```
terms
                                         boolean value
                                         numeric value
                                                                                                     configuration - values
                                                                    ::=
                                               operator
                                                                            b
                                                                                                              boolean value
                                            abstraction
                                                                                                              numeric value
                                                variable
                                                                                                                    operator
                                            application
                                                                            ((\lambda x.\ t)^{T\to T})[s]
                                                                                                                      closure
             \mathsf{mlet}\ x:T=t\ \mathsf{in}\ t
                                        overloading let
             t :: T
                                              ascription
                                                                                                              configurations
                                                                    ::=
                                                                            v
                                         boolean value
b
     ::=
                                                                            t[s]
             true
                                             true value
             false
                                             false value
                                                                            \mathsf{mlet}\ x:T=c\ \mathsf{in}\ c
                                              operators
op
                                                                            error
             add1
                                                    sum
                                                                                                      explicit substitutions
                                               negation
             not
                                                                                                        empty substitution
                                                                                                       variable substitution
T
                                                   types
             Int
                                       type of integers
             Bool
                                      type of booleans
             T \to T
                                      type of functions
```

Figure 1: Syntax of the simply typed lambda-calculus vith overloading.

- Deterministic.
- Type error detection.
- Dispatch error detection.
- Ambiguity error detection.
- Type annotation in lambda functions, mlet and ascription.
- More expressive than Semantic 3, with the use structural tags.
- Do not support context-dependent overloading.

Definition 1 (\oplus). Given an environment s and a variable binding $x \mapsto (v_1 : T_1)$, the operator \oplus is defined as follows:

$$s \oplus x \mapsto (v_1:T_1) = \begin{cases} x \mapsto \{(v_1:T_1)\} & s = \varnothing \\ x \mapsto \{(\overline{v:T})\} \cup \{(v_1:T_1)\}, s' & s = x \mapsto \{(\overline{v:T})\}, s' \\ y \mapsto \{(\overline{v:T})\}, s' \oplus x \mapsto (v_1:T_1) & s = y \mapsto \{(\overline{v:S})\}, s' \end{cases}$$

$$\begin{array}{c} \boxed{c \longrightarrow c} \\ b[s] \longrightarrow b & (\mathsf{Bool}) \\ n[s] \longrightarrow n & (\mathsf{Num}) \\ op[s] \longrightarrow op & (\mathsf{Op}) \\ (t::T)[s] \longrightarrow t[s]::T & (\mathsf{AscSub}) \\ (\mathsf{mlet}\ x:T_1=t_1\ \mathsf{in}\ t_2)[s] \longrightarrow \mathsf{mlet}\ x:T_1=t_1[s]\ \mathsf{in}\ t_2[s] & (\mathsf{LetSub}) \\ (t_1\ t_2)[s] \longrightarrow t_1[s]\ t_2[s] & (\mathsf{AppSub}) \\ v::T \longrightarrow v & (\mathsf{Asc}) \\ \mathsf{mlet}\ x:T_1=v\ \mathsf{in}\ t_2[s] \longrightarrow t_2[x\mapsto (v:T_1)\oplus s] & (\mathsf{Let}) \\ ((\lambda x.\ t_2)^{T_1\to T_2})[s]\ v \longrightarrow ([x\mapsto v]t_2)[s] & (\mathsf{App}) \\ \mathsf{add}\ n \longrightarrow n+1 & (\mathsf{Sum}) \\ \mathsf{not}\ b \longrightarrow \neg\ b & (\mathsf{Negation}) \\ \end{array}$$

Figure 2: Configuration reduction rules.

Definition 2 (flat). The function flat is defined as follows:

$$\mathsf{flat}(s) = \begin{cases} \varnothing & s = \varnothing \\ x \mapsto (v_1:T_1) \cdots, x \mapsto (v_n:T_n), \mathsf{flat}(s') & s = x \mapsto \{(\overline{v:T})\}, s' \end{cases}$$

Definition 3 (lookup). The function lookup is defined as follows:

$$\mathsf{lookup}(x,s,S') = \begin{cases} v_i & s = x \mapsto \{(\overline{v:S})\}, s' \land S' = S_i \\ \mathsf{lookup}(x,s',S') & s = y \mapsto \{(\overline{v:S})\}, s' \\ \mathsf{error} & s = \varnothing \end{cases}$$

$$\mathsf{lookup}(x_1, x_2, s_1, s_2) = \begin{cases} (v_1, v_2) & ! \exists x_1 \mapsto (v_1 : T_1) \in \mathsf{flat}(s_1) \, \wedge \, ! \exists x_2 \mapsto (v_2 : T_1) \in \mathsf{flat}(s_2) \\ \mathsf{error} & otrw \end{cases}$$

Definition 4 (tag). The function tag is defined as follows:

$$\mathsf{tag}(v) = \begin{cases} \mathsf{Int} & v = n \\ \mathsf{Bool} & v = b \\ T_1 \to T_2 & v = (\lambda x.\ t_2)^{T_1 \to T_2} \end{cases}$$

$$\frac{v = \mathsf{lookup}(x,[s],T)}{x[s] :: T \to v :: T} \qquad (\mathsf{AscVar})$$

$$\frac{v = \mathsf{lookup}(x_1,[s_1],T_1)}{\mathsf{mlet} \ x : T_1 = x_1[s_1] \ \mathsf{in} \ c_2 \to \mathsf{mlet} \ x : T_1 = v \ \mathsf{in} \ c_2} \qquad (\mathsf{LetVar})$$

$$\frac{v = \mathsf{lookup}(x_1,[s_1],T_1)}{((\lambda x. \ t_2)^{T_1 \to T_2})[s] \ x_2[s_2] \to \mathsf{mlet} \ x : T_1 = v \ \mathsf{in} \ c_2} \qquad (\mathsf{AppVar}1)$$

$$\frac{v = \mathsf{lookup}(x_2,[s_2],T_1)}{((\lambda x. \ t_2)^{T_1 \to T_2})[s] \ v_2} \qquad (\mathsf{AppVar}1)$$

$$\frac{T = \mathsf{tag}(v_2) \quad v_1 = \mathsf{lookup}(x_1,[s_1],T \to *)}{x_1[s_1] \ v_2 \to v_1 \ v_2} \qquad (\mathsf{AppVar}2)$$

$$\frac{(v_1,v_2) = \mathsf{lookup}(x_1,x_2,[s_1],[s_2])}{x_1[s_1] \ x_2[s_2] \to v_1 \ v_2} \qquad (\mathsf{AppVar}3)$$

$$\frac{v_1[s_1] \ x_2[s_2] \to v_1 \ v_2}{x_1[s_1] \ x_2[s_2] \to v_1 \ v_2} \qquad (\mathsf{AppVar}3)$$

$$\frac{v_1[s_1] \ x_2[s_2] \to v_1 \ v_2}{x_1[s_1] \ x_2[s_2] \to v_1 \ v_2} \qquad (\mathsf{AppVar}3)$$

$$\frac{v_1[s_1] \ x_2[s_2] \to v_1 \ v_2}{x_1[s_1] \ x_2[s_2] \to v_1 \ v_2} \qquad (\mathsf{AppVar}3)$$

$$\frac{v_1[s_1] \ x_2[s_2] \to v_1 \ v_2}{x_1[s_1] \ x_2[s_2] \to v_1 \ v_2} \qquad (\mathsf{AppVar}3)$$

$$\frac{v_1[s_1] \ x_2[s_2] \to v_1 \ v_2}{x_1[s_1] \ x_2[s_2] \to v_1 \ v_2} \qquad (\mathsf{App}3)$$

$$\frac{v_1[s_1] \ x_2[s_2] \to v_1 \ v_2}{x_1[s_1] \ x_2[s_2] \to v_1[s_2]} \qquad (\mathsf{App}3)$$

Figure 3: Configuration reduction rules.