

Back to Self-Driving Car Engineer

Finding Lane Lines on the Road

CODE REVIEW HISTORY

Meets Specifications

This is a good work that meets all the project requirements . Please do go through the comments on your work . Keep up the good work that you have put for this project.

This research paper goes into how to detect curves and will also help in detecting faded lanes. It uses an extended version of hough lines algorithm to detect tangents to the curve which can help you detect the curve. http://airccj.org/CSCP/vol5/csit53211.pdf

Required Files

The project submission includes all required files:

- · Ipython notebook with code
- A writeup report (either pdf or markdown)

Lane Finding Pipeline

The output video is an annotated version of the input video.

Great work! Your annotations are clearly visible in the video

In a rough sense, the left and right lane lines are accurately annotated throughout almost all of the video. Annotations can be segmented or solid lines

there is a clear demarkation between the two lanes! You have taken a very good step towards lane detection and your pipeline reflects that :)

Visually, the left and right lane lines are accurately annotated by solid lines throughout most of the video.

I would suggest tweaking the following values to get an improvement in lane detection for the first two videos : threshold ~ 50

min_line_len ~ 100

max_line_gap ~ 160

Increasing the value threshold increases the minimum number of intersection required to detect a line and thus is able to differentiate between the left and right lanes better

min_line_len as the name suggests will help you make sure that the line segments are drawn on the actual lines and thus help eliminate some of the lines.

Increasing your value of max_line_gap will help you get more connected annotated lines when there are broken lanes as it allow points that are farther away from each other to be connected with a single line.

Reflection

Reflection describes the current pipeline, identifies its potential shortcomings and suggests possible improvements. There is no minimum length. Writing in English is preferred but you may use any language.

nice work

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