

TransportGPT: Prompt Augmentation Generation

Elias Lim, Moreno Koko, Javier Ng, Jden Goh, Yeo Shu Heng

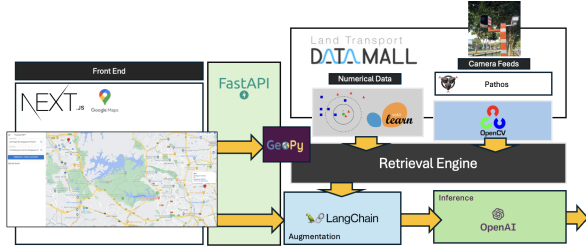


Fig. 2. Proposed Architecture for Prompt Augmentation Generation

I. INTRODUCTION

Large Language Models (LLM) show SOTA performance on NLP tasks, however, they fail when task/context-specific requirements are present. Retrieval Augmented Generation (RAG) [1] allows LLM to work on a given task and prevent hallucinations by augmenting the input embedding with additional ground truth data the model should consider.

II. ARCHITECTURE

Due to lack of time to create good datasets, we abandoned a traditional RAG-like framework, but carry over the intuition by injecting context through a *augmented prompt* over an ensemble of downstream data. Augmentation is done via LangChain. We integrated it with Google Maps to give drivers a platform they are familiar and comfortable with for seamless adoption.

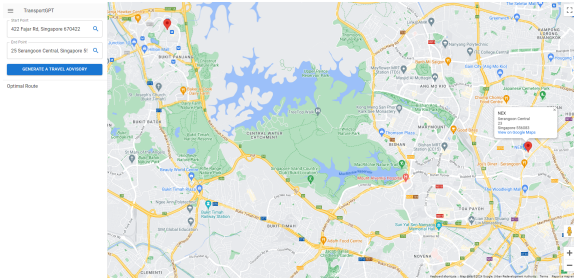


Fig. 1. TransportGPT works seamlessly with Google Maps

III. PERFORMANCE & RESULTS

A. Ensemble of Data

Continuous data from LTA data mall follows a 1-stage retrieval on journey-relevant features (Estimated Travel Time, Traffic Flow, Roadworks) by transposing the user's position and destination into a coordinate vector \mathcal{D}_{user} and using KNN



Fig. 3. YoloV3 shows consistent performance across lighting conditions.

against the coordinate vector representation of LTA data mall points to obtain the most relevant datapoint \mathcal{D}_{rel} via

$$\mathcal{D}_{rel} = \underset{i \in |\mathcal{D}|}{\operatorname{argmin}} \sqrt{\|\mathcal{D}_i - \mathcal{D}_{user}\|_2^2}$$

Live camera feeds, alongside YoloV3, supplements the augmentation process by providing the density of vehicles within user's vicinity. The image processing pipeline could be extended to consider of road works, type of vehicles and road size in the future. We tried to ensure real-time inference via multiprocessing.

B. Prompt Augmentation

The following displays some prompts generated from our augmentation process, we can see traffic conditions being considered in the output.

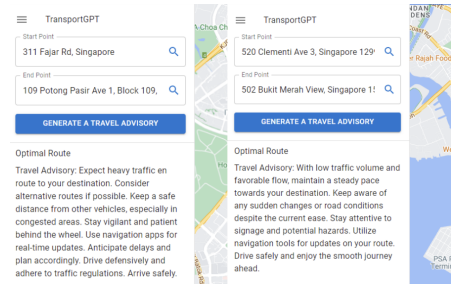


Fig. 4. Outputs generated by TransportGPT across various road conditions.

IV. FURTHER WORK

With more time for data collection, we hope to explore a more RAG-like structure, with augmentation conducted on input-embedding. We could add a separate retrieval engine and train in tandem with PEFT on the LLM via LoRA (Low Rank Adaptation) [2] to cope with compute. Generalization gaps due to LoRA could be avoided by improving its learning capacity using various techniques [3]. LoRA also allow flexibility to extend into low-compute incremental learning deployments [4] and increase task flexibility via a MoA [5] architecture, allowing our platform to be scalable.

V. BIBLIOGRAPHY

The following consists of sources & references used in the construction of our report.

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