1   Introduction

Intro here

2   Sinumerik code

waow

```
EXTERN MEAS_AX_TORQUE(AXIS, INT, INT)

XZ_HOME ;Goto home pos
MEAS_AX_TORQUE(X , 360 , 361) ;Setup axis monitoring
G0 X100

M2
```

Listing 1: Test-program used during test runs.

3   Python code

$$\text{waow}^2 \tag{1}$$

```
def compute_gott_mos(lvl):
  if lvl < 0:
    lvl = np.inf
  return lvl
```

Listing 2: Python 4 life <3