

# Computational Fluid Dynamics

Fluid Mechanics I

Lecture 1

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Krister Wiklund

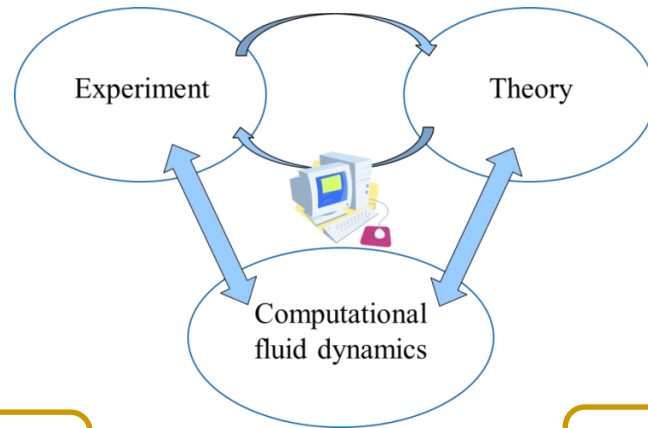
Department of Physics

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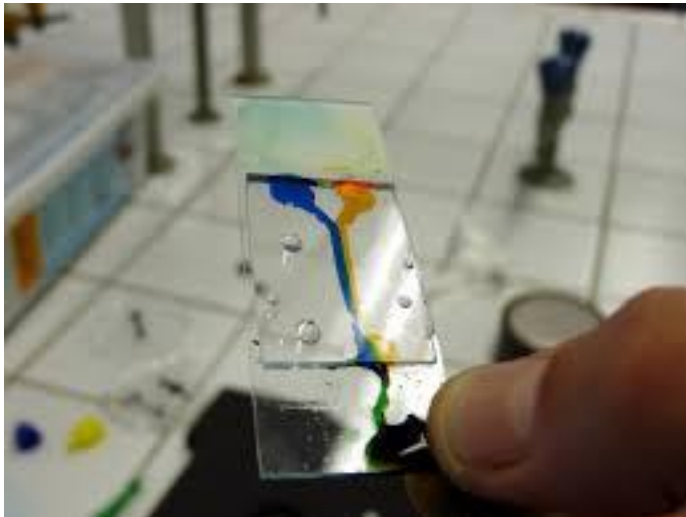
# SUMMARY OF LECTURE: FLUID MECHANICS I

- ☐ Be able to give a physical interpretation of all terms in Navier-Stokes
- ☐ Be able to give a physical interpretation of all terms in Vorticity equation
- ☐ Understand vortex stretching
- ☐ Understand the relation between pressure and velocity
- ☐ Understand the concept of diffusion and convection of vorticity
- ☐ Be able to use Einsteins summation convention and Index formalism
- ☐ Understand the physical interpretation of the Reynolds number

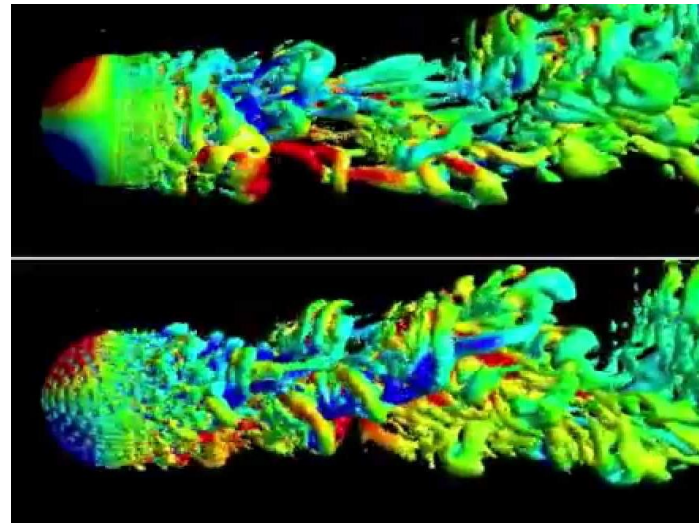
# What is CFD?



Microfluidics



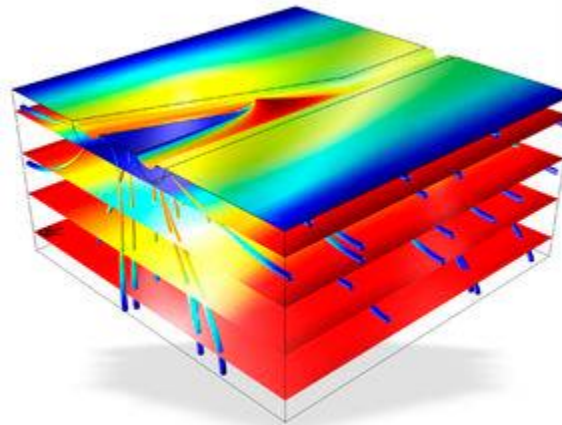
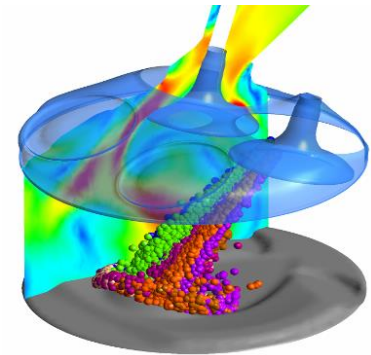
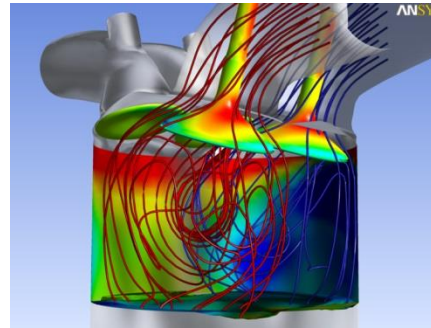
Turbulent flow



# CFD-software

## Different software:

- ANSYS CFX
- ANSYS FLUENT
- CD-adapco STAR-CD
- Open FOAM
- COMSOL
- Many others...



All of these numerically solves fluid equations, more about this later in the course...

# Example: CFD-settings in Comsol

Navier-Stokes

Incompressibility condition

"Newtonian fluid" assumption

Turbulence model: Low Re k-ε

Wall distance eq.

Turbulence production

Settings

Turbulent Flow, Low Re k-ε

Equation

Equation form:

Study controlled

Show equation assuming:

Study 1, Time Dependent

$$\rho \frac{\partial \mathbf{u}}{\partial t} + \rho(\mathbf{u} \cdot \nabla) \mathbf{u} = \nabla \cdot [-p \mathbf{I} + \mathbf{K}] + \mathbf{F}$$

$$\rho \nabla \cdot (\mathbf{u}) = 0$$

$$\mathbf{K} = (\mu + \mu_T)(\nabla \mathbf{u} + (\nabla \mathbf{u})^T)$$

$$\rho \frac{\partial k}{\partial t} + \rho(\mathbf{u} \cdot \nabla) k = \nabla \cdot \left[ \left( \mu + \frac{\mu_T}{\sigma_k} \right) \nabla k \right] + P_k - \rho \epsilon$$

$$\rho \frac{\partial \epsilon}{\partial t} + \rho(\mathbf{u} \cdot \nabla) \epsilon = \nabla \cdot \left[ \left( \mu + \frac{\mu_T}{\sigma_\epsilon} \right) \nabla \epsilon \right] + C_{\epsilon 1} \frac{\epsilon}{k} P_k - C_{\epsilon 2} \rho \frac{\epsilon^2}{k}$$

$$\nabla G \cdot \nabla G + \sigma_w G(\nabla \cdot \nabla G) = (1 + 2\sigma_w) G^4, \quad \ell_w = \frac{1}{G} - \frac{\ell_{ref}}{2}$$

$$\mu_T = \rho C_\mu \frac{k^2}{\epsilon} f_\mu(\rho, \mu, k, \epsilon, \ell_w)$$

$$P_k = \mu_T [\nabla \mathbf{u} : (\nabla \mathbf{u} + (\nabla \mathbf{u})^T)]$$

Physical Model

Turbulence

Turbulence model type:

RANS

Turbulence model:

Low Reynolds number k-ε

Wall treatment:

Low Re

Turbulence model parameters

☐ Edit turbulence model parameters

Consistent Stabilization

Inconsistent Stabilization

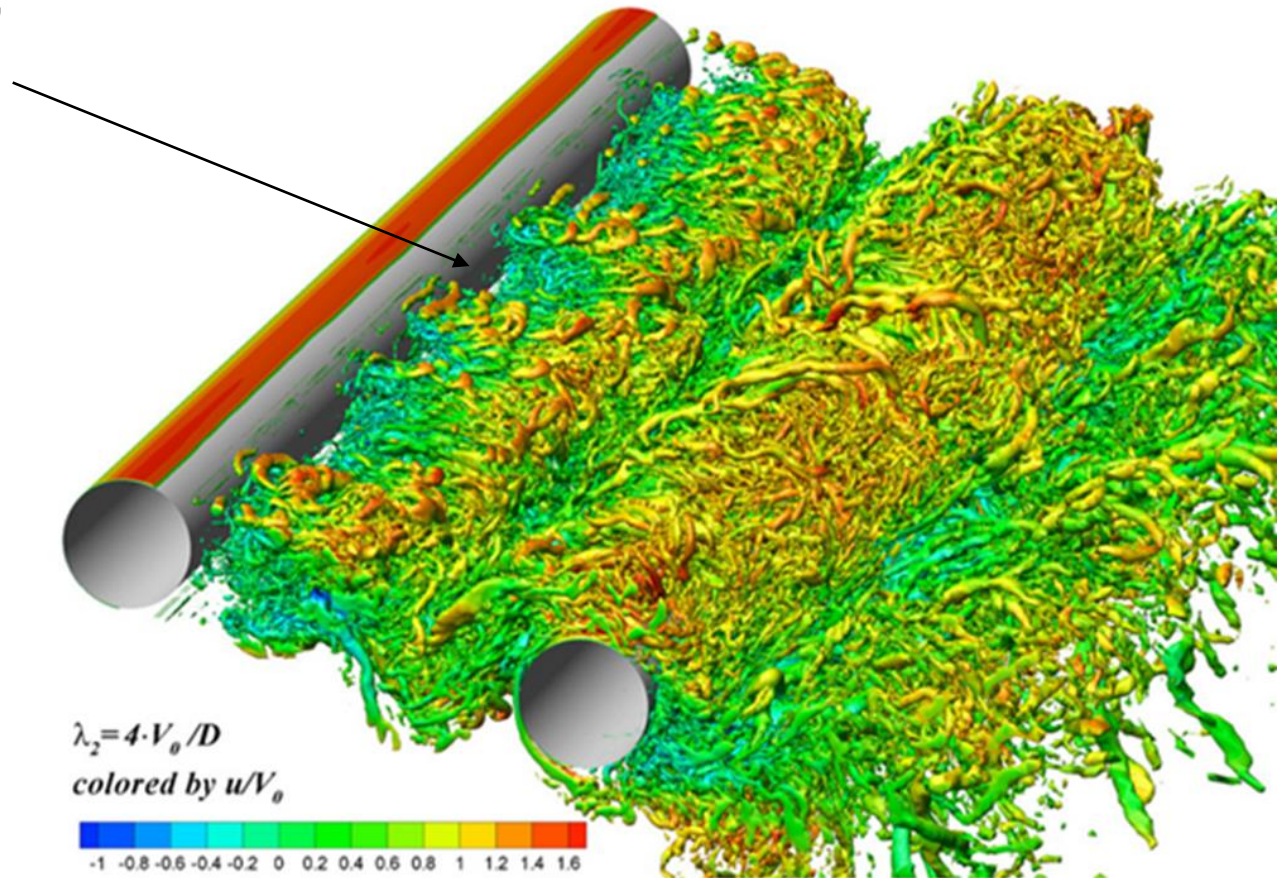
Advanced Settings

This complicated model is actually a simplified model of turbulence...

## Picture of turbulence = Interacting vortex tubes

Small "tornadoes"  
or  
Vortex tubes

Structures with  
high **vorticity**



# Fluid equations

Navier-Stokes equations  $\xrightarrow{\nabla \times}$  The vorticity equation

$$\rho \frac{\partial \mathbf{V}}{\partial t} + \rho (\mathbf{V} \cdot \nabla) \mathbf{V} = -\nabla p + \mu \nabla^2 \mathbf{V} + \mathbf{f}$$

$$\nabla \cdot \mathbf{V} = 0$$

$$\rho \frac{\partial \boldsymbol{\omega}}{\partial t} + \rho (\mathbf{V} \cdot \nabla) \boldsymbol{\omega} = \rho (\boldsymbol{\omega} \cdot \nabla) \mathbf{V} + \mu \nabla^2 \boldsymbol{\omega}$$

$$\nabla \cdot \boldsymbol{\omega} = 0$$

(Assumed:  $\nabla \times \mathbf{f} = 0$ )

$\boldsymbol{\omega} \equiv \nabla \times \mathbf{V}$

$$\underbrace{\rho \left[ \frac{\partial}{\partial t} + (\mathbf{V} \cdot \nabla) \right]}_{\rho \frac{D}{Dt}} \mathbf{V} = -\nabla p + \mu \nabla^2 \mathbf{V} + \mathbf{f}$$

$$\rho \frac{D\mathbf{V}}{Dt} = -\nabla p + \mu \nabla^2 \mathbf{V} + \mathbf{f}$$

$$\underbrace{\rho \left[ \frac{\partial}{\partial t} + (\mathbf{V} \cdot \nabla) \right]}_{\rho \frac{D}{Dt}} \boldsymbol{\omega} = \rho (\boldsymbol{\omega} \cdot \nabla) \mathbf{V} + \mu \nabla^2 \boldsymbol{\omega}$$

$$\rho \frac{D\boldsymbol{\omega}}{Dt} = \rho (\boldsymbol{\omega} \cdot \nabla) \mathbf{V} + \mu \nabla^2 \boldsymbol{\omega}$$

Note:  
No pressure  
term



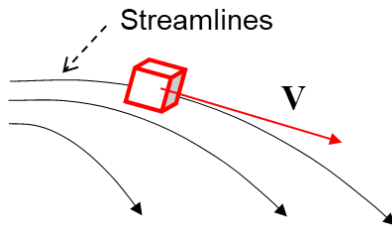
# Fluid equations (cont)

Study Group exercise:  
Derivation of vorticity eq.

## Navier-Stokes equations

$$\rho \frac{D\mathbf{V}}{Dt} = -\nabla p + \mu \nabla^2 \mathbf{V} + \mathbf{f}$$

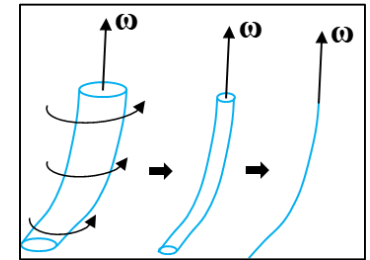
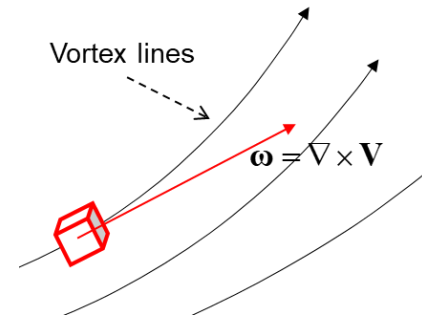
Ex:  
 $\mathbf{f} = \rho \nabla \Phi$



## The vorticity equation

$$\rho \frac{D\boldsymbol{\omega}}{Dt} = \rho (\boldsymbol{\omega} \cdot \nabla) \mathbf{V} + \mu \nabla^2 \boldsymbol{\omega}$$

$$\boldsymbol{\omega} \equiv \nabla \times \mathbf{V}$$



Note: For the **inviscid case** (no viscosity term) we have

$$\frac{D\boldsymbol{\omega}}{Dt} = (\boldsymbol{\omega} \cdot \nabla) \mathbf{V} \quad \rightarrow$$

If we initially have no vorticity, then RHS is zero and we have:

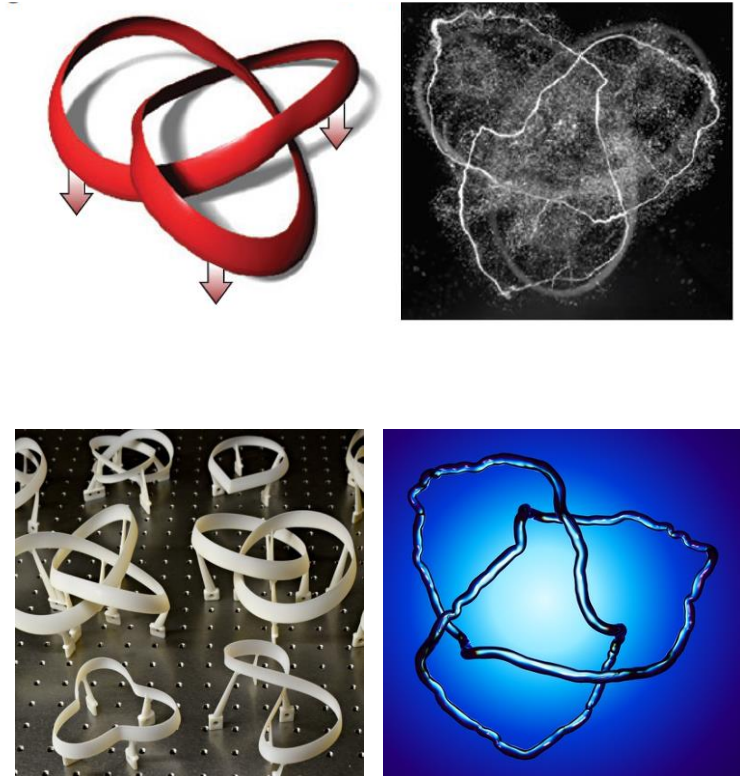
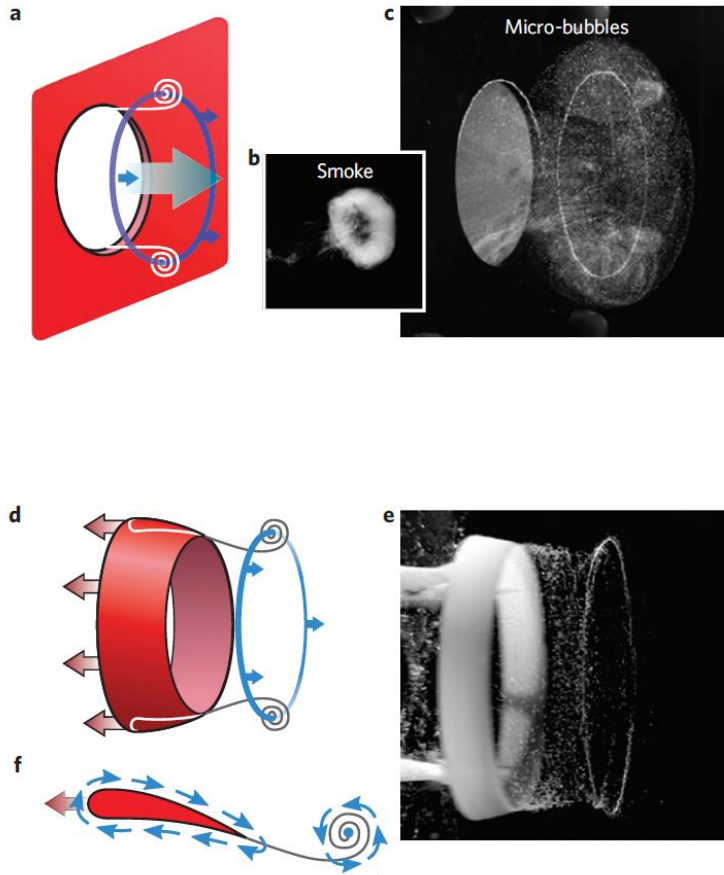
$$\boldsymbol{\omega}(t) = 0 \quad \text{or} \quad \nabla \times \mathbf{V} = 0 \quad (\text{Fundamental assumption in potential theory})$$

### Other properties:

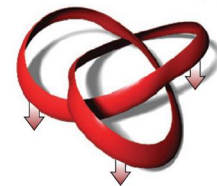
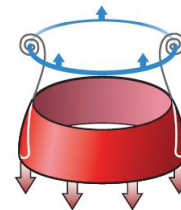
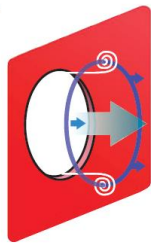
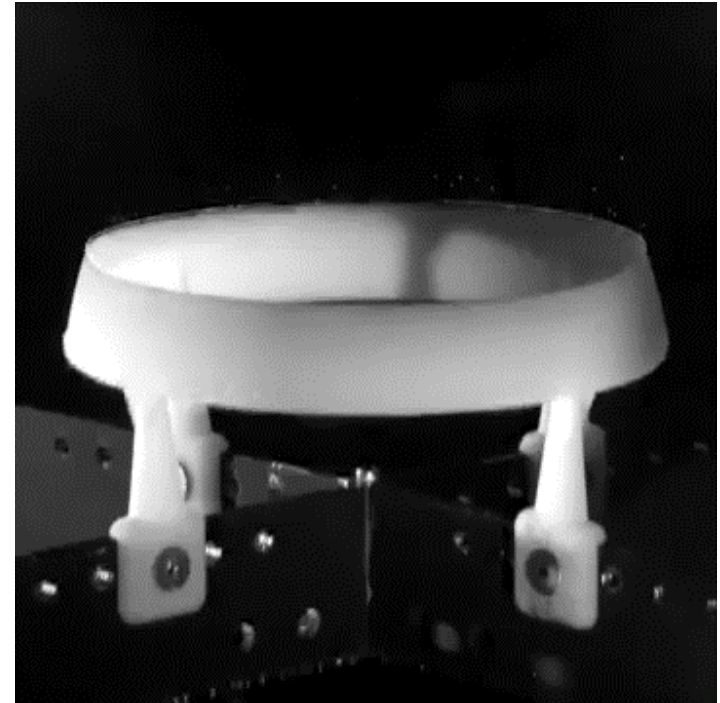
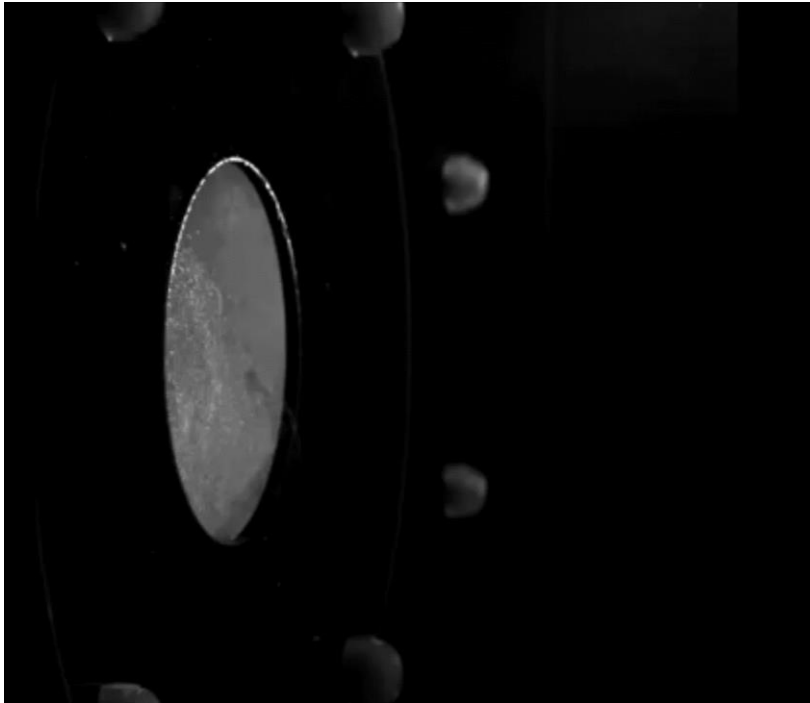
1. Vorticity measures the local rotation of the fluid
2. Vortex lines are "frozen" into inviscid fluids, they move along with the fluid



## Results produced at the Irvine Lab: <http://irvinelab.uchicago.edu/>



Kleckner, D., Irvine, W. Creation and dynamics of knotted vortices. *Nature Phys* **9**, 253–258 (2013).

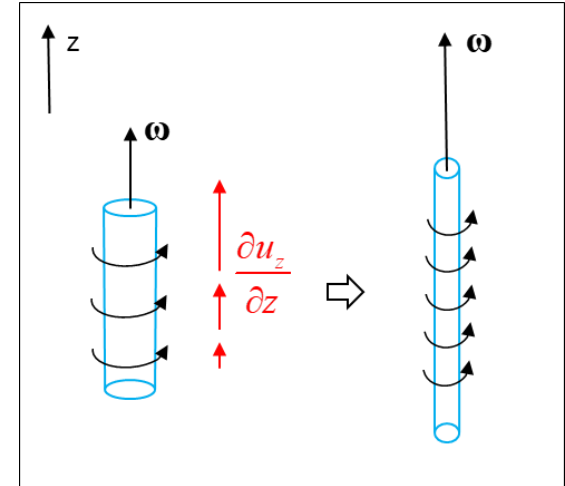
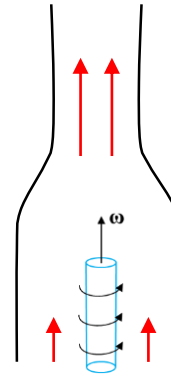


## Vortex tube stretching

$$\rho \frac{D\boldsymbol{\omega}}{Dt} = \rho (\boldsymbol{\omega} \cdot \nabla) \mathbf{V} + \mu \nabla^2 \boldsymbol{\omega}$$

Change of vorticity  
due to stretching  
or compression of  
a vortex

Change of  
vorticity due to  
viscous effects



### Direction parallel to vortex

$$\rho (\boldsymbol{\omega} \cdot \nabla) u_z = \rho \left( \omega_x \frac{\partial}{\partial x} + \omega_y \frac{\partial}{\partial y} + \omega_z \frac{\partial}{\partial z} \right) u_z = \rho \omega_z \frac{\partial u_z}{\partial z}$$

Stretching  $\Leftrightarrow \frac{\partial u_z}{\partial z} > 0$



$$\rho (\boldsymbol{\omega} \cdot \nabla) u_z > 0$$



RHS of vorticity equation may become positive, which means that vorticity increases in time

The figure also indicate that the crosssectional area of the vortex decreases during stretching. This is a combined effect of vortex tubes being material lines (move with the fluid) and mass conservation.

## Pressure vs Velocity & Vorticity

In Navier-Stokes equations we have four unknown variables,  $u, v, w$  and  $p$ , but we have no equation for  $p$ . Or do we...?

$$\rho \frac{\partial \mathbf{V}}{\partial t} + \rho (\mathbf{V} \cdot \nabla) \mathbf{V} = -\nabla p + \mu \nabla^2 \mathbf{V} + \mathbf{f}$$

$$\nabla \cdot \quad \Downarrow \quad \nabla \cdot \mathbf{V} = 0$$

By applying the divergence operator on NS, and using **mass conservation**, we get a Poisson equation for the pressure.

$$\nabla^2 p = -\nabla \cdot [\rho (\mathbf{V} \cdot \nabla) \mathbf{V} - \mathbf{f}]$$

The solution to this Poisson equation links the pressure to the velocity distribution for the whole domain. A change in the velocity at a point affects the whole pressure distribution.

**Physical interpretation:** Pressure waves generated by a change in velocity at a point sends information about the change throughout the whole fluid.

The vorticity equation do not have any pressure term.  $\rho \frac{\partial \boldsymbol{\omega}}{\partial t} + \rho (\mathbf{V} \cdot \nabla) \boldsymbol{\omega} = \rho (\boldsymbol{\omega} \cdot \nabla) \mathbf{V} + \mu \nabla^2 \boldsymbol{\omega}$

The velocity field cannot be considered localized in space, but the vorticity field can.

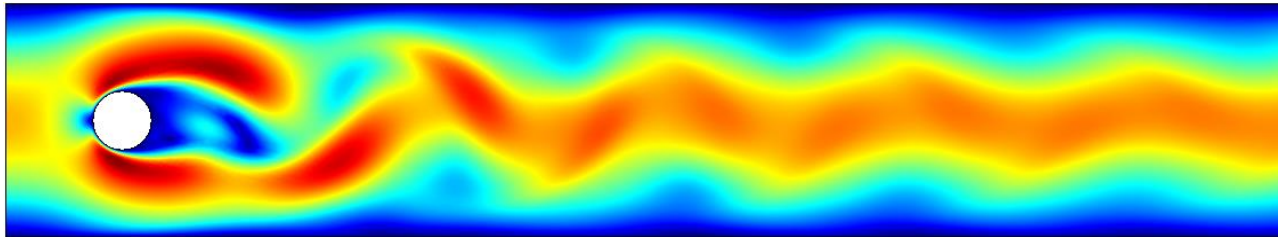
A localized velocity distribution will very fast affect the whole fluid through pressure waves, but a localized vorticity distribution can only spread by **advection** or **diffusion**.

## Vorticity generation in flow around a cylinder (Comsol Introduction lab)

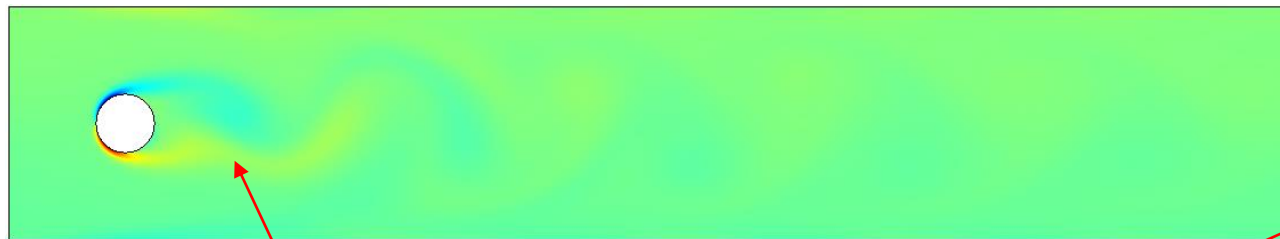
Geometry



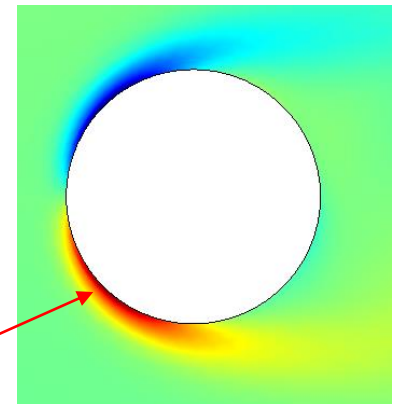
Velocity magnitude



Vorticity

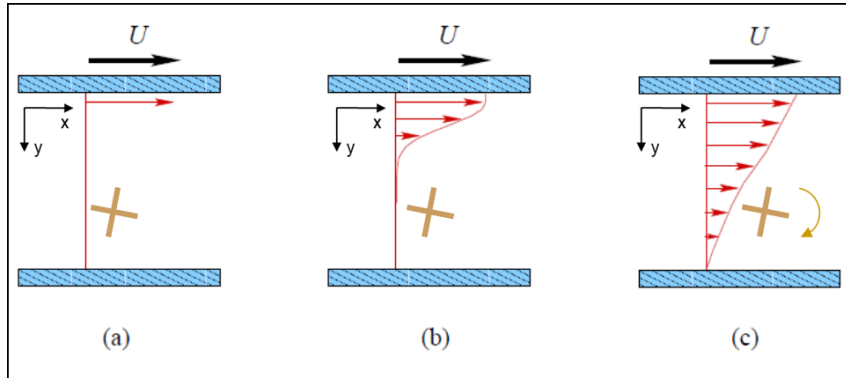


Advection



Diffusion

## Diffusion of vorticity

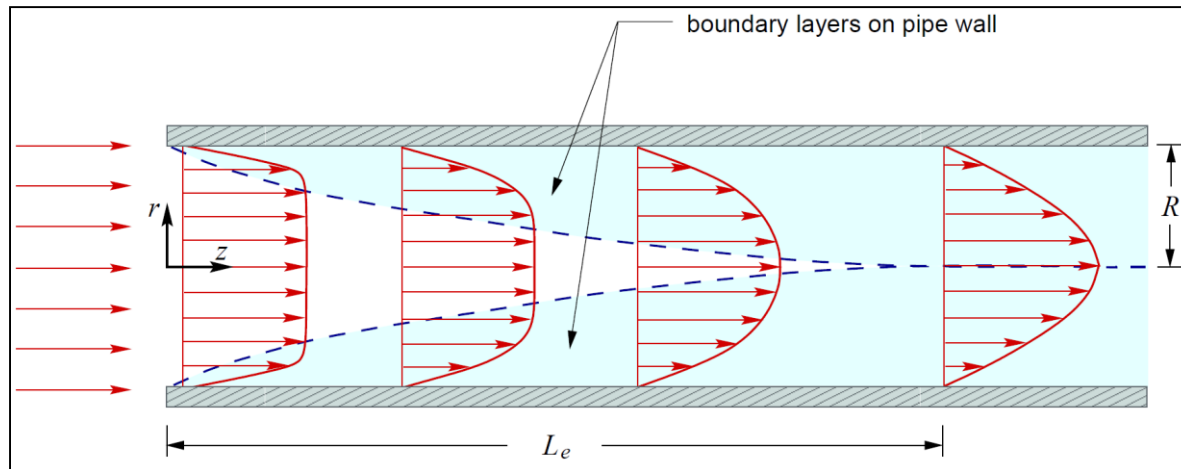


$$\rho \frac{\partial \boldsymbol{\omega}}{\partial t} + \rho (\mathbf{V} \cdot \nabla) \boldsymbol{\omega} = \rho (\boldsymbol{\omega} \cdot \nabla) \mathbf{V} + \mu \nabla^2 \boldsymbol{\omega}$$

$$\begin{aligned} \mathbf{V} &= V(y) \hat{\mathbf{x}} \\ \boldsymbol{\omega} &= \omega(y) \hat{\mathbf{z}} \end{aligned} \quad \rightarrow \quad \begin{aligned} (\mathbf{V} \cdot \nabla) \boldsymbol{\omega} &= 0 \\ (\boldsymbol{\omega} \cdot \nabla) \mathbf{V} &= 0 \end{aligned}$$

$$\rightarrow \frac{\partial \boldsymbol{\omega}}{\partial t} = \frac{\mu}{\rho} \nabla^2 \boldsymbol{\omega} \quad \text{Diffusion of vorticity}$$

$$\frac{\mu}{\rho} \sim \text{"diffusion coefficient"}$$



No vorticity at the inlet, it is created at the walls, **diffused** inwards and **advected**.

At the outlet the vorticity is non-zero throughout the flow.

## Diffusion of vorticity (cont)

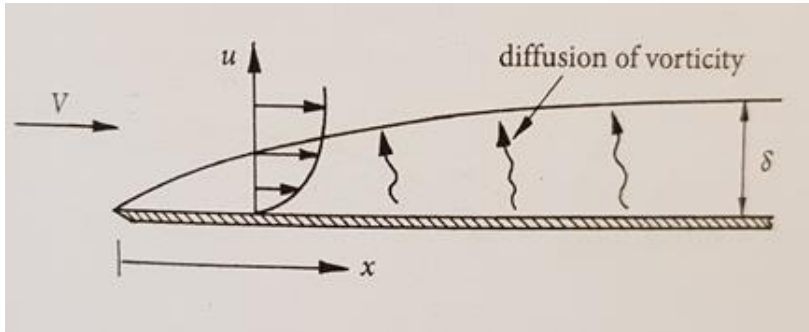


Figure 2.12 in Davidson

A boundary layer, laminar or turbulent, acts as a source of vorticity through diffusion.

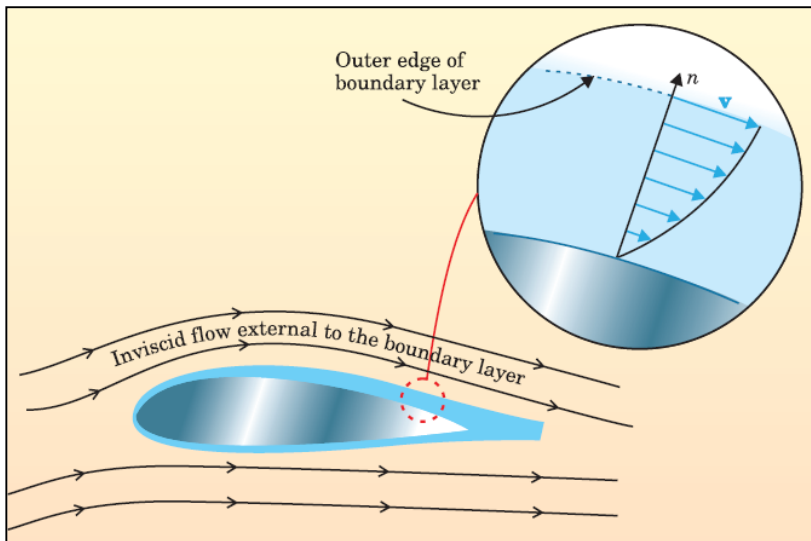
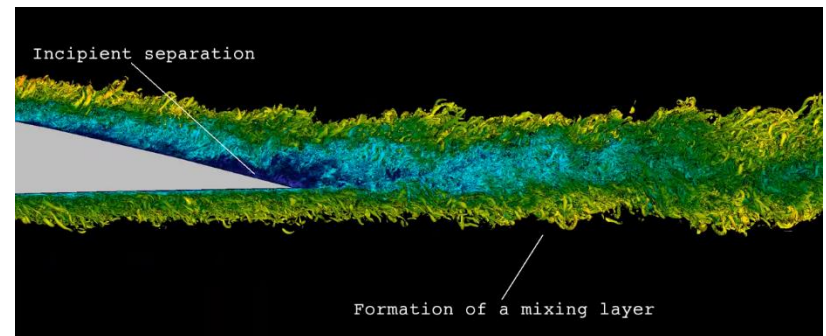
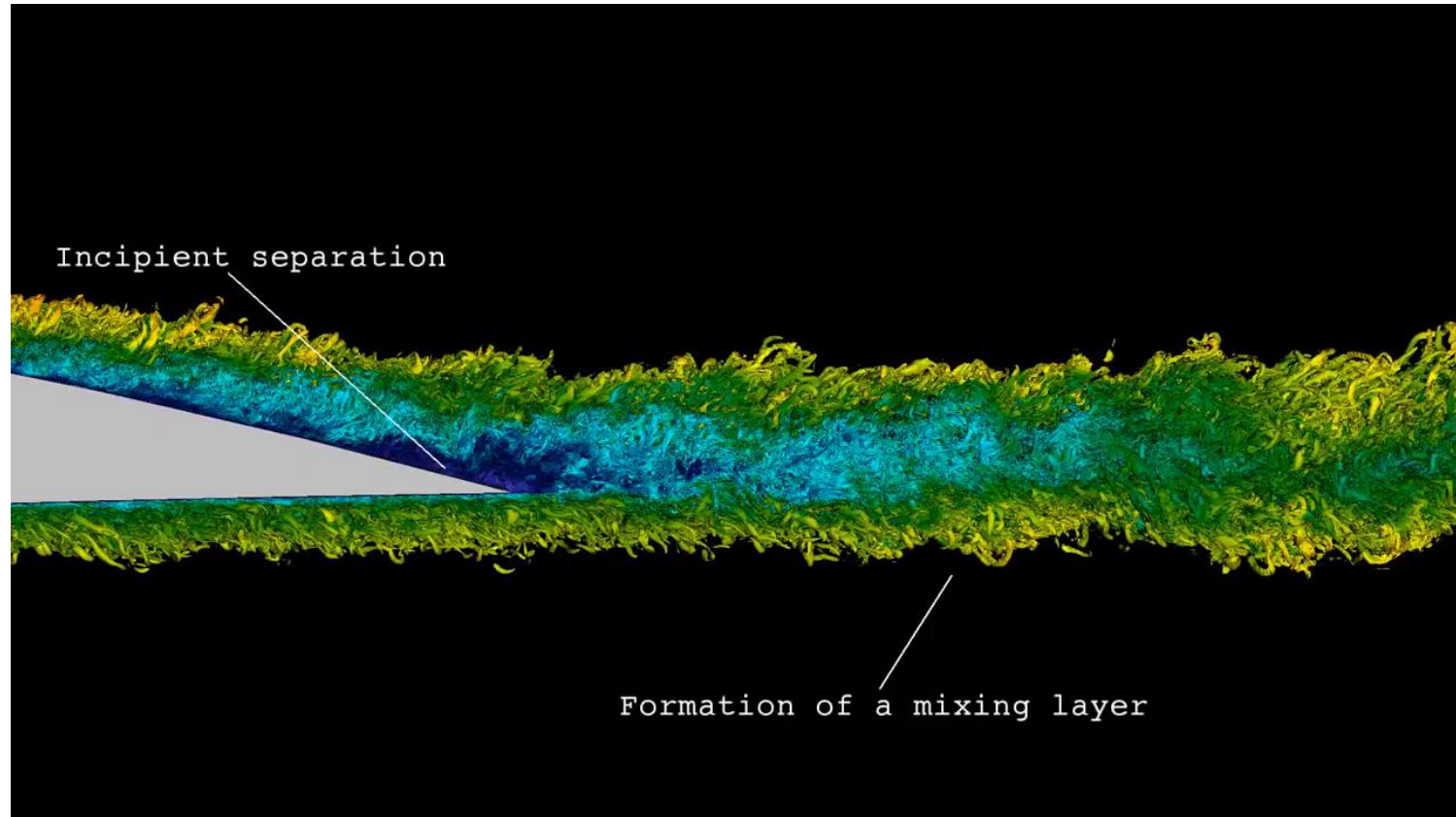


Figure 2 in "Ludvig Prandtl's Boundary Layer" by J.D. Andersson





## DEMO: Visualization of vorticity



# Navier-Stokes equations

## Index notation

## Navier-Stokes equations using index notation

$$\rho \frac{\partial u_i}{\partial t} + \rho \left( u_j \frac{\partial u_i}{\partial x_j} \right) = -\frac{\partial p}{\partial x_i} + \mu \frac{\partial}{\partial x_j} \frac{\partial u_i}{\partial x_j} + f_i$$

$$u_{i,i} = 0$$

$$u_{i,k} \equiv \frac{\partial u_i}{\partial x_k}$$

$$i = 1, 2, 3$$

$$j = 1, 2, 3$$

$$\begin{pmatrix} i = x, y, z \\ j = x, y, z \end{pmatrix}$$

$$u_1 = u_x, \quad u_2 = u_y, \quad u_3 = u_z$$

$$x_1 = x, \quad x_2 = y, \quad x_3 = z$$

### Example

$$u_{1,2} = u_{x,y} \equiv \frac{\partial u_x}{\partial y}$$

**Example:** Important physical quantities connected to velocity gradients

$$u_{i,j} = S_{ij} + \Omega_{ij}$$

$$S_{ij} = \frac{1}{2} (u_{i,j} + u_{j,i}) \quad \text{Rate of strain (symmetric)}$$


$$\Omega_{ij} = \frac{1}{2} (u_{i,j} - u_{j,i}) \quad \text{Rate of rotation (anti-symmetric)}$$

## Short tutorial: Index formalism

Einstein summation convention

$$A_i B_i \equiv \sum_i A_i B_i = A_1 B_1 + A_2 B_2 + \dots$$

Not specified  $i, k$



$A_i B_k$  are elements in a matrix:  $\begin{pmatrix} A_1 B_1 & A_1 B_2 \\ A_2 B_1 & A_2 B_2 \end{pmatrix}$

$$A_k B_k = A_1 B_1 + A_2 B_2$$

Example:

$$u_{k,k} \equiv \frac{\partial u_k}{\partial x_k} = \sum_k \frac{\partial u_k}{\partial x_k} = \frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} = \nabla \cdot \mathbf{V}$$

$$\mathbf{V} = u_x \hat{\mathbf{x}} + u_y \hat{\mathbf{y}} + u_z \hat{\mathbf{z}}$$

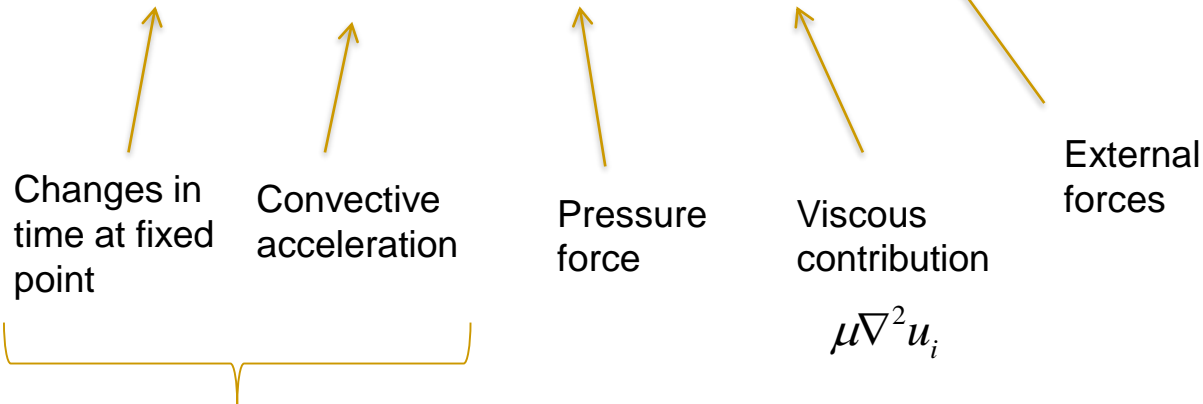
Example:

$$u_k \frac{\partial u_i}{\partial x_k} = u_x \frac{\partial u_i}{\partial x} + u_y \frac{\partial u_i}{\partial y} + u_z \frac{\partial u_i}{\partial z} = \left( u_x \frac{\partial}{\partial x} + u_y \frac{\partial}{\partial y} + u_z \frac{\partial}{\partial z} \right) u_i = (\mathbf{V} \cdot \nabla) u_i$$

$$u_j \frac{\partial u_i}{\partial x_j} = ?$$

## Example 1: Navier-Stokes equation- a physical interpretation of terms

$$\rho \frac{\partial u_i}{\partial t} + \rho \left( u_j \frac{\partial u_i}{\partial x_j} \right) = - \frac{\partial p}{\partial x_i} + \mu \frac{\partial}{\partial x_j} \frac{\partial u_i}{\partial x_j} + f_i$$



$$\rho \frac{Du_i}{Dt}$$

Changes in time following a fluid particle

## Example 2: The vorticity equation- a physical interpretation of terms

$$\rho \frac{\partial \omega_i}{\partial t} + \rho \left( u_j \frac{\partial \omega_i}{\partial x_j} \right) = \rho \left( \omega_j \frac{\partial u_i}{\partial x_j} \right) + \mu \frac{\partial}{\partial x_j} \frac{\partial \omega_i}{\partial x_j} + \xi_i$$

Changes in  
time at fixed  
point

Convective  
term

Vortex  
stretching

Viscous  
contribution  
 $\mu \nabla^2 \omega_i$

External  
source of  
vorticity

$$\rho \frac{D\omega_i}{Dt}$$

Changes in time  
following a fluid  
particle

## Navier-Stokes equation (cont.)

$$\rho \frac{\partial u_i}{\partial t} + \rho \left( u_j \frac{\partial u_i}{\partial x_j} \right) = - \frac{\partial p}{\partial x_i} + \mu \frac{\partial}{\partial x_j} \frac{\partial u_i}{\partial x_j} + f_i$$

Changes in  
time at fixed  
point

Convective  
acceleration

Pressure  
force

Viscous  
contribution  
 $\mu \nabla^2 u_i$

External  
forces

Reynolds number

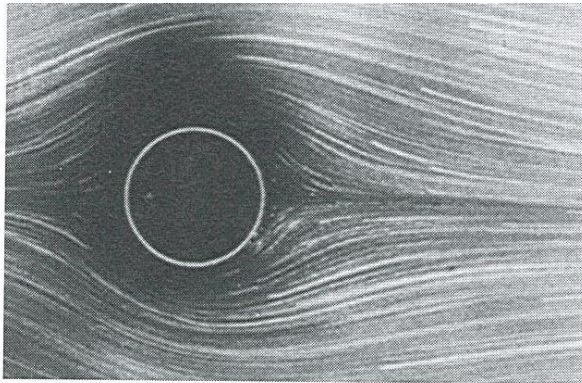
$$\text{Re} = \frac{\text{Convective term}}{\text{Viscous term}} \sim \rho \frac{U^2}{L} / \mu \frac{U}{L^2} = \frac{\rho L U}{\mu}$$

Order of magnitude analysis



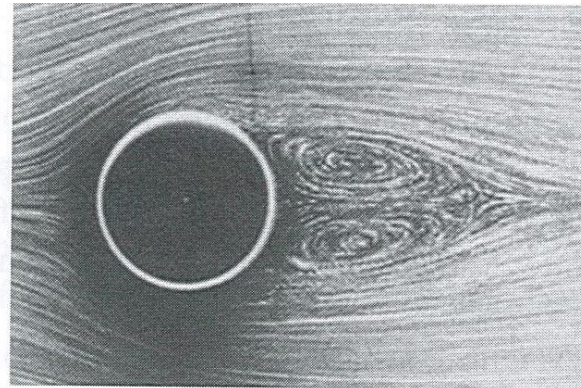
## Reynolds number: Flow pattern around a cylinder

$Re < 1$



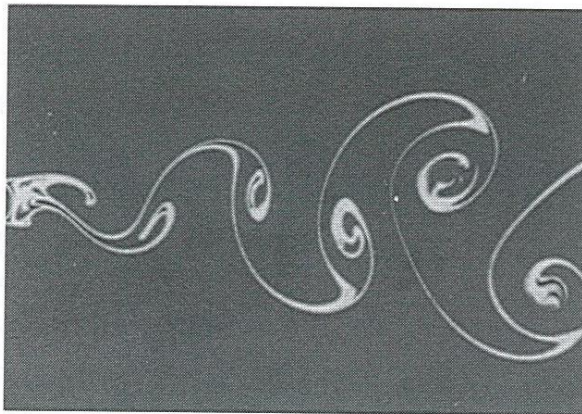
(a)

$Re = 26$



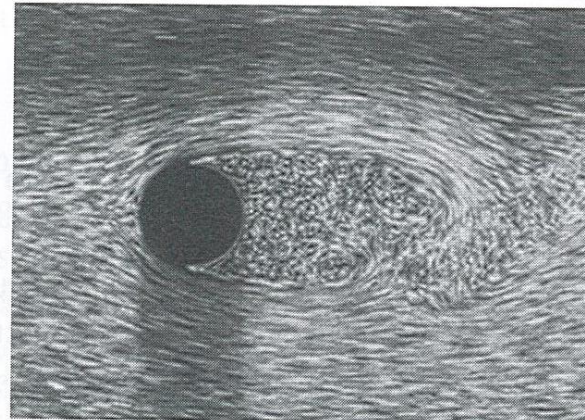
(b)

$Re = 140$



(c)

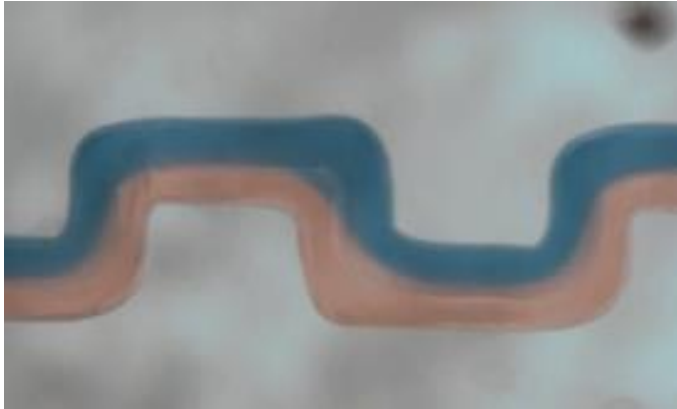
$Re = 2000$



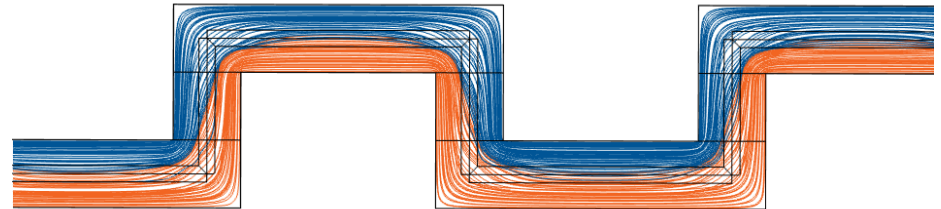
(d)

# Microfluidics in Biophysics: Experiment vs Simulation ( $Re \ll 1$ )

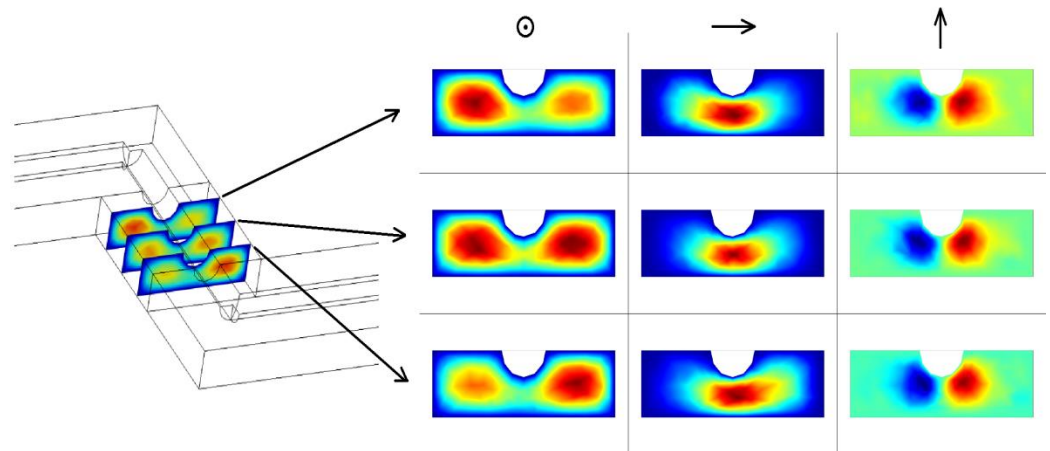
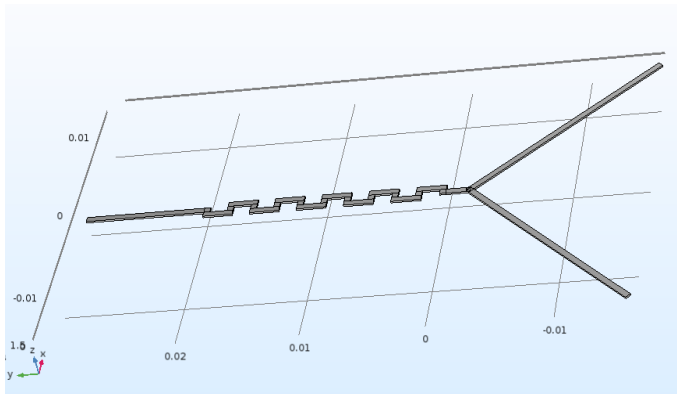
A CFD master thesis by Hampus Söderqvist, 2016



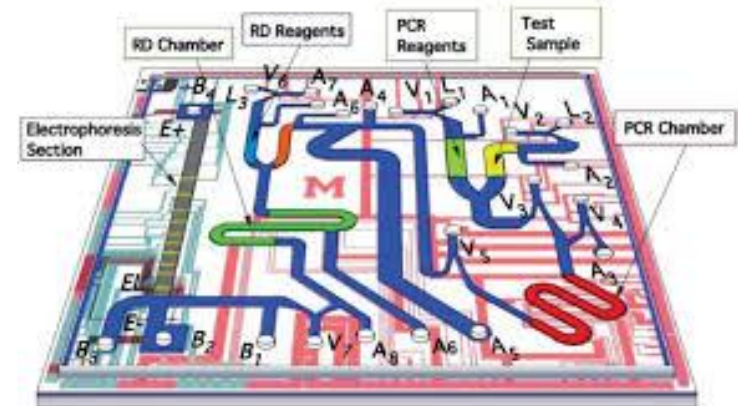
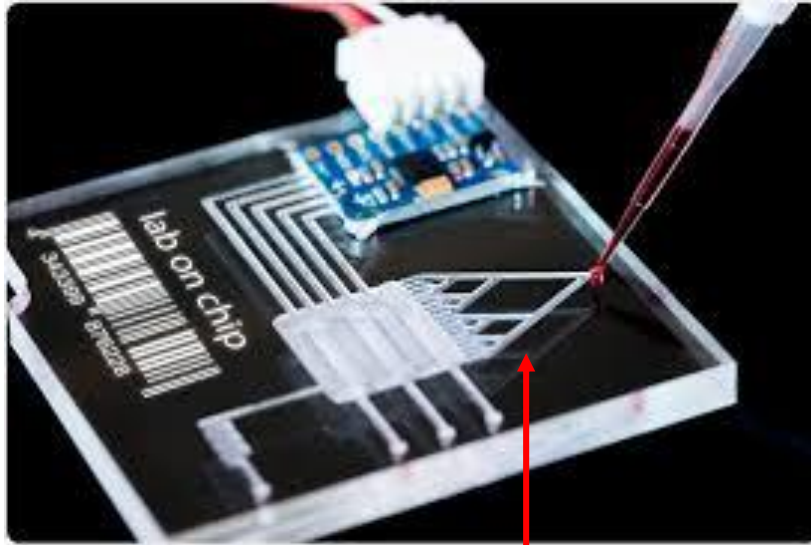
Experiment (3D-printed)



Simulation



## Microfluidics in Biophysics: Bio-chip = "mini factory"



One drop of blood can be splitted into several tests

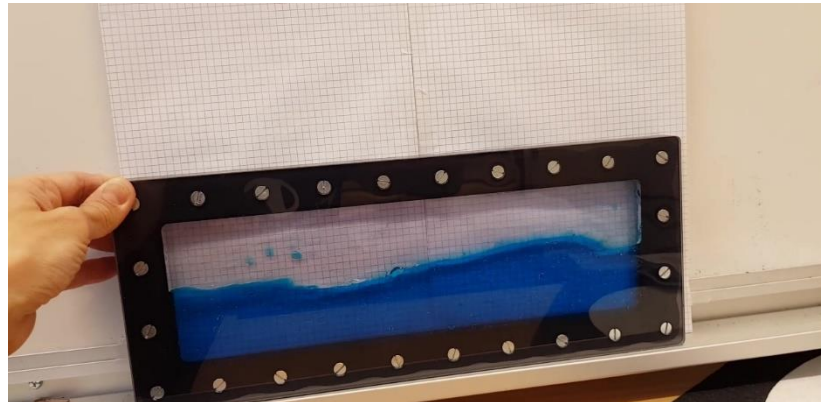
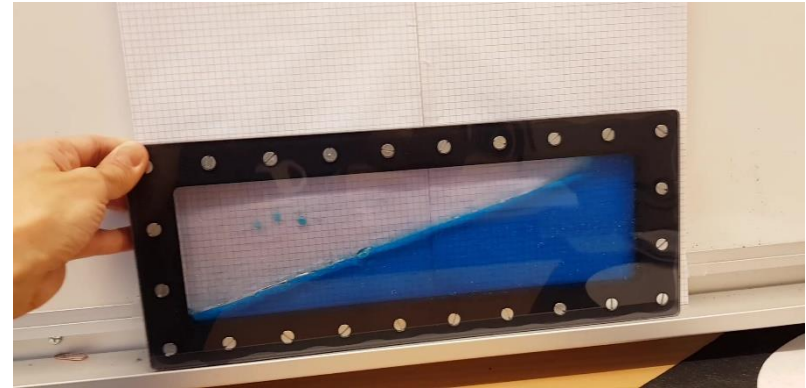
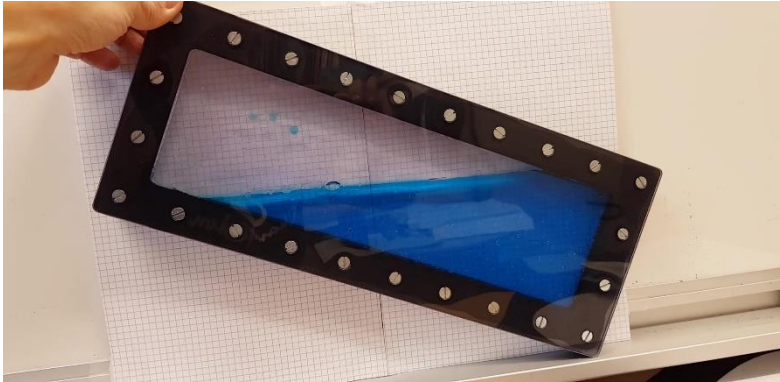
**Many tests on a small chip:**

Benefits = cheap and less volume of testing substrate needed



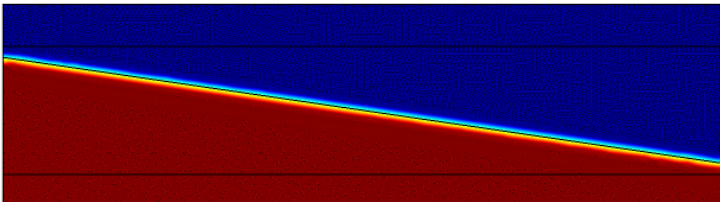
## Comsol Lab 1: Two-fluid Interface Dynamics Experiment (Low Re)

**Task:** Find a way to compare experiment and simulation

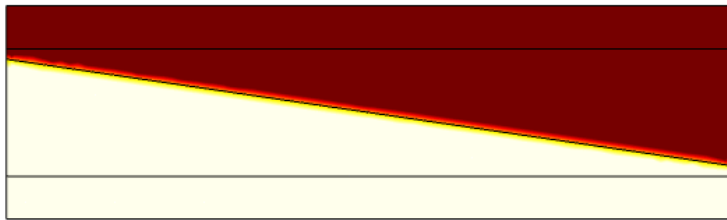


# Two-fluid Interface Dynamics Simulation

## MultiPhase-interface in Cmsol

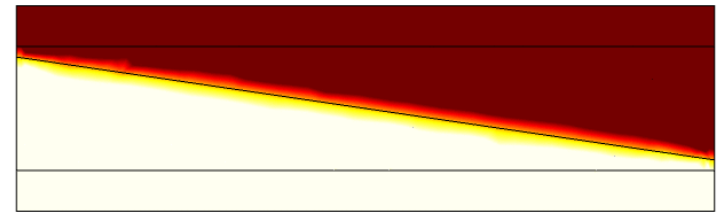


## Single-phase-interface in Cmsol



Fine mesh

## Single-phase-interface in Cmsol



Coarse mesh

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# End of lecture