

# FACTORIAL HMM

Th  is BAZIN, Valentin DE BORTOLI  
theis.bazin@ens-paris-saclay.fr, vdeborto@ens-paris-saclay.fr

## Introduction

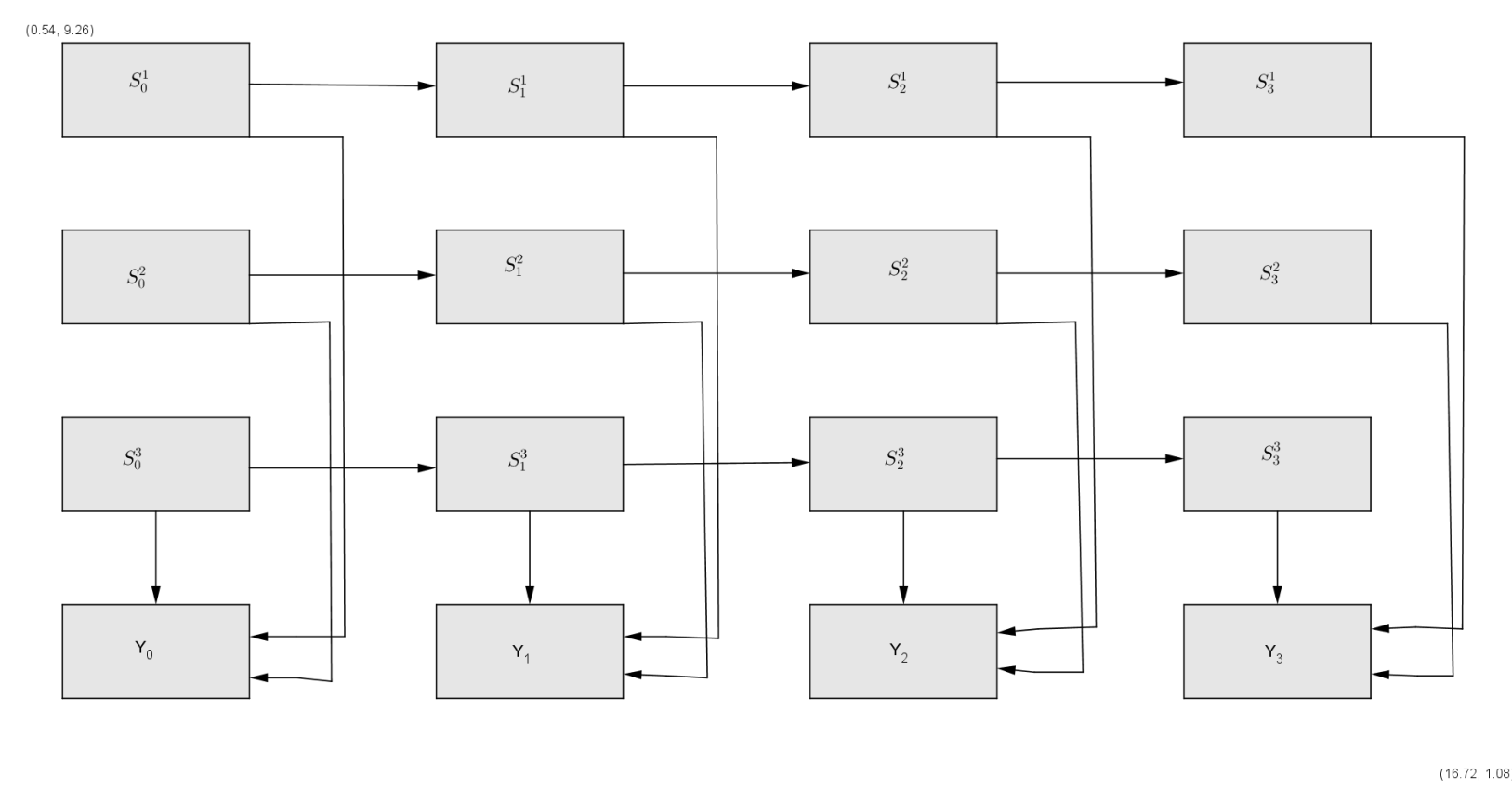
We present the Factorial Hidden Markov Model, FACTORIAL HMM, as introduced by Ghahramani and Jordan, an extension of HMM, and methods to perform inference on this model.

**Context** HMM assumes the hidden variable to be single multinomial variable, this can lead to computational issues,

**HMM limitation** Suppose we want to describe  $M = 30$  binary states [1],

- Using HMM the state space has size  $2^{30}$ ,
- Using *distributed* reduces this to only  $M = 30$  binary states.

This yields the FACTORIAL HMM model:



**Figure 1:** Graphical model for Factorial HMM

## An EM algorithm...

Training this model can be done per the EM algorithm [2].

**E-STEP** Compute the posterior  $p(S_{(t)}^{(m)} | Y_{(t)}, \theta)$

**M-STEP** Update the parameters  $\theta$

M-STEP is *easy* but E-STEP can be *really hard* [1] to compute. Recall that in the HMM we used an alpha-beta recursion to deal with the E-STEP. We present three different ways to deal with E-STEP:

- Exact inference,
- Gibbs sampling,
- Variational methods.

## Exact inference

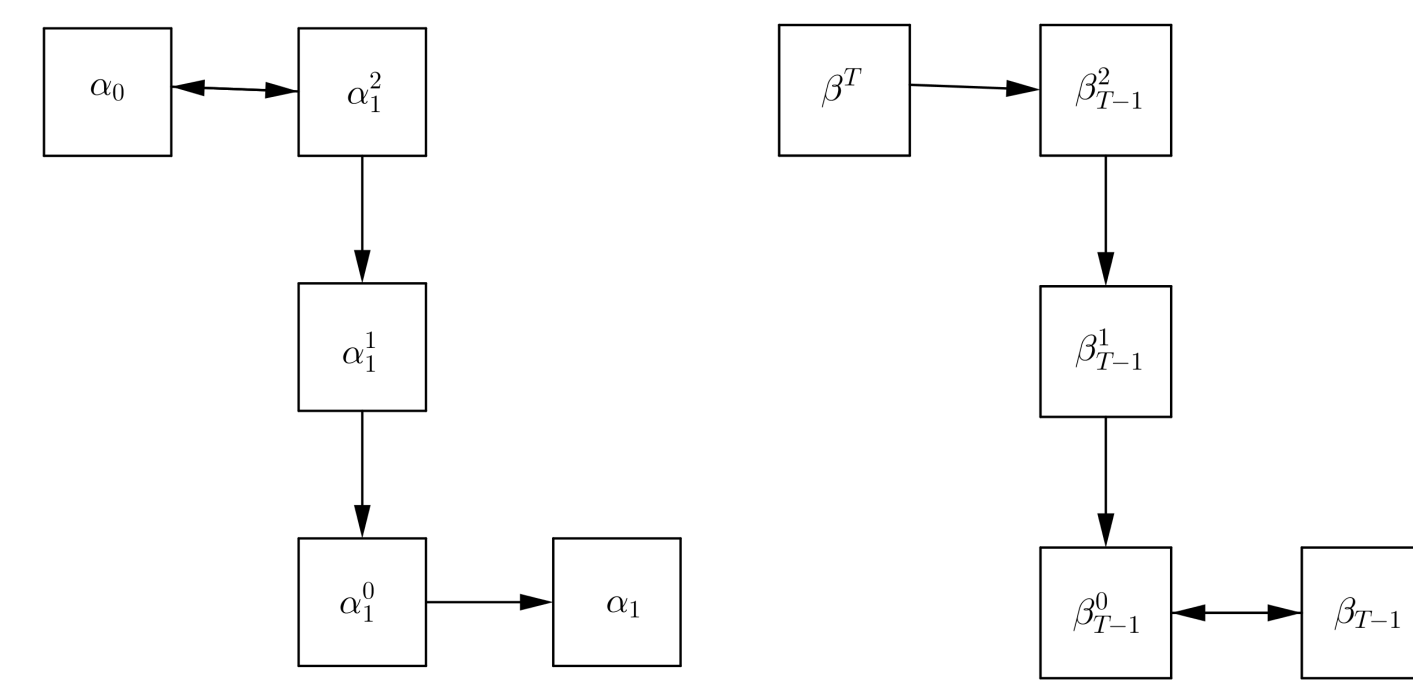
The exact inference allows us to compute the posterior distribution setting:

$$\begin{cases} \alpha_t = p(S_t^1, \dots, S_t^M, Y_{(1,t)} | \theta) \\ \alpha_t^m = p(S_{t-1}^1, \dots, S_{t-1}^m, S_t^{m+1}, \dots, S_t^M | \theta) \\ \beta_t = p(Y_{(t+1,T)} | S_t^1, \dots, S_t^M, \theta) \\ \beta_{t-1}^m = p(Y_{(t+1,T)} | S_t^1, \dots, S_t^m, S_{t-1}^{m+1}, \dots, S_{t-1}^M, \theta) \end{cases} \quad (1)$$

Thus we have:

$$\gamma_t = P(S_t | Y_{(t)}, \theta) \propto \alpha_t \beta_t \quad (2)$$

$\alpha_t$  and  $\beta_t$  can be computed recursively:



**Figure 2:** alpha-beta recursions

## Gibbs sampling

To go through we do not need to compute the posterior but only  $\langle S_t^m \rangle$ ,  $\langle S_t^m S_t^n \rangle$  and  $\langle S_{t-1}^m S_t \rangle$ . Using the law of large numbers and MCMC methods we can avoid doing exact inference. We use Gibbs sampling here. Since we have a graph structure the iteration gives:

$$\begin{aligned} P(S_t^m | S_{(-t)}^{(m)}, Y_{(t)}, \theta) &\propto \\ P(S_t^m | S_{t-1}^{(m)}) P(S_{t+1}^m | S_t^{(m)}) P(Y_t | S_t^{(m)}) \end{aligned} \quad (3)$$

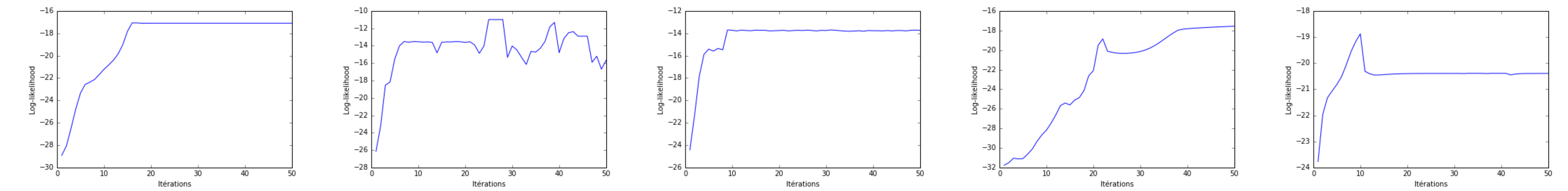
We use an *impatient* Gibbs sampler, that is we only pick few samples and introduce no burn-in period: We do not try to reach convergence since this algorithm can be very slow.

## References

- [1] Zoubin Ghahramani and Michael I Jordan. Factorial hidden markov models. *Machine learning*, 29(2-3):245–273, 1997.
- [2] CF Jeff Wu. On the convergence properties of the em algorithm. *The Annals of statistics*, pages 95–103, 1983.

## Results

We implemented all the four described methods and tested our implementation computing the evolution of the log-likelihood (experiments:  $K = 2$ ,  $M = 3$ ).



**Figure 3:** Log-likelihood over EM iterations for the different models (from left to right: exact inference, impatient Gibbs sampling, Gibbs sampling with burn-in, mean-field, structured mean-field)

Note that the log-likelihood is not always increasing for the variational models since we compute an approximate log-likelihood.

In [1] the author suggested using only 10 samples and no burn-in for the Gibbs sampling however we found that adding a small burn-in period smoothed our log-likelihood.

| E-STEP method                  | Iteration duration (s) |
|--------------------------------|------------------------|
| HMM- exact inference           | 0.453                  |
| FACTORIAL HMM- exact inference | 0.429                  |
| Gibbs sampling                 | 1.100                  |
| MEAN-FIELD                     | 0.053                  |
| STRUCTURED MEAN-FIELD          | 0.319                  |

**Table 1:** Computation times

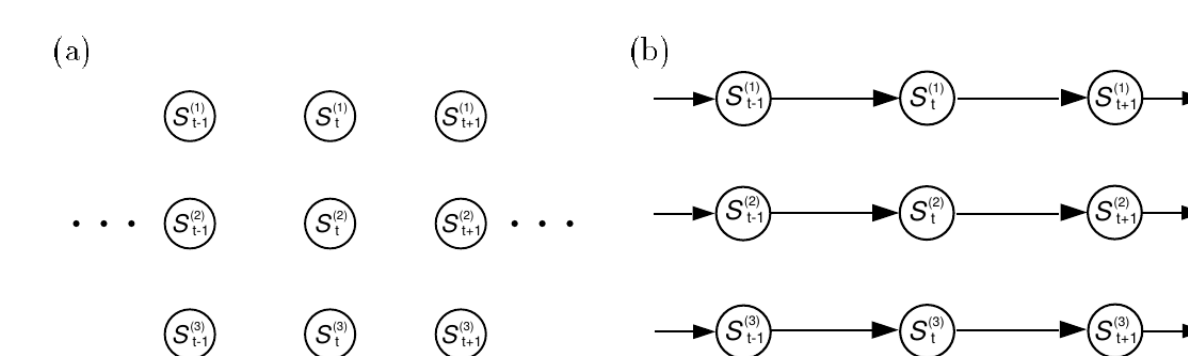
As  $M$  increases exact inference became intractable and Gibbs sampling inefficient. Variational methods are still satisfactory though.

## Variational methods

Using MCMC we have no information regarding the speed of convergence to the posterior.

We now introduce a new family of methods which put constraints on the E-STEP thus not yielding the posterior but a *constrained* posterior:

- MEAN-FIELD: all hidden states are supposed independent,
- STRUCTURED MEAN-FIELD: we relax the constraint and suppose we have  $M$  independent Markov chains.



**Figure 4:** Graphical models for the variational inference (mean-field, structured mean-field)

## Conclusion and future work...

In our work:

- We implemented the four methods to perform inference (the E-STEP) on FACTORIAL HMM,
- we investigated the mathematical model behind FACTORIAL HMM,
- and we experimentally verified the benefits of variational models in dealing with large space states.

**What's next** As next steps, we wish to test our implementation on real data (the Bach Chorales) and compare the properties of this model versus HMM on test data.