochs=ep, batch size=128)
test loss, test accuracy = network.evaluate(test images, test labels onehot)
```