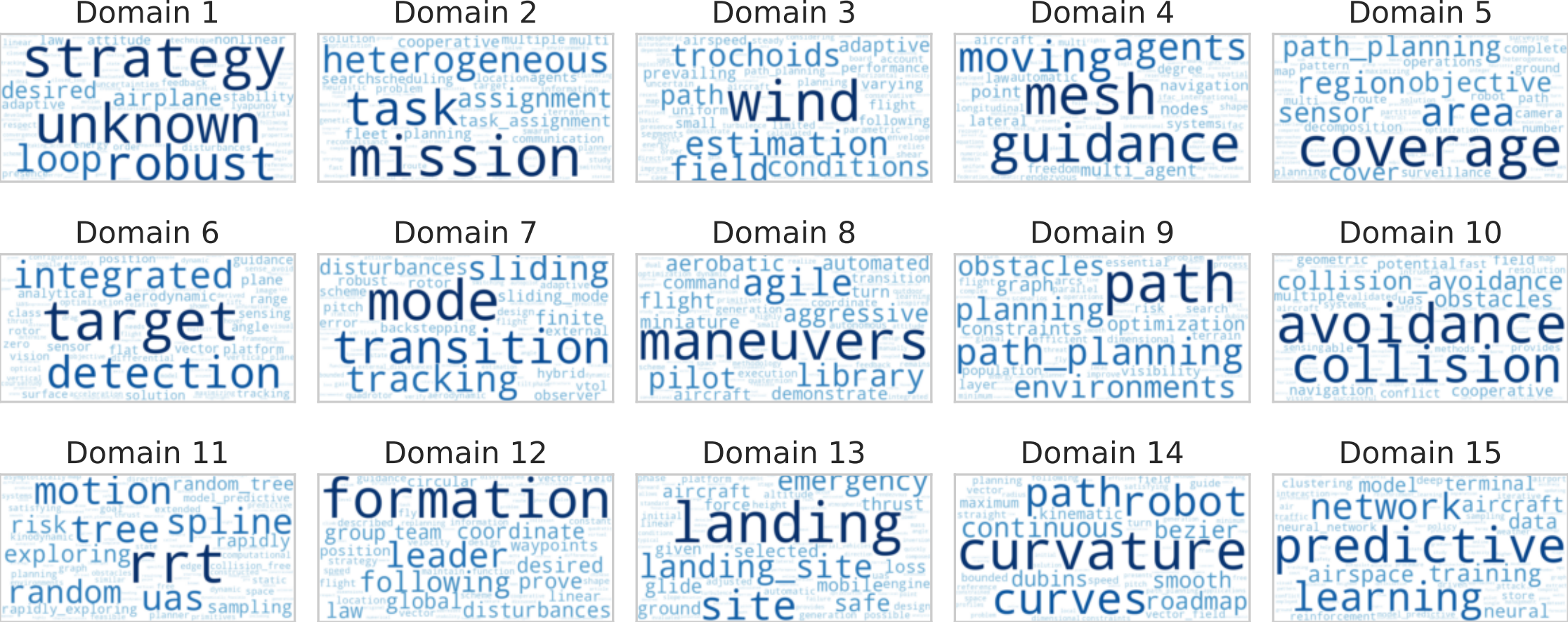
Domain 1
strategy
unknown
robust
loop
desired
airplane
Domain 2
heterogeneous
task
assignment
mission
Domain 3
trochoids
wind
estimation
field
conditions
path
Domain 4
moving
agents
mesh
guidance
Domain 5
path_planning
region
objective
sensor
area
coverage
Domain 6
integrated
target
detection
Domain 7
disturbances
sliding
mode
transition
tracking
Domain 8
aerobatic
agile
maneuvers
pilot
library
Domain 9
obstacles
path
planning
path_planning
environments
Domain 10
collision_avoidance
avoidance
collision
Domain 11
motion
tree
spline
rrt
random
uas
Domain 12
formation
leader
following
Domain 13
emergency
landing
landing_site
site
Domain 14
path
robot
curvature
curves
Domain 15
network
predictive
learning