Sample Report

Your Name

November 3, 2023

Abstract

Brief description of the problem, your solution, and the results.

1 Introduction

Introduce your work.

- Why is it important?
- What's the motivation?
- What's your novelty?

Numbered list also helps summarizing the main contributions.

- 1. First point.
- 2. Second point.

2 Related Work

Cite some important works in this section, for example, [1]. Compare them with your project. One can also combine this section with Section 1.

3 Problem Formulation

Mathematical formulation of your problem. For example

$$\min_{u(t)} \quad \int_0^T g(x, u)dt + h(x(T)) \tag{1}$$

subject to
$$\dot{x} = f(x, u)$$
 (2)

Equation (1) can be referred by setting up its label.

4 Solution Method

Describe your algorithm and its properties.

Theorem 1 (Convergence). My Algorithm 1 is good.

5 Experiments

How does your algorithm work and compare with others? What insights have you gained from the experiments? Use figures (see Figure 5 for example) and tables (see Table 1 for example) to better present your results.

```
Algorithm 1: Calculate y = x^n
Require: n \ge 0 \lor x \ne 0
Ensure: y = x^n
   y \leftarrow 1
  if n < 0 then
      X \leftarrow 1/x
      N \leftarrow -n
   else
      X \leftarrow x
      N \leftarrow n
   while N \neq 0 do
      if N is even then
         X \leftarrow X \times X
         N \leftarrow N/2
      else \{N \text{ is odd}\}
         y \leftarrow y \times X
```

 $N \leftarrow N-1$



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Figure 1: This is the caption for the figure.

	Col1	Col2	Col3
1	6	87837	787
2	7	78	5415
3	545	778	7507

Table 1: This is the caption for the table.

5.1 First case

Use subsections to separate different experiment settings, if needed.

6 Conclusions

Conclusions and potentially future research directions.

Appendix

A Proof of Theorem 1

Proof. Here is my proof. \Box

References

[1] Dimitri Bertsekas. Dynamic programming and optimal control: Volume I, volume 4. Athena scientific, 2012. 1