

## view\_frames Result

Recorded at time: 1733275060.108535

odom

Broadcaster: /ekf\_localization\_node  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

base\_footprint

Broadcaster: /footprint\_to\_imu  
Average rate: 10000.0  
Buffer length: 0.0  
Most recent transform: 0.0  
Oldest transform: 0.0

imu

odom\_enc

Broadcaster: /roboclawfront  
Average rate: 20.206  
Buffer length: 4.999  
Most recent transform: 1733267592.7  
Oldest transform: 1733267587.701

base\_link