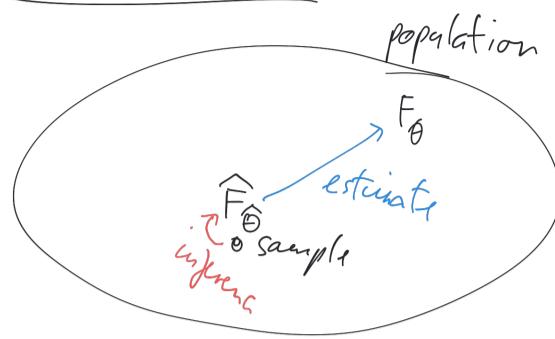


## Basic concepts



infinite ensemble of TS obs.

$$\{x_t^{(i)}\}, t = 1 \dots T, i = 1 \dots N$$

$$N \rightarrow \infty$$

$$\text{example: } \mu_t := E_i[x_t^{(i)}]$$

→ replace by a sample estimate

$$\hat{\mu}_t = \bar{x} = \frac{1}{T} \sum x_t$$

Ergodicity: "ensemble estim. can be replaced by sample estim."

$$\text{e.g. } E_i[x_t^{(i)}] = E_t[x_t^{(i*)}]$$

$$\underbrace{\lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N x_t^{(i)}}_{\text{weak sense stat.}} \quad \underbrace{\lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T x_t^{(i*)}}_{\text{strong stat.}}$$

## Stationarity

"weak sense stat."

$$E[x_t] = \mu_t = \text{const. } \forall t$$

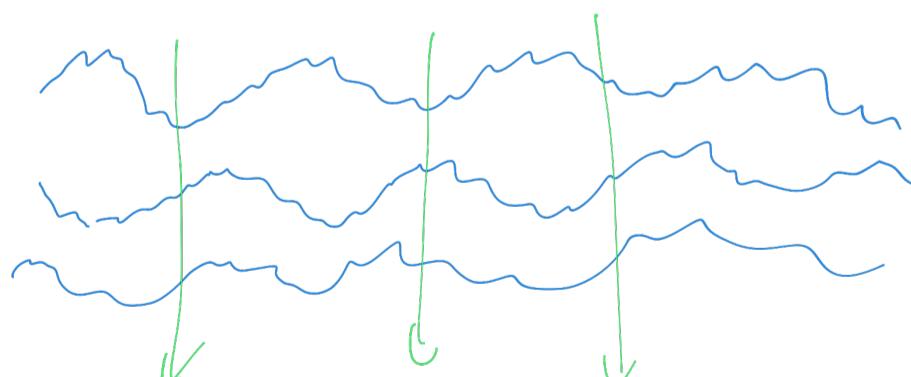
$$\text{acov}[x_t, x_{t+\Delta t}] = \text{acov}[s(t)] \quad \forall t, \Delta t$$

"strong stat."

$$P(\{x_t | t_0 \leq t \leq t_f\}) = P(\{x_t | t_0 + \Delta t \leq t \leq t_f + \Delta t\})$$

$\forall t_0, t_f, \Delta t$

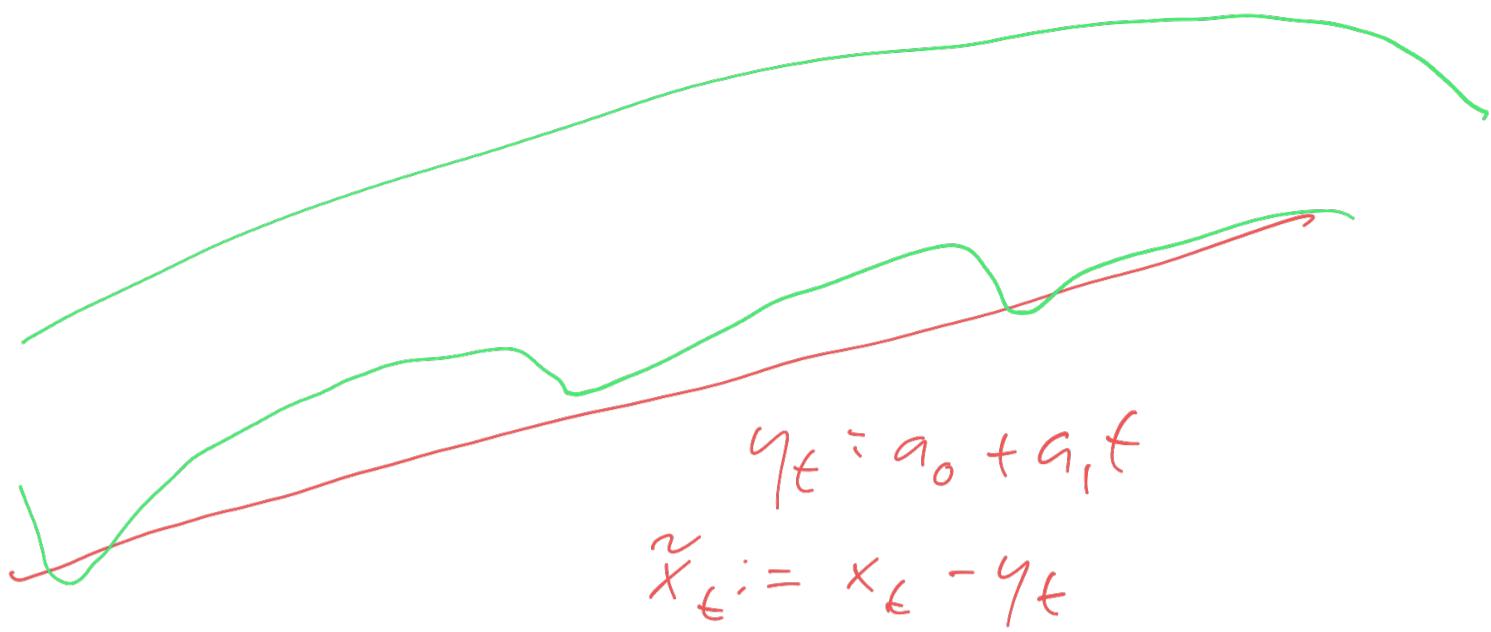
def. apply across an ensemble of TS



$$x_i(t) = a \sin(\omega t + \phi_i) + \varepsilon(t)$$

$$E[x_t | x_{t-1}] \neq E[x_t | x'_{t-1}]$$

$$\text{for } x_{t-1} \neq x'_{t-1}$$



What if my TS is non-stationary?

1) power spectrum : remove lowest  
freq. comp.  $\rightarrow$  transform back

HPF

2) "Differencing TS"  
create new TS  $\tilde{x}_t := x_t - x_{t-1}$   
 $\rightarrow$  may amplify noise!  
 $\rightarrow$  may remove other important aspects  
of TS

3) fit a model to TS that captures  
systematic var.  $\rightarrow$   
subtract off

Def. "white noise"

"no cov. in TS at all" means

$$E[x_t] = 0$$

$$E[x_t x_{t'}] = \begin{cases} G^2 & \text{for } t=t' \\ 0 & \text{for } t \neq t' \end{cases}$$

$$x_t \sim W(0, G^2)$$

power spectrum  
is flat!

Def. autocor & cross func.

$$\text{acov}[x_t, x_{t+\Delta t}] := E[(x_t - \mu_t)(x_{t+\Delta t} - \mu_{t+\Delta t})]$$

$$= E[x_t x_{t+\Delta t}] - \mu_t \mu_{t+\Delta t} \equiv \gamma(x_t, x_{t+\Delta t})$$

↪ def. across infinite ensemble

$$\text{acov}[x_t, x_{t+\Delta t}] := \frac{\gamma(x_t, x_{t+\Delta t})}{G_t G_{t+\Delta t}}$$

$$= \rho(x_t, x_{t+\Delta t}) \in [-1, +1]$$

Cross-cov. among TS  $\{x_t\}$  and  $\{y_t\}$

$$\text{xcov}[x_t, y_{t+\Delta t}] := E[(x_t - \mu_t^{(x)})(y_{t+\Delta t} - \mu_{t+\Delta t}^{(y)})]$$

$$\equiv \gamma(x_t, y_{t+\Delta t})$$

$$\text{xcov}[x_t, y_{t+\Delta t}] := \frac{\gamma(x_t, y_{t+\Delta t})}{G_t^{(x)} G_{t+\Delta t}^{(y)}}$$

Remarks

assume ergodicity and stationarity

$$1) \Rightarrow \mu_t = \mu_{t+\Delta t}$$

$$G_t^2 = G_{t+\Delta t}^2 \quad \text{for any } \Delta t, t$$

$$\text{acov}[x_t, x_{t+\Delta t}] = \text{acov}(\Delta t) \quad \begin{array}{l} \text{parav} \\ \text{st} \end{array}$$

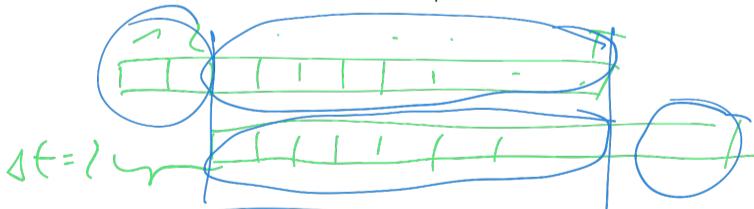
$$\rho(st) := \frac{\gamma(\Delta t)}{\gamma(0)}$$

2) replace ensemble estim. by sample estim.

$$\hat{\mu} = \bar{x} = \frac{1}{T} \sum_{t=1}^T x_t, \{x_t\}, t=1 \dots T$$

$$\hat{G}^2 = S_x^2 = \frac{1}{T} \sum_{t=1}^T (x_t - \bar{x})^2$$

$$\hat{\gamma}(st) = \frac{1}{T-st} \sum_{t=1}^{T-st} (x_t - \bar{x})(x_{t+st} - \bar{x})$$



$$3) \quad \rho(st) = \rho(-st)$$

4) "1:1" relation b/w. acov-func. & power spectrum

→ Wiener-Khinchin theorem

assume periodic func.

$$x(t) = x(t+\Delta t) \quad \forall t; \Delta t \text{ fixed}$$

## Auto-regressive Moving-Average (ARMA) models

- provides a baseline for RNN

Obs.:  $\{x_t, \varepsilon_t, t=1 \dots T\}$

$$x_t = a_0 + \underbrace{\sum_{i=1}^p a_i x_{t-i}}_{\text{AR}(p)} + \underbrace{\sum_{j=1}^q b_j \varepsilon_{t-j}}_{\text{MA}(q)} + \varepsilon_t, \quad \varepsilon_t \sim W(0, \sigma^2)$$

random part

exogenous inputs

$p=2$        $q=3$

$x_{t-2} \ x_{t-1} \ x_t$

$a_1 \quad b_1 \quad b_2 \quad b_3$

$\varepsilon_{t-3} \ \varepsilon_{t-2} \ \varepsilon_{t-1} \ \varepsilon_t$

- inference (cfit.)  
- training (vc)  
- fitting

What to do with such a model?

- Is model a good descrip. of TS?
- stationary?
- optimal order  $p, q$ ? ARMA( $p, q$ )
- test Hyp.:  $a_i \neq 0, b_j \neq 0$   
 $a_i > 0 \quad c_k \neq 0$
- prediction

$0 \rightarrow 0 \rightarrow 0 \rightarrow 0 \rightarrow 0 \rightarrow \overset{T}{\overbrace{0}} \rightarrow 0 \rightarrow 0$

ARMA( $p, q$ )  
run forward in time

Properties of ARMA models

### • Basic duality b/w AR and MA parts

assume AR(1) model:

$$x_t = a_0 + a_1 x_{t-1} + \varepsilon_t, \quad \varepsilon_t \sim W(0, \sigma^2)$$

"initialize"  $x_1 = a_0 + \varepsilon_1$

$$\begin{aligned} E[x_T] &= a_0 + a_1 x_{T-1} + \varepsilon_T \\ &= a_0 + a_1 (a_0 + a_1 x_{T-2} + \varepsilon_{T-1}) + \varepsilon_T \\ &= a_0 + a_1 (a_0 + a_1 (a_0 + a_1 x_{T-3} + \varepsilon_{T-2}) + \varepsilon_{T-1}) + \varepsilon_T \\ &= \dots \end{aligned}$$

$E[a_0] \sum_{i=0}^{T-1} a_1^i + \sum_{i=0}^{T-1} a_1^i E[\varepsilon_{T-i}]$

$\frac{a_0}{1-a_1} \rightarrow \frac{a_0}{1-a_1} \text{ for } T \rightarrow \infty \text{ if } |a_1| < 1$

1) expanded into MA( $\infty$ ),  $T \rightarrow \infty$

2) for  $|a_1| > 1$ : will diverge!!!  
(non-stationary)

$$E[\sum a_1 \varepsilon_i] = \sum a_1 E[\varepsilon_i] \neq 0$$

$$3) E[x_T] = \frac{a_0}{1-a_1} \neq a_0 \text{ for } a_0, a_1 \neq 0$$

• reexpress MA(1) as an AR(∞)

$$x_T = \varepsilon_T + b_1 \varepsilon_{T-1} = \varepsilon_T + b_1 (x_{T-1} - b_1 \varepsilon_{T-2})$$

$$= x_{T-1} - b_1 \varepsilon_{T-2}$$

$$= \dots = \sum_{i=1}^{T-1} b_1 x_{T-i} + \varepsilon_T$$

- Relation betw. coeff. of our AR process and the acor func.

- example: AR(1)

$$x_t = a_0 + a_1 x_{t-1} + \varepsilon_t, \quad \varepsilon_t \sim N(0, \sigma^2)$$

- assume  $a_0 = 0$ , otherwise

subtract off  $E[x_t] = \frac{a_0}{1-a_1}$   
 provided  $|a_1| < 1$

$$E[x_t x_{t-1}] = E[a_1 x_{t-1} x_{t-1}] + E[\varepsilon_t x_{t-1}]$$

$\underbrace{E[\varepsilon_t] E[x_{t-1}]}_{=0} = 0 \quad \underbrace{E[\varepsilon_t \varepsilon_{t-1}]}_{=0} = 0$

$x_{t-1} = \sum_{i=0}^{t-2} a_1^i \varepsilon_{t-1-i} + \dots$  for  $t \neq 1$