Domain 1	Domain 2	Domain 3	Domain 4	Domain 5
desired airplane table y adaptive airplane stability adaptive airplane stability along the company of the compa	heterogeneous searchscheduling locationagents ment problem kassignment searchscheduling locationagents ment searchscheduling locationagents searchscheduling locationagents searchscheduling locationagents searchscheduling locationagents searchscheduling locationagents searchscheduling locationagents fleet planning communication recommunication recom	prevailing path planning performance performance provided in the planning performance perf	moving agents lawautomatic have a lawautomatic have a lawautomatic have a lawautomatic house have a lawautomatic house have a lawautomatic ha lawautomatic have a lawautomatic have a lawautomatic have a lawa	path_planning_complete map pattern region objective multi route split probot path sensor pattico area decomposition of path planning Cover surveillance
Domain 6	Domain 7	Domain 8	Domain 9	Domain 10
integrated guidance plane analytical gardynami carrent laage analytical gardynami carr	disturbancessliding robust rotor of adding mode	command agiletransition flight	obstacles path planning risk search constraints optimization nath risk search constraints	collision avoidance
class to a sensing through the sensing through the sensing through the sensor flat 8 vector platform	scheme mode estiding mode design finite error backstepping external	maneuvers	planning risk search constraints optimization	avoidance
vision in partial detection vector platform optical detection of the property	transition tracking hybrid observer observer	pilotexecution library	path_planning layer environments	collision navigation conflict cooperative
Domain 11	Domain 12	Domain 13	Domain 14	Domain 15
motion random tree	formation	phase platform emergency emergency altitude thrust	planning vector, and path at laying guide wax maximum path robot	clustering modeldeep terminal interaction are network air crafts
risktree spline kindoynamic ree spline exploring rapidly exploring red conjunction free planning graph mostacles redge collision free	group team coordinate position leader waypoints strategy leader desired	landing site loss	curvature	predictive
random uas static space rapidly exploring planner practices.	flight following proveshape locationglobal disturbances	glide adjusted successification mobile engine ground Site engine ground site engine ground site engine generation possible engine	bounded dubins speed smooth speed CULVE Sroadmap	learning store reinforcement well a store neural